Backlund Transformations for Non-Commutative (NC) Integrable Eqs.

Masashi HAMANAKA

University of Nagoya (visiting Glasgow until Feb. 13 and IHES Feb13 - Mar13 2009)

Based on

- Claire R.Gilson (Glasgow), MH and Jonathan J.C.Nimmo (Glasgow), "Backlund trfs for NC anti-self-dual (ASD) Yang-Mills (YM) eqs." arXiv:0709.2069 (to appear in GMJ) & 08mm.nnnn.
- MH, NPB 741 (2006) 368, JHEP 02 (07) 94, PLB 625 (05) 324, JMP46 (05) 052701...

1. Introduction

NC extension of integrable systems

- Matrix generalization
 All variables belong to NC ring, which implies
- Quarternion-valued system associativity.
- Moyal deformation (=extension to NC spaces =presence of magnetic flux)
- 4-dim. Anti-Self-Dual Yang-Mills Eq.
- plays important roles in QFT
- a master eq. of (lower-dim) integrable eqs. (Ward's conjecture)

4-dim. NC ASDYM eq. (G=GL(N))

$$F_{\mu\nu} = - *F_{\mu\nu} \qquad \mu, \nu = 0,1,2,3$$

$$(F_{\mu\nu} := \partial_{\mu} A_{\nu} - \partial_{\nu} A_{\mu} + [A_{\mu}, A_{\nu}])$$

$$\begin{pmatrix} \tilde{z} & w \\ \tilde{w} & z \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} x^{0} + ix^{1} & x^{2} - ix^{3} \\ x^{2} + ix^{3} & x^{0} - ix^{1} \end{pmatrix}$$

$$\begin{cases} F_{zw} = 0, \\ F_{z\tilde{w}} = 0, \\ F_{z\tilde{z}} - F_{w\tilde{w}} = 0 \end{cases}$$

Reduction to NC KdV from NC ASDYM

$$\begin{cases} F_{zw} = 0, & \text{sNC ASDYM eq.} \\ F_{\widetilde{z}\widetilde{w}} = 0, & \text{G=GL(2)} \end{cases}$$

$$(z, \widetilde{z}, w, \widetilde{w}) \rightarrow (t, x) = (z, w + \widetilde{w})$$

$$A_{z} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, A_{\widetilde{w}} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \quad \text{Reduction conditions}$$

$$A_{w} = \begin{pmatrix} q & -1 \\ q' + q^{2} & -q \end{pmatrix}, A_{z} = \begin{pmatrix} \frac{1}{2}q'' + q'q & -q' \\ \frac{1}{4}q''' + \frac{1}{2}(q'^{2} + qq'' + q''q) + qq'q & -\frac{1}{2}q'' - qq' \end{pmatrix}$$

$$\dot{u} = \frac{1}{4}u''' + \frac{3}{4}(u'u + uu')$$
 $u = 2q'$:NC KdV eq.!

