

Supersymmetric Solutions in Supergravity

Lunchtime Talk on 09 Jan. 2008

Supersymmetric Solutions

~classical solutions of supergravity preserving some of supersymmetries

They are useful to study

- string compactification (with fluxes)
- exotic solutions like black hole, black ring ...
- Holographic dual of supersymmetric gauge theories
etc

The conditions preserving supersymmetry

$$\begin{aligned}\delta(\text{fermions}) &= \langle 0 | \{Q, \text{fermions}\} | 0 \rangle \\ &= 0\end{aligned}$$

$$[\because \delta(\text{bosons}) \equiv 0 \quad \text{if } \langle 0 | \text{fermion} | 0 \rangle = 0]$$

For Supergravity,

$$\begin{array}{ll}\hat{\nabla}\epsilon = 0 & \text{(KSE)} \\ M\epsilon = 0 & (*)\end{array}$$

where, $\hat{\nabla} = \nabla + (\text{fluxes}) \cdot \gamma$ and $M = (\text{fluxes}) \cdot \gamma$.

Key Point

The integrability condition of KSE includes

$$\begin{aligned} 0 &= \gamma^\nu [\hat{\nabla}_\mu, \hat{\nabla}_\nu] \epsilon \\ &= (R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R - T_{\mu\nu}) \gamma^\nu \epsilon + \dots \end{aligned}$$

where \dots vanish if we impose

- KSE's (including (*))
- EOM of fluxes

i.e. [For $K^\mu K_\mu \neq 0$ ($K_\mu = \bar{\epsilon} \gamma_\mu \epsilon$)]

KSE's

(1-st order and linear) +

EOM's of fluxes

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Einstein's Eq.

(2-nd order and
nonlinear)

G(roup)-structure -characterization of geometry with fluxes-

e.g. For 6-dimensional compact space X_6 , **SU(3)-structure**

If there is a Killing spinor (solution of KSE's) η_{\pm} ($\gamma_7\eta_{\pm} = \pm\eta$),
we can construct

$$J_{mn} = -i(\eta_+^\dagger \gamma_{mn} \eta_+), \quad \text{almost complex structure or (1,1)-form}$$
$$\Omega_{mnp} = (\eta_-^\dagger \gamma_{mnp} \eta_+), \quad \text{(3,0)-form}$$

which satisfy, due to Fierz identity,

$$J_i^j J_j^k = -\delta_i^k,$$
$$(\Pi^+)_{m } \Omega_{npq} = \Omega_{mpq}, \quad (\Pi^-)_{m } \Omega_{npq} = 0,$$
$$\Omega \wedge J = 0, \quad \Omega \wedge \bar{\Omega} = \frac{4i}{3} J \wedge J \wedge J,$$

where $(\Pi^\pm)_{m } = \frac{1}{2}(\delta_m^n \mp iJ_m^n)$

(J, Ω) completely specify SU(3)-structure on X_6 .

All the tensors can be decomposed into irreps. of SU(3).

Then geometry of X_6 is characterized by the intrinsic torsion class, which parametrize the failure of the manifold to be of Calabi-Yau:

$$dJ = -\frac{3}{2} \text{Im}(\mathcal{W}_1 \bar{\Omega}) + \mathcal{W}_4 \wedge J + \mathcal{W}_3,$$

$$d\Omega = \mathcal{W}_1 J \wedge J + \mathcal{W}_2 \wedge J + \bar{\mathcal{W}}_5 \wedge \Omega.$$

e.g.

	$\mathcal{W}_1 = \mathcal{W}_2 = 0$	hermitian
	$\mathcal{W}_1 = \mathcal{W}_2 = \mathcal{W}_4 = 0$	balanced
complex	$\mathcal{W}_1 = \mathcal{W}_2 = \mathcal{W}_4 = \mathcal{W}_5 = 0$	special hermitian
	$\mathcal{W}_1 = \mathcal{W}_2 = \mathcal{W}_3 = \mathcal{W}_4 = 0$	Kähler
	$\mathcal{W}_1 = \mathcal{W}_2 = \mathcal{W}_3 = \mathcal{W}_4 = \mathcal{W}_5 = 0$	Calabi-Yau
	$\mathcal{W}_2 = \mathcal{W}_3 = \mathcal{W}_4 = \mathcal{W}_5 = 0$	nearly-Kähler
non-complex	$\mathcal{W}_1 = \mathcal{W}_3 = \mathcal{W}_4 = \mathcal{W}_5 = 0$	almost-Kähler
	$\text{Re}\mathcal{W}_1 = \text{Re}\mathcal{W}_2 = \mathcal{W}_4 = \mathcal{W}_5 = 0$	half-flat