

Duality covariant geometry for brane systems

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- I. INTRODUCTION
- II. MANIFESTLY T-DUAL FORMULATION
- III. MANIFESTLY T-DUAL SUPERSPACE FROM TYPE II
SUPERSTRING
- IV. M-BRANES & D-BRANES
- V. CONCLUSIONS

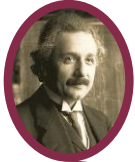
References

- **Superspace with manifest T-duality from type II superstring.** 1403.3887[hep-th] , Kiyoshi Kamimura, Warren Siegel & M.H.
- **M5 & SO(5,5).** '13; **SL(5) & M2.**'12, K.Kamimura & M.H.; **D-branes.**'12, Tetsuji Kimura & M.H.
- Natural curvature for **manifest T-duality.** '13, M. Polacek & Siegel.
- **Two vielbein formalism** for string inspired axionic gravity; **Superspace duality** in low-energy superstrings; **Manifest duality** in low-energy superstrings.'93
W.Siegel
- Randomizing the **superstring.** '94 W. Siegel.

I. Introduction

motivation

◆ Gravity theory beyond Einstein's gravity



“general covariance” \Rightarrow Einstein gravity theory



“ **Manifest T-duality** ” \Rightarrow effective gravity of string
(T-duality symmetry in massless sector of string)

◆ New string background geometry beyond Riemann

- Double field theory

‘93 Siegel, ‘09 Hull&Zwiebach, ‘10 Hohm, Kwaw; Jeon, Lee, Park; Thompson; Tseytlin,...

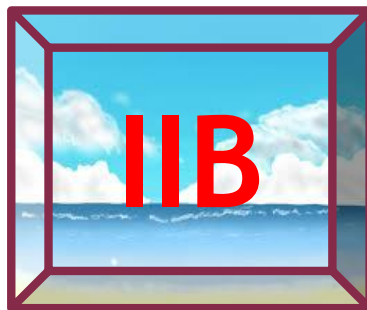
- Generalized geometry

‘02 Hitchin, ‘04 Gualtieri, ‘07 Hull ‘08 Paccheco & Waldram, ‘09 Grana, Louis, Sim, ‘10 Berman & Perry, ‘11 Coimbra, Strickland-Constable ...; Koerber, Baraglia, Dabholkar, Copland, Reid-Edwards Godazgar's, West...



T-duality in SUGRA's

- Hidden T-duality



a background

- Manifest T-duality



All backgrounds

T-duality in gravity vs string

momenta \leftrightarrow winding



Hidden in target space
Effective gravity action

$$\mathcal{L} = R + (\partial\phi)^2 + (\partial B)^2$$

$$(G + B) \rightarrow \frac{a(G + B) + b}{c(G + B) + d}$$

- Fractional transf. of components fields under $O(d,d)$

Manifest in worldsheet
String Hamiltonian

$$\mathcal{H}_\tau = (p, \partial_\sigma x) \mathcal{M} \begin{pmatrix} p \\ \partial_\sigma x \end{pmatrix}$$

$$\mathcal{M} = \begin{pmatrix} G^{mn} & G^{mp} B_{pn} \\ -B_{mp} G^{pn} & G_{mn} - B_{mp} G^{pq} B_{qn} \end{pmatrix}$$

$$\mathcal{M} = E^T E, \quad E \rightarrow EA$$

- Linear transf. of vielbein under $O(d,d)$

Q. How to approach it?



★ SUGRA IN SUPERSPACE

FROM SUPERSTRING

II. Manifestly T-dual formalism

1. Affine Lie algebra
2. Vielbein
3. Torsions
4. Dimensional reductions

II-1. Affine Lie algebra

flat

'93 Siegel

- Bosonic string current: $\mathring{\Delta}_M = (p_m, \partial_\sigma x^m)$
- Algebra:

$$[\mathring{\Delta}_M(\sigma), \mathring{\Delta}_N(0)] = f_{MN}{}^K \mathring{\Delta}_K \delta(\sigma) + \eta_{MN} \partial_\sigma \delta(\sigma)$$

