

# Flowing to the Bounce

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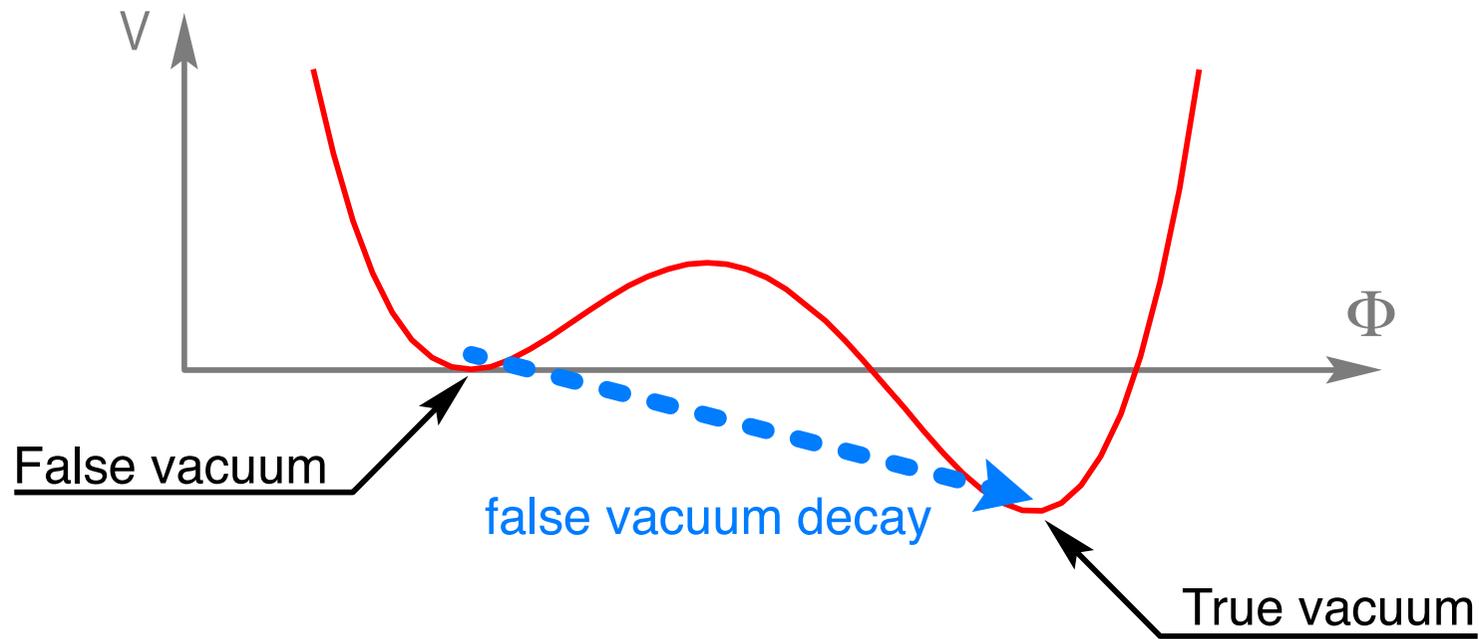
Refs:

Chigusa, TM, Shoji, 1906.10829 [hep-ph]

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# 1. Introduction

The subject today: a new method to calculate the bounce



- False vacua show up in many particle-physics models
- Tunneling process is dominantly induced by the field configuration called “bounce”

Today, I try to explain

- Why is the calculation of the bounce difficult?
- What is our new idea?
- Why does it work?
- Does it really work?

