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Isomonodromic Deformations and Whitham Equations

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- Int. J. Mod. Phys. A11 (38) (1996), 5505.
(With T. Nakatsu) hep-th/.....
- solu-int/9704009
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Outline

- isospectral v.s. isomonodromic problems
— motivation
- isomonodromic problem as MODULATION
of isospectral problem — general idea
- examples

Isospectral Problem

$$\frac{dM(\lambda)}{dt} = [A(\lambda), M(\lambda)] \quad (\text{Lax representation})$$

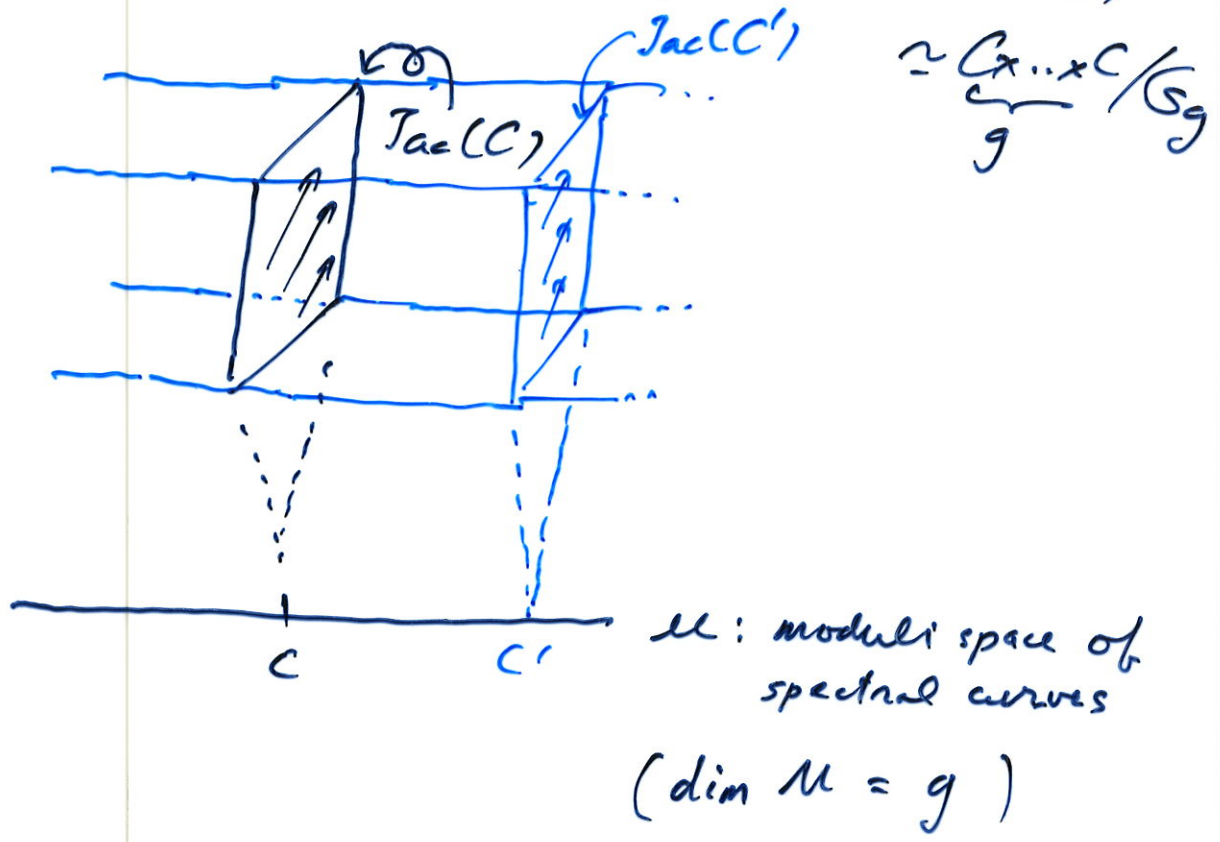
$$\Rightarrow \boxed{\frac{d}{dt} f(\lambda, \mu) = 0} \quad \text{where}$$