Jacobi identity \Rightarrow

$$f_{[MN}{}^K f_{L]K}{}^J = 0 \quad \& \quad f_{MNK} \equiv f_{MN}{}^L \eta_{LK} = f_{[MNK]}$$

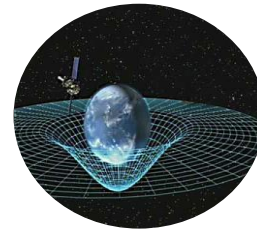
symmetric group metric

$$\eta_{MN} = \begin{pmatrix} p_m & \delta_m^n \\ \partial_\sigma x^m & \delta_n^m \end{pmatrix}$$

totally antisymmetric

★ nondegenerate group metric required.

II-2. Vielbein



curved

- Covariant derivative: $\triangleright_A = E_A^M \overset{\circ}{\triangleright}_M$

- Algebra:

$$[\triangleright_A(\sigma), \triangleright_B(0)] = T_{AB}^C \triangleright_C \delta(\sigma) + \underline{\eta_{AB} \partial_\sigma \delta(\sigma)}$$

- Orthonormal condition on E_A^M

Same as flat

$$E_\eta E^T = \eta \quad , \quad \eta_{MN} = \eta_{AB}$$

totally antisym. torsion

$$T_{ABC} = (D_{[A} E_B^M) E_{C]M} + E_A^M E_B^N E_C^L f_{MNL}$$

★ Vielbein can be orthonormal $O(d,d)$

- Hamiltonian constraint:

$$\mathcal{H}_\tau = \dot{\Delta}_M \mathcal{M}^{MN} \dot{\Delta}_N = \Delta_A \hat{\delta}^{AB} \Delta_B$$

$$\hat{\delta} = \begin{pmatrix} 1 & \\ & 1 \end{pmatrix}$$

Bosonic string

- Vielbein: $E_A^M = \begin{pmatrix} e_a^m & e_a^n B_{nm} \\ 0 & e_m^a \end{pmatrix}$

$O(d,d)/O(d)^2$

$\#(G, B) = d^2$

$$E^T \hat{\delta} E = \mathcal{M} = \begin{pmatrix} G^{mn} & G^{mp} B_{pn} \\ -B_{mp} G^{pn} & G_{mn} - B_{mp} G^{pq} B_{qn} \end{pmatrix}$$

- ★ Vielbein is $O(d,d)/O(d)^2$
- ★ G&B are coset parameter

- Diffeo. constraint:

$$\mathcal{H}_\sigma = \overset{\circ}{\triangleright}_M \eta^{MN} \overset{\circ}{\triangleright}_N = \triangleright_A \eta^{AB} \triangleright_B$$

$$\eta = \begin{pmatrix} & \mathbf{1} \\ \mathbf{1} & \end{pmatrix}$$

- derivatives

$$[\overset{\circ}{\triangleright}_M, \Phi(Z)] = (D_M \Phi)$$

$$[\int \mathcal{H}_\sigma, \Phi(Z)] = \partial_\sigma \Phi = \overset{\circ}{\triangleright}_M \eta^{MN} (D_N \Phi)$$

- condition on double coordinates

$$\mathcal{H}_\sigma = \overset{\circ}{\triangleright}_m \overset{\circ}{\triangleright}^m = p_m \partial_\sigma x^m = 0$$

- ★ σ -Diffeo. Is given by string algebra basis.
- ★ It gives cond. In double coordinate space

- T-duality covariant gauge symmetry

$$\delta \hat{E}_A = [\hat{E}_A, \hat{\lambda}]_T$$

zero-mode part
of string algebra!

$$[E_A^M \overset{\circ}{\triangleright}_M, \lambda^N \overset{\circ}{\triangleright}_N] = \delta E_A^M \overset{\circ}{\triangleright}_M + c \overset{\circ}{\partial}_\delta$$

- General coordinate transf. & gauge transf.

$$\begin{cases} \delta G_{mn} = \lambda^l \partial_l G_{mn} + \partial_{(m} \lambda^l G_{l|n)} \\ \delta B_{mn} = \lambda^l \partial_l B_{mn} + \partial_{[m} \lambda^l B_{l|n]} + \partial_{[m} \lambda_n] \end{cases}$$

★ zero-mode string alg. Gives T-dual gauge sym.