Reduction to NC NLS from NC ASDYM

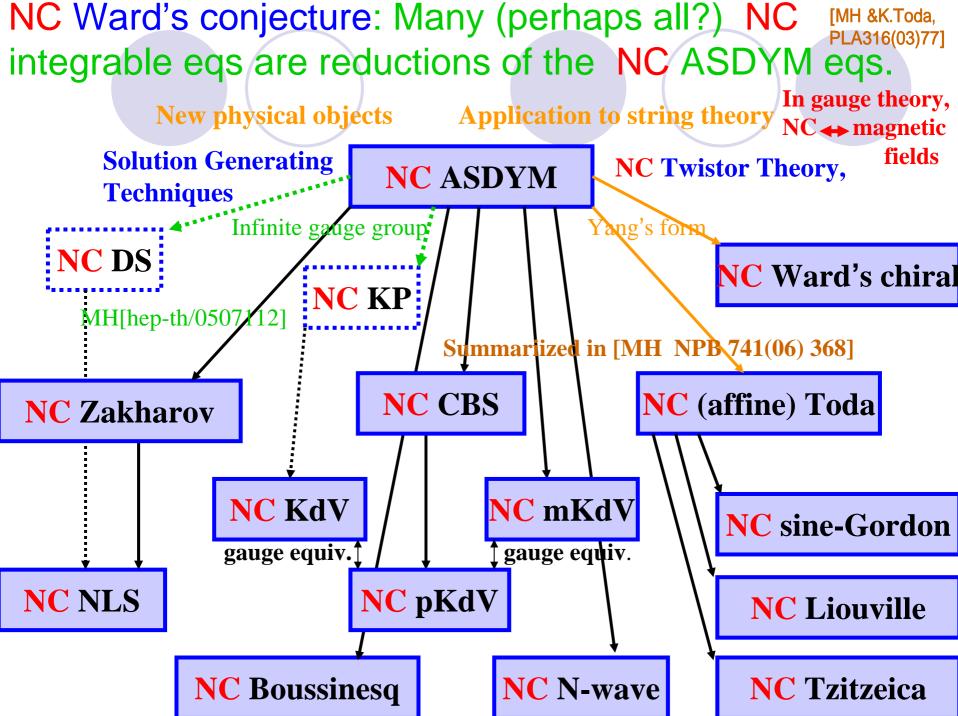
$$\begin{cases} F_{zw} = 0, \\ F_{\widetilde{z}\widetilde{w}} = 0, \\ F_{z\widetilde{z}} - F_{w\widetilde{w}} = 0 \end{cases} \text{ inc asdy M eq.}$$

$$(z, \widetilde{z}, w, \widetilde{w}) \rightarrow (t, x) = (z, w + \widetilde{w})$$

$$A_{\widetilde{z}} = \sqrt{-1} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, A_{\widetilde{w}} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \text{ Reduction conditions}$$

$$A_{w} = \begin{pmatrix} 0 & \psi \\ \overline{\psi} & 0 \end{pmatrix}, A_{z} = \sqrt{-1} \begin{pmatrix} -\psi \overline{\psi} & -\psi' \\ \psi' & \overline{\psi} \psi \end{pmatrix}$$

$$\sqrt{-1}\dot{\psi} = \psi'' - 2\psi\overline{\psi}\psi$$
 :NC NLS eq.!



Plan of this talk

- 1. Introduction
- 2. Backlund Transforms for the NC ASDYM eqs. (and NC Atiyah-Ward ansatz solutions in terms of quasideterminants)
- 3. Origin of the Backlund trfs from NC twistor theory
- 4. Conclusion and Discussion

- 2. Backlund transform for NC ASDYM eqs.
- In this section, we derive (NC) ASDYM eq. from the viewpoint of linear systems, which is suitable for discussion on integrability.
- We define NC Yang's equations which is equivalent to NC ASDYM eq. and give a Backlund transformation for it.
- The generated solutions are NC Atiyah-Ward ansatz solutions in terms of quasideterminants, which contain not only finite-action solutions (NC instantons) but also infinite-action solutions (non-linear plane waves and so on.)

A derivation of NC ASDYM equations

We discuss G=GL(N) NC ASDYM eq. from the viewpoint of NC linear systems with a (commutative) spectral parameter ζ .

Linear systems:

$$\begin{cases} L\psi = (D_w - \zeta D_{\tilde{z}})\psi = 0, \\ M\psi = (D_z - \zeta D_{\tilde{w}})\psi = 0. \end{cases}$$

Compatibility condition of the linear system:

$$[L,M] = [D_{w},D_{z}] + \zeta([D_{z},D_{\widetilde{z}}] - [D_{w},D_{\widetilde{w}}]) + \zeta^{2}[D_{\widetilde{z}},D_{\widetilde{w}}] = 0$$

$$\Leftrightarrow \begin{cases} F_{zw} = [D_z, D_w] = 0, \\ F_{\widetilde{z}\widetilde{w}} = [D_{\widetilde{z}}, D_{\widetilde{w}}] = 0, \\ F_{z\widetilde{z}} - F_{w\widetilde{w}} = [D_z, D_{\widetilde{z}}] - [D_w, D_{\widetilde{w}}] = 0 \end{cases}$$
 :NC ASDYM eq.

