

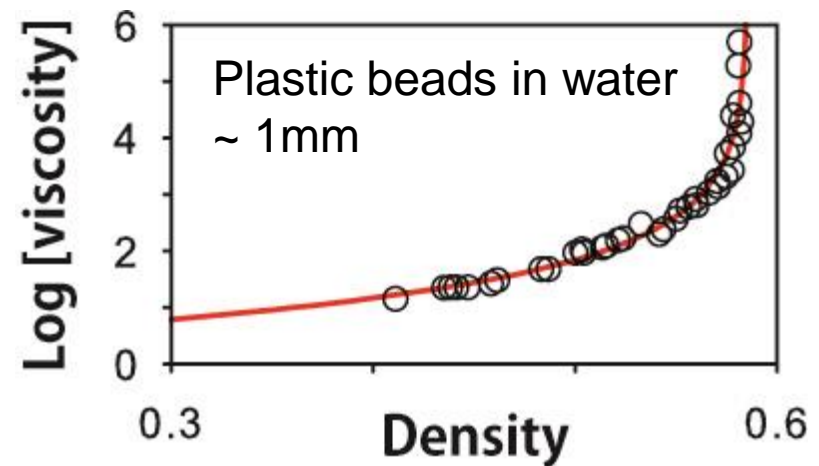
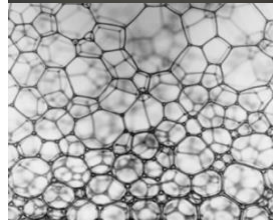
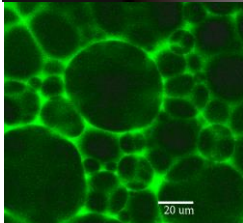
# Viscosity divergence and dynamical slowing down at the jamming transition

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# Jamming transition

- ◆ **Athermal particles**: particles that are large enough to be free from Brownian motions
  - ◆ Large colloidal particles, emulsions, foams, granular materials etc
- ◆ **Jamming transition** = Viscosity divergence of athermal particles at the critical density  $\sim$  random close packing density.



$$\eta \propto (\varphi_J - \varphi)^{-\gamma}, \quad \gamma \approx 2$$

# Glass vs Jamming

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- ◆ **Glass transition = Viscosity divergence of thermal particles**
  - ◆ Small colloidal particles, atoms, molecules etc
  - ◆ Viscosity increases following **Vogel-Fulcher law**
  - ◆ **Relaxation time increases** as the viscosity increases (Green-Kubo formula)
- ◆ **Jamming transition = Viscosity divergence of athermal particles**
  - ◆ Large colloidal particles, foams, grains etc
  - ◆ Viscosity diverges following **the power-law**
  - ◆ **Relaxation time do NOT increase** near the transition
    - I will explain these points.

# Jamming: Simple model

## ◆ Athermal soft particles in solvent

### ◆ Inter-particle interaction

$$v(r) = \epsilon \delta^2 \quad \delta = \begin{cases} 1 - \frac{r}{\sigma} & (r < \sigma) \\ 0 & (r > \sigma) \end{cases} \quad \begin{array}{l} \text{Overlap length} \\ \text{between particles} \end{array}$$

\* Energy penalty when overlapping

\* Finite range, repulsive

*contacts between particles are well-defined*

### ◆ Overdamp equation of motion

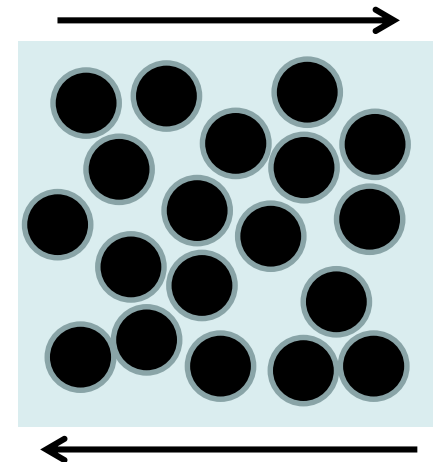
$$\xi \left( \frac{\partial \vec{r}_i}{\partial t} - \dot{\gamma} y_i \vec{e}_x \right) = - \sum_{j \neq i} \frac{\partial v(|\vec{r}_i - \vec{r}_j|)}{\partial \vec{r}_i}$$

Viscous dissipation

$\xi$  = damping coefficient

$\dot{\gamma}$  = shear rate

Inter-particle interaction



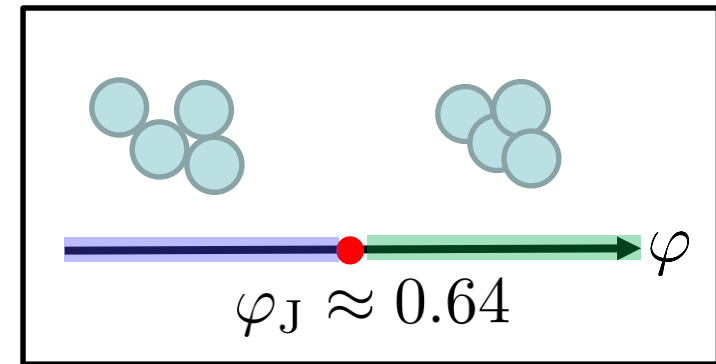
# Jamming: Phase diagram

## ◆ Control parameter

- ◆ Packing density  $\varphi$  (or pressure)
- ◆ Shear rate  $\dot{\gamma}$  (or shear stress)

