

# Measuring lensing effect on temperature and polarizations

Toshiya Namikawa (PD@YITP)

# CONTENTS

---

1. Brief introduction
2. How to estimate lensing fields
3. Bias-hardened estimator for lensing reconstruction from polarization  
*TN*, Hanson & Takahashi (2013)  
*TN*, Hanson & Takahashi in prep.
4. Summary

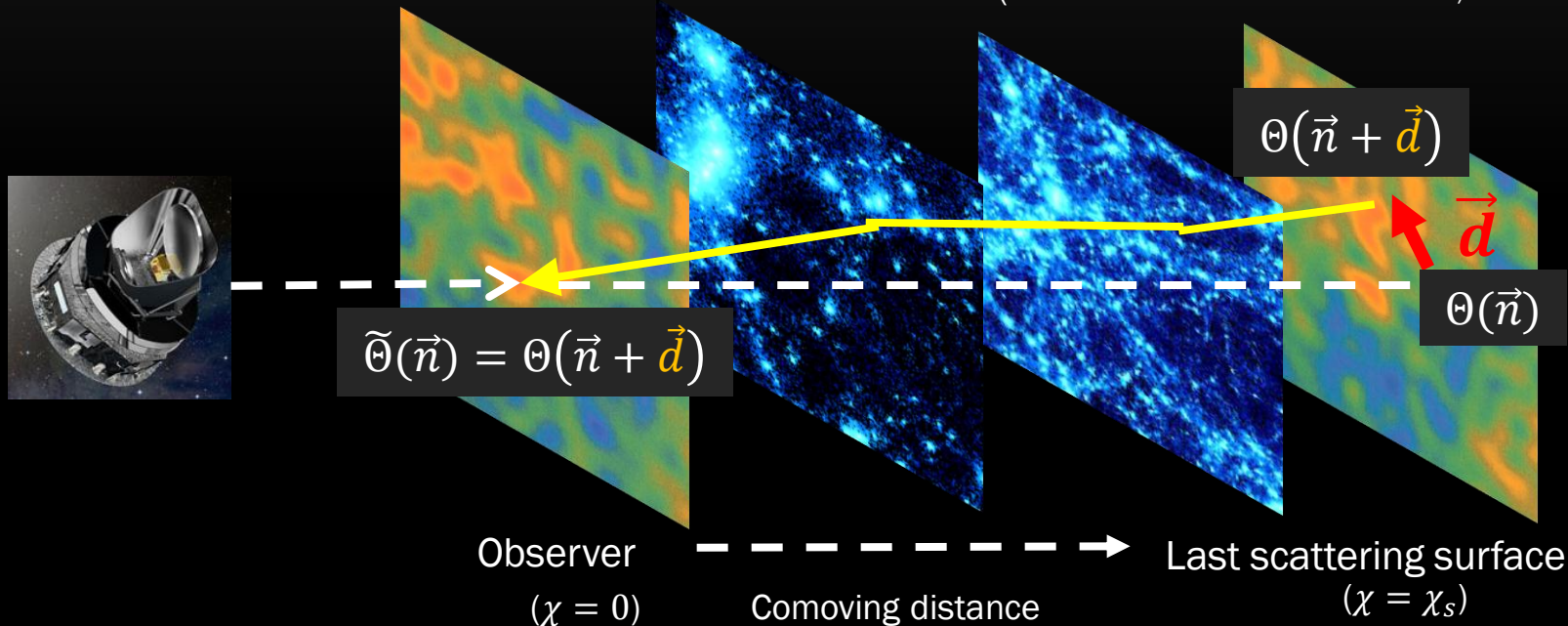
# 1. BRIEF INTRODUCTION

---

# CMB LENSING

- CMB Lensing = distortion of spatial pattern of CMB anisotropies

(Reviews : Lewis&Challinor'06, Hanson+'10)



- Deflection angle

$$\vec{d}(\vec{n}) = \nabla \phi(\vec{n})$$

$\nearrow$   
Lensing potential

$$\phi(\vec{n}) = -2 \int_0^{\chi_s} d\chi \frac{\chi_s - \chi}{\chi \chi_s} \Psi(\eta_0 - \chi, \chi \vec{n})$$

Gravitation potential from LSS

Estimate lensing potential from lensed CMB maps,  
and extract cosmological information

# Cosmological Application 1: Dark energy/ Massive Neutrinos

Dark energy, massive neutrinos



Density perturbations



Gravitational potential



$\phi(\vec{n})$

gradient mode

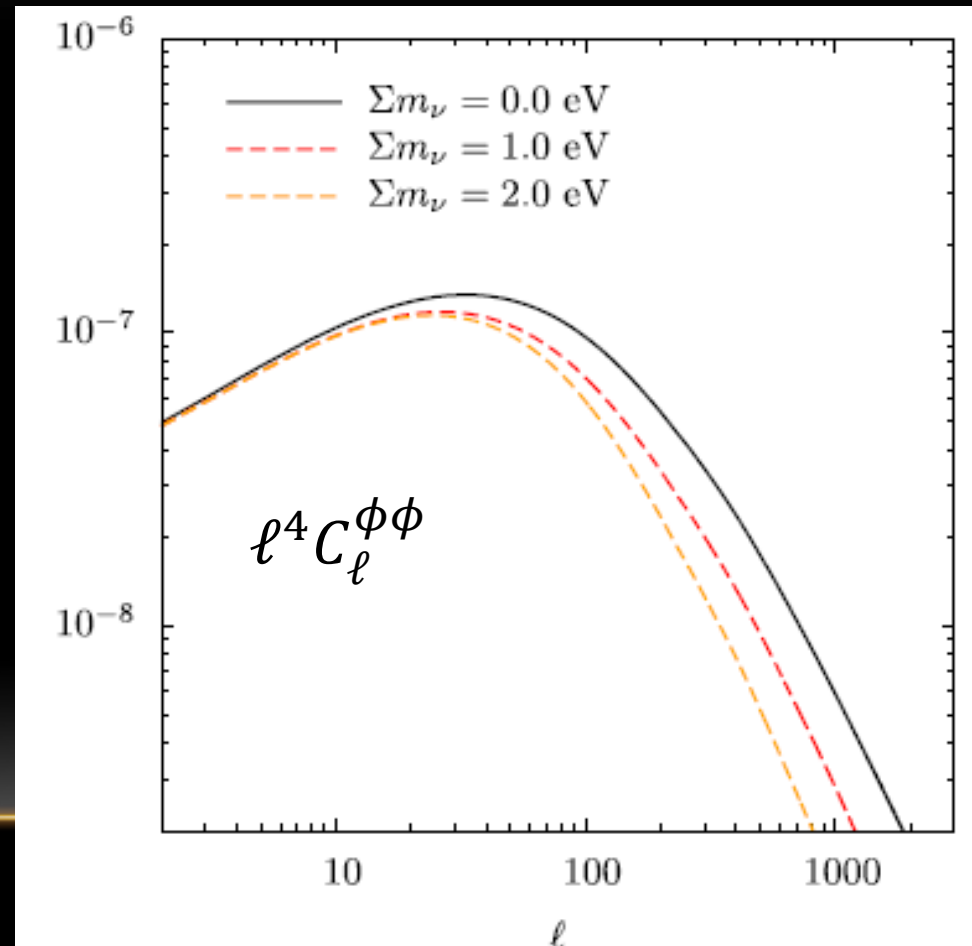


$$\phi_{\ell m} = \int d^2\vec{n} Y_{\ell, m}(\vec{n}) \phi(\vec{n})$$



$$C_{\ell}^{\phi\phi} = \frac{1}{2\ell + 1} \sum_{m=-\ell}^{\ell} |\phi_{\ell m}|^2$$

(see, e.g., Hu'01, Lesgourgues&Pastor'06)



# COSMOLOGICAL APPLICATION 2: CURL MODE

- Even/Odd parity decomposition

(e.g., Cooray+'05; TN+'12; Book+'12; Yamauchi+'12; Yamauchi+'13 ; TN+'13 )

✓ Deflection angle

$$d_a = \underbrace{\partial_a \phi}_{\text{gradient}} + \epsilon_a^b \underbrace{\partial_b \omega}_{\text{curl}}$$