II-3. Torsions

- Covariant derivative & curvature

$$\triangleright_A = \omega_A^S S + e_A^M P_M \quad [\triangleright_A, \triangleright_B] = R_{AB}^S S + T_{AB}^C \triangleright_C$$

- Constrain torsion **by hand**

$$T_{PP}^P = 0 \Rightarrow \underline{\omega_{PP}^P} = e(\partial e)e, \quad \omega_{PPP} = \partial B$$

- Curvature tensor

$$R_{PP}^S = \partial\omega + \omega\omega$$

NS-NS 3 form

curvature in terms of ω 's

★ T-dual cov. geometry is given !

II-3. Torsions

- Covariant derivative & curvature

$$\triangleright_A = \omega_A^S S + e_A^M P_M \quad [\triangleright_A, \triangleright_B] = R_{AB}^S S + T_{AB}^C \triangleright_C$$

ω_A^S E_P^S
 R_{AB}^S T_{PP}^S

- Constrain torsion **by hand**

$$T_{PP}^P = 0 \Rightarrow \underline{\omega_{PP}^P} = e(\partial e)e, \quad \omega_{PPP} = \partial B$$

- Curvature tensor

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NS-NS 3 form
curvature in terms of ω 's

★ T-dual cov. geometry is given !

String algebra

‘13 Polacek & Siegel
 “Natural curvature for
 manifest T-duality”

nondegenerate Poincare

$$\mathring{\Delta}_M = (S, P, \Sigma) \times 2$$

- metric

$$\eta_{MN} = \begin{matrix} S \\ P \\ \Sigma \end{matrix} \begin{pmatrix} & & \mathbf{1} \\ & \mathbf{1} & \\ \mathbf{1} & & \end{pmatrix}$$

- Vielbein

$$E_A^M = \begin{matrix} S \\ P \\ \Sigma \end{matrix} \begin{pmatrix} \mathbf{1} & & \\ \omega & e & \\ r & -\omega^T & \mathbf{1} \end{pmatrix}$$

$$\begin{aligned} [P_m, P_n] &= \Sigma_{mn} + \eta_{mn} \partial_\sigma \delta \\ [S_{mn}, \Sigma^{lk}] &= \delta_{[m}^k \Sigma_{n]}^l + \eta_{S\Sigma} \partial_\sigma \delta \end{aligned}$$

NS-NS 3 form
 & torsion

- ★ T-dual geometry is given by Poincare/Lorentz
- ★ NS-NS 3form & torsion are mixed under T

II-4. Dimensional reduction

- Constraints by symmetry generators

$$\tilde{\Sigma}_{\pm} = \frac{\partial}{\partial Z^{\Sigma_{\pm}}} + \dots = 0$$

$$\tilde{P}_{+} - \tilde{P}_{-} = 0 \Rightarrow \tilde{P}_{+} + \tilde{P}_{-} \rightarrow \tilde{P} = \frac{\partial}{\partial x}$$

$$S_{+} = S_{-} = 0 \Rightarrow Z_{\pm}^S = 0$$

$$\tilde{S} = \tilde{S}_{+} + \tilde{S}_{-} = [x, \partial_P]$$

- Coordinates: ~~$(Z^S, Z^{S'}, x, x', Z^{\Sigma}, Z^{\Sigma'})$~~

★ Symmetry generator commutes with covariant derivative, so it does not change local structure.

RECIPE: manifestly T-dual gravity

1. Affine Lie algebra & double generators
2. Make covariant derivatives with vielbein
3. Constrain torsions by hands
4. Break manifest T-duality to hidden one

III. Manifestly T-dual superspace from type II superstring

1. Affine Lie algebra
2. Vielbein
3. Torsions
4. Dimensional reductions

RECIPE: manifestly T-dual **superspace**

1. Superstring algebra $\times 2$
2. Supervielbein
3. Constrain torsions **by kappa symmetry**
4. Break manifest T-duality to hidden one

RECIPE: manifestly T-dual **superspace**

1. Supestring algebra $\times 2$

III-1. Superstring algebra

- Non-degenerate super-Poincare

$$\overset{\circ}{\Delta}_M = (S_{mn}, D_\mu, P_m, \Omega^\mu, \Sigma^{mn}) \times 2$$

susy

Dim. 0 1/2 1 3/2 2

- Metric:

$$\eta_{MN} = \begin{matrix} S & D & P & \Omega & \Sigma \\ S & & & & 1 \\ D & & & -1 & \\ P & & 1 & & \\ \Omega & & & 1 & \\ \Sigma & 1 & & & \end{matrix}$$

★ 2 sets of P, (D,Ω), (S,Σ) are used as sust.alg.