## ◆ Phase diagram at low shear rate limit

- ◆ Low density:  $\varphi < \varphi_J$ 
  - ◆ Newtonian flow
  - ◆ Particles are just touching each other
- ◆ High density:  $\varphi > \varphi_J$ 
  - ◆ Yielding of solid
  - ◆ Particles are overlapping
- ◆ Critical density:  $\varphi = \varphi_J$ 
  - ◆ Marginally stable solid
  - ◆ Number of contacts per particle becomes **isostatic**

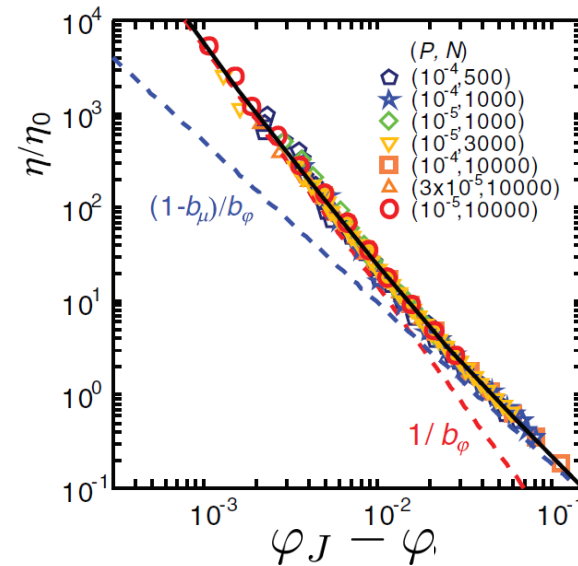
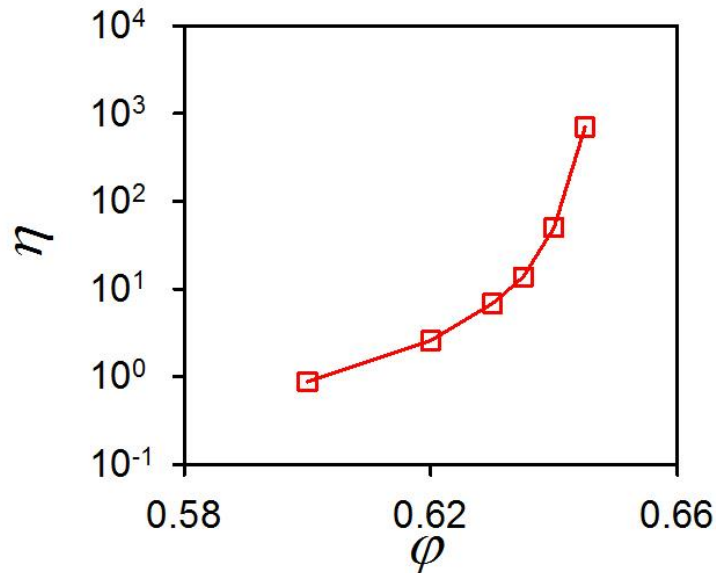


$$z = 2d (= 6)$$

[O'Hern 2003, Olsson-Teitel 2007]

# Jamming: Viscosity

## ◆ Newtonian viscosity (at low shear rate)



## ◆ Power-law divergence

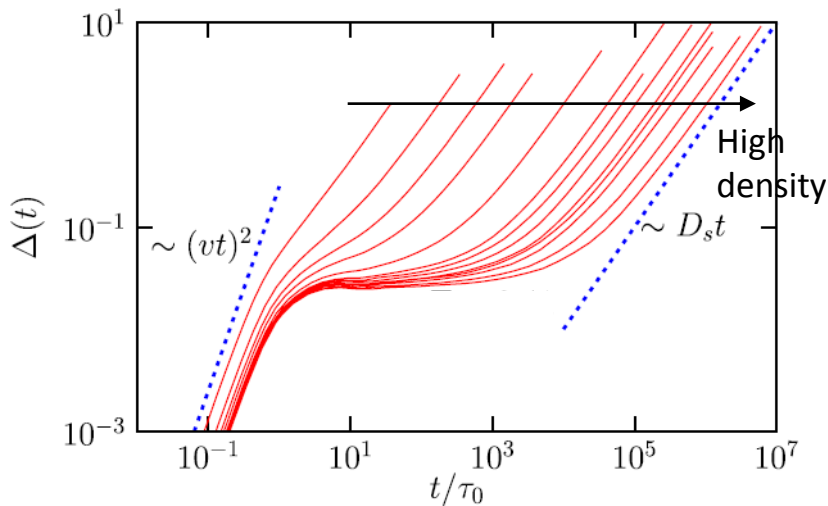
$$\eta \propto (\phi_J - \phi)^{-2.6} \quad \phi_J \approx 0.64$$