- Sources

Gradient

$\phi$



Scalar



Vector



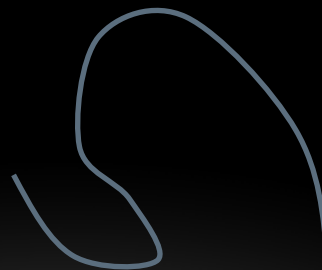
Curl

$\omega$

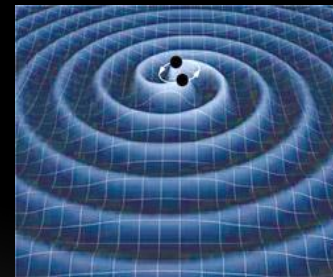
Tensor

density perturbations (linear)

Cosmic string



GWs



from NASA

Magnetic fields



from ESO

Also important for a test of systematics

# Other motivations to measure CMB lensing

- ✓ CMB Lensing generates **B-mode** and **secondary non-Gaussianity**

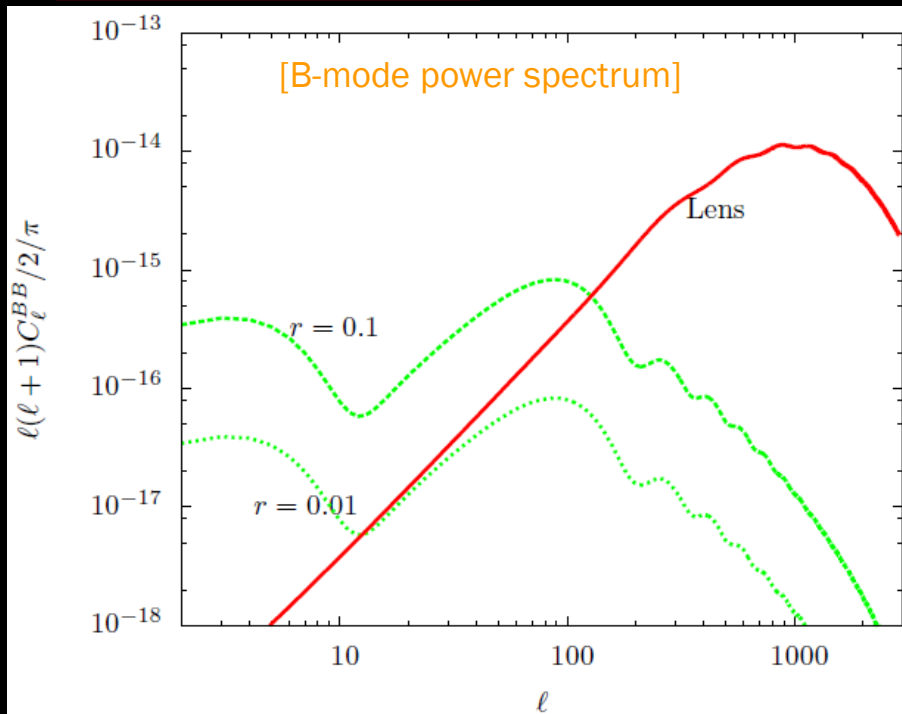


noise for primordial GWs detection



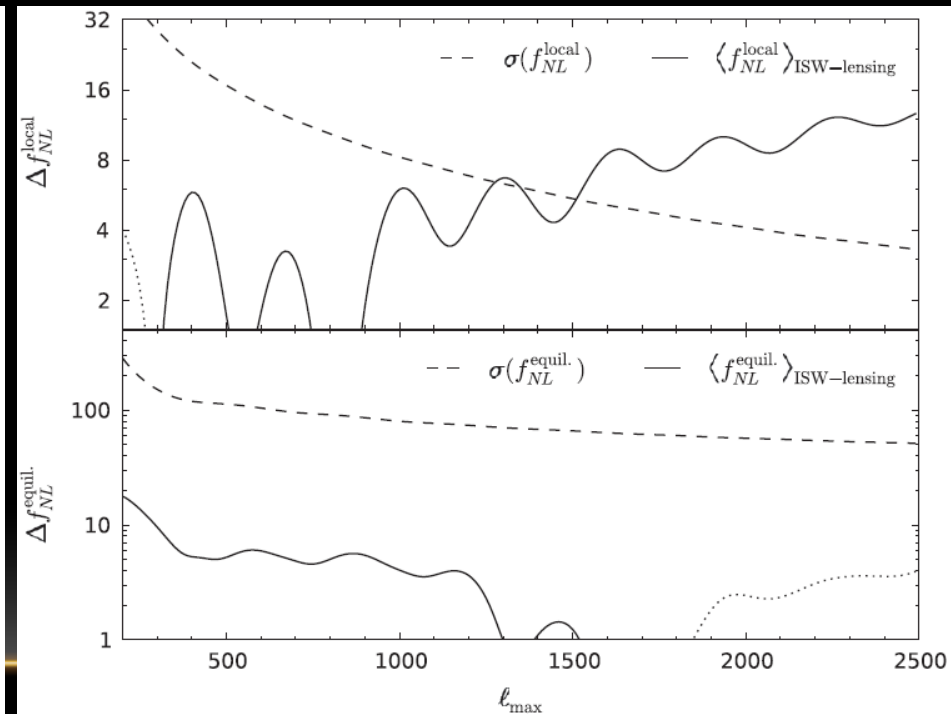
noise for primordial non-Gaussianity

## Primordial GWs



e.g., Knox+'02, Kesden+'02, Smith+'09

## Primordial non-Gaussianity



Hanson+'09

## 2. HOW TO ESTIMATE LENSING EFFECT

---



# ESTIMATING LENSING FIELDS THROUGH ...

---

- Angular power spectrum
  - ✓ useful to see whether the observed CMB anisotropies are lensed or not
  
- **Lensing reconstruction** = estimate lensing potentials  
(Das+'11; van Engelen+'12; PLANCK'13)
  - ✓ useful for cross-correlation studies with, e.g., cosmic shear, galaxy clustering, etc
  
- Minkowski Functionals (e.g., Schmalzinger+'00) may be another possible method to measure lensing effect

# LENSING RECONSTRUCTION

- Basic Idea (Review: Hanson+'10)

- ✓ Anisotropy induced by lensing creates mode coupling between different Fourier modes

$$\tilde{\Theta}_{\vec{\ell}} = \Theta_{\vec{\ell}} - \int d^2\vec{L} \left[ \underline{\vec{L}'} \phi_{\underline{\vec{L}'}} + (\star \underline{\vec{L}'}) \underline{\varpi_{\vec{L}'}} \right] \cdot \vec{L} \Theta_{\vec{L}} \quad (L' = L - \ell)$$

- Estimator for  $x (= \phi, \varpi)$  (e.g., Hu&Okamoto'02; Hirata&Seljak'03a,b; Namikawa+'12)

(Filtered) observed data

$$\hat{x}_L^{(\Theta\Theta)} = A_L^{xx,(\Theta\Theta)} \int d^2\ell \, g_{L,\ell}^{x,(\Theta\Theta)} \boxed{\bar{\Theta}_\ell \bar{\Theta}_{\vec{L}-\vec{\ell}}} \quad \bar{\Theta}_L = \frac{\tilde{\Theta}_L}{C_L^{\Theta\Theta}}$$

optimal weighting

Determined by “unbiased” and “optimal” (minimize non-lensing contributions) conditions

Lensing fields are estimated through mode-coupling (off-diagonal covariance) of CMB anisotropies

# LENSING RECONSTRUCTION

- Parity decomposition of polarization

$$E_{\vec{\ell}} \pm i B_{\vec{\ell}} = - \int d^2 n e^{-in\ell} (Q \pm iU) e^{\mp 2i\varphi_\ell}$$

Stokes Q and U parameters

- ✓ Similar to temperature case, anisotropy induced by lensing creates mode coupling between different Fourier modes

$$\tilde{E}_{\vec{\ell}} = E_{\vec{\ell}} - \int d^2 L \left[ \vec{L}' \phi_{\vec{L}'} + (\star \vec{L}') \varpi_{\vec{L}'} \right] \cdot \vec{L} (E_{\vec{L}} \cos 2\varphi_{L,\ell} - B_{\vec{L}} \sin 2\varphi_{L,\ell})$$