$$f(\lambda, \mu) = \det(\mu I - M(\lambda))$$

$$= \mu^n + c_1(\lambda)\mu^{n-1} + \dots + c_n(\lambda)$$

$C: f(\lambda, \mu) = 0$ Spectral curve

Lax equation \rightarrow linear flow on $\text{Jac}(C)$



Isomonodromic Problem

$$\frac{\partial M(\lambda)}{\partial t} - \frac{\partial A(\lambda)}{\partial \lambda} = [A(\lambda), M(\lambda)]$$

$$\Rightarrow \boxed{\frac{\partial}{\partial t} f(\lambda, \mu) \neq 0}$$

$$\left(\frac{\partial}{\partial t} \log f(\lambda, \mu) = - \text{Tr} \frac{\partial A(\lambda)}{\partial \lambda} (\mu I - M(\lambda))^{-1} \right)$$

Spectral curve depends on t .

(\Rightarrow usual methods for solving isospectral problems do not work.)

Remark $\text{Jac}(C) \simeq \underbrace{C \times \dots \times C}_g / \mathbb{S}_g$ is still useful for construction of "Darboux coordinates" ("spectral Darboux coordinates" Harnad et al)

↓

"Hamiltonian structure" of isomonodromic problems (K. Okamoto, et al)

cf. Manin's work (P_{II} etc) ?

isomonodromic problem \neq isospectral problem

However, there is much evidence that

isomonodromic problem \approx modulation of isospectral problem

asymptotically

$x \rightarrow \infty$

$\varepsilon \rightarrow 0$

Examples:

- Boutroux (1913) P_I, P_{II}, \dots
- Garnier (1919) Schlesinger equation

⋮

- Dubrovin, Krichever, Novikov (around '90)

String equations of 2d q-gravity
($\approx P_I, \dots$)

- Vereschagin ('96) $P_I \sim P_{VI}$

Problem

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0-4

Give asymptotic description of isomonodromic problems as modulation of isospectral problem!

Boutroux (1913) Painlevé I, II, ...
approximation as modulated elliptic function

$$(PI) \quad \frac{d^2 u}{dx^2} = 6u^2 - x, \quad x \rightarrow \infty$$

$$u \sim \wp(x \mid g_2 = x, g_3 = \dots)$$

$$(PI) \quad \varepsilon^2 \frac{d^2 u}{dx^2} = 6u^2 - x, \quad \varepsilon \rightarrow 0$$

$$u \sim \wp\left(\underbrace{\frac{x}{\varepsilon}}_{x''} \mid \underbrace{g_2 = x, g_3 = g_3(x)}_{\text{slow dynamics}}\right)$$

Garnier (1979)

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0-5

Schlesinger equation

$$\frac{\partial A_i}{\partial t_j} = (1 - \delta_{ij}) \frac{[A_i, A_j]}{t_i - t_j} - \delta_{ij} \sum_{k \neq i} \frac{[A_i, A_k]}{t_i - t_k}$$

e.g. Asymptotics as $t_i \rightarrow \infty$ (etc..)

Autonomous (isospectral) analogue

$t_i \rightarrow c_i$ on RHS

$$\frac{\partial A_i}{\partial t_j} = (1 - \delta_{ij}) \frac{[A_i, A_j]}{c_i - c_j} - \delta_{ij} \sum_{k \neq i} \frac{[A_i, A_k]}{c_i - c_k}$$

→ spectral curve \mathcal{C}

What is slow dynamics of spectral curve?

What is "modulation"?

1.

1-1

"finite-gap solution" of isospectral problem (e.g. KdV, Toda chain, Neumann, ...)

$$u = u_0 \left(\sum U_j t_j \mid \{I_n\} \right)$$

$u_0(z \mid \{I_n\})$... Abelian function

$$z \in \mathbb{C}^g \quad (\text{Jac} = \mathbb{C}^g / L)$$

$\{I_n\}$... constants of motion

$\{U_j\}$... constant vectors

period of Abelian
differentials on
"spectral curve" C

(time independent)

