

Rheology of dense suspensions under oscillatory shear with lattice Boltzmann Method

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Physics of Jammed Matter
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Suspensions

particle radius

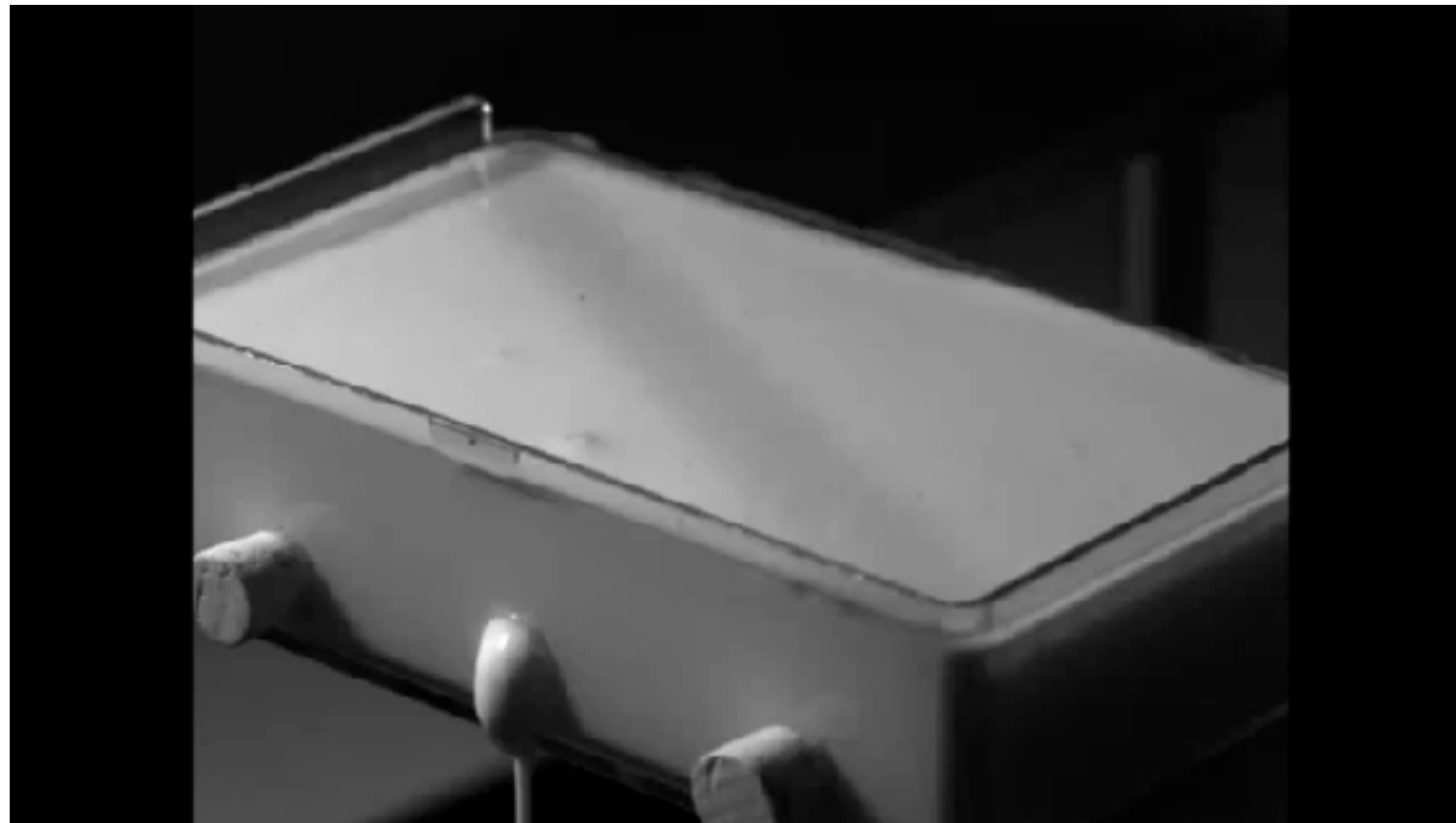
$$\longrightarrow a \approx 1 - 100 \mu m \longrightarrow$$

Stokes Equation

$$\eta \nabla^2 \mathbf{u} = \nabla p$$
$$\nabla \cdot \mathbf{u} = 0$$



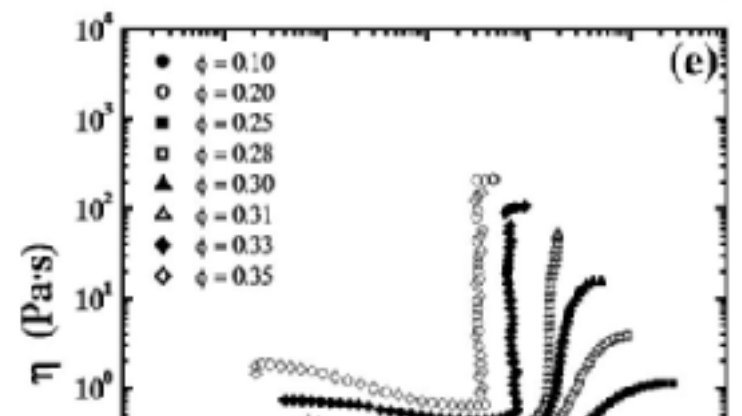
**Discontinuous shear
thickening!**



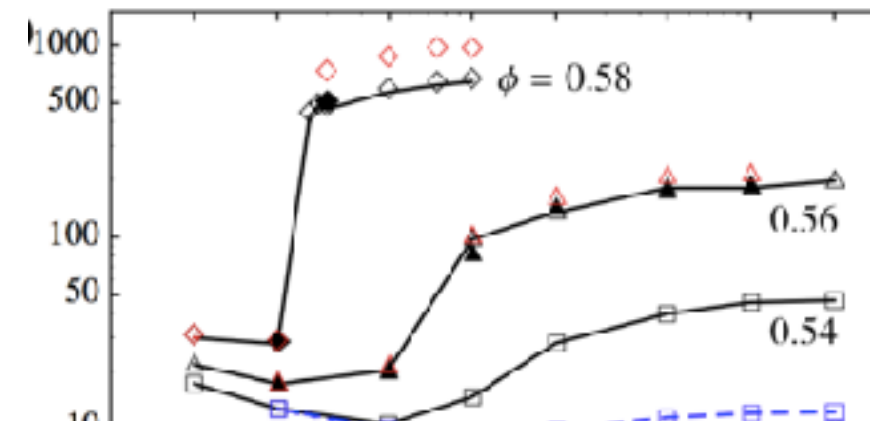
source: https://www.youtube.com/watch?v=hP88C-_LgnE&list=PLVjilPzFTOLpxiwdwrFuPYSIBpr6jFm32

STEADY SHEAR

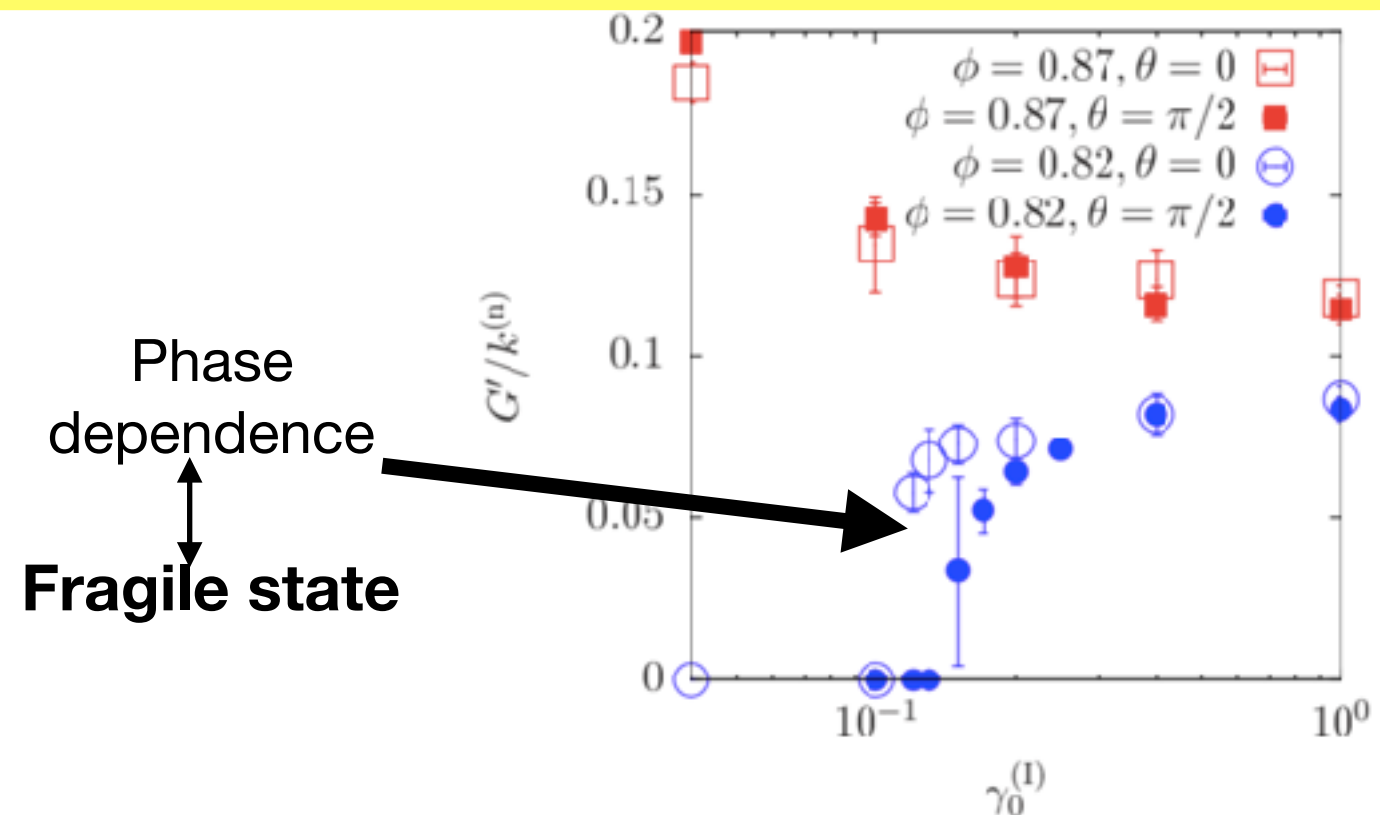
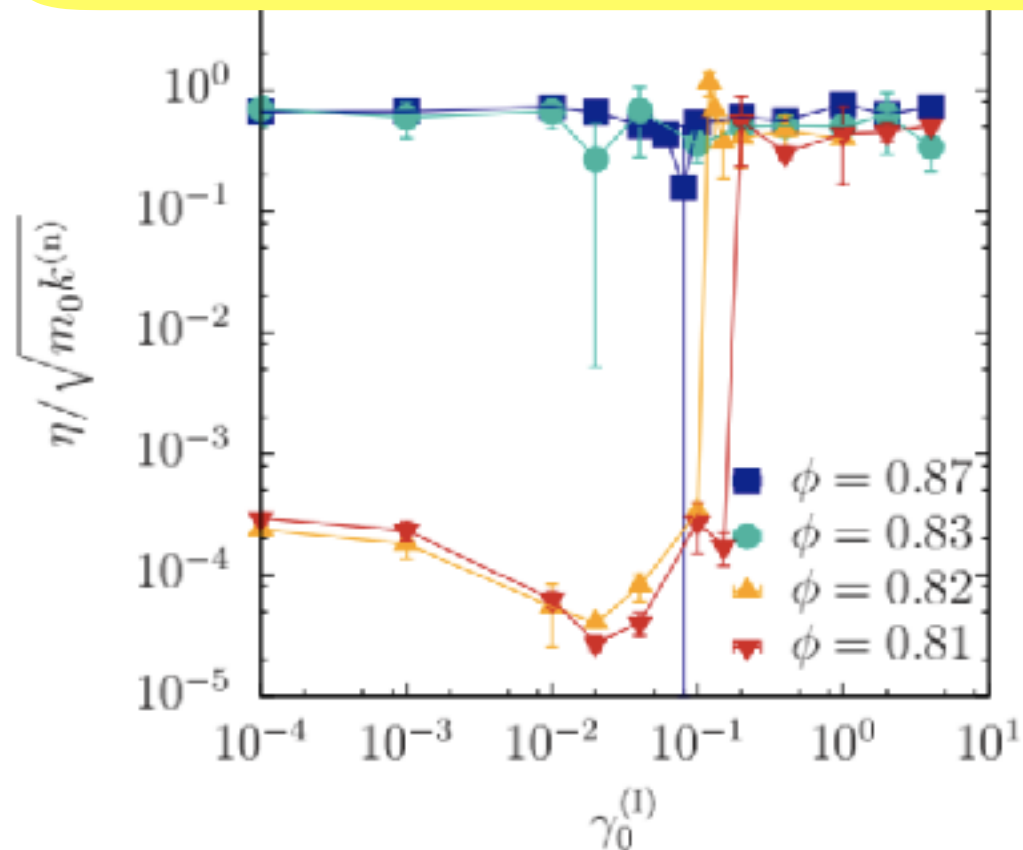
Experimental Observation:



Numerical Simulations:



WHAT HAPPEN IF WE IMPOSE OSCILLATORY SHEAR TO SUSPENSIONS?