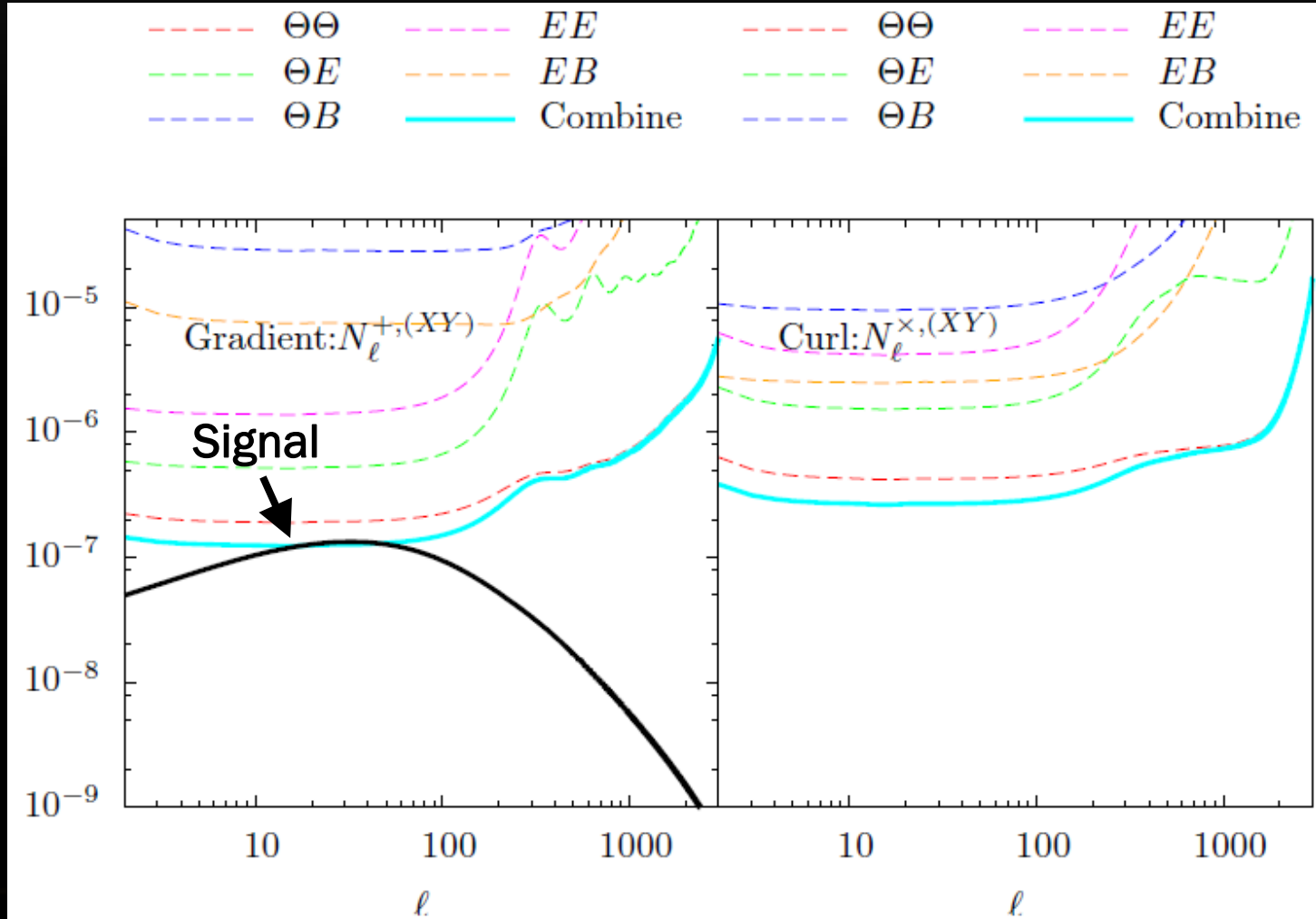
$$\tilde{B}_{\vec{\ell}} = B_{\vec{\ell}} - \int d^2 L \left[ \vec{L}' \phi_{\vec{L}'} + (\star \vec{L}') \varpi_{\vec{L}'} \right] \cdot \vec{L} (B_{\vec{L}} \cos 2\varphi_{L,\ell} + E_{\vec{L}} \sin 2\varphi_{L,\ell})$$

- Generalizing quadratic estimator

$$\hat{x}_L^{(XY)} = A_L^{xx(XY)} \int d^2 \ell g_{L,\ell}^{x,(XY)} \bar{X}_\ell \bar{Y}_{\vec{L}-\vec{\ell}} \quad (X, Y = \Theta, E, B)$$

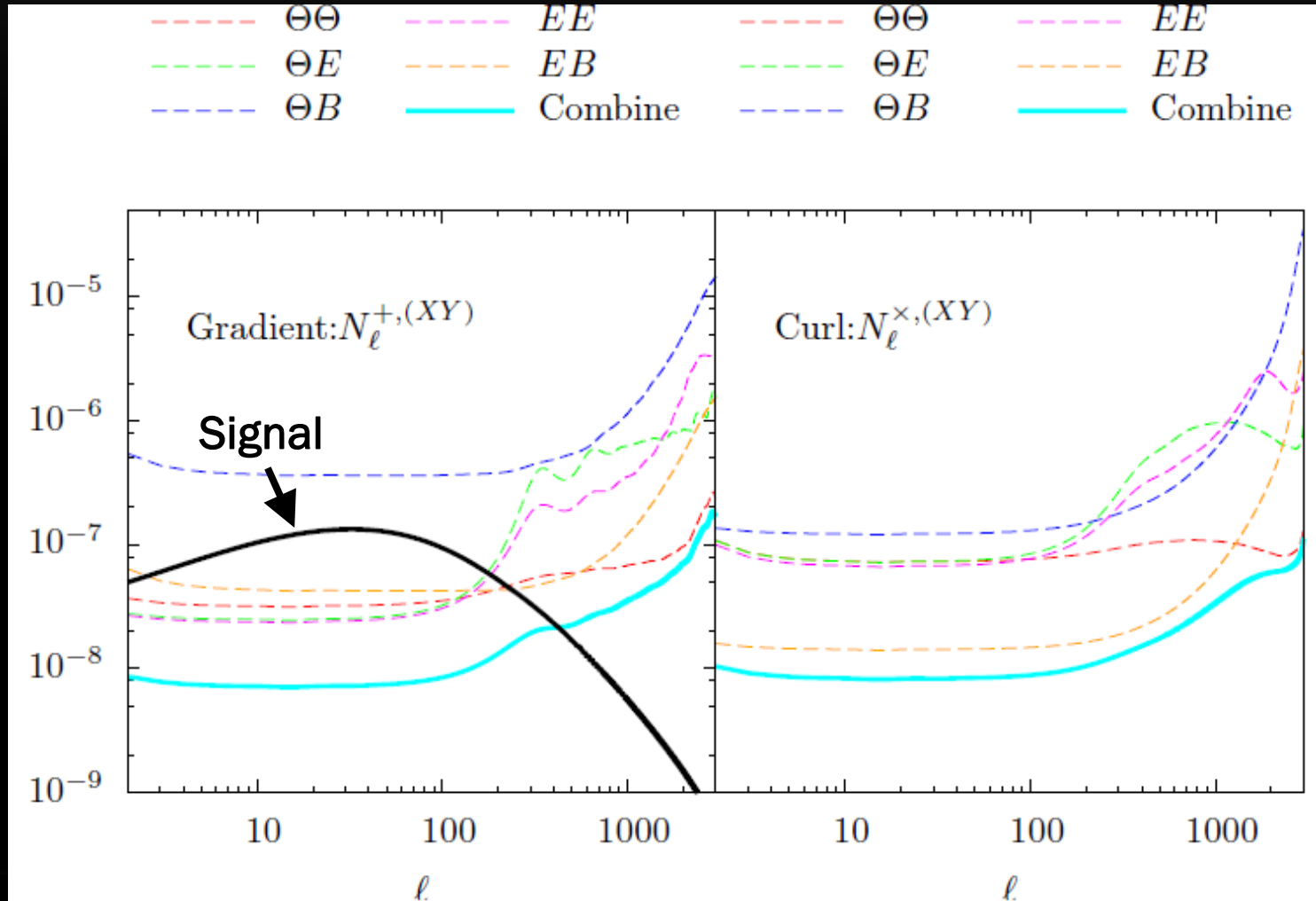
# LENSING RECONSTRUCTION

- Signal and noise (Planck)



# LENSING RECONSTRUCTION

- Signal and noise (ground based experiment like SPTpol, PolarBear, ACTPol)



- ✓ Near future, polarizations are quite useful to reconstruct lensing fields.