↓
isospectral

"modulation" of finite-gap solution

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1-2

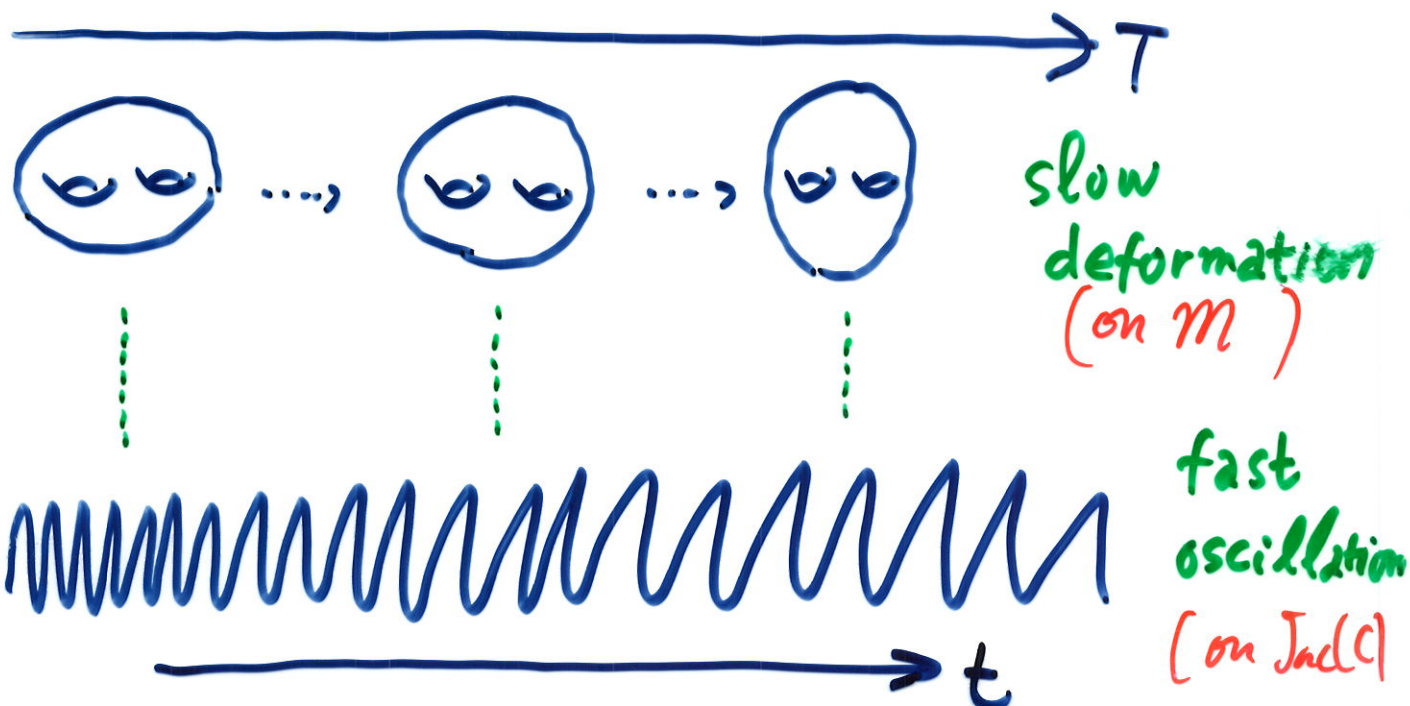
$$\boxed{\varepsilon \rightarrow 0}$$

$$u \sim u_0 \left(\sum U_j(T) t_j / \{I_n(T)\} \right)$$

t_j : fast variables

$T_j = \varepsilon t_j$: slow variables

$U_j \rightarrow U_j(T)$
 $I_n \rightarrow I_n(T)$ } functions of slow variables



and now for more general cases

It is known (at least for KdV, SG, etc) that slow dynamics is described by equations of the form

$$\frac{\partial}{\partial T_i} d\Omega_j = \frac{\partial}{\partial T_j} d\Omega_i$$

(Flaschka-Forest.
McLaughlin's equations)

$d\Omega_i$: meromorphic differentials

$$\psi = \frac{\prod(\text{theta functions})}{\text{theta functions}} \exp\left(\int t_i \int \frac{\partial \Omega_i}{\partial x} d\Omega_i\right)$$

This kind of equations describing modulation are called "Whitham equations" or "modulation equations".

isomonodromic problem with small parameter

- general prescription

$$\frac{\partial}{\partial t} \rightarrow \frac{\partial}{\partial t} + \varepsilon \frac{\partial}{\partial T}$$