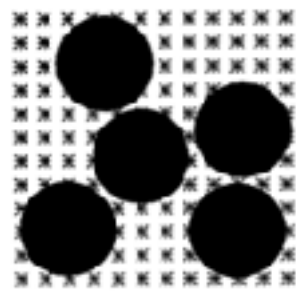


Lattice Boltzmann Method (LBM)

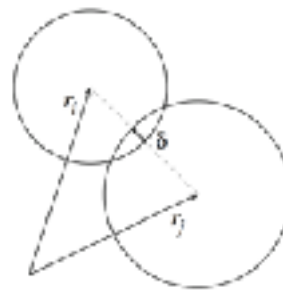
Hydrodynamics

Contact

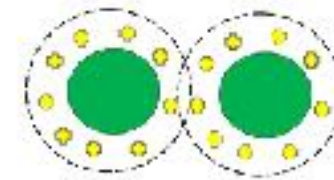
Electrostatic repulsive force



+



+



Equation of motion

$$m \cdot \frac{d}{dt} \begin{pmatrix} \mathbf{U} \\ \mathbf{\Omega} \end{pmatrix} = \sum_{\alpha} \begin{pmatrix} \mathbf{F}_{\alpha} \\ \mathbf{T}_{\alpha} \end{pmatrix}$$

$$\sum_{\alpha} \mathbf{F}_{\alpha} = \mathbf{F}^h + \mathbf{F}^c + \mathbf{F}^R$$

Ladd's LBM A.J.C Ladd, JFM, 271,285-339 (1994)

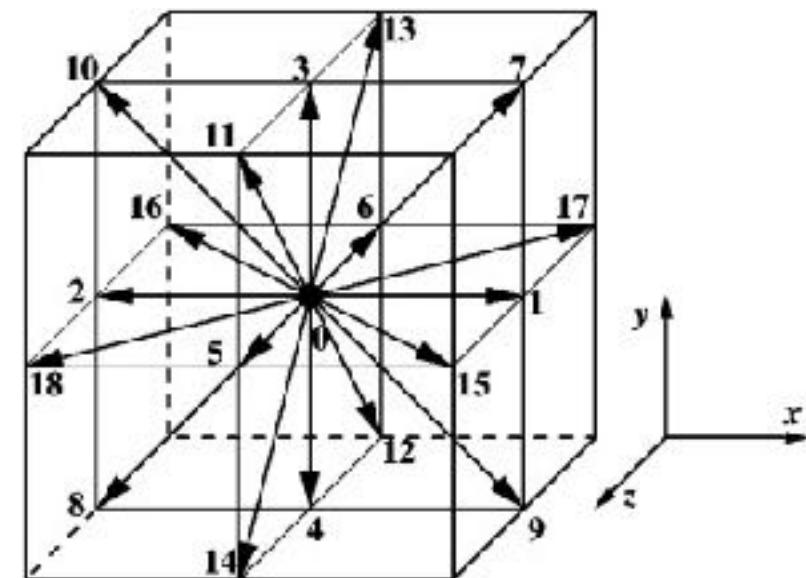
$$n_i(\mathbf{r} + \mathbf{c}_i, t + 1) = n_i(\mathbf{r}, t) + \Delta_i(\mathbf{r}, t)$$

discrete
velocity
distribution
function on
lattice

discrete
velocity

Streaming

Collision



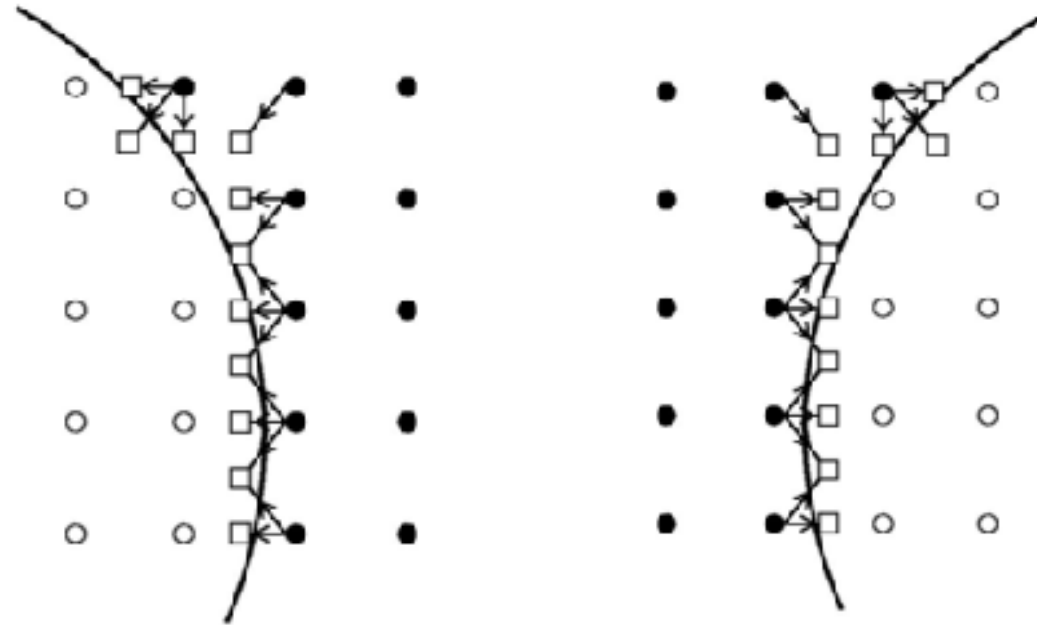
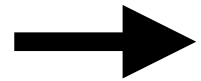
mass density $\rho = \sum_i n_i$

momentum density $\mathbf{j} = \sum_i n_i \mathbf{c}_i$

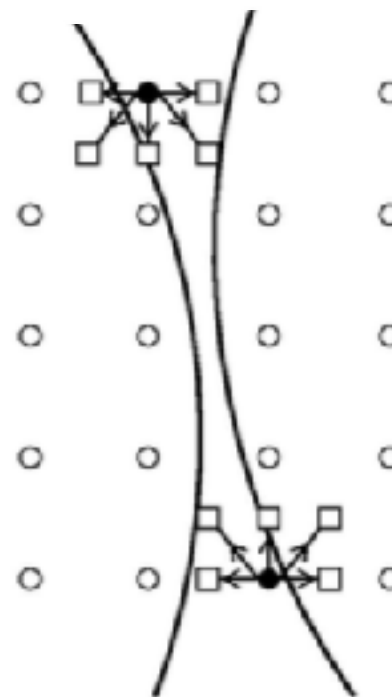
momentum flux $\Pi = \sum_i n_i \mathbf{c}_i \mathbf{c}_i$

Treatment of hydrodynamics and contact forces

Forces on
boundary nodes



shared nodes



*Use resistance
matrix formulation
for the lubrication
forces*

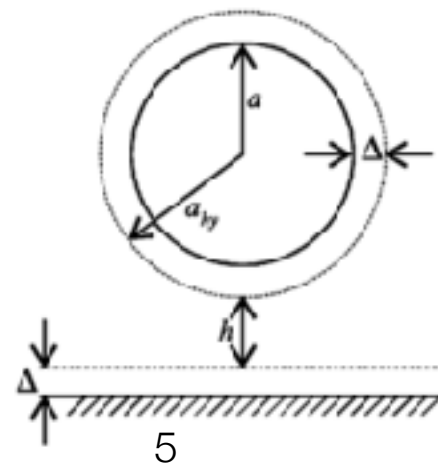
(Kim and Karilla, 1991)

Nguyen and Ladd, PRE **66**, 046708,(2002)

Contact

Linear spring model used in DEM
(with friction)

Luding, Granular Matter **10**:235–246 , (2008)

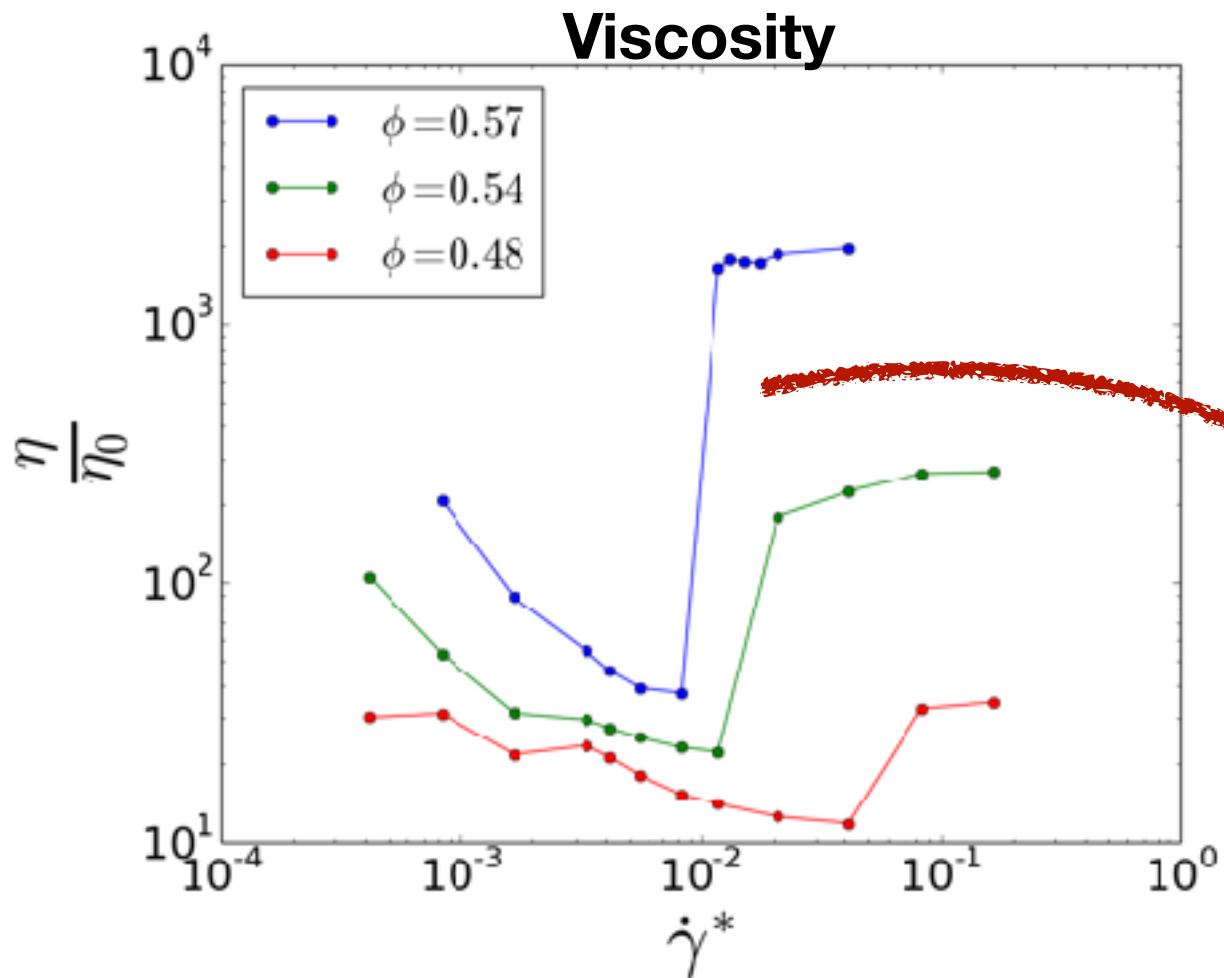


Lubrication vanishes at
some distances to allow
contact

$$\Delta = \frac{a_{\text{contact}} - a_{\text{hydro}}}{a_{\text{contact}}}$$

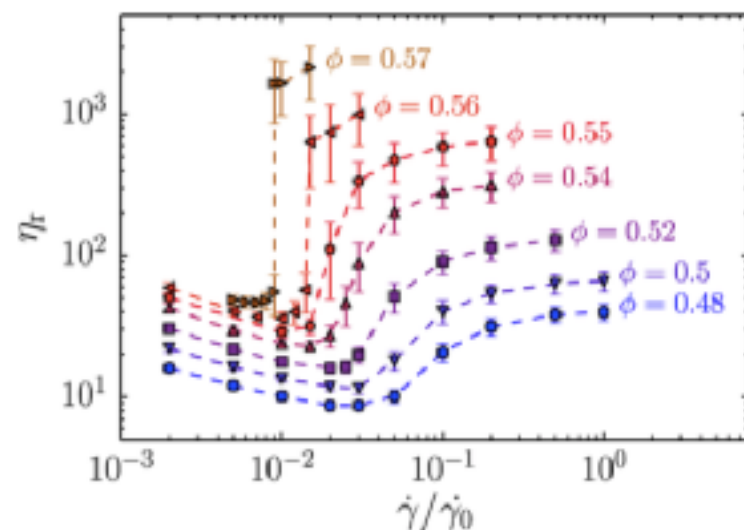
Steady shear simulation

N=512 particles



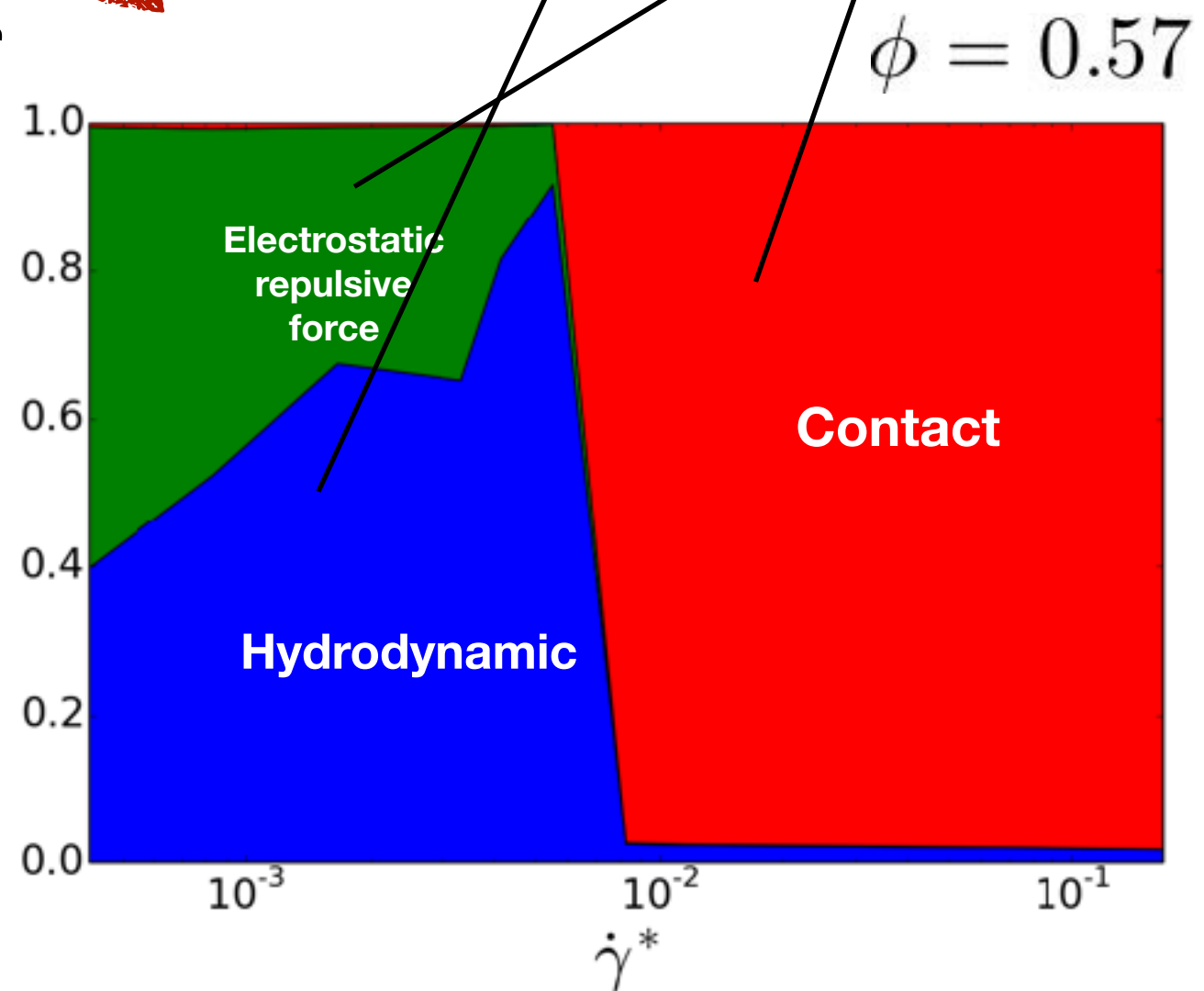
$$\dot{\gamma}^* = \frac{6\pi\eta_0 a^2 \dot{\gamma}}{F_{er}}$$