### 3. BIAS-HARDENED ESTIMATOR FOR LENSING RECONSTRUCTION FROM CMB MAPS

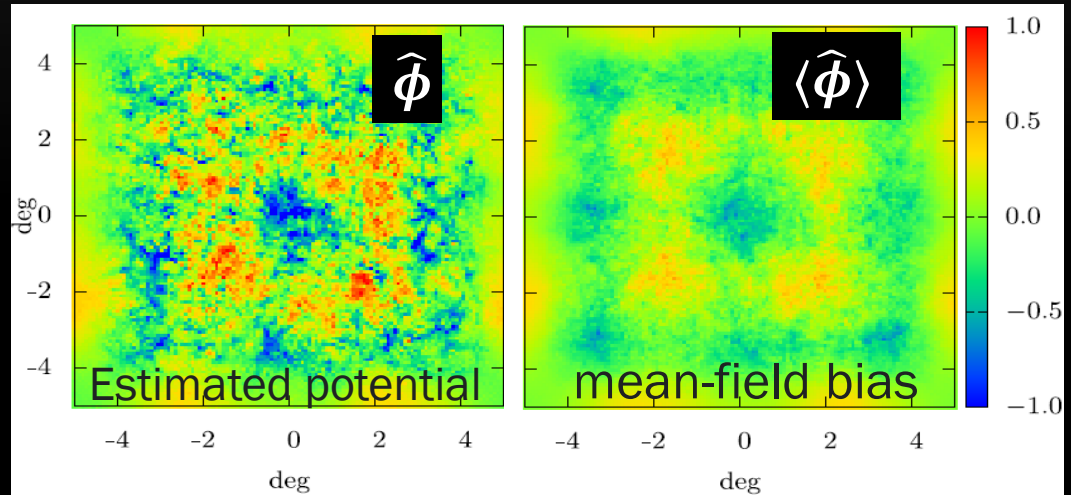
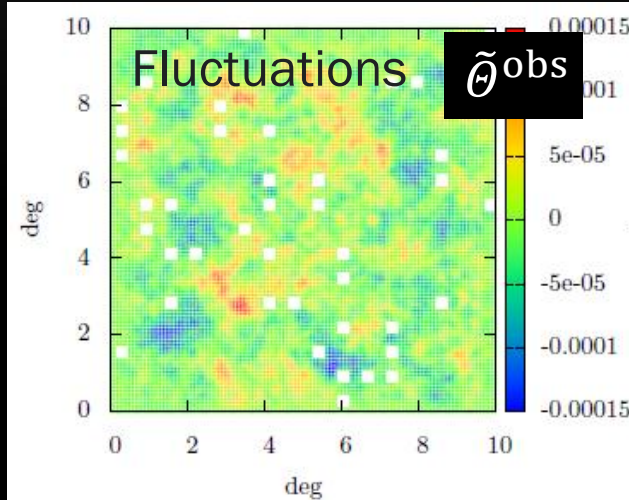
---

Based on *TN*, Hanson & Takahashi (2013)

*TN*, Hanson & Takahashi in prep.

# MEAN-FIELD BIAS (MASK)

- Survey boundary, points source masks



- Mean-field bias

$$\tilde{\Theta}^{\text{obs}}(\vec{n}) = (1 - M(\vec{n}))\tilde{\Theta}(\vec{n})$$

$$M(\vec{n}) = \begin{cases} 0 & \text{(observed region)} \\ 1 & \text{(otherwise)} \end{cases}$$

$$\rightarrow \tilde{\Theta}_{\vec{\ell}}^{\text{obs}} = \tilde{\Theta}_{\vec{\ell}} - \int d^2L M_{\vec{\ell}-\vec{L}} \tilde{\Theta}_{\vec{L}}$$

Window function

$$\rightarrow \langle \hat{x}_{\vec{L}}^{(\Theta\Theta)} \rangle = \underbrace{R_L^{xM,(\Theta\Theta)}}_{\text{mean-field bias}} M_L \left( R_L^{xM,(\Theta\Theta)} \equiv A_L^{xx,(\Theta\Theta)} \int d^2L g_{\ell,L}^{x,(\Theta\Theta)} f_{\ell,L}^{M,(\Theta\Theta)} \right)$$

mean-field bias

$$f_{\ell,L}^{M,(\Theta\Theta)} = -C_L^{\Theta\Theta} - C_{|\ell-L|}$$

- ✓ The situation is similar for polarizations (Q,U)

# MEAN-FIELD BIAS (UNRESOLVED PS)

- Unresolved point sources/inhomogeneous noise

Data model must be

$$X^{obs}(\vec{n}) = X(\vec{n}) + n^X(\vec{n}) \quad (X = \Theta, E, B)$$

Assumptions:

$$\langle n^X(\vec{n})n^Y(\vec{n}') \rangle = S^{XY}(\vec{n})\delta(\vec{n} - \vec{n}')$$

$$\langle \tilde{X}n^Y \rangle = 0$$

- Mean-field bias

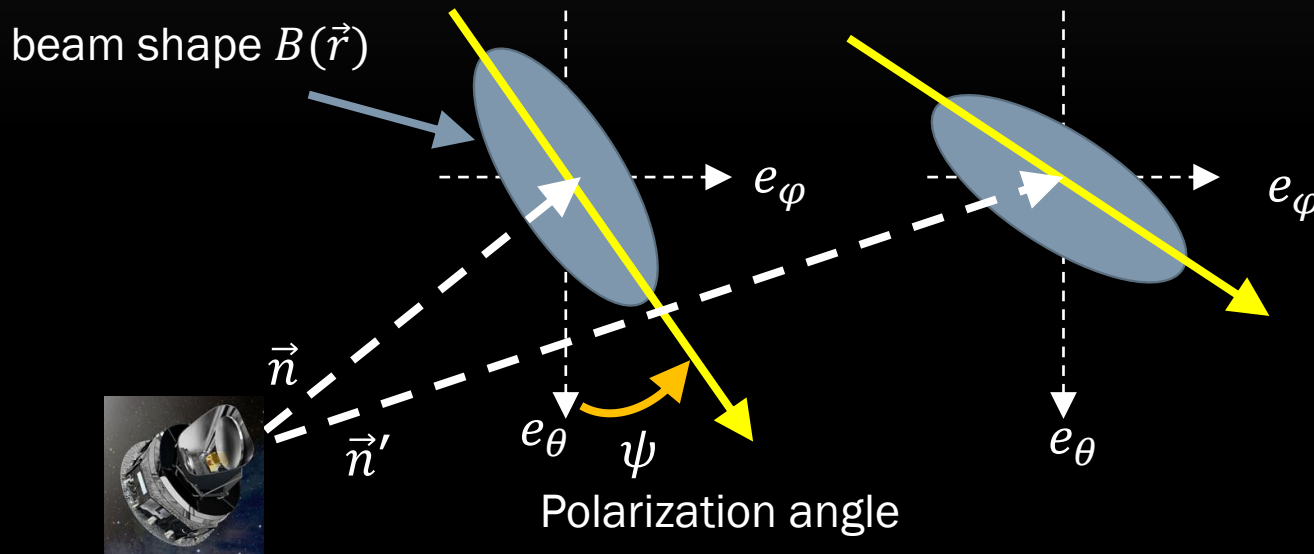
$$\langle \hat{x}_{\vec{L}}^{(XY)} \rangle = R_L^{xS,(XY)} S_L^{XY} \left( R_L^{xS,(XY)} \equiv A_L^{xx,(XY)} \int dL g_{\ell,L}^x f_{\ell,L}^{S,(XY)} \right)$$
$$f_{\ell,L}^{S,(XY)} = 1$$



# MEAN-FIELD BIAS (BEAM)

- Polarization angle systematics associated with beam

(e.g., Souradeep+'01; Ng'05; Shimon+'08)



$$\tilde{X}^{obs}(\vec{n}; \psi) = \int d^2\vec{r} B(\vec{r}; \psi) \tilde{X}(\vec{n} - \vec{r})$$