Nondegenerate super-poincare algebra

Dim.

$$1 \quad \{D, D\} = \mathbb{P}$$

$$3/2 \quad [D, P_m] = \gamma_m \Omega$$

$$2 \quad [P_m, P_n] = \underline{\Sigma_{mn}} + \eta_{mn} \underline{\partial_\sigma \delta}$$

$$[D, \Omega] = \underline{\Sigma^{mn} \gamma_{mn}} + \eta_{D\Omega} \underline{\partial_\sigma \delta}$$

$$[S_{mn}, \Sigma^{lk}] = \delta_{[m}^k \underline{\Sigma_{n]}^l} + \eta_{S\Sigma} \underline{\partial_\sigma \delta}$$

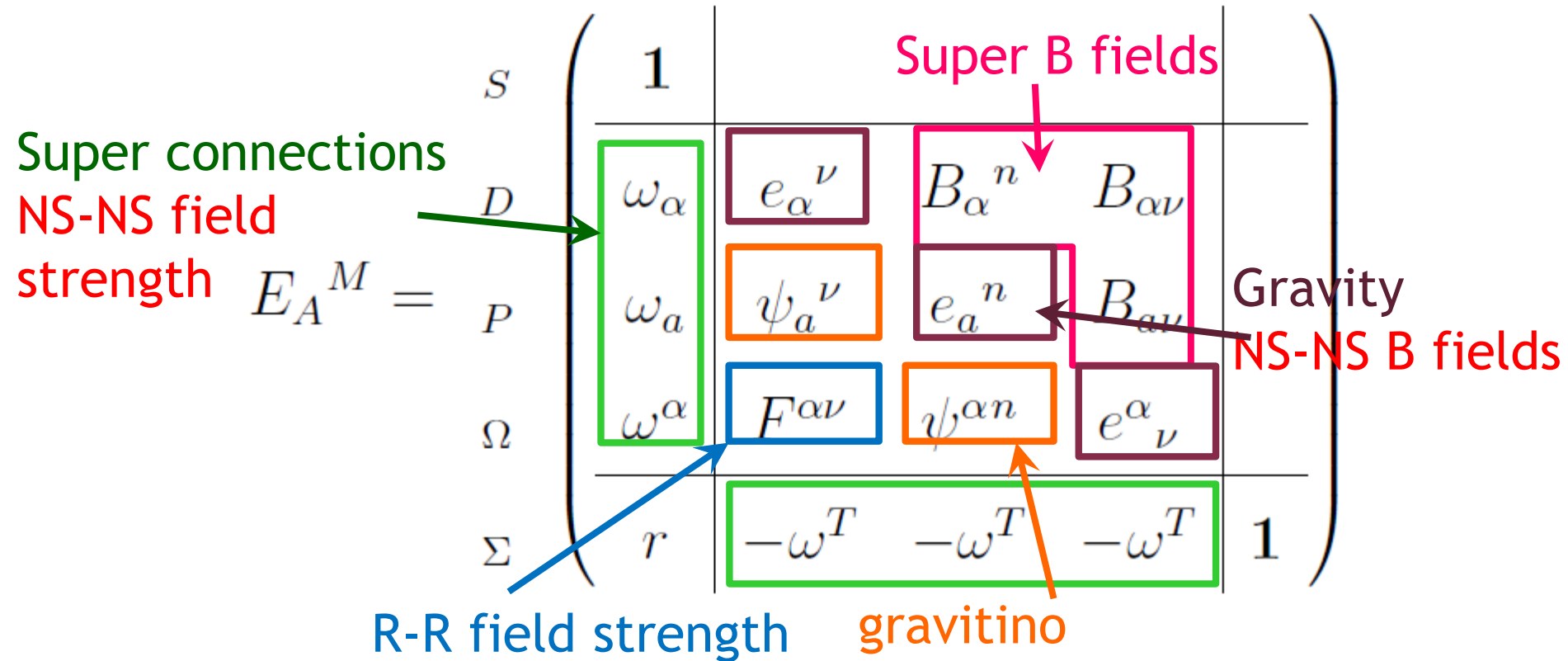
RECIPE: manifestly T-dual **superspace**