Magnitude of electrostatic repulsive forces



Shear stress $\sigma = \sigma^h + \sigma^c + \sigma^r$

fraction of each contribution to viscosity



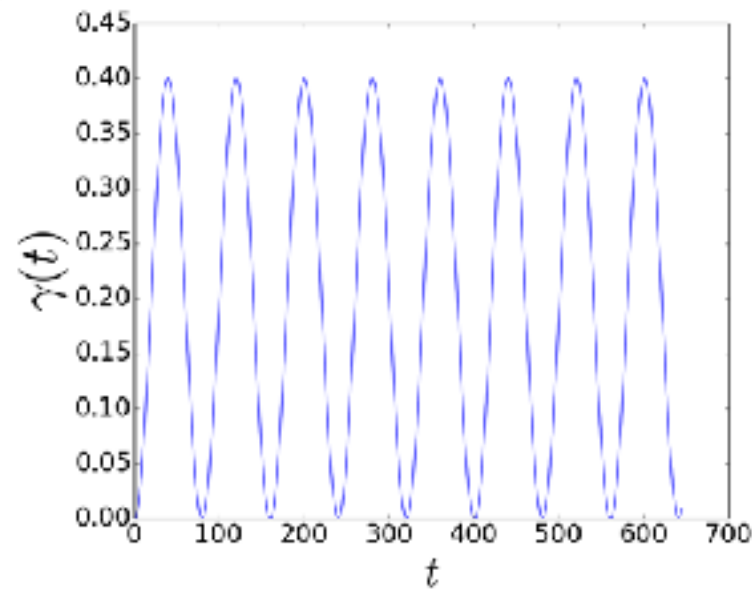
Oscillatory shear simulation

Strain

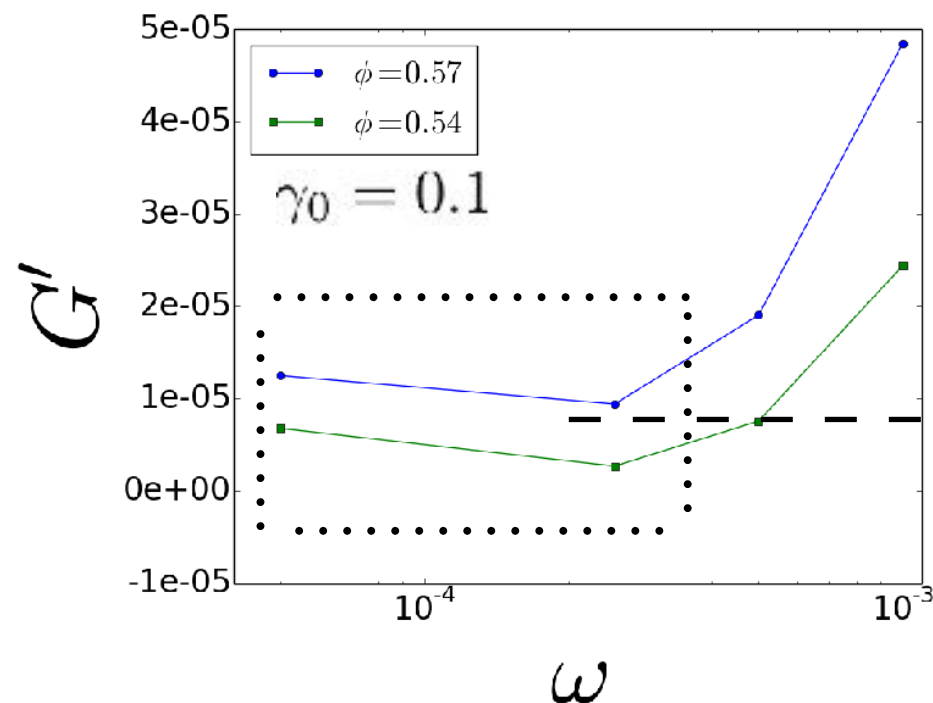
$$\gamma(t) = \gamma_0(\cos \theta - \cos(\omega t + \theta))$$

Strain rate

$$\dot{\gamma}(t) = \gamma_0 \omega \sin(\omega t + \theta)$$



ω dependence



Storage modulus

$$G' = -\frac{\omega}{\pi} \int_0^{2\pi/\omega} dt \frac{\sigma(t) \cos(\omega t + \theta)}{\gamma_0}$$

rigidity

Loss modulus

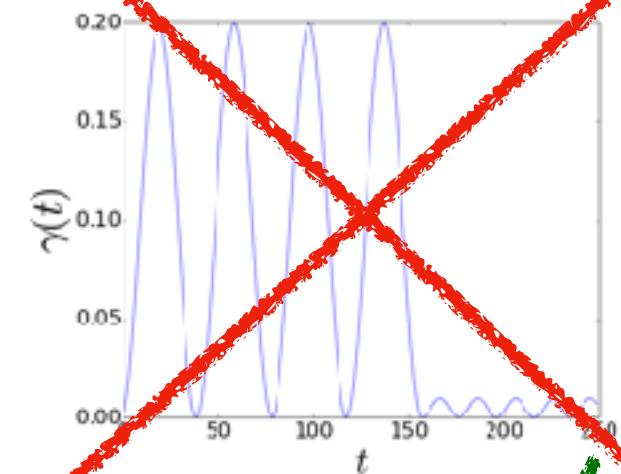
$$G'' = \frac{\omega}{\pi} \int_0^{2\pi/\omega} dt \frac{\sigma(t) \sin(\omega t + \theta)}{\gamma_0}$$

viscosity

Michio Otsuki's protocol

Using initial strain amplitude γ_0^I

$\gamma_0 = 10^{-4}$ (very small for observation)

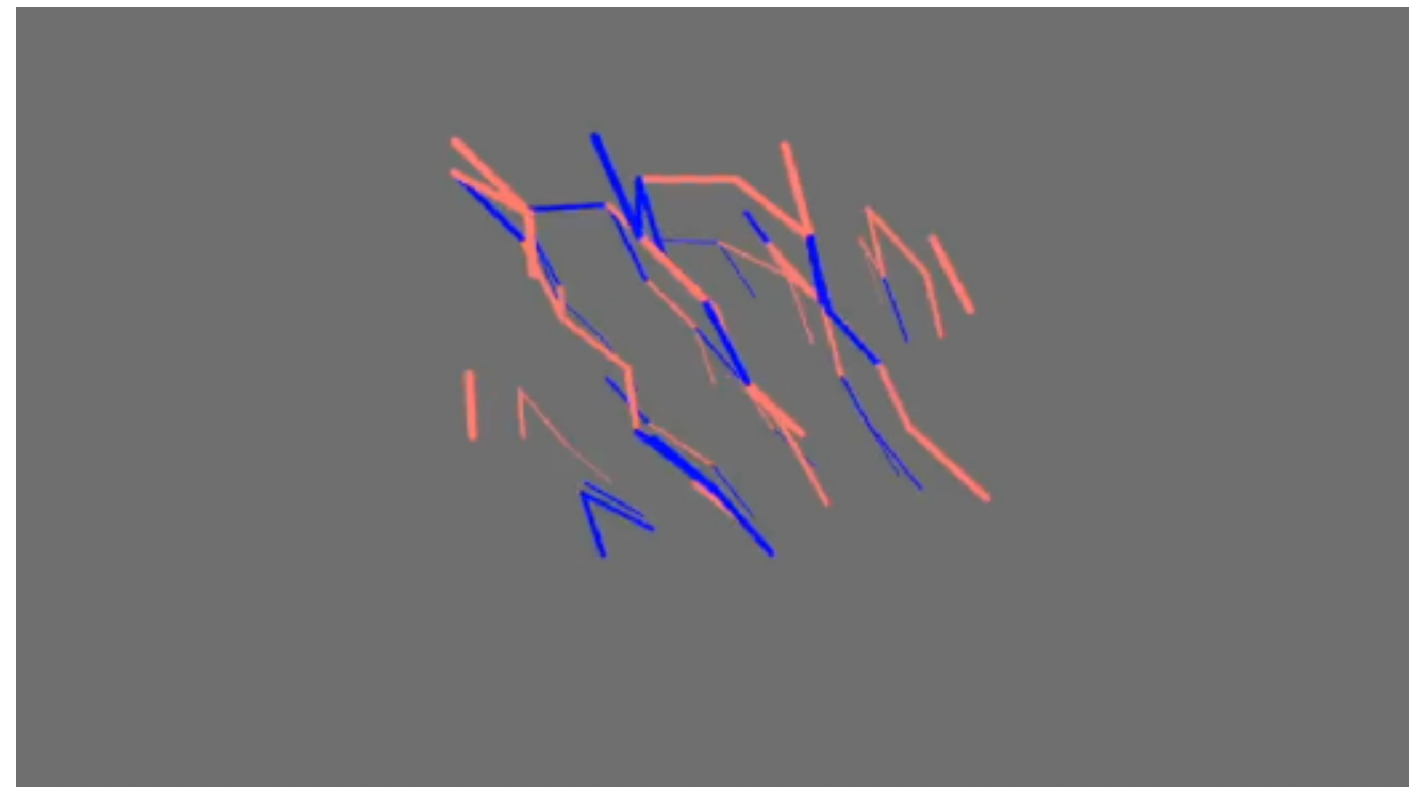
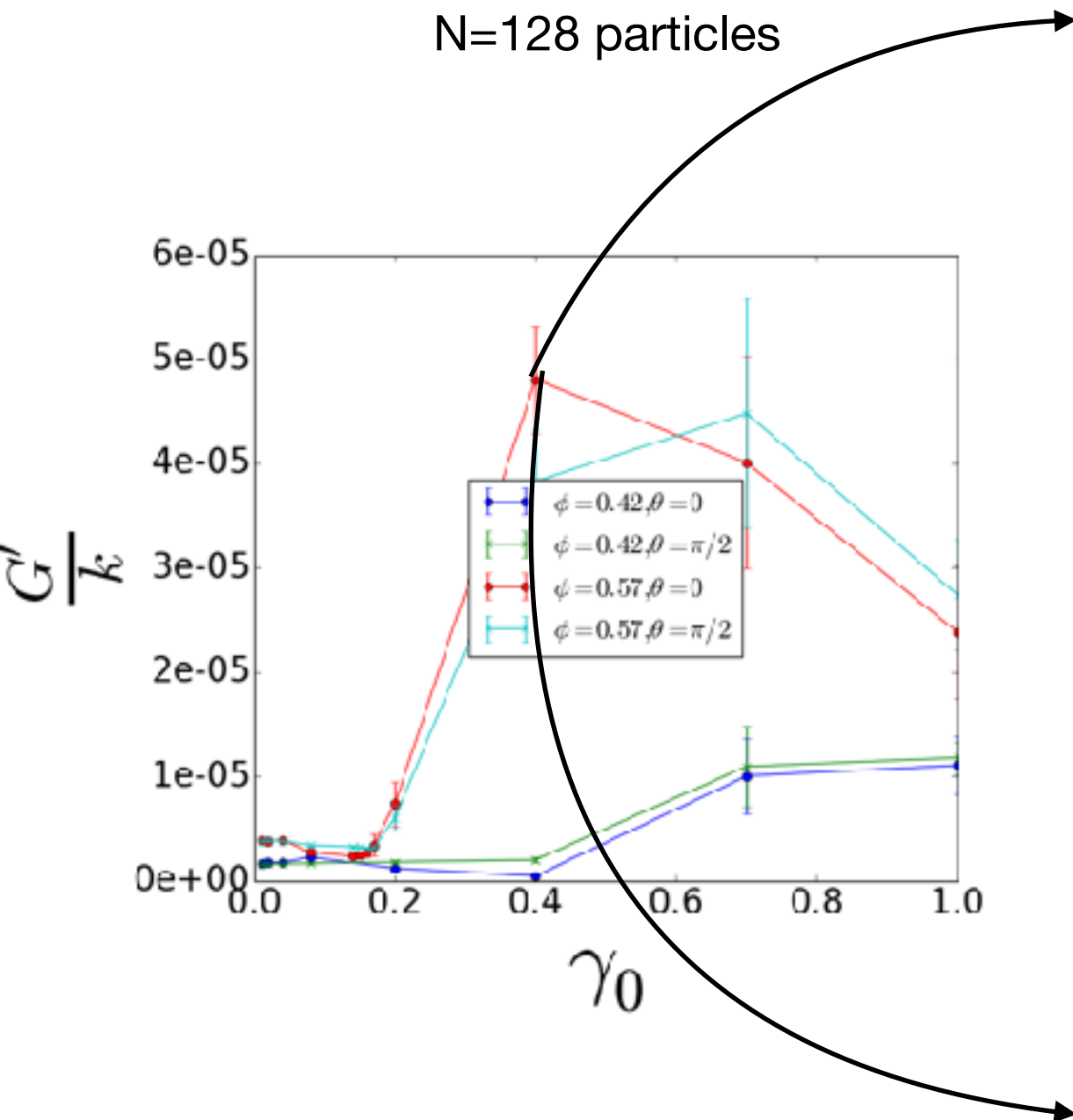
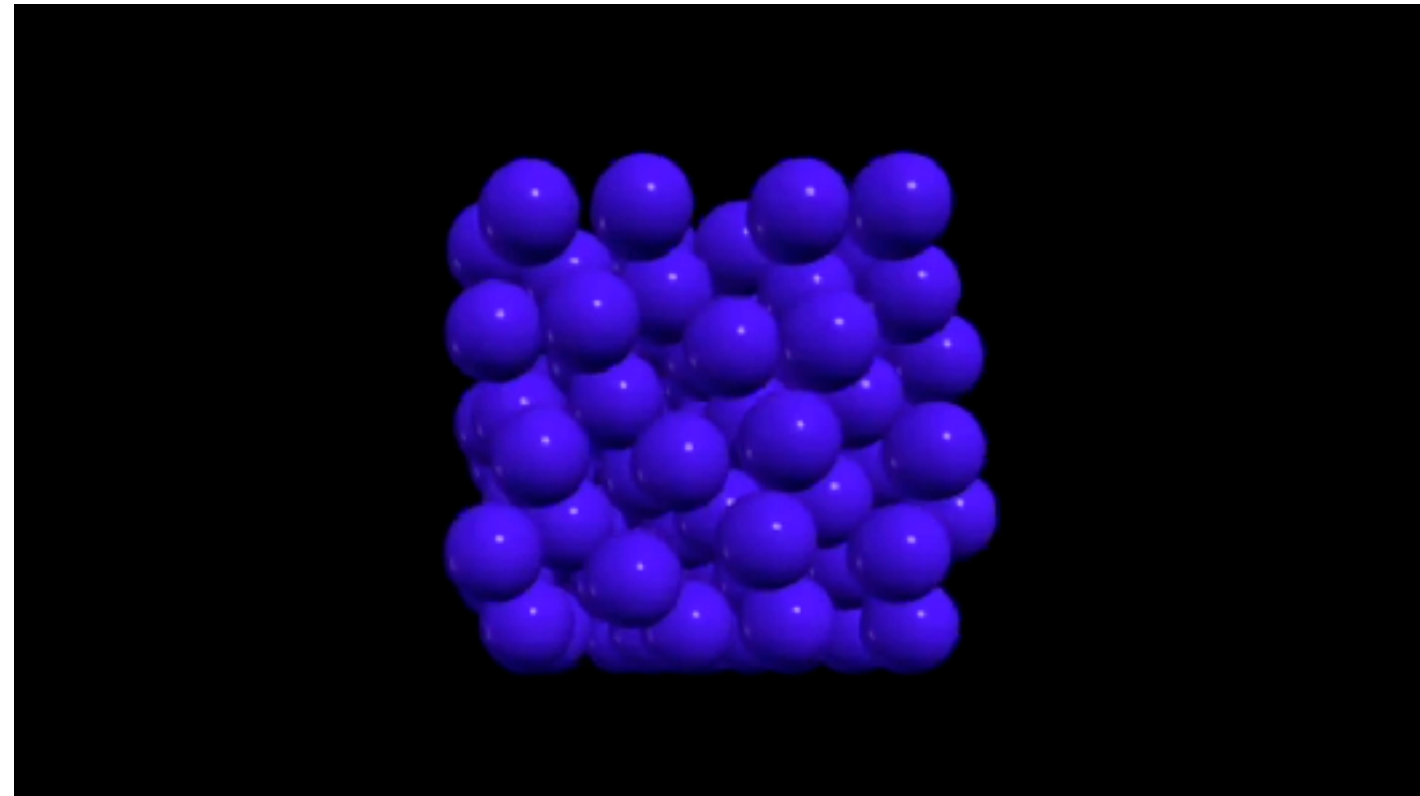