If  $\psi$  depends on sky position, the observed anisotropies have off-diagonal covariance

- Mean-field bias

For two-beam experiment,

$$\langle \hat{x}_{\vec{\ell}} \rangle = \sum_{p=0,\pm} \sum_n R_{\ell}^{x,(n,p)} \psi_{\ell}^{(n,p)}$$

# EXPRESSION FOR MEAN-FIELD BIAS

- Mean-field bias  $\alpha = \Theta\Theta, \Theta E, \dots$

$$\langle \hat{x}_L^{(\alpha)} \rangle = \sum_{y=\phi, \bar{\omega}, M, \dots} R_L^{xy,(\alpha)} y_L^{(\alpha)}$$

$$\left( R_\ell^{xy,(\alpha)} \equiv A_\ell^{xx,(\alpha)} \int dL g_{\ell,L}^{x,(\alpha)} f_{\ell,L}^{y,(\alpha)} \right)$$

	Masking
$\Theta\Theta$	$-\tilde{C}_L^{\Theta\Theta} - \tilde{C}_{L'}^{\Theta\Theta}$
$\Theta E$	$-\tilde{C}_L^{\Theta E} \cos 2\varphi_{L,L'} - \tilde{C}_{L'}^{\Theta E}$
$EE$	$(\tilde{C}_L^{EE} + \tilde{C}_{L'}^{EE}) \cos \varphi_{L,L'}$
$\Theta B$	$-\tilde{C}_L^{\Theta E} \sin 2\varphi_{L,L'}$
$EB$	$(\tilde{C}_L^{EE} + \tilde{C}_{L'}^{BB}) \sin \varphi_{L,L'}$
$BB$	$(\tilde{C}_L^{BB} + \tilde{C}_{L'}^{BB}) \cos \varphi_{L,L'}$

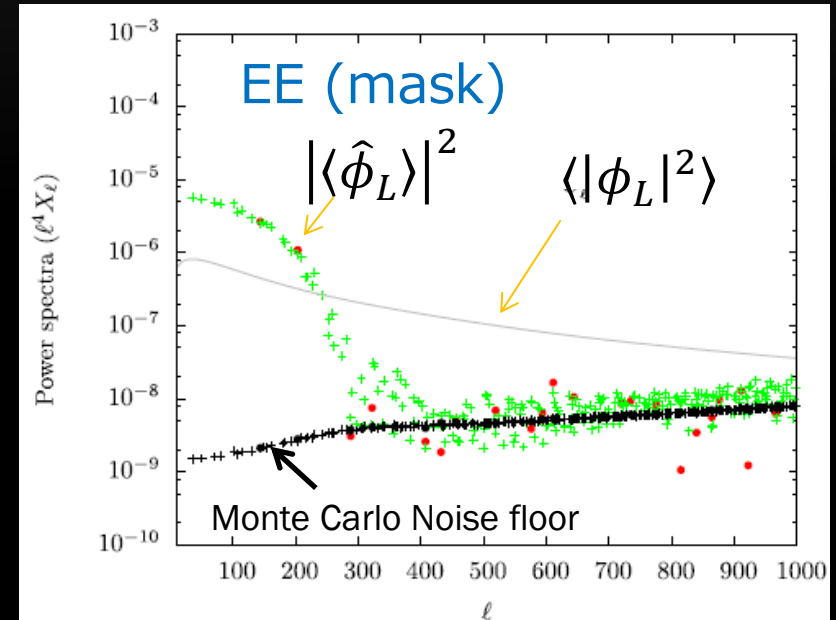
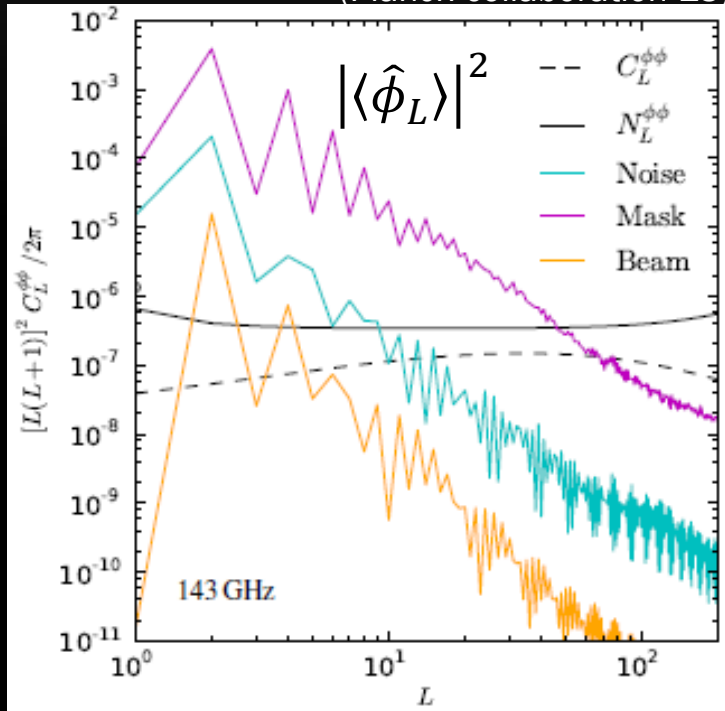
	Masking (with pure E and B modes)
$\Theta\Theta$	0
$\Theta E$	$(L/L')^2 \tilde{C}_L^{\Theta E} + \tilde{C}_{L'}^{\Theta E}$
$EE$	$(L/L')^2 \tilde{C}_L^{EE} + (L \leftrightarrow L')$
$\Theta B$	0
$EB$	0
$BB$	$(L/L')^2 \tilde{C}_L^{BB} + (L \leftrightarrow L')$

Beam, $p = 0$	
$\Theta\Theta$	$[\mathcal{B}_L^{(\Theta,\Theta),(n,0)} \tilde{C}_L^{\Theta\Theta} + \mathcal{B}_L^{(\Theta,E),(n,0)} \tilde{C}_L^{\Theta E}] + (L \leftrightarrow L')$
$\Theta E$	$\mathcal{B}_{L'}^{(\Theta,\Theta),(n,0)} \tilde{C}_{L'}^{\Theta E} + \mathcal{B}_{L'}^{(\Theta,E),(n,0)} \tilde{C}_{L'}^{EE}$
$EE$	0
$\Theta B$	$\mathcal{B}_{L'}^{(\Theta,B),(n,0)} \tilde{C}_{L'}^{BB}$
$EB$	0
$BB$	0
Beam, $p = \pm$	
$\Theta\Theta$	0
$\Theta E$	$e^{\mp 2i\varphi_{L'}} [\mathcal{B}_L^{(E,\Theta),(n,\pm)} \tilde{C}_L^{\Theta\Theta} + \mathcal{B}_L^{(E,E),(n,\pm)} \tilde{C}_L^{\Theta E}]$
$EE$	$e^{\mp 2i\varphi_{L'}} [\mathcal{B}_L^{(E,\Theta),(n,\pm)} \tilde{C}_L^{\Theta E} + \mathcal{B}_L^{(E,E),(n,\pm)} \tilde{C}_L^{EE}] + (L \leftrightarrow L')$
$\Theta B$	$e^{\mp 2i\varphi_{L'}} [\mathcal{B}_L^{(B,\Theta),(n,\pm)} \tilde{C}_L^{\Theta\Theta} + \mathcal{B}_L^{(B,E),(n,\pm)} \tilde{C}_L^{\Theta E}]$
$EB$	$e^{\mp 2i\varphi_{L'}} [\mathcal{B}_L^{(B,\Theta),(n,\pm)} \tilde{C}_L^{\Theta E} + \mathcal{B}_L^{(B,E),(n,\pm)} \tilde{C}_L^{EE}] + e^{\mp 2i\varphi_L} \mathcal{B}_{L'}^{(E,B),(n,\pm)} \tilde{C}_{L'}^{BB}$
$BB$	$e^{\mp 2i\varphi_{L'}} \mathcal{B}_{L,n}^{(B,B),(n,\pm)} \tilde{C}_L^{BB} + (L \leftrightarrow L')$

# SIGNIFICANCE OF MEAN-FIELD BIAS

## ✓ Mean field bias

(Planck collaboration'13)