Yang's form and NC Yang's equation

NC ASDYM eq. can be rewritten as follows

$$\begin{cases} F_{zw} = [D_z, D_w] = 0, & \Rightarrow \exists h, D_z h = 0, D_w h = 0 & (A_z = -h_z h^{-1}, etc.) \\ F_{\tilde{z}\tilde{w}} = [D_{\tilde{z}}, D_{\tilde{w}}] = 0, & \Rightarrow \exists \tilde{h}, D_{\tilde{z}}\tilde{h} = 0, D_{\tilde{w}}\tilde{h} = 0 & (A_{\tilde{z}} = -\tilde{h}_{\tilde{z}}\tilde{h}^{-1}, etc.) \\ F_{z\tilde{z}} - F_{w\tilde{w}} = [D_z, D_{\tilde{z}}] - [D_w, D_{\tilde{w}}] = 0 \end{cases}$$

If we define Yang's J-matrix: $J := h^{-1}h$ then we obtain from the third eq.:

$$\partial_z (J^{-1}\partial_{\tilde{z}}J) - \partial_w (J^{-1}\partial_{\tilde{w}}J) = 0$$
 :NC Yang's eq.

The solution J reproduce the gauge fields as

$$A_z = -h_z h^{-1}, \ A_w = h_w h^{-1}, \ A_{\widetilde{z}} = -\widetilde{h}_{\widetilde{z}}\widetilde{h}^{-1}, \ A_{\widetilde{w}} = \widetilde{h}_{\widetilde{w}}\widetilde{h}^{-1}$$

J is gauge invariant. The decomposition into h and h corresponds to a gauge fixing

Backlund trf. for NC Yang's eq. G=GL(2)

• Yang's J matrix can be reparametrized as follows $(f - ab^{-1}a - ab^{-1})$

$$J = \begin{pmatrix} f - gb^{-1}e & -gb^{-1} \\ b^{-1}e & b^{-1} \end{pmatrix}$$

Then NC Yang's eq. becomes

$$\begin{split} &\partial_{z}(f^{-1}g_{\tilde{z}}b^{-1}) - \partial_{w}(f^{-1}g_{\tilde{w}}b^{-1}) = 0, \quad \partial_{\tilde{z}}(b^{-1}e_{z}f^{-1}) - \partial_{\tilde{w}}(b^{-1}e_{w}f^{-1}) = 0, \\ &\partial_{z}(b_{\tilde{z}}b^{-1}) - \partial_{w}(b_{\tilde{w}}b^{-1}) + e_{z}f^{-1}g_{\tilde{z}}b^{-1} - e_{w}f^{-1}g_{\tilde{w}}b^{-1} = 0, \\ &\partial_{z}(f^{-1}f_{\tilde{z}}) - \partial_{w}(f^{-1}f_{\tilde{w}}) + f^{-1}g_{\tilde{z}}b^{-1}e_{z} - f^{-1}g_{\tilde{w}}b^{-1}e_{w} = 0. \end{split}$$

The following trf. leaves NC Yang's eq. as it is: $(a e^{new} - f^{-1}a b^{-1} + a e^{new} - f^{-1}a b^{-1})$

$$\beta : \begin{cases} \partial_{z}e^{new} = f^{-1}g_{\widetilde{w}}b^{-1}, \ \partial_{w}e^{new} = f^{-1}g_{\widetilde{z}}b^{-1}, \\ \partial_{\widetilde{z}}g^{new} = b^{-1}e_{w}f^{-1}, \ \partial_{\widetilde{w}}g^{new} = b^{-1}e_{z}f^{-1}, \\ f^{new} = b^{-1}, \ b^{new} = f^{-1} \end{cases}$$

Backlund transformation for NC Yang's eq.

Yang's J matrix can be reparametrized as follows

$$J = \begin{pmatrix} f - gb^{-1}e & -gb^{-1} \\ b^{-1}e & b^{-1} \end{pmatrix}$$