observation

no contact observed during observation by using this protocol!

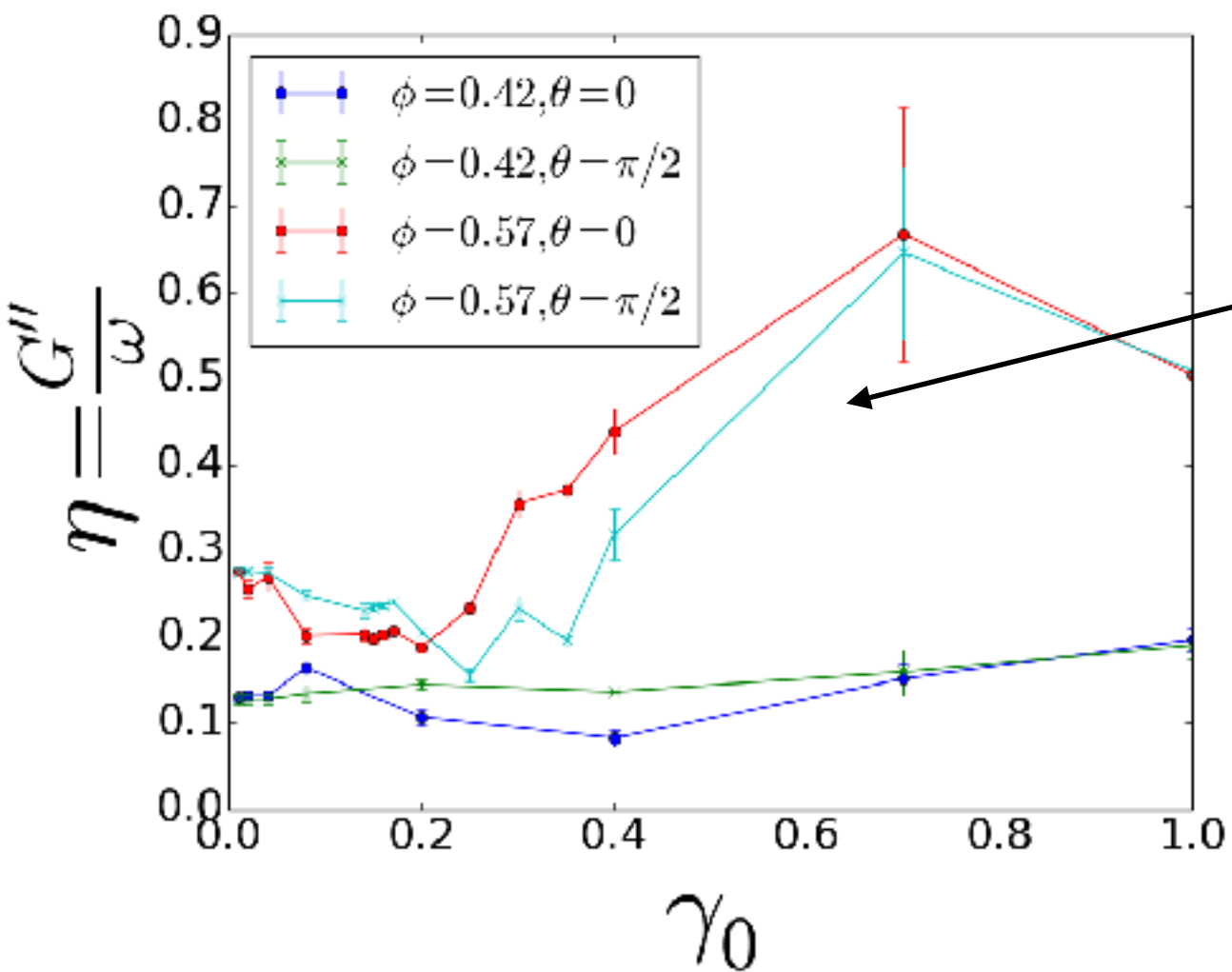
Oscillatory shear simulation

Particle motion



Contact network

all contributions

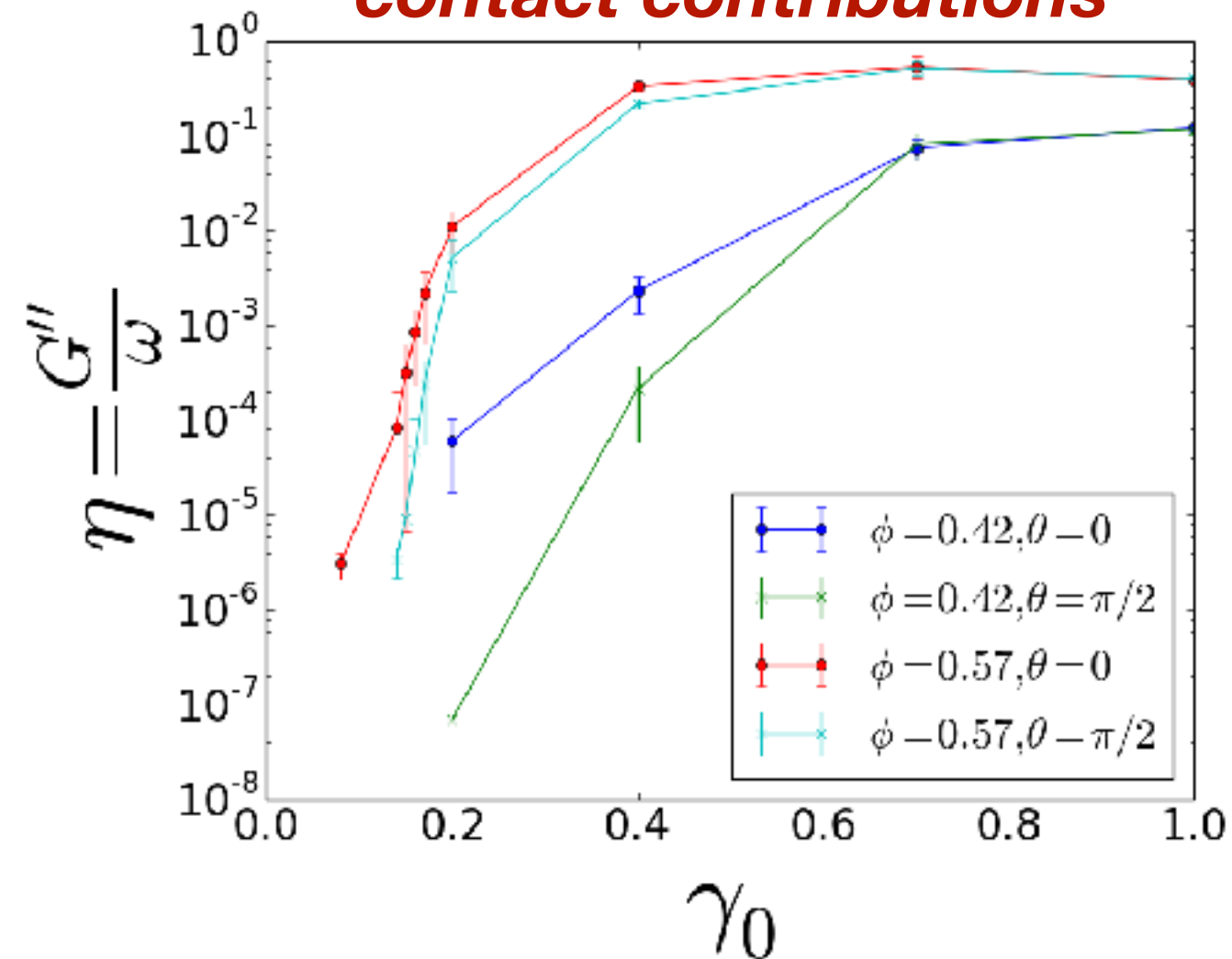


No discontinuous jump

Hydrodynamics is still strong

Thickening is caused by contact

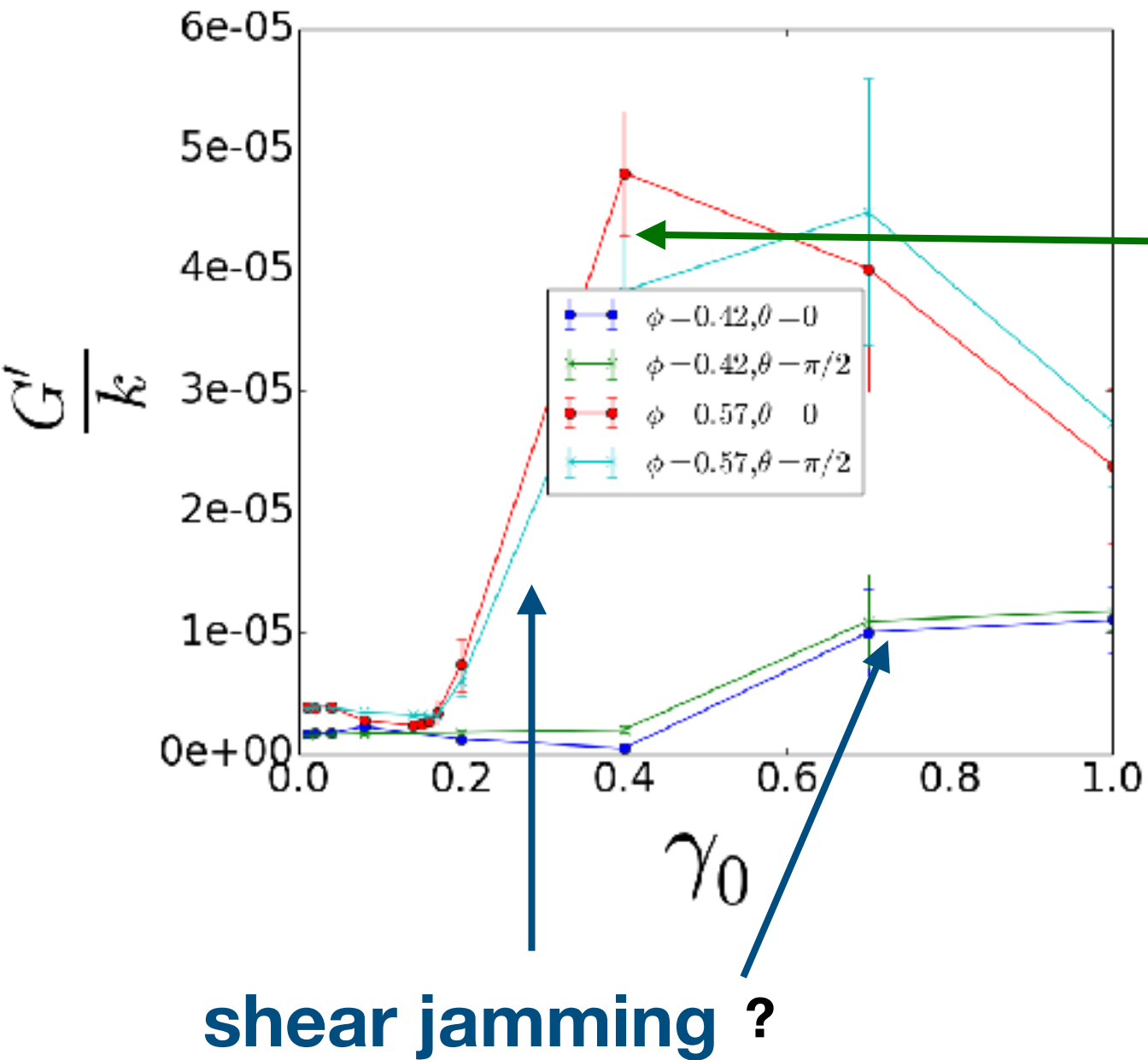
contact contributions



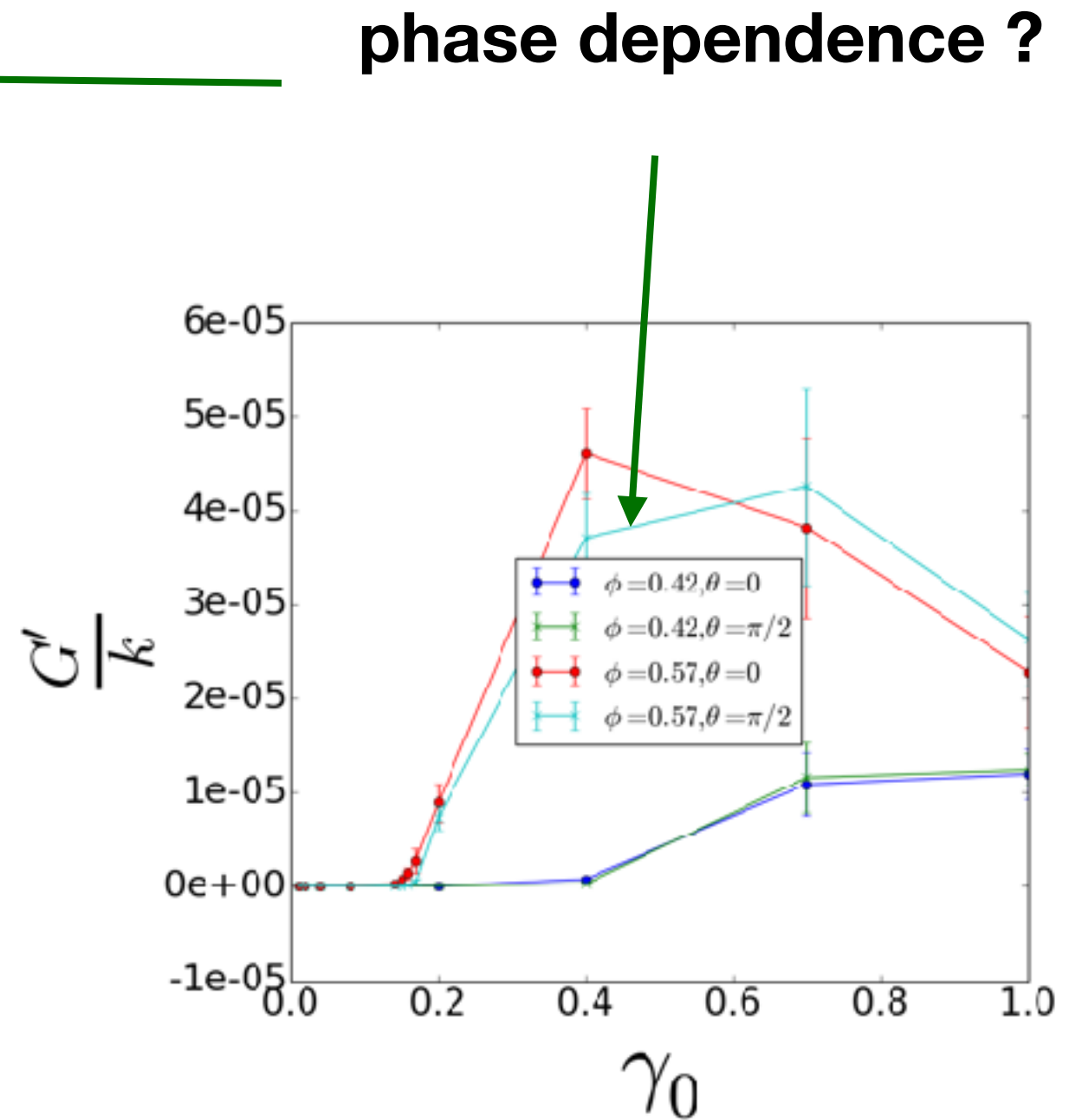