✓ In conventional method, we compute  $R_\ell^{\phi M}$  with CI's to estimate  $\langle \hat{\phi}_\ell \rangle$ , and then subtract as  $\hat{\phi}_L - \langle \hat{\phi}_L \rangle$

✓ This method rely entirely on the knowledge of  $R_\ell^{\phi M}$ , but  $\hat{\phi}$  would be biased due to uncertainties of e.g., CI's,

**We need alternative method for cross-check**

# BIAS-HARDENED ESTIMATOR

✓ We formulate an estimator as follows

1. Similar to  $\hat{x}$ , we formulate estimator for  $a (= M, S, \Psi^{(n,p)})$
2.  $\hat{a}$  also has mean-field bias, so we combine  $\hat{a}$  and  $\hat{\phi}$  to construct an estimator which has no mean-field bias:

$$\hat{x}_L^{(\alpha)} = \sum_{y=\phi, \varpi, M, \dots} \{R_L^{-1}\}^{x,y,(\alpha)} \hat{y}_L^{(\alpha)} \quad \left( \{R_L\}^{x,y,(\alpha)} = A_\ell^{xx,(\alpha)} \int d^2 \ell g_{L,\ell}^{x,(\alpha)} f_{L,\ell}^{x,(\alpha)} \right)$$

- ✓ Comparing with the conventional approach, uncertainty in  $R_L^{xy}$  propagates to estimator in a different way, so the above estimator would utilize for cross check (more robust but a bit noisy than the conventional approach)
- ✓ Higher order terms of  $a$  is ignored
- ✓ It would be possible to estimate origin of unknown systematics (e.g., patchy reionization, motion of the earth, unresolved point sources, etc)

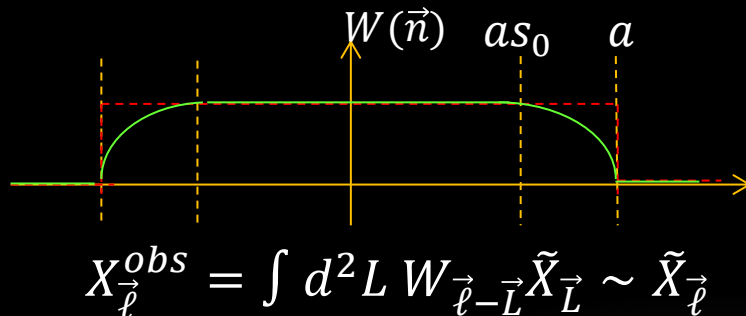
# NUMERICAL TEST

- Purpose

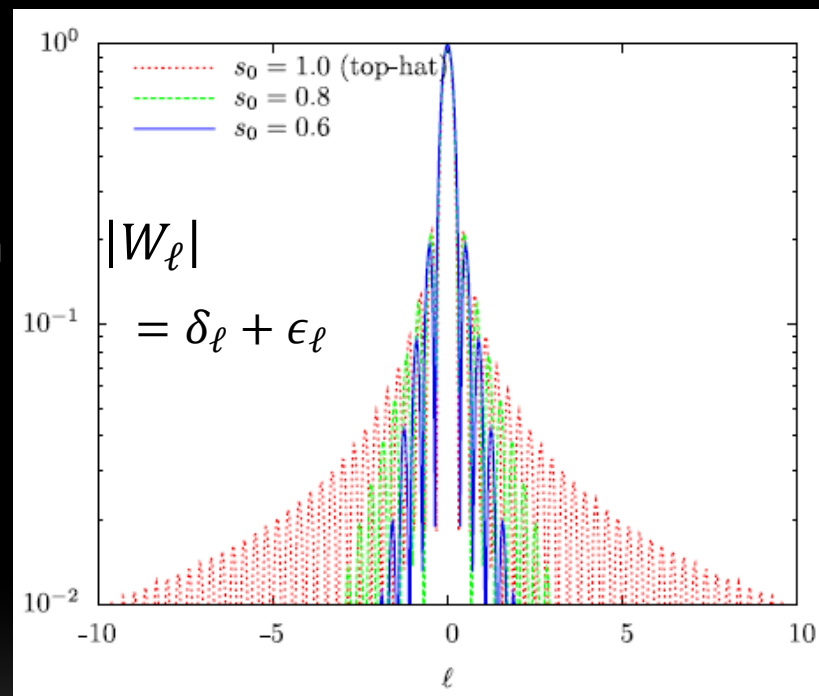
- ✓ For mask, the assumption  $\epsilon_\ell \ll 1$  is not always satisfied
- ✓ With "filtering" ( suppress  $\epsilon_\ell$  ), we test how well the bias-hardened estimator works

- Filtering for survey boundary

1. Apodization: window function is modified so that the Fourier counterpart becomes  $\delta$ -like function



2. Pure-EB estimator (e.g., Smith+'06)

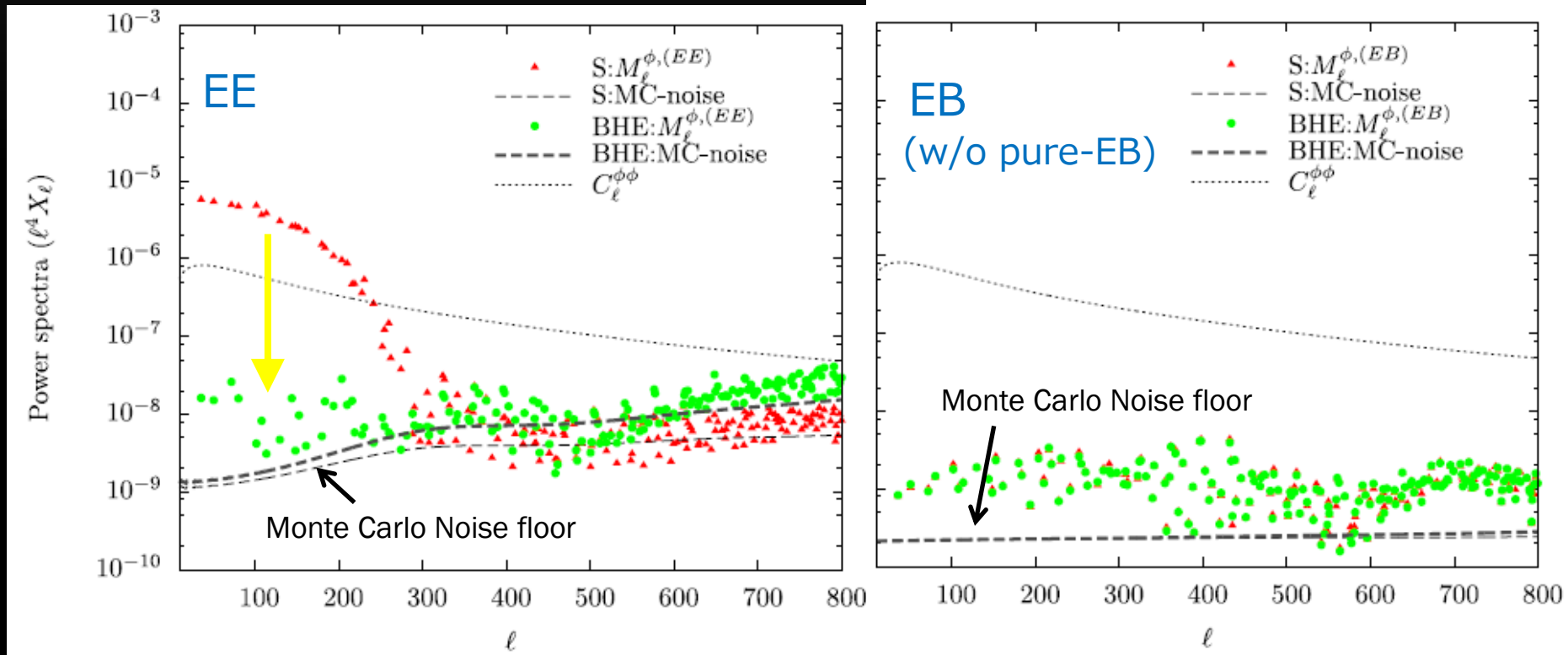


- Simulated lensed map made by Takahashi-san

- ✓  $5 \times 5 \text{ deg}^2$
- ✓  $1024^2$  grids
- ✓ 100 realizations

# NUMERICAL RESULTS

- Mean-field bias from masking [Gradient mode]