## ◆ Exponent changes near the transition: $1.7 \rightarrow 2.6$

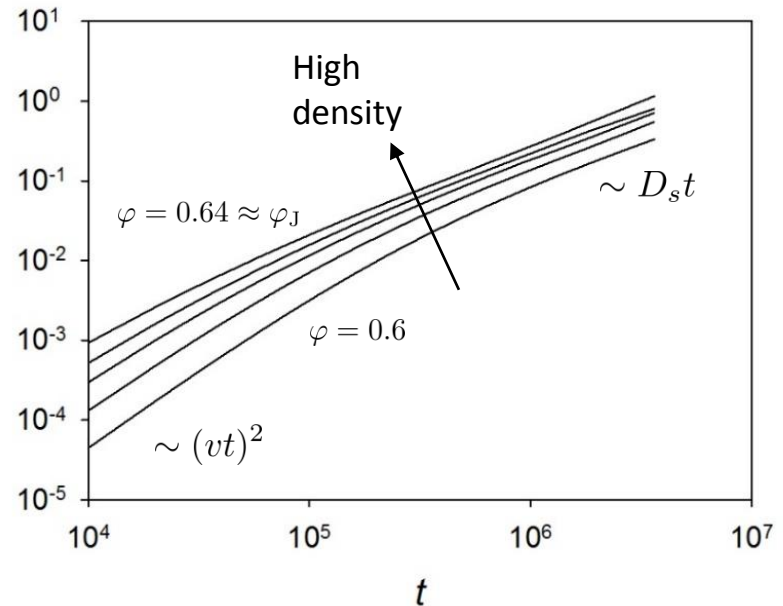
# Jamming: Dynamics

## ◆ Mean-square displacement (at low shear rate, Newtonian regime)

Thermal particles  
(glass transition)



Athermal particles  
(jamming transition)

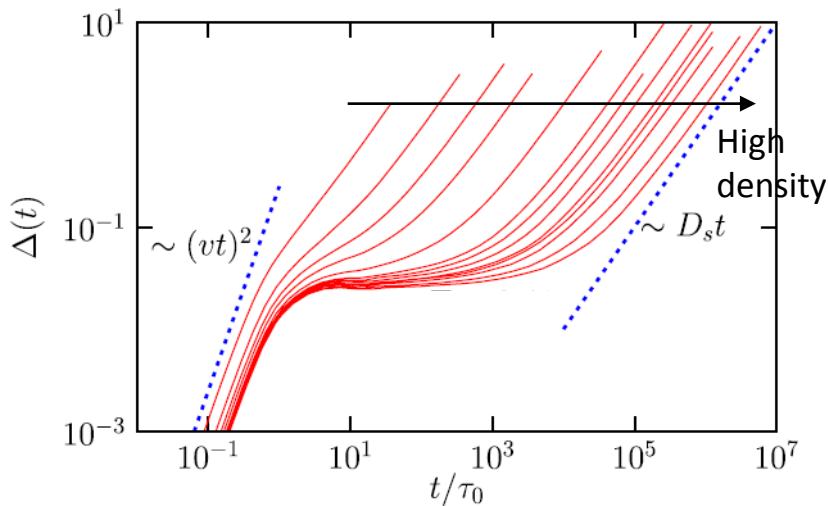


## ◆ Jamming transition do not slow down the dynamics.

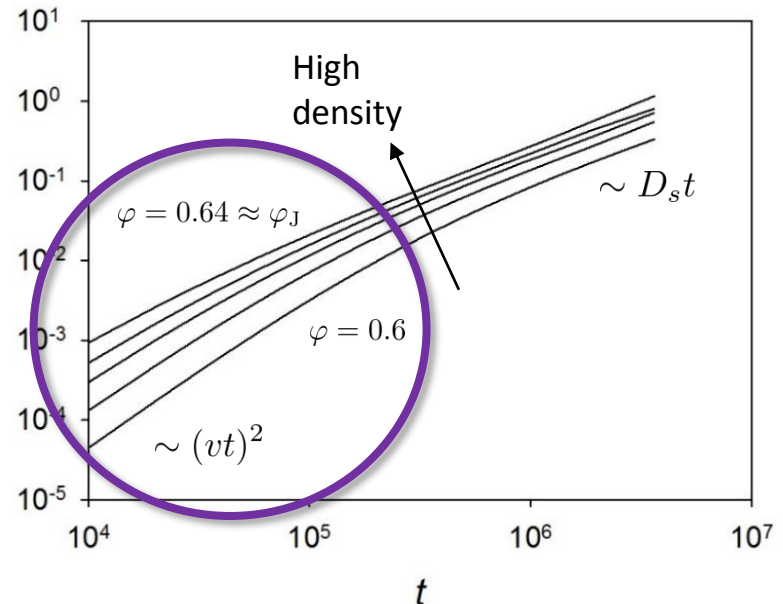
# Jamming: Dynamics

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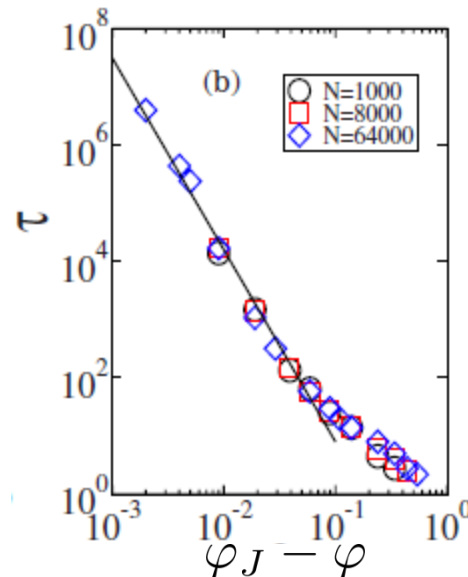
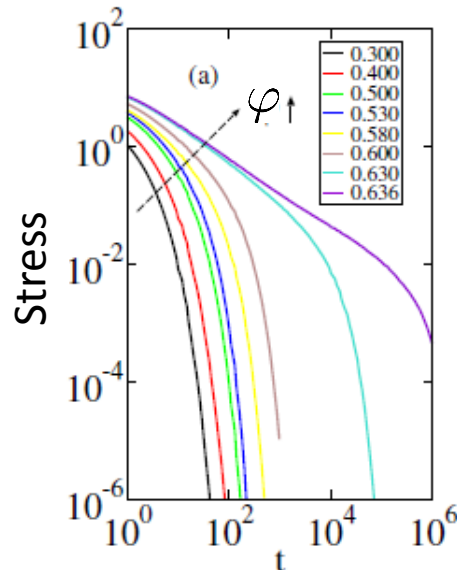
◆ Jamming even “speeds up” the short-time ballistic dynamics!