Storage modulus

N=128 particles

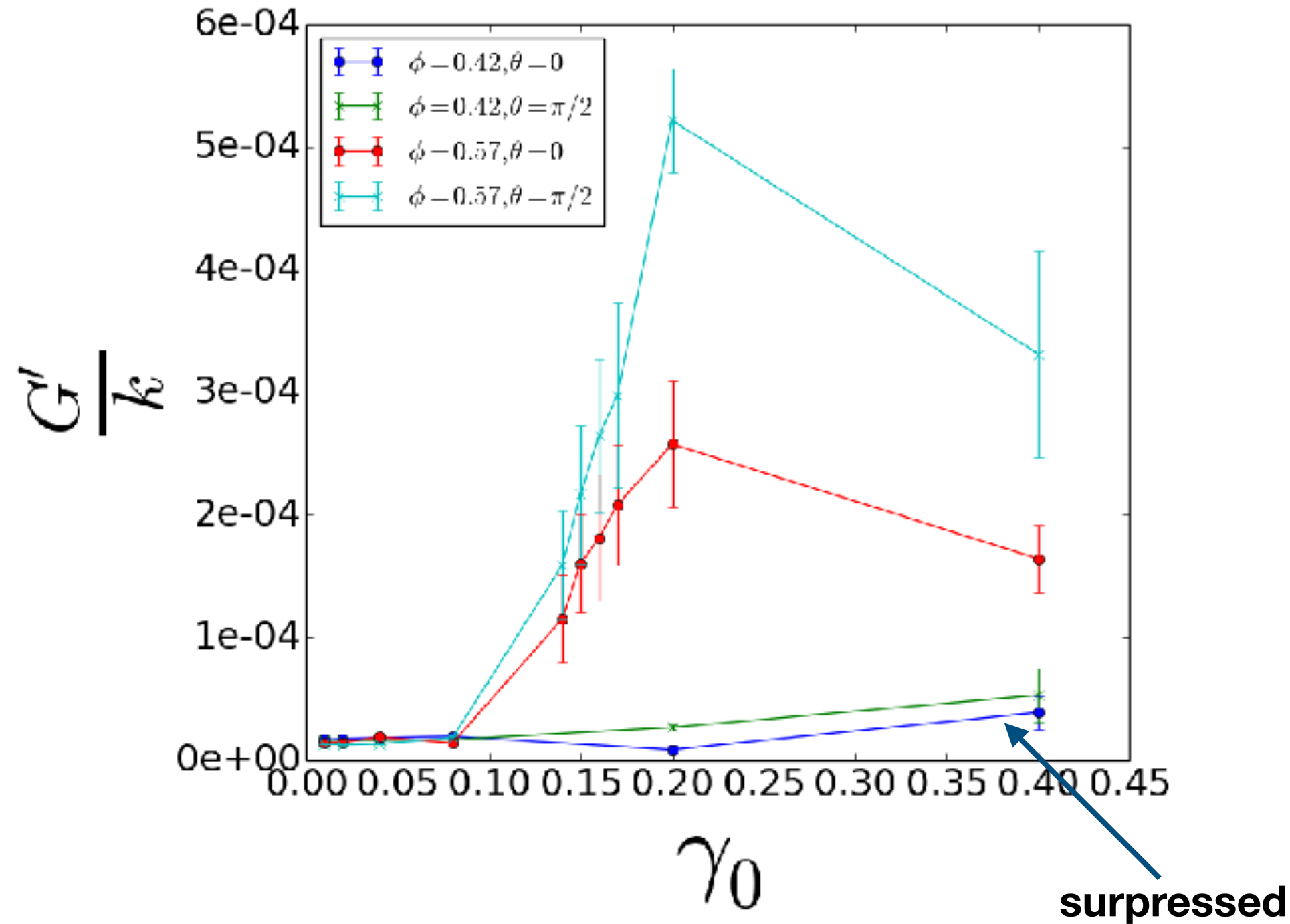
all contributions



Dominated by contact

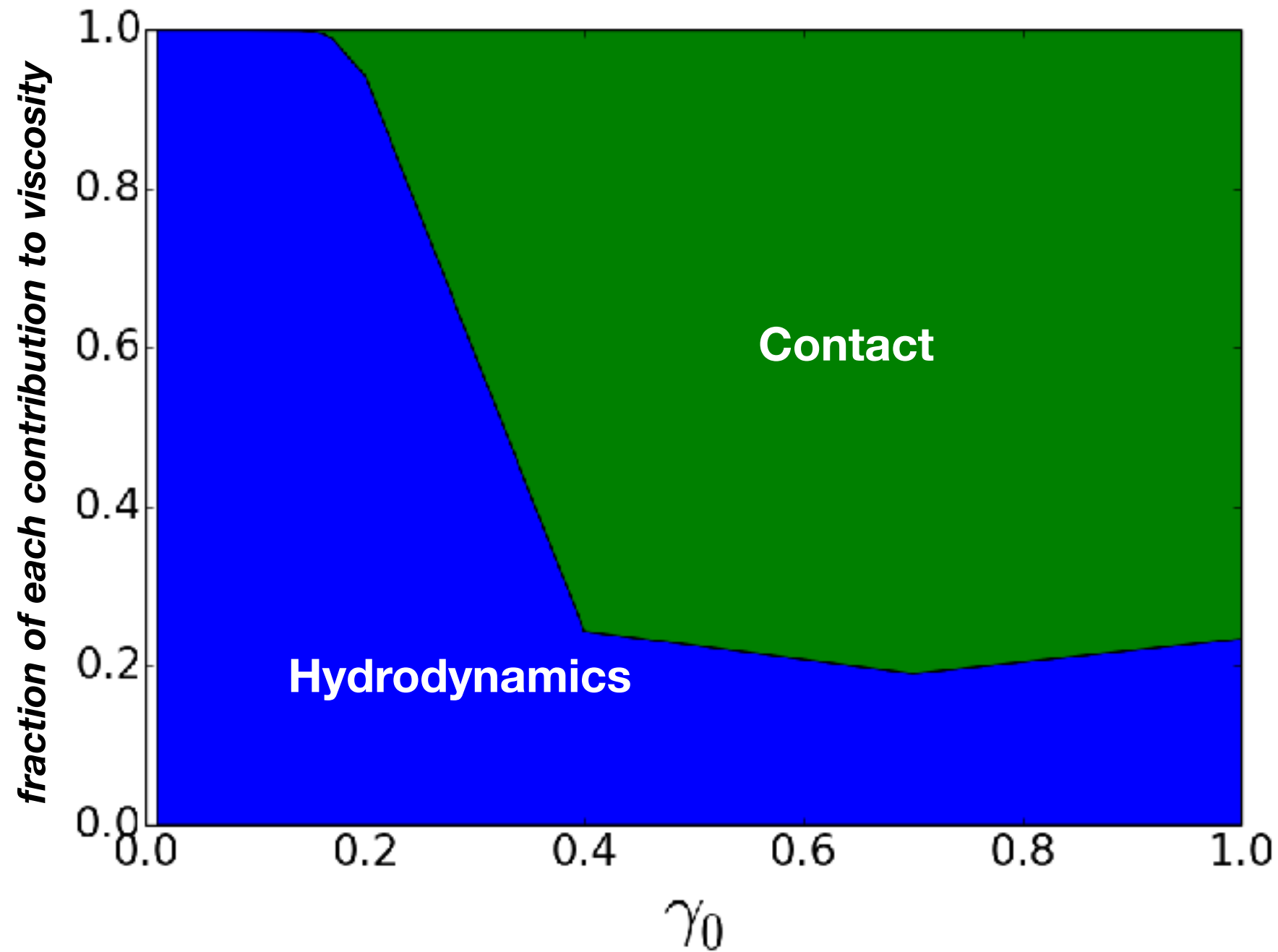


Contact contributions



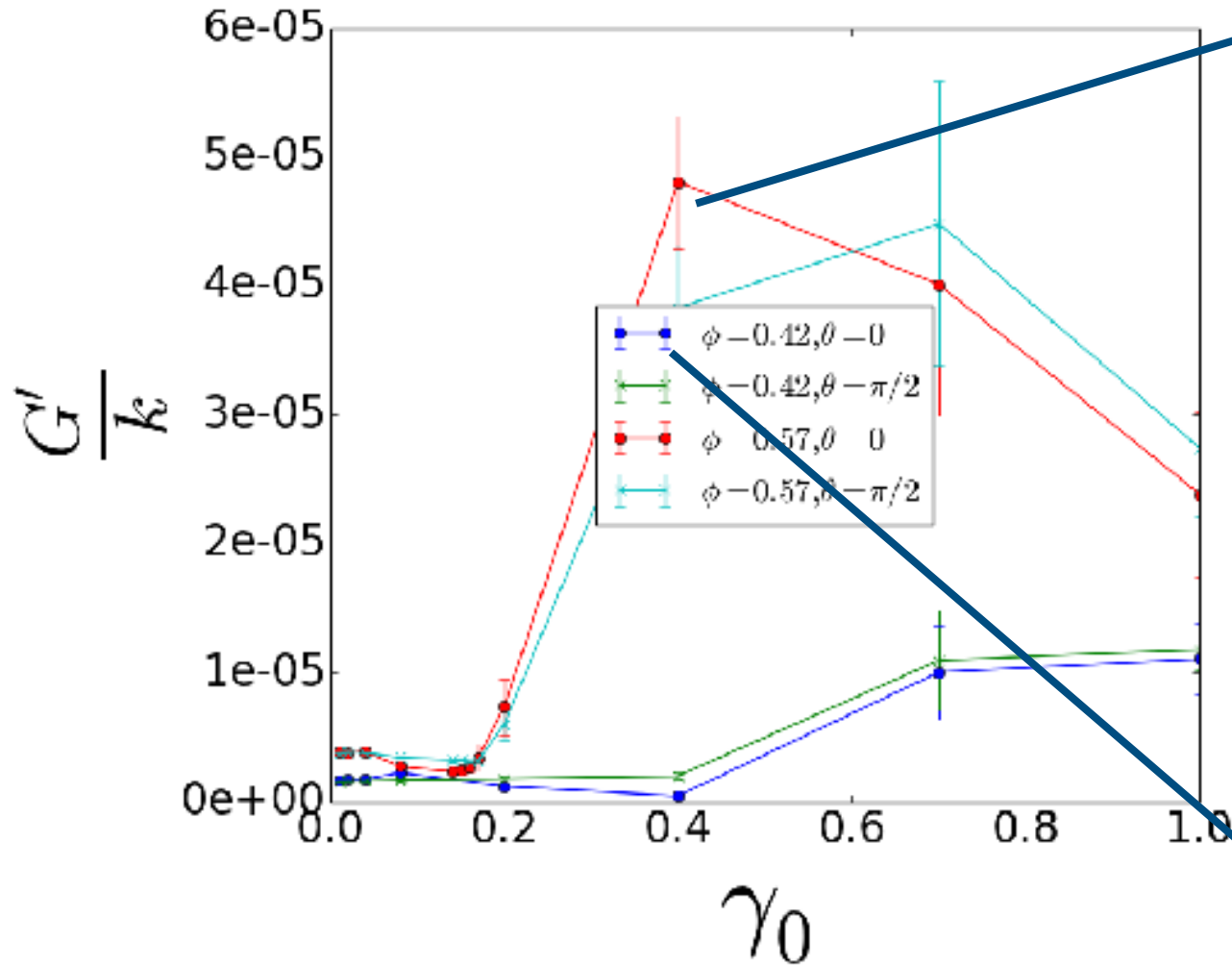
shear jamming in low density was fake! (size dependence)

Contributions to viscosity



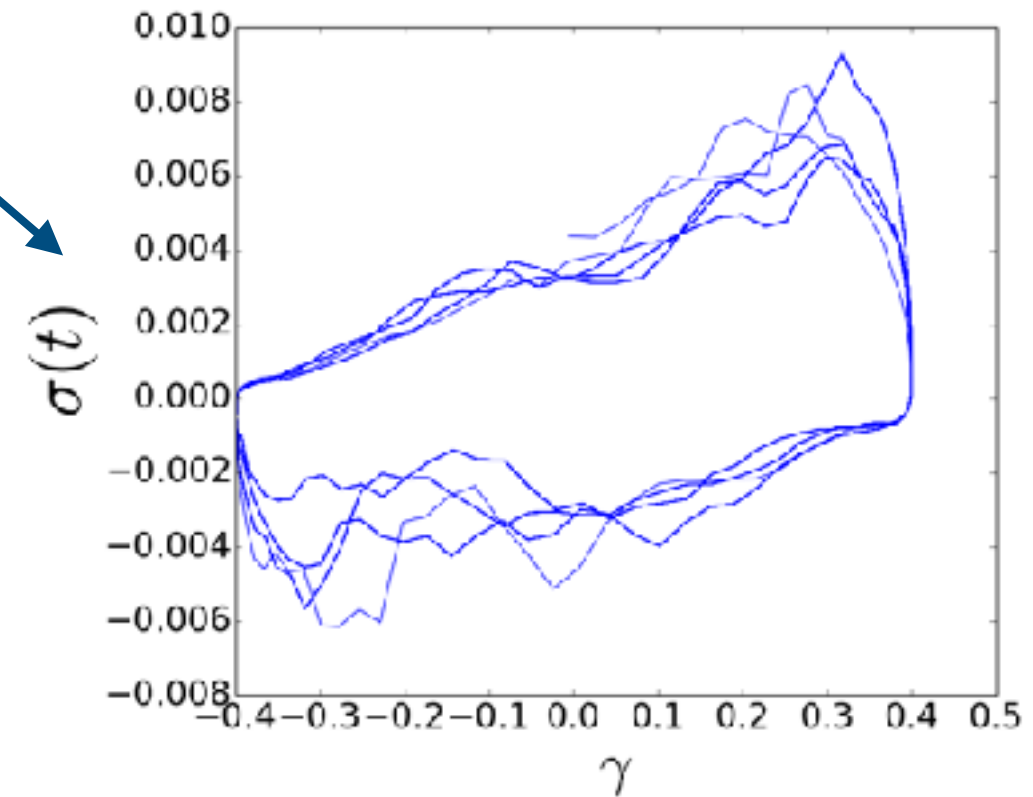
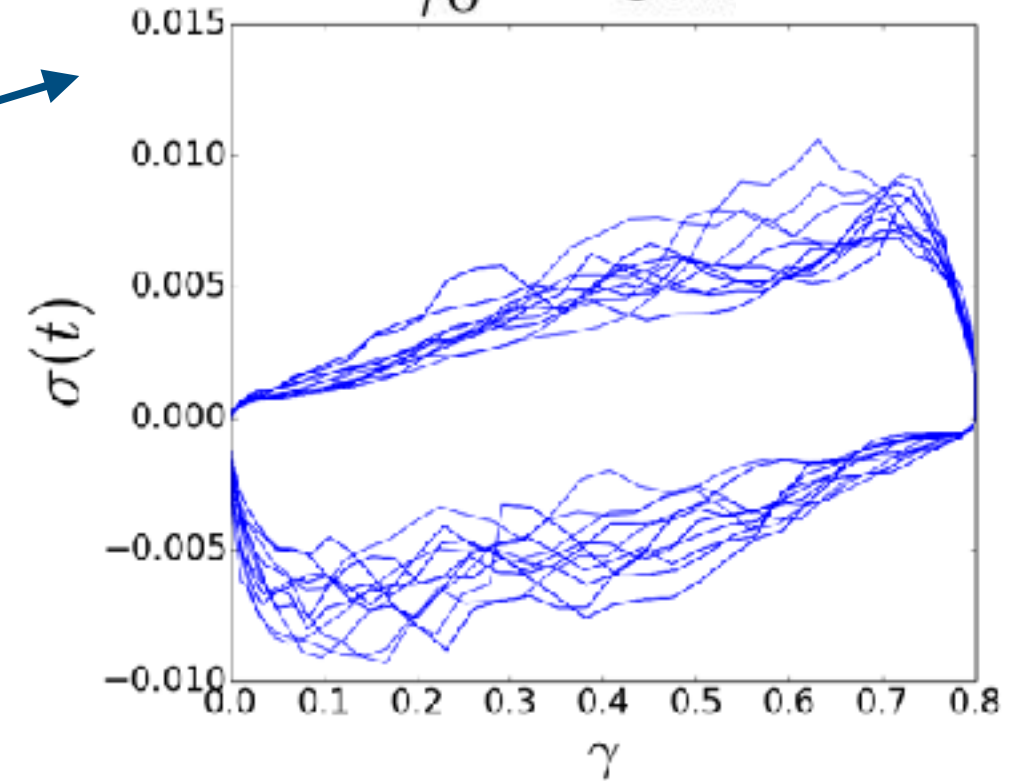
$$\theta = 0$$
$$\phi = 0.57$$

Fragile state?