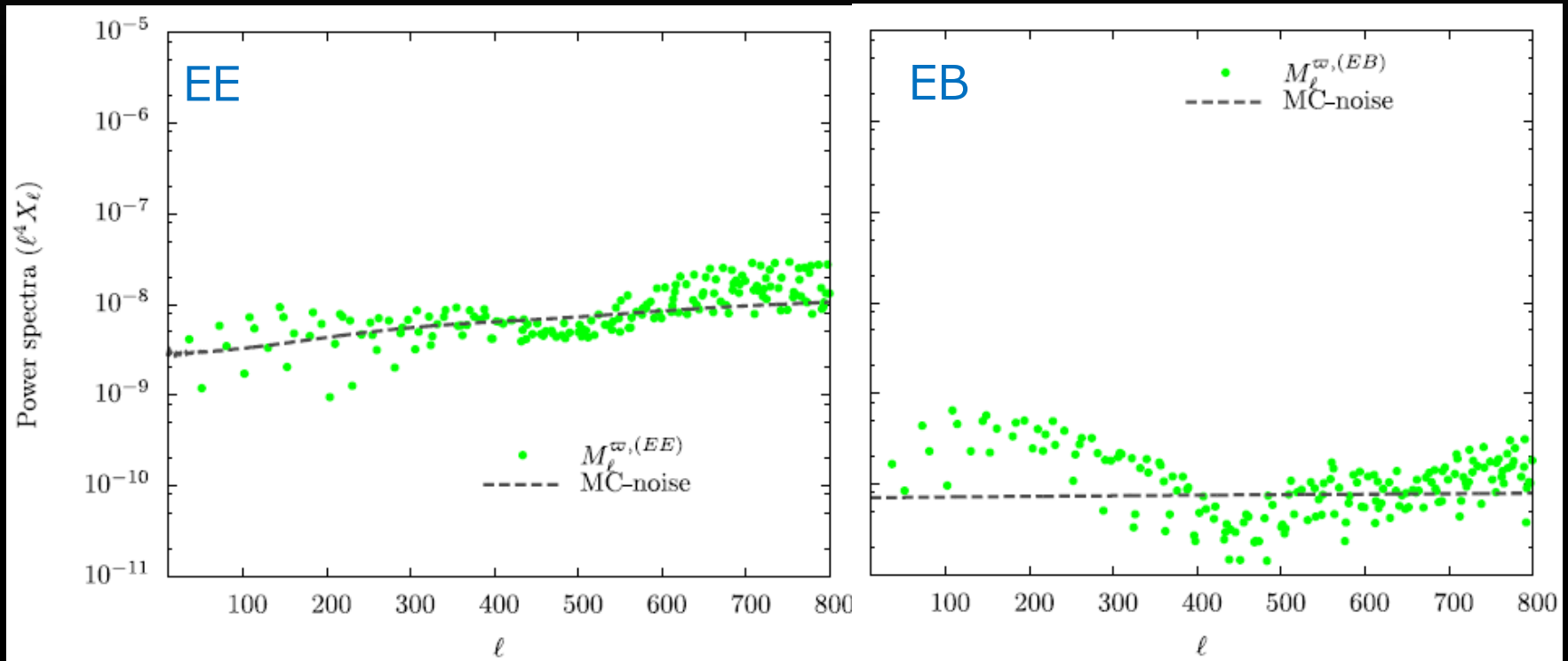


EE: Bias-hardened estimator suppresses mean-field bias down to MC noise level

EB: Even without pure-EB estimator, mean-field bias from masking is negligible compared to the signal

# NUMERICAL RESULTS

- Mean-field bias from masking [Curl mode]

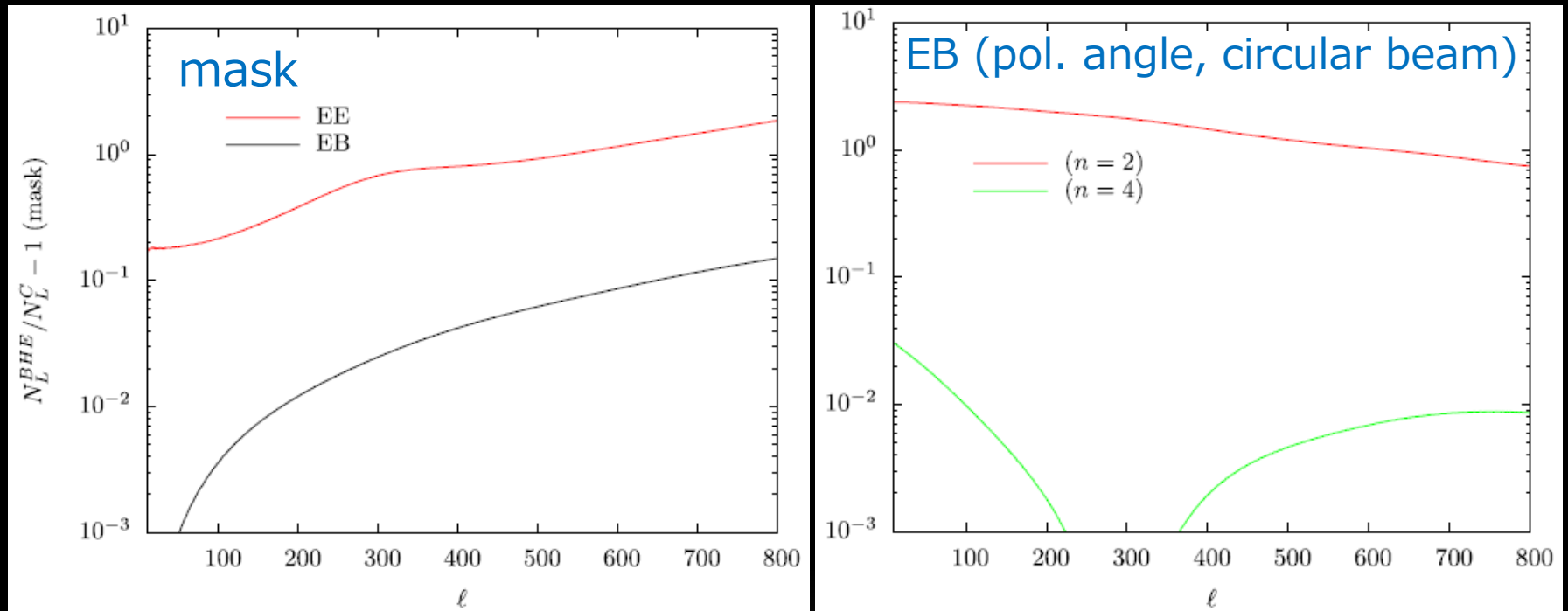


Mean-field bias from masking is negligible

# LOSS OF SIGNAL-TO-NOISE

- ✓ One concern for using bias-hardened estimator is the loss of signal-to-noise.

[Fractional difference of noise level between BHE and conventional]

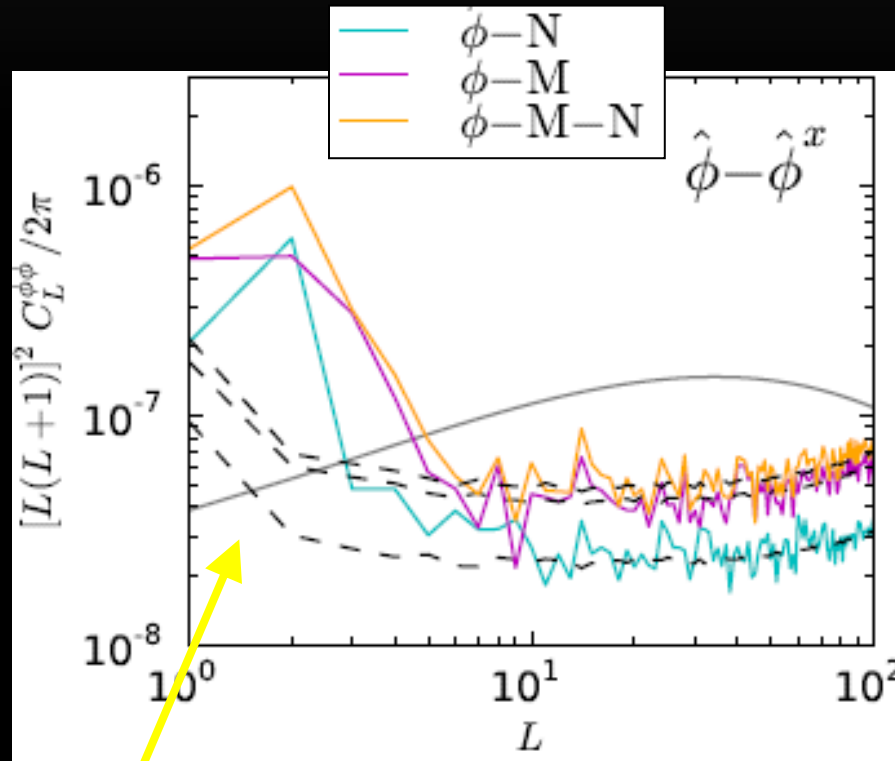


- ✓ The loss of S/N is not so significant (but depends on scale)