# Slowing down (1)

◆ However in several settings, slowing down near the jamming have been observed

- ◆ Prepare particles configuration by the steepest descent without shear
- ◆ Apply an infinitesimally small step strain.
- ◆ Then, the system is relaxed by overdamped dynamics without shear and the relaxation of the stress is studied



**Relaxation time  
diverges at the  
jamming transition**

$$\tau \propto (\phi_J - \phi)^{-3.3}$$

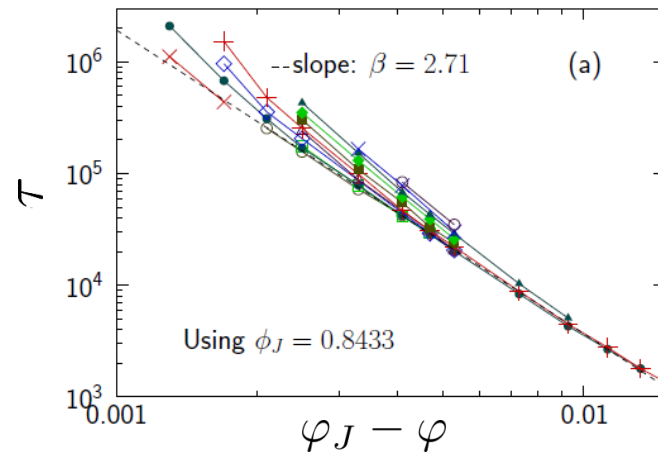
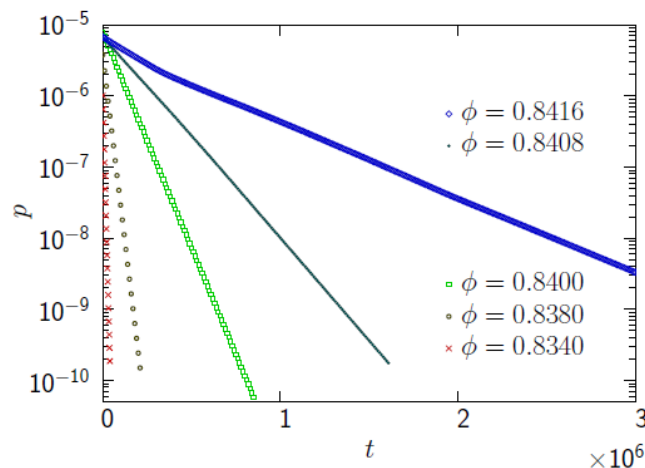
[Hatano 2010]

# Slowing down (2)

◆ However in several settings, slowing down near the jamming have been observed

◆ Perform overdamped dynamics with shear

◆ Stop the shear. Then, the system is relaxed by overdamped dynamics without shear, and the relaxation of the pressure is studied



◆ Viscosity and relaxation time diverges with the same power-law

$$\eta \propto \tau \propto (\varphi_J - \varphi)^{-2.7}$$

# This work

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?? Speed up near the jamming in steady-state, while slowing down in some cases ??

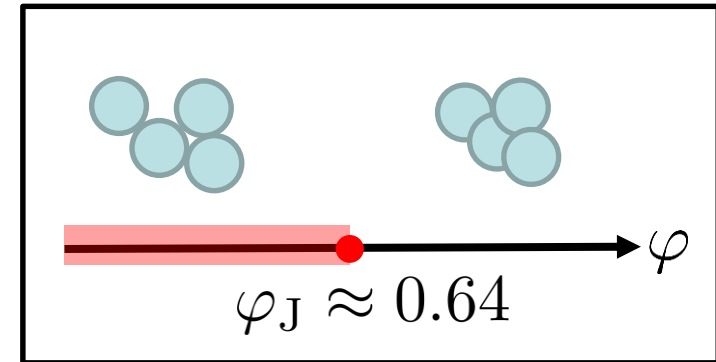
This work: Comprehensive study of the “dynamics” of the system near the jamming transition. And connect the “dynamics” to “the viscosity divergence”.