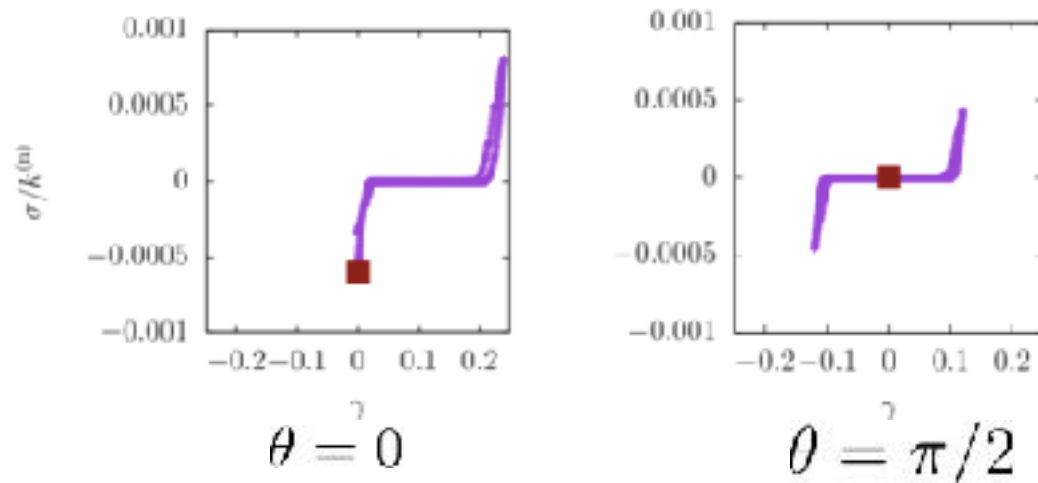


stress-strain curve

$$\gamma_0 = 0.4$$



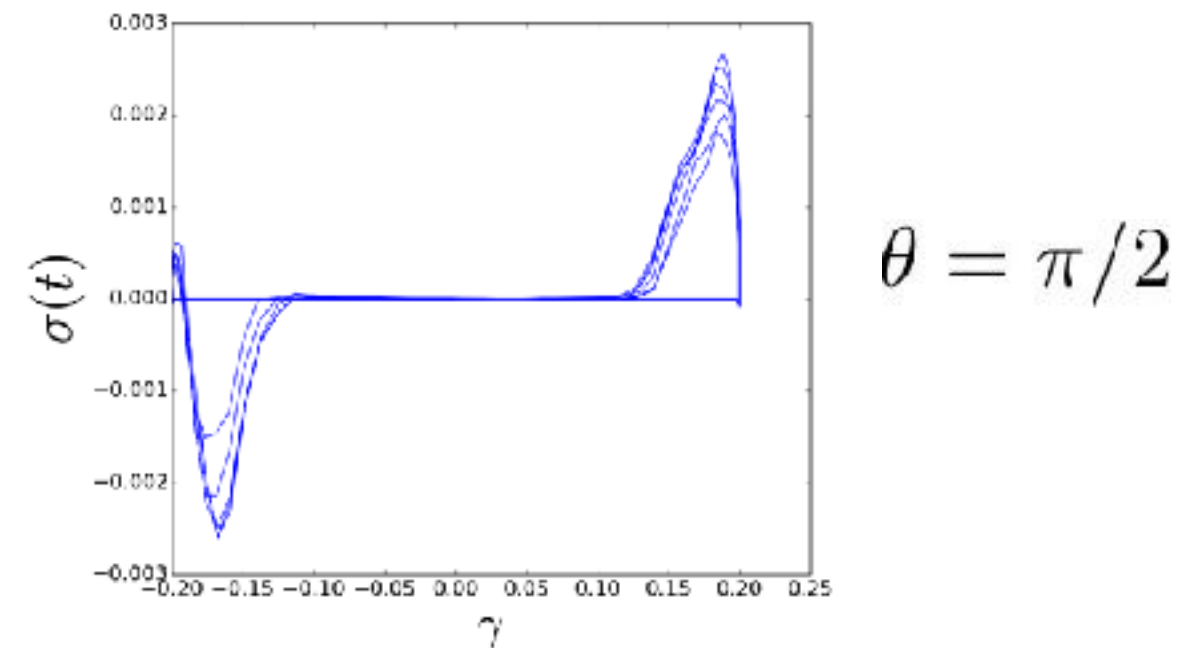
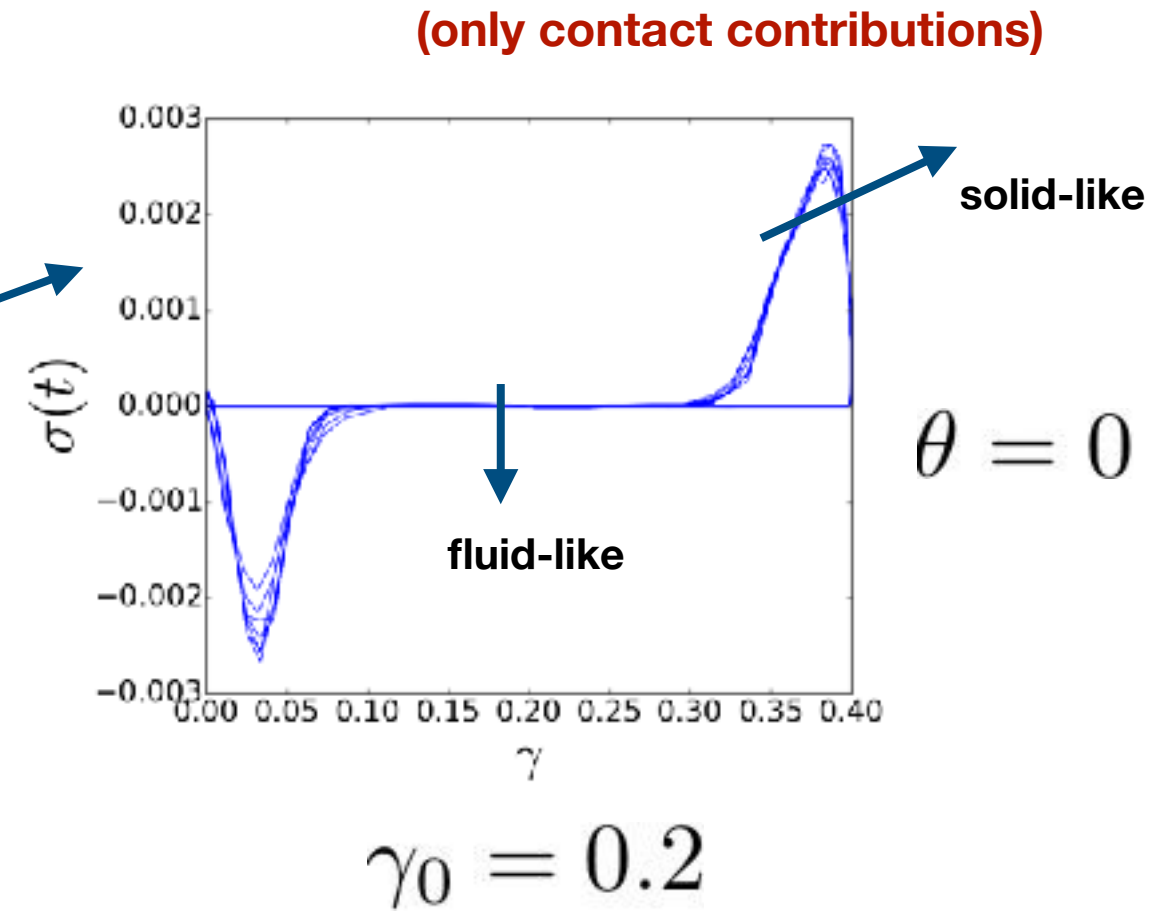
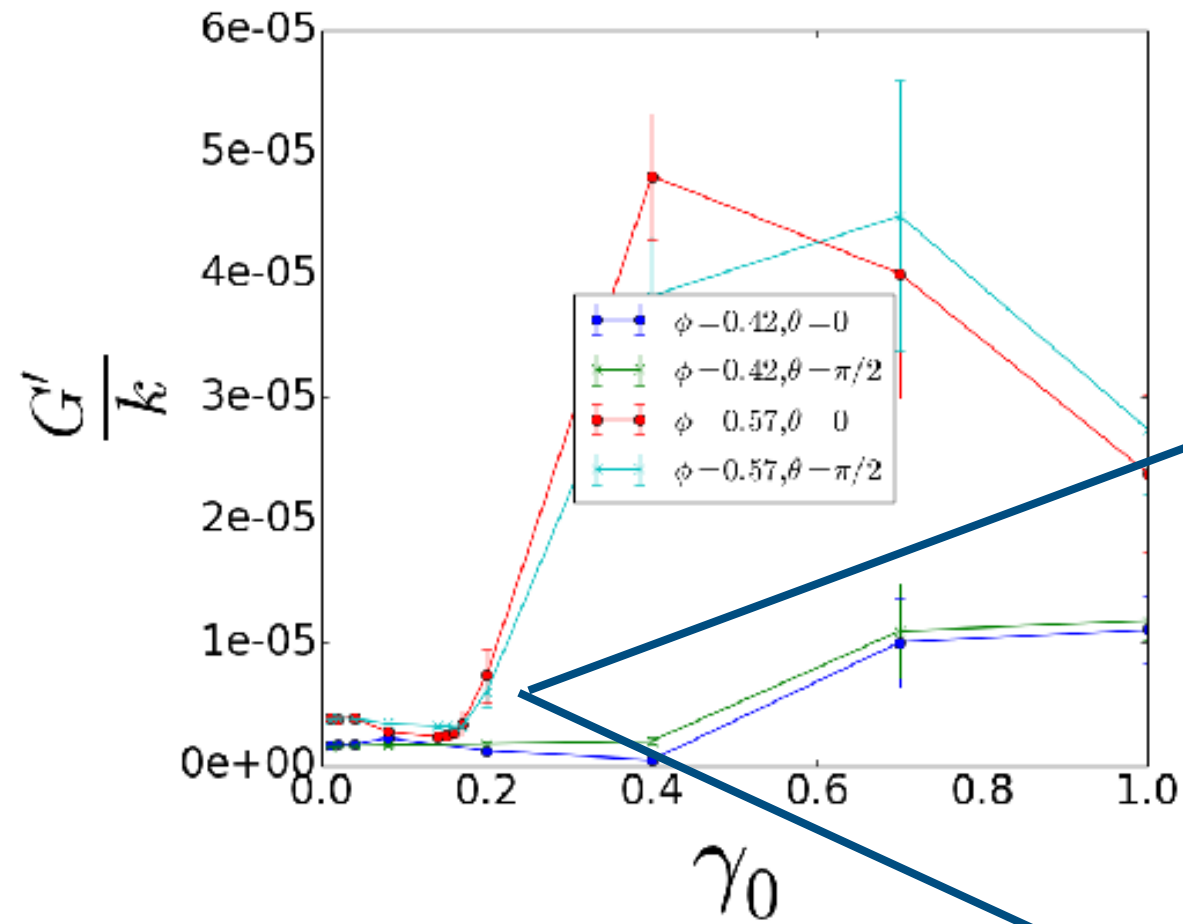
the stress strain curve of the fragile state in Otsuki san's talk



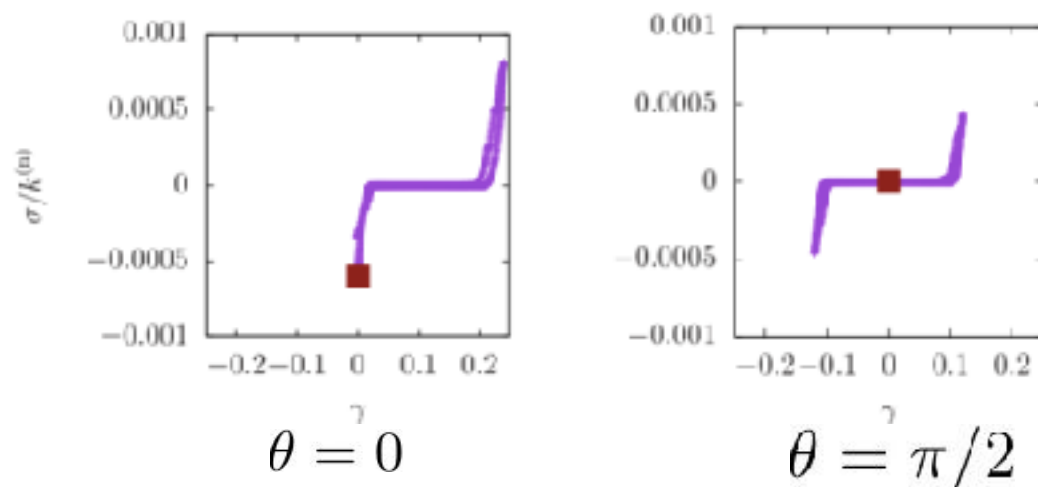
the phase dependence in this simulation might be caused by insufficient simulation time

Fragile state?

stress-strain curve