Then NC Yang's eq. becomes

$$\begin{split} &\partial_{z}(f^{-1}g_{\widetilde{z}}b^{-1}) - \partial_{w}(f^{-1}g_{\widetilde{w}}b^{-1}) = 0, \quad \partial_{\widetilde{z}}(b^{-1}e_{z}f^{-1}) - \partial_{\widetilde{w}}(b^{-1}e_{w}f^{-1}) = 0, \\ &\partial_{z}(b_{\widetilde{z}}b^{-1}) - \partial_{w}(b_{\widetilde{w}}b^{-1}) + e_{z}f^{-1}g_{\widetilde{z}}b^{-1} - e_{w}f^{-1}g_{\widetilde{w}}b^{-1} = 0, \\ &\partial_{z}(f^{-1}f_{\widetilde{z}}) - \partial_{w}(f^{-1}f_{\widetilde{w}}) + f^{-1}g_{\widetilde{z}}b^{-1}e_{z} - f^{-1}g_{\widetilde{w}}b^{-1}e_{w} = 0. \end{split}$$

Another trf. also leaves NC Yang's eq. as it

$$\gamma_0 : \begin{pmatrix} f^{new} & g^{new} \\ e^{new} & b^{new} \end{pmatrix} = \begin{pmatrix} b & e \\ g & f \end{pmatrix}^{-1} = \begin{pmatrix} (b - ef^{-1}g)^{-1} & (g - fe^{-1}b)^{-1} \\ (e - bg^{-1}f)^{-1} & (f - gb^{-1}e)^{-1} \end{pmatrix}$$

- Both trfs. are involutive ($\beta \circ \beta = id$, $\gamma_0 \circ \gamma_0 = id$), but the combined trf. $\gamma_0 \circ \beta$ is non-trivial.)
- Then we could generate various (nontrivial) solutions of NC Yang's eq. from a (trivial) seed solution (so called, NC Atiyah-Ward solutions)

$$J_{[0]} \xrightarrow{\alpha = \gamma_0 \circ \beta} J_{[1]} \xrightarrow{\alpha} J_{[2]} \xrightarrow{\alpha} \cdots$$

$$J_{[n]} = \begin{pmatrix} f_{[n]} - g_{[n]} b_{[n]}^{-1} e_{[n]} & -g_{[n]} b_{[n]}^{-1} \\ b_{[n]}^{-1} e_{[n]} & b_{[n]}^{-1} \end{pmatrix}$$

$$\beta : \begin{cases} \partial_{z}e^{new} = f^{-1}g_{\widetilde{w}}b^{-1}, \ \partial_{w}e^{new} = f^{-1}g_{\widetilde{z}}b^{-1}, \\ \partial_{\widetilde{z}}g^{new} = b^{-1}e_{w}f^{-1}, \ \partial_{\widetilde{w}}g^{new} = b^{-1}e_{z}f^{-1}, \\ f^{new} = b^{-1}, \ b^{new} = f^{-1} \end{cases} \qquad \gamma_{0} : \begin{pmatrix} f^{new} & g^{new} \\ e^{new} & b^{new} \end{pmatrix} = \begin{pmatrix} b & e \\ g & f \end{pmatrix}^{-1}$$

Generated solutions (NC Atiyah-Ward sols.)

Let's consider the combined Backlund trf.

$$J_{[0]} \xrightarrow{\alpha = \gamma_0 \circ \beta} J_{[1]} \xrightarrow{\alpha} J_{[2]} \xrightarrow{\alpha} \cdots$$

$$J_{[n]} = \begin{pmatrix} f_{[n]} - g_{[n]} b_{[n]}^{-1} e_{[n]} & -g_{[n]} b_{[n]}^{-1} \\ b_{[n]}^{-1} e_{[n]} & b_{[n]}^{-1} \end{pmatrix}$$

with a seed solution:
$$b_{[0]} = -f_{[0]} = e_{[0]} = -g_{[0]} = \Delta_0^{-1}, \ \partial^2 \Delta_0 = 0$$

Then, the generated solutions are:

$$b_{[n-1]} = \left| D_{[n]} \right|_{nn}^{-1}, f_{[n-1]} = -\left| D_{[n]} \right|_{11}^{-1}, e_{[n-1]} = \left| D_{[n]} \right|_{1n}^{-1}, g_{[n-1]} = -\left| D_{[n]} \right|_{n1}^{-1}$$

$$\frac{\partial \Delta_{i}}{\partial z} = \frac{\partial \Delta_{i+1}}{\partial \widetilde{w}}, \frac{\partial \Delta_{i}}{\partial w} = \frac{\partial \Delta_{i+1}}{\partial \widetilde{z}}$$

$$\mathbf{Quasideterminants!}$$

$$\mathbf{Quasideterminants!}$$

$$(a kind of NC)$$

(a kind of NC

determinants)