◆ Relaxation dynamics near the jamming in the simplest setting

# Setting

- ◆ Put particles randomly in a box.  
Focus only on the unjammed phase:

$$\varphi < \varphi_J$$

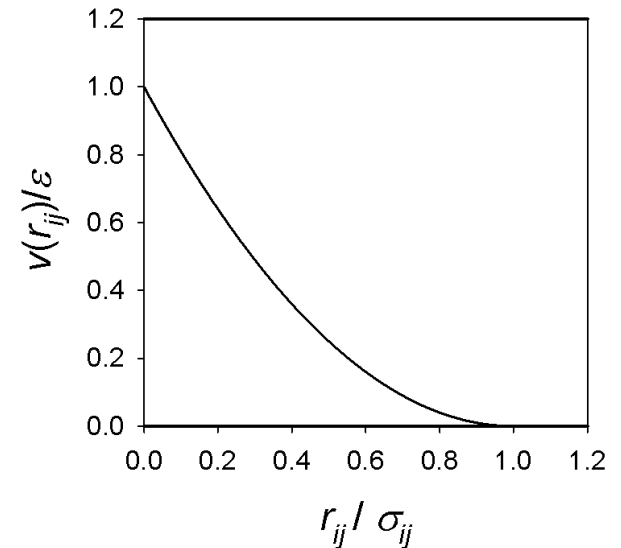


- ◆ Inter-particles interaction is

$$v(r) = \begin{cases} \epsilon \left(1 - \frac{r}{\sigma}\right)^2 & (r \leq \sigma) \\ 0 & (r > \sigma) \end{cases}$$

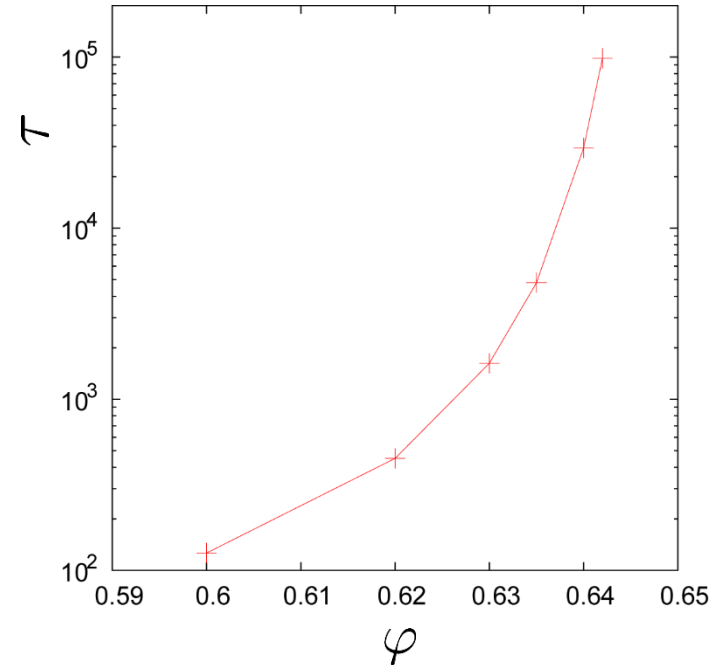
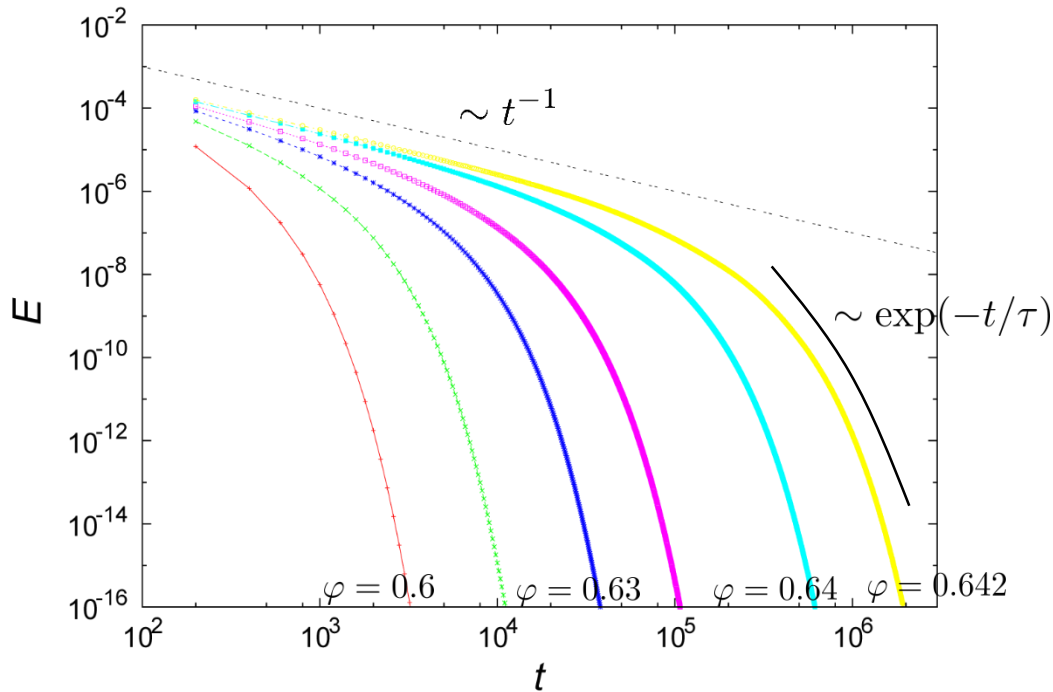
- ◆ Then study the relaxation dynamics  
(No shear)

$$\xi \frac{\partial \vec{r}_i}{\partial t} = - \sum_{j \neq i} \frac{\partial v(|\vec{r}_i - \vec{r}_j|)}{\partial \vec{r}_i}$$