the stress strain curve of the fragile state in Otsuki san's talk



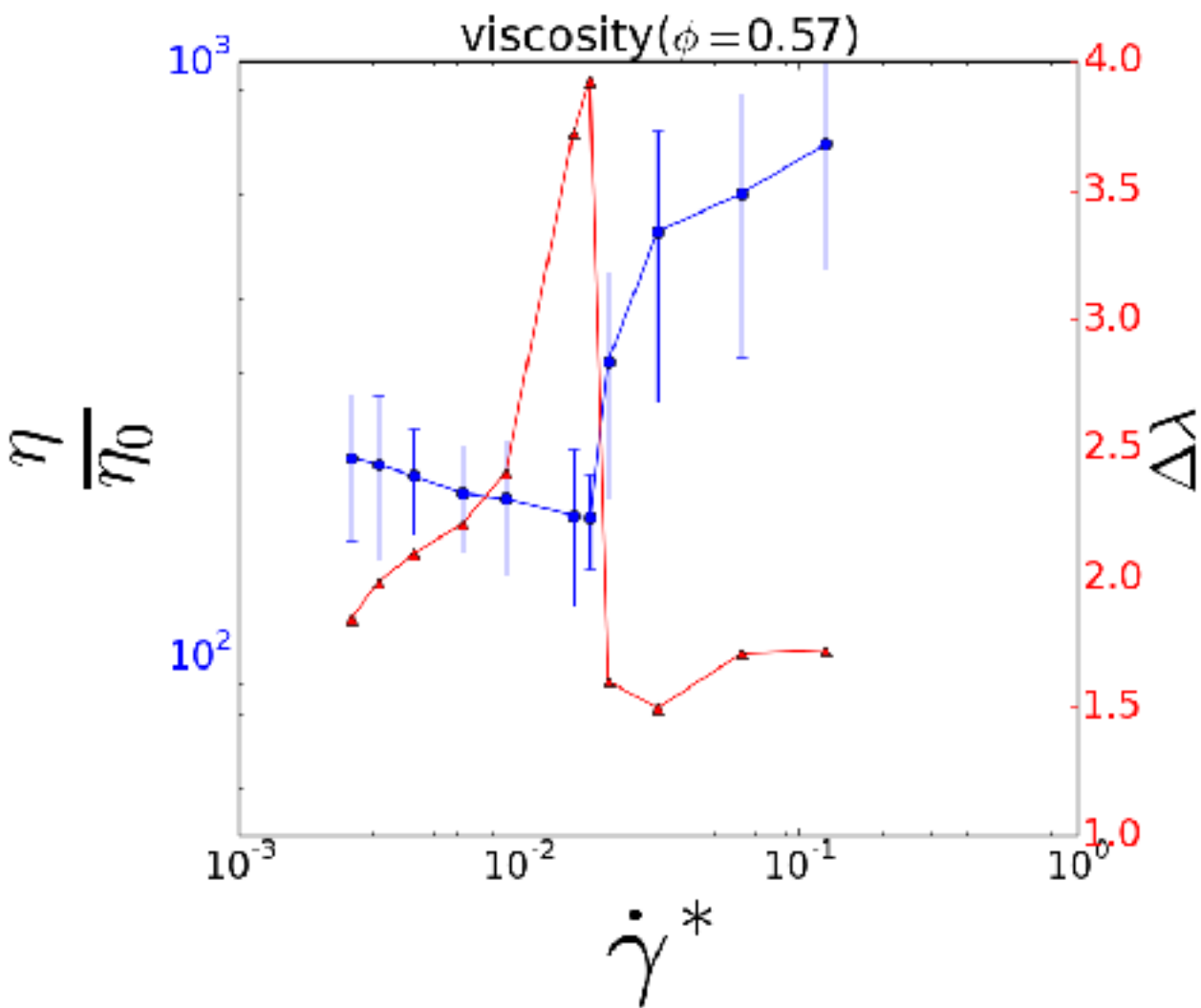
Discussions

$$|\sigma_{ij} - \lambda \delta_{ij}| = 0$$
$$\Delta\lambda = \sigma_1 - \sigma_3$$

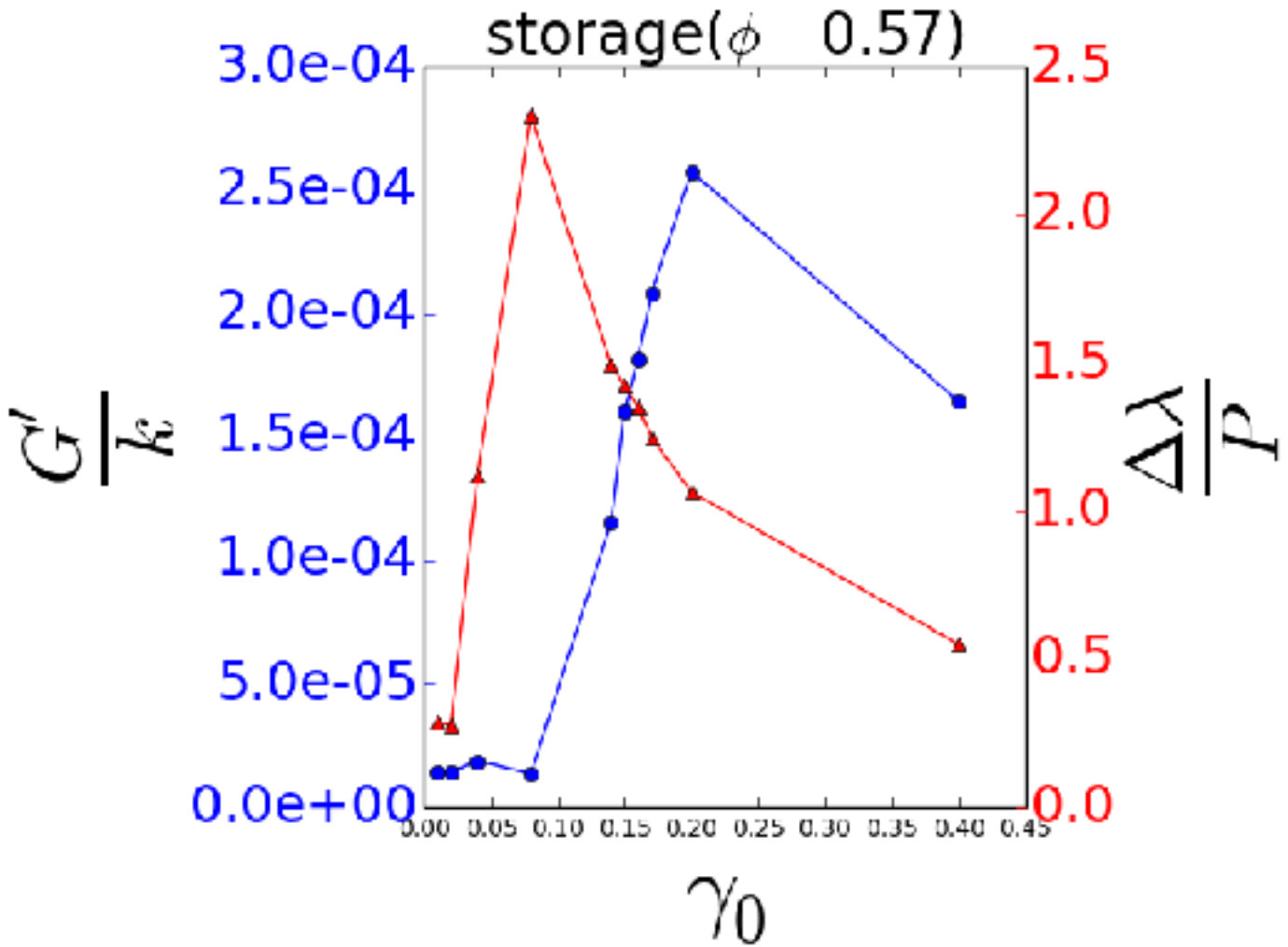
$$\sigma_1 = \max(\lambda_1, \lambda_2, \lambda_3)$$
$$\sigma_3 = \min(\lambda_1, \lambda_2, \lambda_3)$$
$$P = \frac{1}{3}(\sigma_1 + \sigma_2 + \sigma_3)$$

When DST takes place in steady shear, the anisotropy becomes maximum.