## Outline

1. Introduction
2. Bounce
3. Calculating Bounce with Flow Equation
4. Numerical Analysis
5. Summary

## 2. Bounce

## Calculation of the decay rate *à la* Coleman

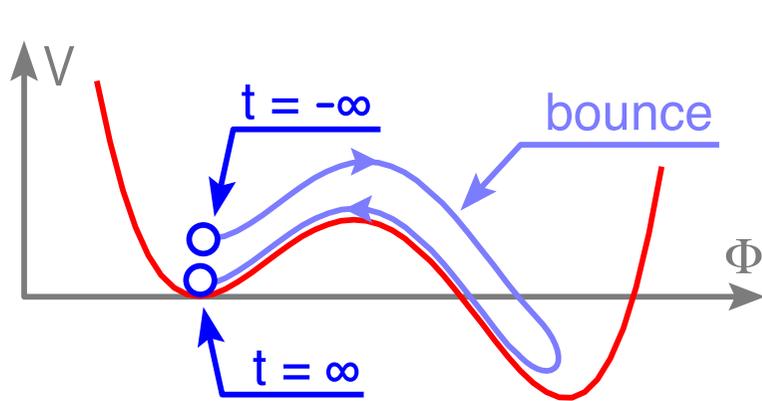
- The decay rate is related to Euclidean partition function

$$Z = \langle \mathbf{FV} | e^{-HT} | \mathbf{FV} \rangle \simeq \int \mathcal{D}\phi e^{-\mathcal{S}[\phi]} \propto \exp(i\gamma VT)$$

- Euclidean action

$$\mathcal{S}[\phi] = \int d^D x \left( \frac{1}{2} \partial_\mu \phi \partial_\mu \phi + V \right)$$

- The false vacuum decay is dominated by the classical path



$$Z = \text{---} + \text{---} \circ \text{---} + \text{---} \circ \circ \text{---} + \dots$$

= --- exp [  $\circ$  ]

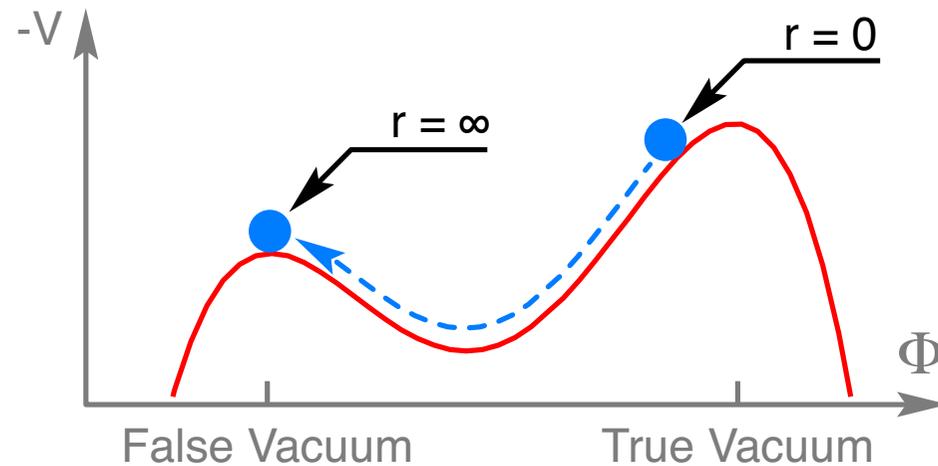
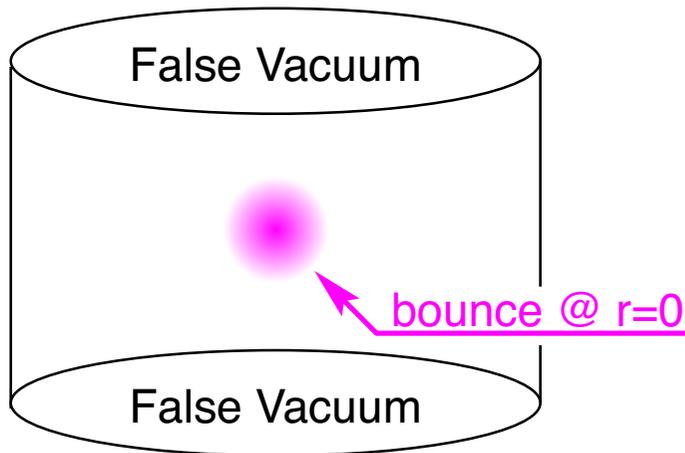
one-bounce