[Gelfand-Retakh]

Quasi-determinants

- Quasi-determinants are not just a NC generalization of commutative determinants, but rather related to inverse matrices.
- For an n by n matrix $X = (x_{ij})$ and the inverse $Y = (y_{ij})$ of X, quasi-determinant of X is directly defined by

$$|X|_{ij} = y_{ji}^{-1} \qquad \xrightarrow{\begin{array}{c} \text{commutative} \\ \text{linmit} \end{array}} \xrightarrow{\begin{array}{c} (-1)^{i+j} \\ \text{det } X^{ij} \end{array}} \text{det } X \qquad X^{ij} \text{: the matrix obtained}$$

$$\text{from } X \text{ deleting i-th column}$$

from X deleting i-th row and j-th column

Recall that

$$X = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \implies$$

$$Y = X^{-1} = \begin{pmatrix} A^{-1} + A^{-1}B(D - CA^{-1}B)^{-1}CA^{-1} & -A^{-1}B(D - CA^{-1}B)^{-1} \\ -(D - CA^{-1}B)^{-1}CA^{-1} & (D - CA^{-1}B)^{-1} \end{pmatrix}$$

→ We can also define quasi-determinants recursively

Quasi-determinants

[For a review, see Gelfand et al., math.QA/0208146]

Defined inductively as follows

$$|X|_{ij} = x_{ij} - \sum_{i',j'} x_{ii'} ((X^{ij})^{-1})_{i'j'} x_{j'j} = x_{ij} - \sum_{i',j'} x_{ii'} (|X^{ij}|_{j'i'})^{-1} x_{j'j} = \begin{vmatrix} \vdots \\ x_{ij} \end{vmatrix} \cdots \begin{vmatrix} \vdots \\ x_{ij} \end{vmatrix}$$
n+1 by n+1

n+1 by n+1

$$n = 1: |X|_{ij} = x_{ij}$$
 notation
$$n = 2: |X|_{11} = \begin{vmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{vmatrix} = x_{11} - x_{12} \cdot x_{22}^{-1} \cdot x_{21}, |X|_{12} = \begin{vmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{vmatrix} = x_{12} - x_{11} \cdot x_{21}^{-1} \cdot x_{22},$$

$$|X|_{21} = \begin{vmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{vmatrix} = x_{21} - x_{22} \cdot x_{12}^{-1} \cdot x_{11}, |X|_{22} = \begin{vmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{vmatrix} = x_{22} - x_{21} \cdot x_{11}^{-1} \cdot x_{12},$$

$$n = 3: |X|_{11} = \begin{vmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{vmatrix} = x_{11} - (x_{12}, x_{13}) \begin{pmatrix} x_{22} & x_{23} \\ x_{32} & x_{33} \end{pmatrix}^{-1} \begin{pmatrix} x_{21} \\ x_{31} \end{pmatrix}$$

$$= x_{11} - x_{12} \cdot (x_{22} - x_{23} \cdot x_{33}^{-1} \cdot x_{32})^{-1} \cdot x_{21} - x_{13} \cdot (x_{32} - x_{33} \cdot x_{23}^{-1} \cdot x_{22})^{-1} \cdot x_{21} - x_{12} \cdot (x_{23} - x_{22} \cdot x_{32}^{-1} \cdot x_{33})^{-1} \cdot x_{31} - x_{13} \cdot (x_{33} - x_{32} \cdot x_{22}^{-1} \cdot x_{23})^{-1} \cdot x_{31}$$

. . .