# Relaxation dynamics

## ◆ Relaxation dynamics of the potential energy

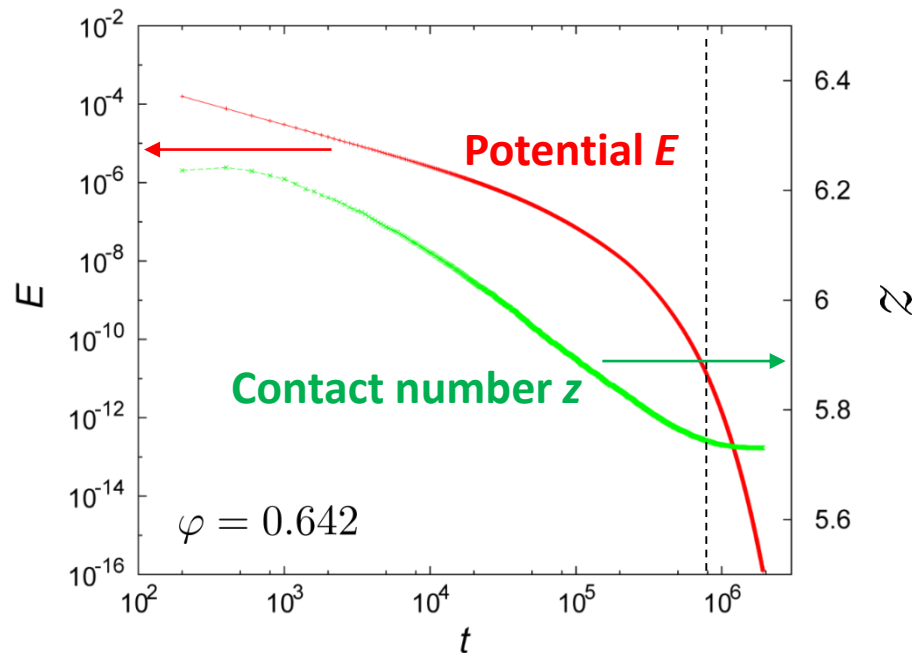


◆ Power-law\*exponential:  $E(t) \sim t^{-1} \exp(-t/\tau)$

◆ Relaxation time  $\tau$  diverges at  $\varphi \rightarrow \varphi_J$

# Contact number

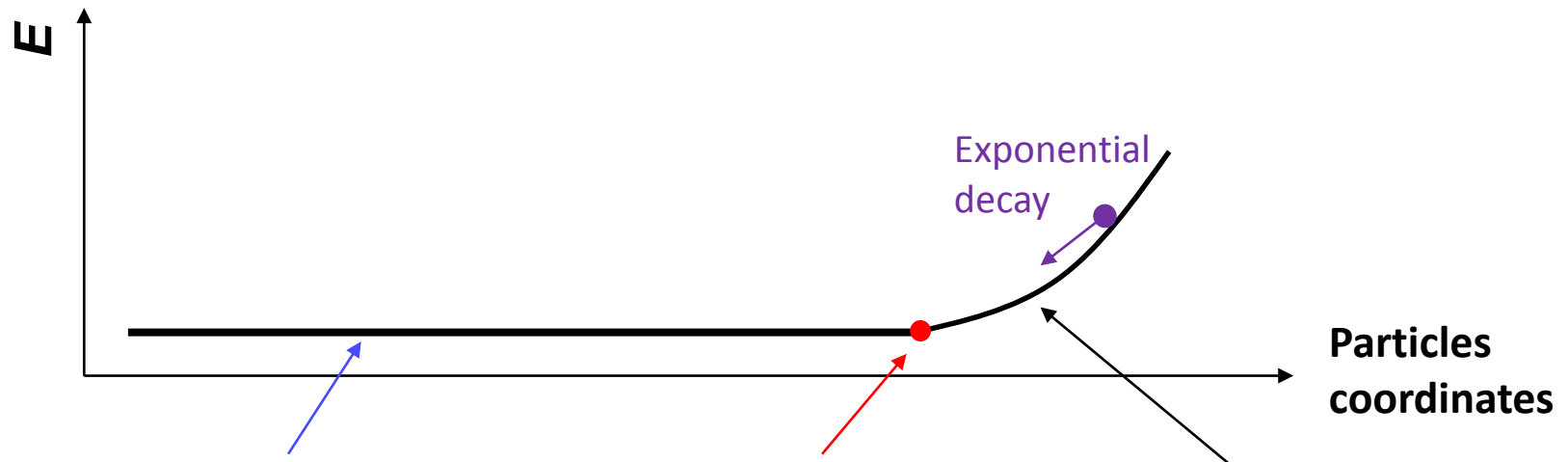
- ◆ Relaxation dynamics of contact number  $z$ 
  - ◆ Contact number = average number of overlapping particles per particle



- ◆ Power-law region:  $z$  decreases (contacts are broken)
- ◆ Exponential region:  $z$  converges into a constant
  - ◆ Relaxation without changing the contact network of particles

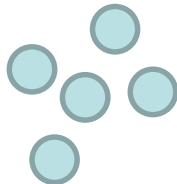
# What's going on?