T : slow variable

$$\frac{\partial}{\partial \lambda} \rightarrow \varepsilon \frac{\partial}{\partial \lambda}$$

t : fast —

$$u = u_0(t, T/I(T)) \Big|_{T=\varepsilon t} + \varepsilon u_1(t, T/I(T)) \Big|_{T=\varepsilon t} + \dots$$

$$A(\lambda) \rightarrow A^{(0)}(\lambda) + \varepsilon A^{(1)}(\lambda) + \dots$$

$$M(\lambda) \rightarrow M^{(0)}(\lambda) + \varepsilon M^{(1)}(\lambda) + \dots$$

$$\frac{\partial M}{\partial t} + \varepsilon \frac{\partial M}{\partial T} - \varepsilon \frac{\partial A}{\partial \lambda} = [A, M]$$

(\rightarrow ε -expansion) perturbation theory

lowest order:

$$\frac{\partial M^{(0)}}{\partial t} = [A^{(0)}, M^{(0)}] : \text{isospectral problem!}$$

$$f(\lambda, \mu) = \det(\mu I - M^{(0)}(\lambda))$$

$$\frac{\partial}{\partial t} f(\lambda, \mu) = 0, \quad \boxed{\frac{\partial}{\partial T} f(\lambda, \mu) \neq 0}$$

slow dynamics (on M)

"multi-scale analysis"

For all known cases, slow dynamics of the spectral curve in isomonodromic problems obeys an equation of the form

$$\frac{\partial}{\partial T} dS = d\Omega$$

- $dS = \mu d\lambda$
- $d\Omega =$ meromorphic differential that arises in the algebra-geometric construction of ψ :

$$\psi = \frac{\prod(\text{theta functions})}{\text{theta function}} \exp\left(t \int \frac{\Omega(\lambda)}{d\lambda}\right)$$

- $\frac{\partial}{\partial T} d\lambda = 0$

$$\frac{\partial}{\partial T} dS \Big|_{\lambda=\text{const}} = \nabla_{\partial/\partial T} dS : \text{connection}$$

(Krichever - Phong)

Remark: A symplectic basis of $H_1(C, \mathbb{Z})$ has to be fixed in order to determine $d\Omega$.

If there are several isomonodromic flows
 (t_1, \dots, t_m) , then the equations of motion of
 slow dynamics can be written

$$\frac{\partial}{\partial t_i} dS = d\Omega_i$$

$d\Omega_i$:

$$\psi = \frac{\mathcal{T}(\text{theta function})}{\text{theta function}} \exp\left(\sum t_i \int^{A_i} d\Omega_i\right)$$

$$\oint_{A_I} d\Omega_i = 0 \quad (I=1 \dots g)$$

$$\left(\langle A_I, B_J \rangle = \delta_{IJ} \right)$$

Examples and OPEN PROBLEMS...

2-1.

⊙ $P_I, P_{II}, P_{III}, \dots, P_{VII}$: all related to elliptic curve

⊙ Self-similar reduction of periodic ^{2D} Toda equation

→ $dS \equiv$ Seiberg - Witten differential

$\frac{\partial}{\partial a_i} dS = dw_i$: holomorphic differentials

(Gaiety, Krichever, Marchioro, Minomov, Morozov)

(... many people ... $SU(2)$)

⊙ { Schlesinger equation
Jimbo - Miwa - Mori - Sato equation } solv-int/...

NOT a self-similar reduction of soliton equations

(cf) WDVV equation with self-similarity condition
→ special case of Schlesinger equation

(Dubrovin)

quasi-homog.

⊙ isomonodromic problems on torus?

⊙ construction of isomonodromic problems itself is a problem

(K. Okamoto, K. Iwasaki, ...
2nd order scalar isomonodromic problems)

What about matrix systems?

Hint: Gaudin models

$XXX \rightarrow XYZ$
rational elliptic

isospectral problems = Hitchin system
(on punctured torus)

possible relation to $KZ(B)$ equations?

----- in progress!

⊙ Is derivation of slow dynamics rigorous?