Explicit Atiyah-Ward ansatz solutions

of NC Yang's eq. G=GL(2) [Gilson-MH-Nimmo. arXiv:0709.2069]

$$b_{[0]} = -f_{[0]} = e_{[0]} = -g_{[0]} = \Delta_0^{-1}, \ \partial^2 \Delta_0 = 0$$

$$b_{[1]} = \begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ f_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = \begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = \begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ g_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = \begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_{-1} \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_0 \end{vmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1 \end{pmatrix}^{-1}, \ e_{[1]} = -\begin{vmatrix} \Delta_0 & \Delta_1 \\ \Delta_1 & \Delta_1$$

$$b_{[n]} = \begin{bmatrix} \Delta_0 & \cdots & \Delta_{-n} \\ \vdots & \ddots & \vdots \\ \Delta_n & \cdots & \Delta_0 \end{bmatrix}^{-1}, \ f_{[n]} = -\begin{bmatrix} \Delta_0 & \cdots & \Delta_{-n} \\ \vdots & \ddots & \vdots \\ \Delta_n & \cdots & \Delta_0 \end{bmatrix}^{-1}, \ f_{[n]} = -\begin{bmatrix} \Delta_0 & \cdots & \Delta_{-n} \\ \vdots & \ddots & \vdots \\ \Delta_n & \cdots & \Delta_0 \end{bmatrix}^{-1}, \ \begin{bmatrix} 0 & -1 & 0 & \cdots & 0 & 0 \\ 1 & \Delta_0 & \Delta_{-1} & \cdots & \Delta_{-n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \Delta_{n-1} & \Delta_{n-2} & \cdots & \Delta_0 & \Delta_{-1} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & \Delta_n & \Delta_{n-1} & \cdots & \Delta_1 & \Delta_0 \end{bmatrix}$$

$$e_{[n]} = \begin{bmatrix} \Delta_0 & \cdots & \Delta_{-n} \\ \vdots & \vdots & \ddots & \vdots \\ \Delta_n & \cdots & \Delta_0 \end{bmatrix}^{-1}, \ g_{[n]} = -\begin{bmatrix} \Delta_0 & \cdots & \Delta_{-n} \\ \vdots & \vdots & \ddots & \vdots \\ \Delta_n & \cdots & \Delta_0 \end{bmatrix}^{-1}, \ J_{[n]} = \begin{bmatrix} J_{[n]} & \vdots & \vdots & \ddots & \vdots \\ 0 & J_{[n]} & J_{[n]} & \vdots & \vdots & \ddots & \vdots \\ 0 & J_{[n]} & J_{[n]} & \vdots & \vdots & \ddots & \vdots \\ 0 & J_{[n]} & J_{[n]$$

$$\frac{\partial \Delta_{i}}{\partial z} = \frac{\partial \Delta_{i+1}}{\partial \widetilde{w}}, \quad \frac{\partial \Delta_{i}}{\partial w} = \frac{\partial \Delta_{i+1}}{\partial \widetilde{z}}$$

The Backlund trf. is not just a gauge trf. but a non-trivial one!

We could generate various solutions of NC ASDYM eq. from a simple seed solution Δ_0 by using the previous Backlund trf. $\alpha = \gamma_0 \circ \beta$

A seed solution:

$$\Delta_0 = 1 + \tilde{z} = \frac{1}{z\tilde{z} - w\tilde{w}}$$
 \rightarrow NC instantons
$$\Delta_0 = \exp(linear \ of \ z, \tilde{z}, w, \tilde{w})$$
 \rightarrow NC Non-Linear plane-waves

Proof is made simply by using special identities of quasideterminants (NC Jacobi's identities and a homological relation, Gilson-Nimmo's derivative formula etc.), in other words, "NC Backlund trfs are identities of quasideterminants." (common feature in commutative Backlund in lower-dim.!)

3. Interpretation from NC twistor theory

- In this section, we give an origin of the Backlund trfs. from the viewpoint of NC twistor theory.
- NC twistor theory has been developed by several authors [Kapustin-Kuznetsov-Orlov, Takasaki, Hannabuss, Lechtenfeld-Popov, Brain-Majid...]
- What we need here is NC Penrose-Ward correspondence between sol. sp. of ASDYM and "NC holomorphic vector bundle" on a NC twistor space.