Anisotropy is also maximum at the onset of shear jamming.



Steady shear



Oscillatory shear

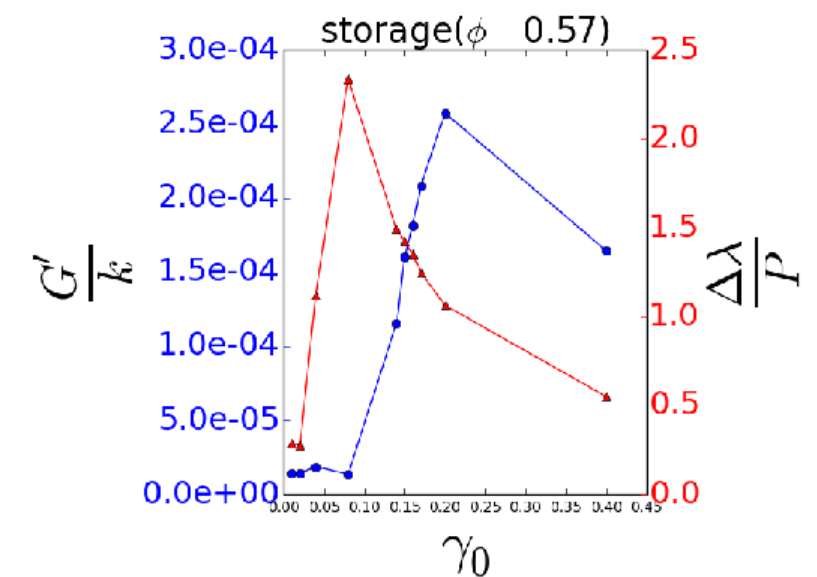
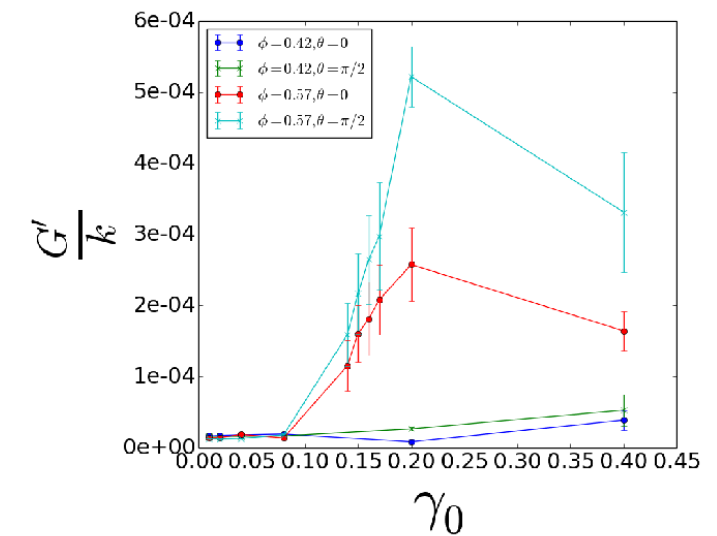
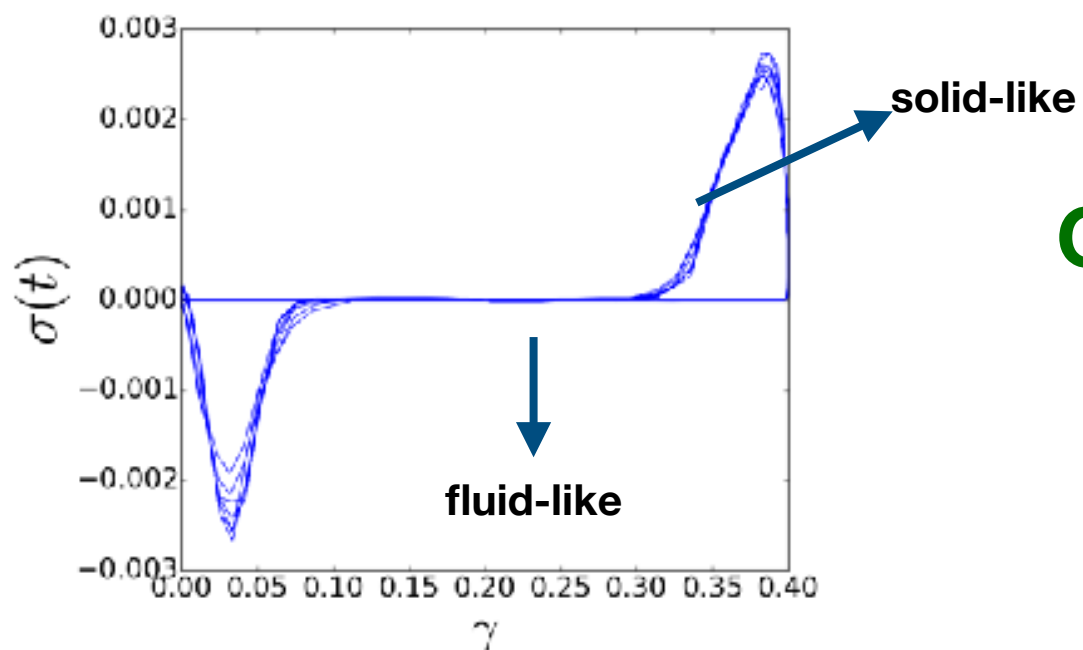
DST \longleftrightarrow Anisotropy

Conclusions

We simulate rheology of dense suspensions by using LBM.

Big increment of the viscosity and shear jamming in high strain rate has been observed.

Discontinuous change of the viscosity and the onset of shear jamming might be related to anisotropy.



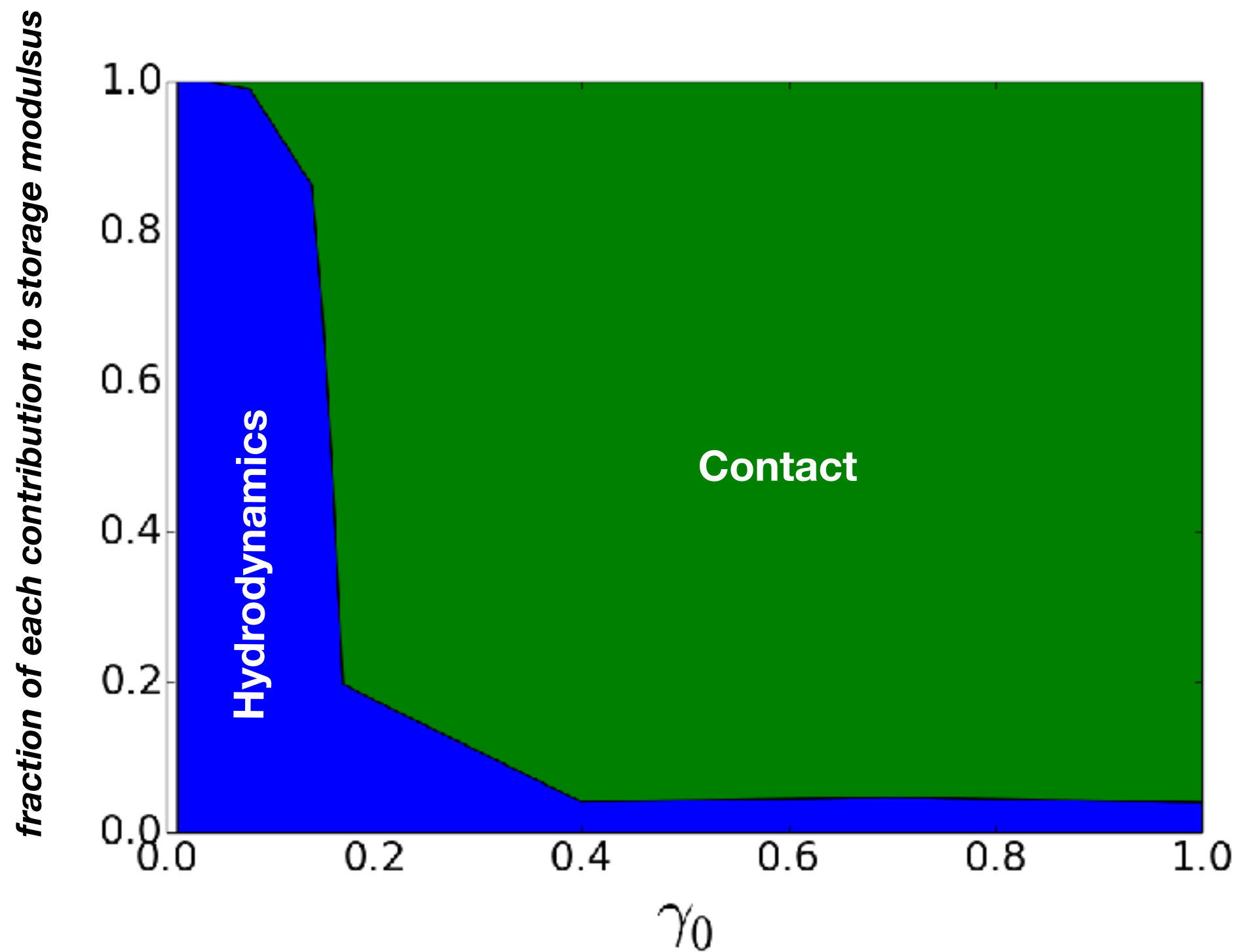
Future works

Clarify the existence of fragile state.

Analyze the percolation network (by simulating more particles in 2D).

appendix:

Contributions to storage modulus



$$\theta = 0$$
$$\phi = 0.57$$

appendix:
details of the lbm
(collision operator)

Discrete equilibrium d.f

$$n_i^{eq} = a^{c_i} \left(\rho + \frac{\mathbf{j} \cdot \mathbf{c}_i}{c_s^2} + \frac{(\rho \mathbf{u} \mathbf{u}) : (\mathbf{c}_i \mathbf{c}_i - c_s^2 \mathbf{1})}{2c_s^4} \right)$$

Post collision d.f

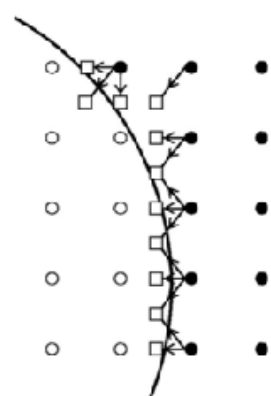
$$n_i^* = a^{c_i} \left(\rho + \frac{\mathbf{j} \cdot \mathbf{c}_i}{c_s^2} + \frac{(\rho \mathbf{u} \mathbf{u} + \mathbf{\Pi}^{neq,*}) : (\mathbf{c}_i \mathbf{c}_i - c_s^2 \mathbf{1})}{2c_s^4} \right)$$

$$\mathbf{\Pi}^{neq,*} = (1 + \lambda) \bar{\mathbf{\Pi}}^{neq} + \frac{1}{3} (1 + \lambda_\nu) (\mathbf{\Pi}^{neq} : \mathbf{1}) \mathbf{1}$$

Related to solvent viscosity

$$\eta = -\rho c_s^2 \Delta t \left(\frac{1}{\lambda} + \frac{1}{2} \right) \quad \eta_\nu = -\rho c_s^2 \Delta t \left(\frac{2}{3\lambda_\nu} + \frac{1}{3} \right)$$

appendix:
Stress Calculation
Hydrodynamics



$$f(\mathbf{r}_b, t + \frac{1}{2}\Delta t) = \frac{\Delta x^3}{\Delta t} \left[2n_b^*(\mathbf{r}, t) - \frac{2a^{c_b} \rho_0 \mathbf{u}_b \cdot \mathbf{c}_b}{c_s^2} \right] \mathbf{c}_b$$

$$\sigma^h = \sum_b \mathbf{r}_b \mathbf{f}(\mathbf{r}_b)$$

or

$$\begin{pmatrix} \mathbf{F}_1 \\ \mathbf{T}_1 \\ \mathbf{T}_2 \\ \mathbf{S}_1 \\ \mathbf{S}_2 \end{pmatrix} = - \begin{pmatrix} \mathbf{A}_{11} & -\mathbf{B}_{11} & \mathbf{B}_{22} \\ \mathbf{B}_{11} & \mathbf{C}_{11} & \mathbf{C}_{12} \\ -\mathbf{B}_{22} & \mathbf{C}_{12} & \mathbf{C}_{22} \\ \mathbf{G}_{11} & \mathbf{H}_{11} & \mathbf{H}_{12} \\ \mathbf{G}_{22} & -\mathbf{H}_{21} & \mathbf{H}_{22} \end{pmatrix} \begin{pmatrix} \mathbf{U}_{12} \\ \Omega_1 \\ \Omega_2 \end{pmatrix}$$

**lubrication grand resistance
formulation**

Contact

$$\sigma^c = \sigma^{\text{nor}} + \sigma^{\text{tan}}$$

$$\sigma^{\text{nor}} = -\frac{1}{2V} \sum_i \sum_{j \neq i} (\mathbf{r}_{ij,\alpha} \mathbf{F}_{ij,\beta}^{\text{nor}} + \mathbf{r}_{ij,\beta} \mathbf{F}_{ij,\alpha}^{\text{nor}})$$

$$\sigma^{\text{tan}} = -\frac{1}{V} \sum_i \sum_{j \neq i} \mathbf{r}_{ij,\alpha} \mathbf{F}_{ij,\beta}^{\text{tan}}$$

Electrostatic repulsive

$$\sigma^r = -\frac{1}{V} \sum_i \sum_{j \neq i} \mathbf{R}_{ij,\alpha} \mathbf{F}_{ij,\beta}^R$$