1. Superstring algebra $\times 2$
2. Supervielbein

III-2. Supervielbein

$$E_A^M = \begin{array}{c} S \\ D \\ P \\ \Omega \\ \Sigma \end{array} \left(\begin{array}{c|ccc|c} \mathbf{1} & & & & \\ \hline \omega_\alpha & e_\alpha^\nu & B_\alpha^n & B_{\alpha\nu} & \\ \omega_a & \psi_a^\nu & e_a^n & B_{a\nu} & \\ \omega^\alpha & F^{\alpha\nu} & \psi^{\alpha n} & e^\alpha_\nu & \\ \hline r & -\omega^T & -\omega^T & -\omega^T & \mathbf{1} \end{array} \right)$$

III-2. Supervielbein



★ NS-NS, R-R field strengths are mixed

III-2. Supervielbein

$$E_A^M = \begin{array}{c} S \\ D \\ P \\ \Omega \\ \Sigma \end{array} \left(\begin{array}{c|ccc|c} & \text{Dim.} & & & \\ \hline & 1 & 0 & -1/2 & -1 \\ \hline & \omega_\alpha & e_\alpha^\nu & B_\alpha{}^n & B_{\alpha\nu} \\ \hline & \omega_a & \psi_a^\nu & e_a{}^n & B_{a\nu} \\ \hline & \omega^\alpha & F^{\alpha\nu} & \psi^{\alpha n} & e^\alpha{}_\nu \\ \hline & r & -\omega^T & -\omega^T & -\omega^T & 1 \\ \hline & 2 & 3/2 & 1 & 1/2 & \end{array} \right)$$

Prepotential

★ $B_{\mu\nu}$ turns out to be a prepotential of all fields

RECIPE: manifestly T-dual **superspace**

1. Superstring algebra $\times 2$
2. Supervielbein
3. Constrain torsions **by kappa symmetry**

III-3. κ -sym. constrains torsions

- Fermionic constraints: $D_\alpha = 0$

$$\{D_\alpha, D_\beta\} = \cancel{P}_{\alpha\beta}, \quad P^2 = 0$$

- 1st class ---kappa-symmetry generator

$$D_\alpha \cancel{P} = 0 \quad \Rightarrow \quad ABCD = 0$$

- 2nd class ---must be eliminated

$$D_\alpha = 0$$

- K-symmetric Virasoro constraints

Dim.

2	$\mathcal{A} = \frac{1}{2}P^2 + \Omega D + \frac{1}{2}\Sigma S$	Virasoro
3/2	$\mathcal{B}^\mu = D\cancel{P} - \cancel{S}\Omega$	Kappa-symmetry
1	$\mathcal{C}_{\mu\nu} = D_\mu D_\nu + (\cancel{S}\cancel{P})_{[\mu\nu]}$	(2 nd class) ²
3	$\mathcal{D}_m = D\gamma_m\partial_\sigma D + \Sigma_{mn}S^{nl}P_l$	
0	$S_{mn} = S_{m'n'} = 0$	Lorentz

- Consistency of κ -sym. \Rightarrow Torsion constraints.

$$\underline{\triangleright_\alpha = 0}$$

$$\underline{[\triangleright_\alpha, \mathcal{A}] \approx 0}$$

$$\Leftrightarrow T_{\alpha BC'} = 0 \text{ for } B, C = (S, D_\alpha, P)$$

$$\underline{\{\triangleright_\alpha, \mathcal{B}\} \approx 0}$$

$$\Leftrightarrow \boxed{\{\triangleright_\alpha, \triangleright_\beta\} \approx \triangleright_P}$$

$$T_{\alpha\beta P} = (\gamma_P)_{\alpha\beta}, \quad T_{\alpha\beta X} = 0 \text{ for } X = (S, S', D_\alpha, D_{\alpha'}, P')$$

$$T_{\alpha PY} = 0 \text{ for } Y = (S, S', D_{\alpha'}, P, P', \Omega, \Omega')$$