NC Penrose-Ward correspondence

Linear systems of ASDYM "NC hol. Vec. bdl"

$$\begin{cases} L\psi = (D_w - \zeta D_{\widetilde{z}})\psi = 0, \\ M\psi = (D_z - \zeta D_{\widetilde{w}})\psi = 0. \end{cases}$$
 Patching matrix
$$\tilde{\zeta} = 1/\zeta \qquad \qquad \qquad P(\zeta w + \widetilde{z}, \zeta z + \widetilde{w}, \zeta)$$

$$\tilde{\zeta} = 1/\zeta \qquad \qquad \qquad = \widetilde{\psi}^{-1}\psi$$

$$\begin{cases} \tilde{L}\widetilde{\psi} = (\widetilde{\zeta}D_w - D_{\widetilde{z}})\widetilde{\psi} = 0, \\ \tilde{M}\widetilde{\psi} = (\widetilde{\zeta}D_z - D_{\widetilde{w}})\widetilde{\psi} = 0. \end{cases}$$
 [Takasaki]
$$\psi(x;\zeta) = h(x) + O(\zeta)$$

$$\widetilde{\psi}(x;\zeta) = \tilde{h}(x) + O(\zeta)$$

$$h(x) = \psi(x, \zeta = 0),$$

$$\tilde{h}(x) = \tilde{\psi}(x, \zeta = \infty)$$

$$\downarrow$$

ASDYM gauge fields are reproduced

We have only to factorize a given patching matrix into ψ and $\widetilde{\psi}$ to get ASDYM fields. (Birkhoff factorization or Riemann-Hilbert problem)

Origin of NC Atiyah-Ward (AW) ansatz sols.

n-th AW ansatz for the Patching matrix

$$P_{[n]} = \begin{pmatrix} 0 & \zeta^{-n} \\ \zeta^{n} & \Delta(x;\zeta) \end{pmatrix} \qquad \Delta(x;\zeta) = \underline{\Delta(\zeta w + \widetilde{z}, \zeta z + \widetilde{w}, \zeta)} = \sum_{i} \Delta_{i}(x)\zeta^{i}$$
The chasing relation is derived from:

$$l\Delta(x;\zeta) = (\partial_{w} - \zeta \partial_{\tilde{z}})\Delta = 0,$$

$$m\Delta(x;\zeta) = (\partial_{z} - \zeta \partial_{\tilde{w}})\Delta = 0,$$

$$\frac{\partial \Delta_{i}}{\partial z} = \frac{\partial \Delta_{i+1}}{\partial \widetilde{w}}, \quad \frac{\partial \Delta_{i}}{\partial w} = \frac{\partial \Delta_{i+1}}{\partial \widetilde{z}}$$

Origin of NC Atiyah-Ward (AW) ansatz sols.

The n-th AW ansatz for the Patching matrix

$$P_{[n]} = \begin{pmatrix} 0 & \zeta^{-n} \\ \zeta^{n} & \Delta(x;\zeta) \end{pmatrix} \qquad \Delta(x;\zeta) = \Delta(\zeta w + \widetilde{z}, \zeta z + \widetilde{w}, \zeta) = \sum_{i} \Delta_{i}(x) \zeta^{i}$$

$$P_{[n]} = \begin{pmatrix} 0 & \zeta^{-n} \\ \zeta^{n} & \Delta(x;\zeta) \end{pmatrix} \qquad \Delta(x;\zeta) = \Delta(\zeta w + \widetilde{z}, \zeta z + \widetilde{w}, \zeta) = \sum_{i} \Delta_{i}(x)\zeta^{i}$$
The Birkoff factorization
$$P = \widetilde{\psi}^{-1}\psi \quad \text{leads to:}$$

$$h_{11} = h_{12} \left| D_{[n+1]} \right|_{n+1,1}^{-1} - \widetilde{h}_{11} \left| D_{[n+1]} \right|_{1,1}^{-1} \qquad \widetilde{h}(x) + O(\widetilde{\zeta}) \qquad h(x) + O(\zeta)$$

$$h_{21} = h_{22} \left| D_{[n+1]} \right|_{n+1,n+1}^{-1} - \widetilde{h}_{21} \left| D_{[n+1]} \right|_{n+1,1}^{-1}$$

$$\widetilde{h}_{12} = h_{12} \left| D_{[n+1]} \right|_{n+1,n+1}^{-1} - \widetilde{h}_{11} \left| D_{[n+1]} \right|_{n+1,1}^{-1}$$

$$\widetilde{h}_{22} = h_{22} \left| D_{[n+1]} \right|_{n+1,n+1}^{-1} - \widetilde{h}_{21} \left| D_{[n+1]} \right|_{n+1,1}^{-1}$$

$$h_{12} = \widetilde{h}_{21} = 0,$$

Under a gauge ($\frac{h_{12} = \widetilde{h}_{21} = 0}{h_{22} = \widetilde{h}_{11} = 1}$), this solution coincides with the quasideterminants sols!