# APPLICATION TO PLANCK DATA (TEMPERATURE)

- Difference of the results between bias-hardened estimator and conventional method



(Planck collaboration'13)

Unexpected discrepancy

(so they conservatively use  $L > 40$  for parameter estimation)

# LENSING POWER SPECTRUM ESTIMATE

- ✓ For cosmology we are interested in  $C_\ell^{xx}$  rather than  $x$
- ✓ From  $\hat{x}$  to  $C_\ell^{xx}$  (e.g., Kesden+'03; Hanson+'11)

$$\langle |\hat{x}_L^{XY}|^2 \rangle = \int d\vec{\ell}_1 \int d\vec{\ell}_2 F_{L,\ell_1}^{x,(XY)} F_{L,\ell_2}^{x,(XY)} \langle \bar{X}_{\ell_1}^* \bar{Y}_{L-\vec{\ell}_1}^* \bar{X}_{\ell_2} \bar{Y}_{L-\vec{\ell}_2} \rangle$$

$$= \underbrace{M_\ell^x}_{\text{due to non-lensing anisotropy (residual mean-field bias)}} + \underbrace{N_\ell^{x,(0)}}_{\text{from intrinsic scatter of CMB anisotropies (Gaussian bias)}} + \underbrace{C_\ell^{xx}}_{\mathcal{O}(C_\ell^{xx})} + \underbrace{N_\ell^{x,(1)}}_{\mathcal{O}(C_\ell^{xx})} + \underbrace{N_\ell^{x,(2)}}_{\mathcal{O}([C_\ell^{xx}]^2)} + \dots$$

due to non-lensing anisotropy (residual mean-field bias)

from intrinsic scatter of CMB anisotropies (Gaussian bias)

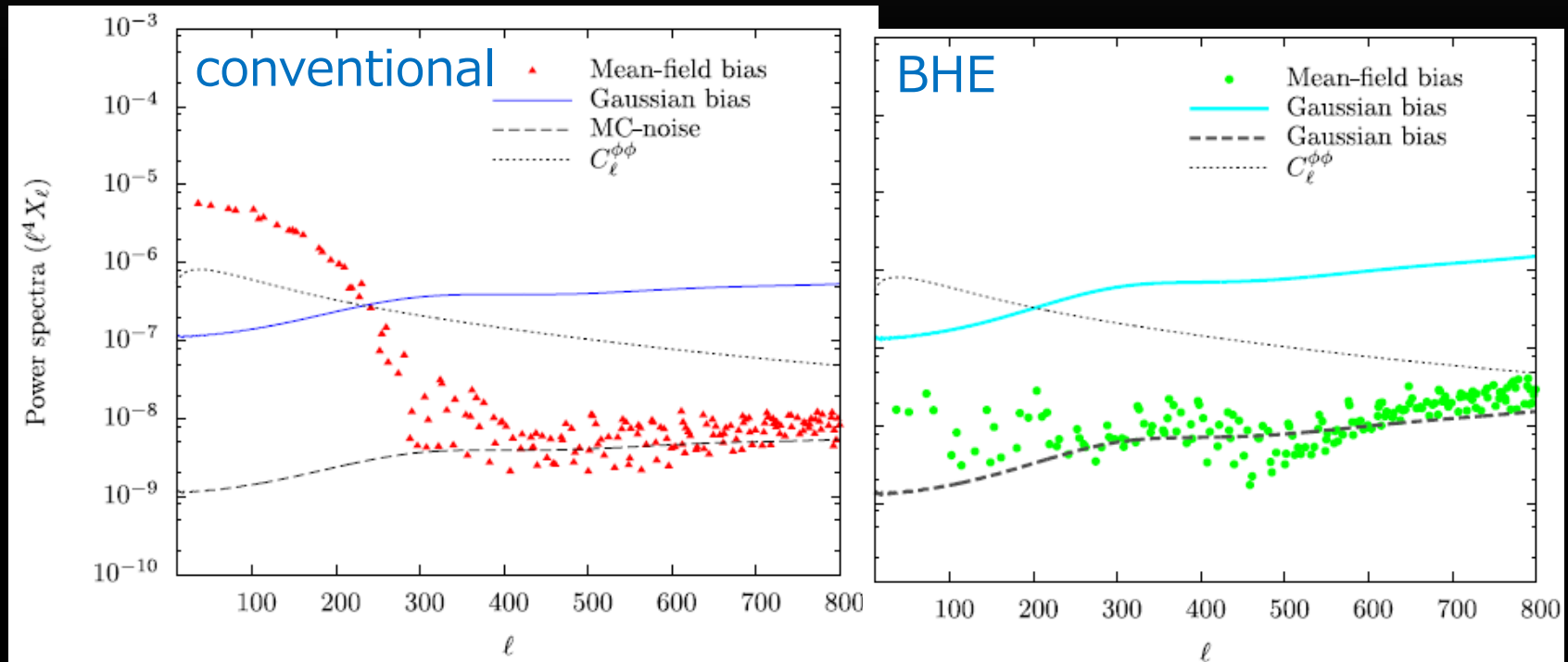
Generated by lensing

In estimating power spectrum, we have to know many bias terms accurately

# SIGNIFICANCE OF BIAS TERMS ON CL ESTIMATE

- Mean-field bias and Gaussian bias in the power spectrum estimate

[Gradient mode, EE-estimator]



- ✓ Bias-hardened estimator suppress mean-field bias enough to ignore in the power spectrum estimates
- ✓ Gaussian bias, however, is significant and should be accurately corrected

# ESTIMATOR FOR GAUSSIAN BIAS

- Gaussian bias estimate

- ✓ Conventional (e.g., Hu'01)

$$\widehat{N}_\ell^{x,(0)} = 2 \int d\vec{\ell}_1 \int d\vec{\ell}_2 F_{L,\ell_1}^x F_{L,\ell_2}^x \bar{C}_{\ell_1,\ell-\ell_2} \bar{C}_{\ell-\ell_1,\ell_2} \quad (\bar{C}_{L_1,L_2} \equiv \langle \bar{X}_{L_1} \bar{Y}_{L_2}^* \rangle)$$

- ✓ Our approach

- Naturally derived as an optimal trispectrum estimator with maximum likelihood approach

$$\widehat{N}_\ell^{x,(0)} = 2 \int d\vec{\ell}_1 \int d\vec{\ell}_2 F_{L,\ell_1}^x F_{L,\ell_2}^x [2\bar{C}_{\ell_1,\ell-\ell_2} \bar{X}_{\ell-\ell_1} \bar{Y}_{\ell_2}^* - \bar{C}_{\ell_1,\ell-\ell_2} \bar{C}_{\ell-\ell_1,\ell_2}]$$

- More accurate than previous method ( e.g.,  $\bar{C}_{L_1,L_2}$  )

( if  $\bar{C}_{L_1,L_2} \rightarrow \bar{C}_{L_1,L_2} + \delta\bar{C}_{L_1,L_2}$  , the bias propagates as 2<sup>nd</sup> order of  $\delta\bar{C}_{L_1,L_2}$  )

---

# Summary

---

- We present estimators to mitigate
  - 1) **mean field bias** (from masking, point sources, beam, etc)
  - 2) **Gaussian bias**
- Using numerical test, we found that the mean-field bias from masking is suppressed by combining “bias-hardened estimator” and some filtering approach
- Noise level would be degraded at most by factor of 2-3