★ All vielbein fields are written by

a prepotential $\boxed{B_{\mu\nu} = E_D^\Omega = E_{DD}}$

RECIPE: manifestly T-dual **superspace**

1. Superstring algebra $\times 2$
2. Supervielbein
3. Constrain torsions **by kappa symmetry**
4. Break manifest T-duality to hidden one

- Dimensional reduction

$$\tilde{\Sigma}_{\pm} = \tilde{\Omega}_{\pm} = 0$$

$$\tilde{P}_+ - \tilde{P}_- = 0 \Rightarrow \tilde{P}_+ + \tilde{P}_- \rightarrow \tilde{P}$$

$$S_{\pm} = 0$$

$$\tilde{S}_+ + \tilde{S}_- \rightarrow \tilde{S} = x \frac{\partial}{\partial x} + \theta \partial_{\alpha} + \theta' \partial_{\alpha'}$$

- Coordinates

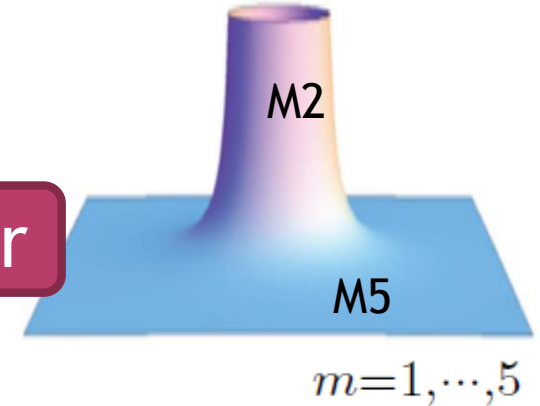
$$(\underline{\cancel{Z^S}}, \underline{\cancel{Z^{S'}}}, \theta, \theta', x, \underline{\cancel{Z^{\Omega}}}, \underline{\cancel{Z^{\Omega'}}}, \underline{\cancel{Z^{\Sigma}}}, \underline{\cancel{Z^{\Sigma'}}})$$

★ Dim. Red.gives usual coordinate space

IV. M & D-branes

1. Affine Lie algebra
2. Vielbein

M5-brane



- M5 algebra base: $O(5,5)$ spinor

$$\begin{aligned} \mathring{\Delta}_M &= (\mathring{\Delta}_m, \mathring{\Delta}^{[2]mn}, \mathring{\Delta}^{[5]}) \\ &= (p_m, E^{ij} \partial_i x^m \partial_j x^n, \partial_{[i_1} x^{m_1} \dots \partial_{i_5]} x^{m_5}) \end{aligned}$$

- “metric” $\mathcal{H}_i = p_m \partial_i x^m + \epsilon_{ij_1 \dots j_4} E^{j_1 j_2} E^{j_3 j_4}$

$O(5,5)$
vector

$$\mathring{\Delta}_M \rho^{MN} \mathring{\Delta}_N = 0 \quad \& \quad \rho^{MN} = \begin{pmatrix} & a & b \\ a & b & \\ b & & \end{pmatrix}$$

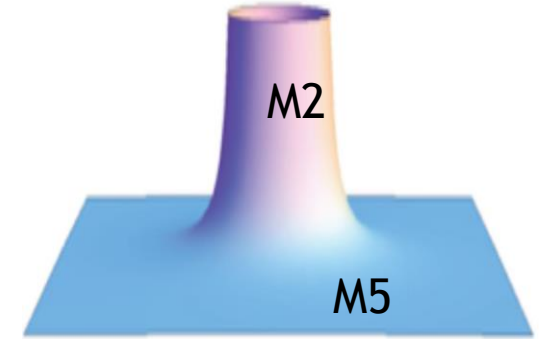
$$a \left\{ \begin{aligned} (\mathring{\Delta} \Gamma^m \mathring{\Delta}) &= \mathring{\Delta}_n \mathring{\Delta}^{[2]nm} = 0 \end{aligned} \right.$$

$$b \left\{ \begin{aligned} (\mathring{\Delta} \Gamma_m \mathring{\Delta}) &= \mathring{\Delta}_m \mathring{\Delta}^{[5]} + \epsilon_{mn_1 \dots n_4} \mathring{\Delta}^{[2]n_1 n_2} \mathring{\Delta}^{[2]n_3 n_4} = 0 \end{aligned} \right.$$