## ◆ Potential energy landscape at $\varphi < \varphi_J$



\* Zero-energy configurations

\* Particles are separated by finite distance, so the contact number is zero



\* Zero energy configurations

\* Particles are just touching, so the contact number is finite



\* Finite energy configurations

\* Particles are overlapping  
\* The contact network is the same as ● state

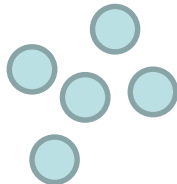


# What's going on?

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- \* Zero-energy configurations
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**Relaxation time should be determined by this curvature**

**→ Look into the eigenvalue of the Hessian of the dynamical matrix at the final configuration ●**





# Eigenvalues

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- ◆ For each  $\varphi$ , many final configurations are obtained from many initial configurations
- ◆ Obtain the Hessian of each final configuration

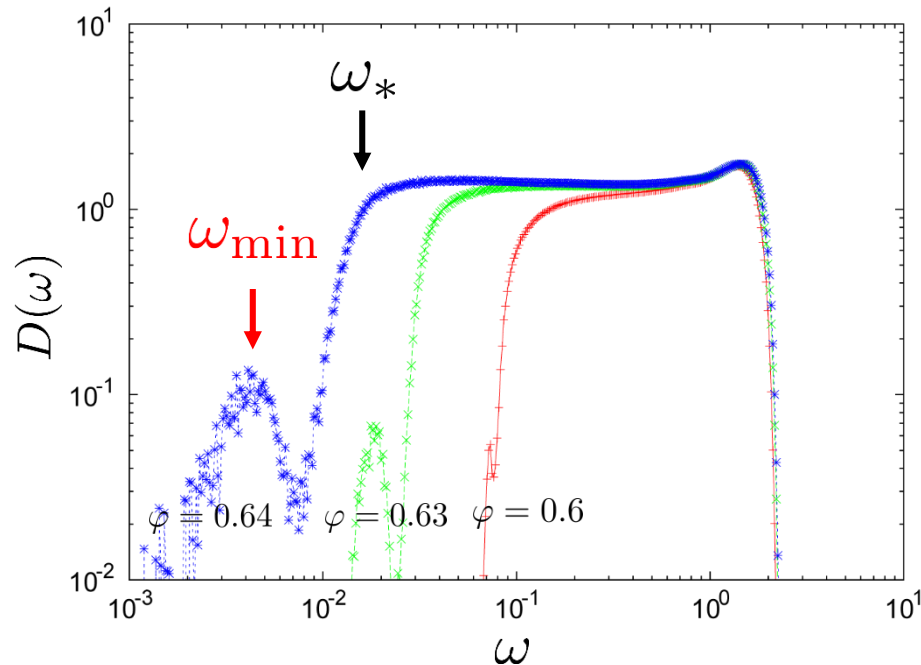
$$\mathbf{M} \equiv \frac{\partial^2 V}{\partial \vec{r}_i \partial \vec{r}_j} \quad V = \sum_{i,j} v(|\vec{r}_i - \vec{r}_j|)$$

- ◆ Diagonalize the Hessian, obtain the eigenvalues  $\{\lambda_\alpha\}$ , calculate the vibrational density of states:

$$D(\omega) \equiv \frac{1}{N} \sum_{\alpha} \delta(\omega - \omega_{\alpha}) \quad \omega_{\alpha} \equiv \sqrt{\lambda_{\alpha}}$$

- ◆ We ignore the  $3N^*(6-z)$  zero modes, because we consider the relaxation from finite energy configurations
- ◆ Average  $D(\omega)$  over obtained final configurations

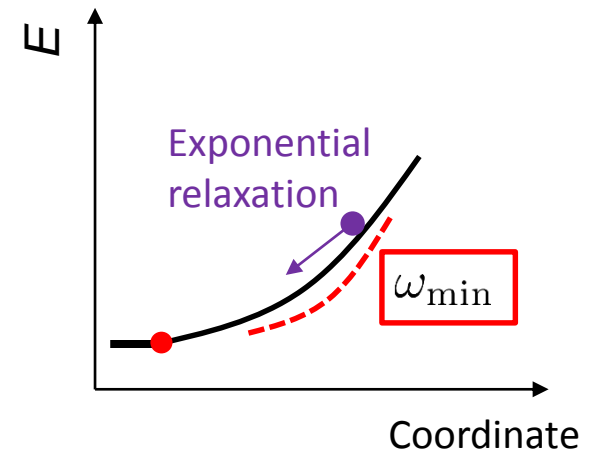
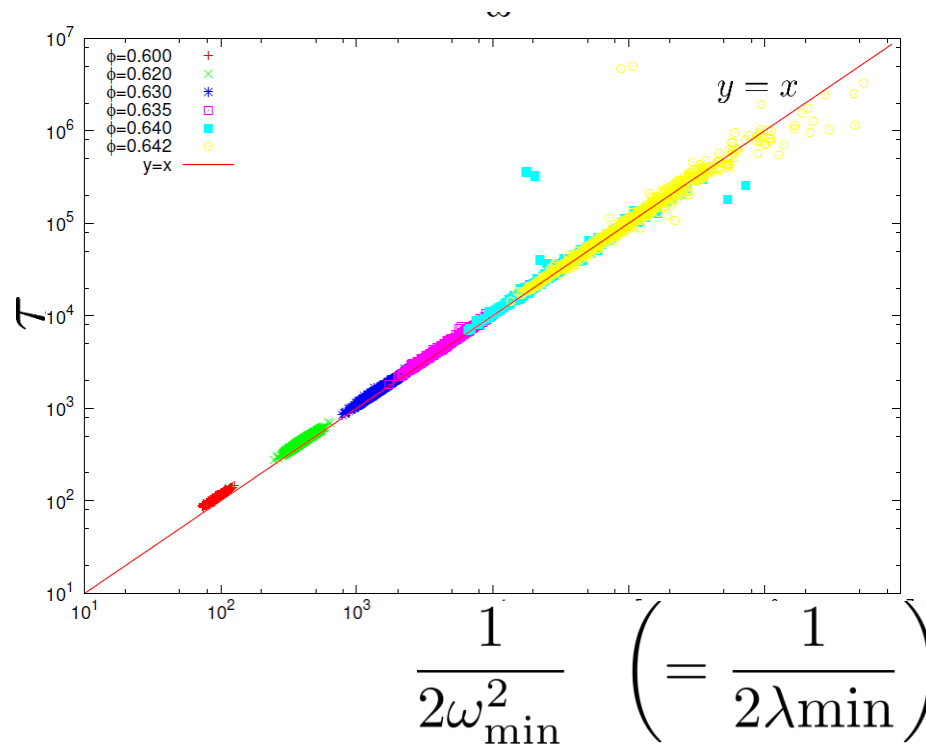
# Eigenvalues