- At least my derivation is *heuristic*.
- choice of cycles $\{A_I, B_I\}$

Schlesinger equation with small parameter

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2-3

$$\textcircled{1} \quad \frac{\partial A_i}{\partial t_j} = (1 - \delta_{ij}) \frac{[A_i, A_j]}{t_i - t_j} - \delta_{ij} \sum_{k \neq i} \frac{[A_i, A_k]}{t_i - t_k}$$

$$\textcircled{2} \quad \frac{\partial Y}{\partial \lambda} = M(\lambda) Y, \quad M(\lambda) := \sum_{i=1}^N \frac{A_i}{\lambda - t_i}$$

$$\frac{\partial Y}{\partial t_i} = - \frac{A_i}{\lambda - t_i} Y, \quad (i=1 \dots N)$$

$$\downarrow \quad t_i \rightarrow T_i, \quad \frac{\partial}{\partial t_i} \rightarrow \varepsilon \frac{\partial}{\partial T_i}, \quad \frac{\partial}{\partial \lambda} \rightarrow \varepsilon \frac{\partial}{\partial \lambda}$$

$$\textcircled{1} \quad \varepsilon \frac{\partial A_i}{\partial T_j} = (1 - \delta_{ij}) \frac{[A_i, A_j]}{T_i - T_j} - \delta_{ij} \sum_{k \neq i} \frac{[A_i, A_k]}{T_i - T_k}$$

$$\textcircled{2} \quad \varepsilon \frac{\partial Y}{\partial \lambda} = M(\lambda) Y, \quad M(\lambda) := \sum_{i=1}^N \frac{A_i}{\lambda - T_i}$$

$$\varepsilon \frac{\partial Y}{\partial T_i} = - \frac{A_i}{\lambda - T_i} Y, \quad (i=1 \dots N)$$

$$\varepsilon \frac{\partial}{\partial T_i} \rightarrow \frac{\partial}{\partial \tau_i} + \varepsilon \frac{\partial}{\partial T_i} \quad T_i: \text{fast variables}$$

Modulation Equation

(to Garnier's problem)

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2-4

Spectral curve (discovered by Garnier)

$$\det(M(\lambda) - \mu I) = 0.$$

Assumption

eigenvalues $\theta_{i\alpha}$ ($\alpha=1, \dots, r$)
of A_i are pairwise distinct

(stronger assumption: $\theta_{i\alpha} - \theta_{i\beta} \notin \mathbb{Z}$
(if $\alpha \neq \beta$))

$\rightarrow \pi^{-1}(T_i)$ compactified by r points
(not ramified over $\lambda = T_i$)

Modulation equation (derived by
heuristic argument)

$$\frac{\partial}{\partial T_i} dS = d\Omega_i, \quad \text{where } \left(\frac{\partial}{\partial T_i} \lambda = 0 \right)$$

$$dS = \mu d\lambda$$

$d\Omega_i$: mero. diff. of 2nd kind
poles at $\pi^{-1}(T_i)$, and...

Normalized as

$$\oint_{A_I} d\Omega_i = 0 \quad I=1 \dots g$$

$A_I, B_I \quad I=1 \dots g$: symplectic
homology basis

(*) parameters of spectral curve

$$F(\lambda, \mu) = \det(M(\lambda) - \mu I) = 0$$

① $\{\Theta_i\}$... constant (coad.
orbit invariants)

② $\{T_i\}$... deformation
variables

③ $\{h_I\} (I=1 \dots g)$... other coeff.

↑ (\approx isospectral Hamiltonians)

moduli of spectral curve

modulation equation $\rightarrow h_I = h_I(\underline{T})$

Solution by inverse period map

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period map :

$$C = C(\{h_I\}, \{\tau_i\})$$

$$h = \{h_I\} \mapsto a = \{a_I\}$$

$$a_I = \oint_{A_I} dS$$

invertibility :

$h \mapsto a$ is (locally) invertible

inverse period map :

$$a \mapsto h, \quad h_I = h_I(\{a_J\}, \underbrace{\{\tau_i\}}_{\text{parameter}})$$

① This solves the modulation eq:

$$\frac{\partial}{\partial \tau_i} dS = d\Omega_i$$

② Also satisfies the deformation equation of Seiberg - Witten type:

$$\frac{\partial}{\partial a_I} dS = d\omega_I \quad (\text{normalized diff. of } \underline{\underline{1st}} \text{ kind})$$