‘13 Kamimura & M.H.

- Vielbein

$$E_A^M = \begin{pmatrix} e_a^m & C^{[3]} & C^{[6]} + C^{[3]} \wedge C^{[3]} \\ & (e_m^a)^2 & C^{[3]} \\ & & (e_m^a)^5 \end{pmatrix}$$



- Gauge symmetry

$$\delta_\xi E_a^M = [\xi, E_a]_{M5}$$

$$\begin{cases} \delta_\xi G = \mathcal{L}_\xi G & \text{General transf.} \\ \delta_\xi C^{[3]} = \mathcal{L}_\xi C^{[3]} + d\xi^{[2]} & \text{Gauge transf.} \\ \delta_\xi C^{[6]} = \mathcal{L}_\xi C^{[6]} + d\xi^{[5]} + C^{[3]} \wedge d\xi^{[2]} \end{cases}$$

★ M5 alg. is closed with self-dual gauge field & define gauge sym.

D3-brane

'12 Kimura & M.H.

- D3 algebra base:

DBI U(1)
field

$$\begin{aligned} \mathring{\Delta}_M &= (\mathring{\Delta}_m, \mathring{\Delta}^m | \mathring{\Delta}^{[1]m}, \mathring{\Delta}^{[3]mnl}) \\ &= (p_m, E^i \partial_i x^m | \epsilon^{ijk} F_{ij} \partial_k x^m, \epsilon^{ijk} \partial_i x^m \partial_j x^n \partial_k x^l) \end{aligned}$$

- “metric”

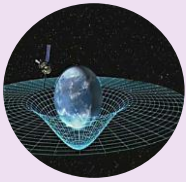
$$\begin{aligned} \mathcal{H}_i &= p_m \partial_i x^m + F_{ij} E^j \\ \Rightarrow \mathring{\Delta}_M \rho^{MN} \mathring{\Delta}_N &= 0 \end{aligned}$$

★ Dp alg. is closed with DBI gauge field & give gauge transf.

$$\rho^{MN} = \left(\begin{array}{cc|cc} & a & b & c \\ a & & c & \\ \hline b & c & & \\ c & & & \end{array} \right) \Leftrightarrow \begin{cases} a & \mathring{\Delta}_m \mathring{\Delta}^m = 0 \\ b & \mathring{\Delta}_m \mathring{\Delta}^{[1]m} = 0 \\ c & \mathring{\Delta}_m \mathring{\Delta}^{[3]mnl} + \mathring{\Delta}^{[n} \mathring{\Delta}^{[1]l]} = 0 \end{cases}$$

- Vielbein:

$$E_a^M = e_a^n \left(\delta_n^m, B_{nm} | C_{nm}^{[2]}, C_{nm_1 m_2 m_3}^{[4]} + C_{nm_1}^{[2]} C_{m_2 m_3}^{[2]} \right)$$

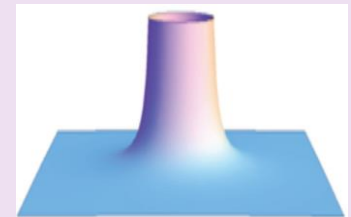


V. Conclusions



◆ Duality covariant geometry is formulated from brane algebras:

- ◆ Superspace with manifestly T-duality from superstring (nondegenerate super-Poincare)
- ◆ Kappa-Virasoro gives torsion constraints
- ◆ $B_{\mu\nu}$ is a prepotential



◆ Future problems

- ◆ R-R sector, D-branes, M branes, exotic branes
- ◆ effective theory of F theory
- ◆ . . .