$$\begin{split} \widetilde{h}_{22} &= b_{[n]} = \left| D_{[n+1]} \right|_{n+1,n+1}^{-1}, \, h_{11} = f_{[n]} = - \left| D_{[n+1]} \right|_{11}^{-1}, \\ h_{21} &= e_{[n]} = \left| D_{[n+1]} \right|_{1,n+1}^{-1}, \, \widetilde{h}_{12} = g_{[n]} = - \left| D_{[n+1]} \right|_{n+1,1}^{-1} \\ \end{split} \quad \begin{array}{l} J_{[n]} = \widetilde{h}^{-1} h = \begin{pmatrix} 1 & g_{[n]} & 0 \\ 0 & b_{[n]} \end{pmatrix}^{-1} \begin{pmatrix} f_{[n]} & 0 \\ e_{[n]} & 1 \end{pmatrix} \\ &= \begin{pmatrix} f_{[n]} - g_{[n]} b_{[n]}^{-1} e_{[n]} & - g_{[n]} b_{[n]}^{-1} \\ b_{[n]}^{-1} e_{[n]} & b_{[n]}^{-1} \end{pmatrix} \end{split}$$

Origin of the Backlund trfs

The Backlund trfs can be understood as the adjoint actions for the Patching matrix:

$$\beta: P^{new} = B^{-1}PB, \quad \gamma_0: P^{new} = C_0^{-1}PC_0, \quad B = \begin{pmatrix} 0 & 1 \\ \zeta^{-1} & 0 \end{pmatrix}, \quad C_0 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

actually:

$$\alpha = \gamma_0 \circ \beta: \quad P_{[n]} = \begin{pmatrix} 0 & \zeta^{-n} \\ \zeta^n & \Delta \end{pmatrix} \mapsto C_0^{-1} B^{-1} \begin{pmatrix} 0 & \zeta^{-n} \\ \zeta^n & \Delta \end{pmatrix} B C_0 = \begin{pmatrix} 0 & \zeta^{-(n+1)} \\ \zeta^{n+1} & \Delta \end{pmatrix} = P_{[n+1]}$$

- The γ_0 -trf. leads to $J^{new} = C_0^{-1}JC_0 \Rightarrow$ The previous γ_0 -trf!
- The β -trf. is derived with a singular gauge trf. $\beta : w \mapsto w^{new} = swB$ $s = \begin{pmatrix} 0 & \zeta b^{-1} \end{pmatrix}$

trf.
$$\beta: \psi \mapsto \psi^{new} = s \psi B, \qquad s = \begin{pmatrix} 0 & \zeta b^{-1} \\ -f^{-1} & 0 \end{pmatrix} \qquad \text{1-2 component of } L\psi = (D_w - \zeta D_{\widetilde{z}})\psi = 0$$

$$h^{new} = \begin{pmatrix} f^{new} & 0 \\ e^{new} & 1 \end{pmatrix} = \begin{pmatrix} b^{-1} & 0 \\ -f^{-1}k_{12} & 1 \end{pmatrix} \Rightarrow \qquad f^{new} = b^{-1}$$

$$\psi = h + k\zeta + O(\zeta^2) \qquad \text{The previous } \beta\text{-trf!}$$

4. Conclusion and Discussion

NC integrable eqs (ASDYM) in higher-dim.

- **ADHM (OK)**
- **OTwistor (OK)**

Quasi-determinants are important!

Backlund trf (DK), Symmetry (Next) cf, NC binary Darboux trf. [Saleem-Hassan-Siddiq]

Profound relation ?? (via Ward conjecture)

NC integrable eqs (KdV) in lower-dims.

OHierarchy(OK)

Quasideterminants

Infinite conserved quantities (OK)

might be

Exact N-soliton solutions (OK)

a key...

- **OSymmetry (NC Sato's theory) (Next)**
- O...

Quasi-determinants are important!