- ◆  $\omega > \omega_*$  : Flat density of states
- ◆  $\omega = \omega_{\min}$  : **There is one anomalously soft mode**
  - ◆ This mode is one isolated mode for one configuration

# Relaxation time vs $\omega_{\min}$

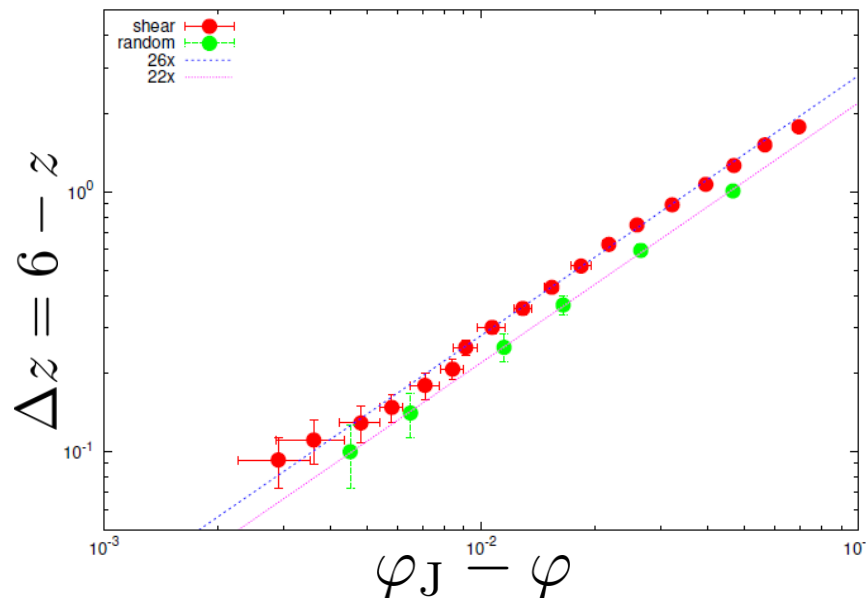
- ◆ Plot the relaxation time against  $\omega_{\min}$  for each configuration



**One configuration has only one extremely soft mode.  
Exponential relaxation is the relaxation along this mode.**

# Critical behavior

- ◆ The terminal contact number vs density

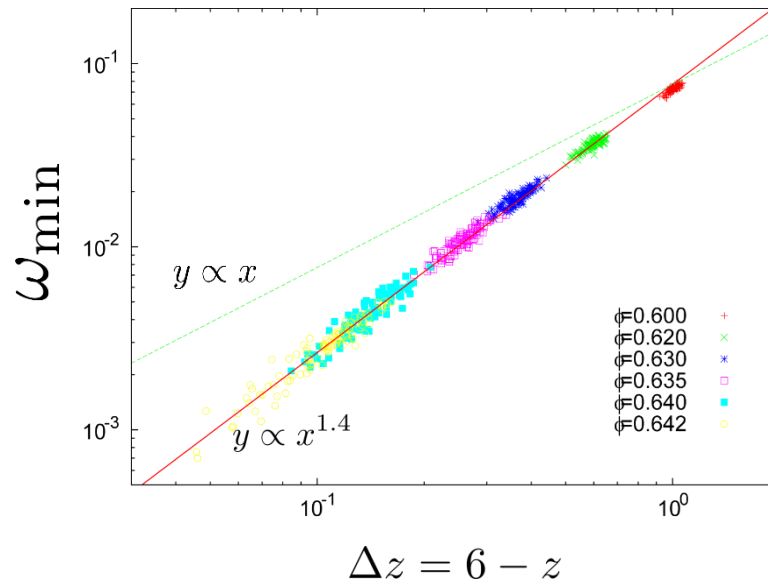


- ◆ The terminal contact number linearly approaches the isostatic value, 6.

$$\Delta z \propto (\varphi_J - \varphi)$$

# Critical behavior

- ◆ The terminal contact number vs  $\omega_{\min}$



- ◆ Lowest frequency:  $\omega_{\min} \propto \Delta z^{1.4} \propto (\varphi_J - \varphi)^{1.4}$
- ◆ Relaxation time:  $\tau \sim (\varphi_J - \varphi)^{-2.8}$

# Summary

- ◆ The terminal relaxation is exponential, and takes place without changing the contact network.
- ◆ Each unjammed configuration has one **anomalously soft mode**. The terminal relaxation is the relaxation along this mode.
- ◆ The relaxation time (= inverse of the eigenvalue of the anomalously soft mode) diverges as

$$\tau \sim (\varphi_J - \varphi)^{-2.8}$$