# The bounce: spherical solution of Euclidean EoM

[Coleman; Callan & Coleman]

$$\left[ \partial^2 \phi - \frac{\partial V}{\partial \phi} \right]_{\phi \rightarrow \bar{\phi}} = \left[ \partial_r^2 \phi + \frac{D-1}{r} \partial_r \phi - \frac{\partial V}{\partial \phi} \right]_{\phi \rightarrow \bar{\phi}} = 0$$

with  $\begin{cases} \bar{\phi}(r = \infty) = v : \text{false vacuum} \\ \bar{\phi}'(0) = 0 \end{cases}$



Bounce is important for the study of false vacuum decay

$$\gamma = \mathcal{A}e^{-\mathcal{S}[\bar{\phi}]}$$

Why is the calculation of  $\bar{\phi}$  so difficult?

Bounce is a saddle-point solution of the EoM

Expansion of the action around the bounce:  $\phi = \bar{\phi} + \Psi$

- $\mathcal{S}[\bar{\phi} + \Psi] = \mathcal{S}[\bar{\phi}] + \frac{1}{2} \int d^D x \Psi \mathcal{M} \Psi + O(\Psi^3)$

$$\mathcal{M} \equiv -\partial_r^2 - \frac{D-1}{r} \partial_r + \left. \frac{\partial^2 V}{\partial \phi^2} \right|_{\phi \rightarrow \bar{\phi}} \quad : \text{fluctuation operator}$$

- $\mathcal{M}$  has one negative eigenvalue (which we call  $\lambda_-$ )

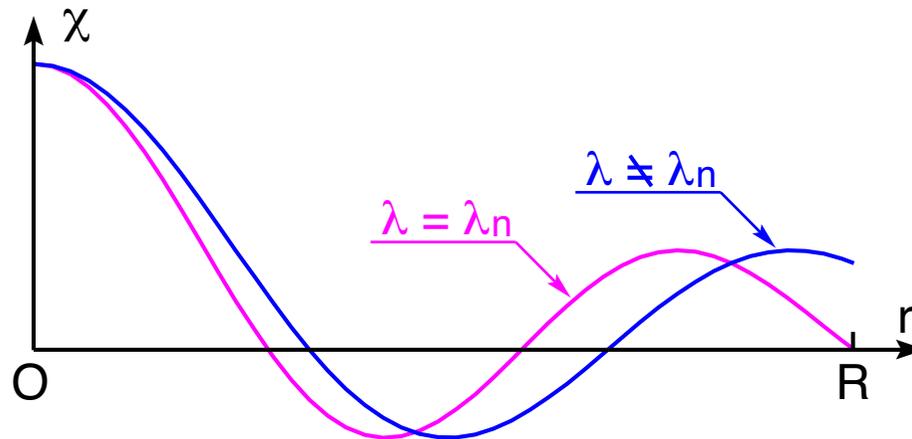
[Callan & Coleman]

Fluctuation around the bounce:  $\phi = \bar{\phi} + \Psi$

- $\partial_r \Psi(r = 0) = 0$
- $\Psi(r = \infty) = 0$

We expand  $\Psi$  by using eigenfunctions of  $\mathcal{M}$

$$\Rightarrow \mathcal{M}\chi = \lambda\chi$$



We need to impose relevant boundary conditions

- $\partial_r \chi_n(r = 0) = 0$
- $\chi_n(r = \infty) = 0$

## An evidence of the existence of negative eigenvalue

- Functions are expanded by  $\chi_n$  (eigenfunctions of  $\mathcal{M}$ )

$$\langle \chi_n | \chi_m \rangle = \delta_{nm}, \text{ where } \langle f | f' \rangle \equiv \int_0^\infty dr r^{D-1} f(r) f'(r)$$

- $f(r) = \sum_n \langle f | \chi_n \rangle \chi_n(r)$

- $\langle f | \mathcal{M} f \rangle = \sum_n \lambda_n \langle \chi_n | f \rangle^2$

Example:  $f(r) = r \partial_r \bar{\phi}$

- $\langle (r \partial_r \bar{\phi}) | \mathcal{M} (r \partial_r \bar{\phi}) \rangle = -(D - 2) \int_0^\infty dr r^{D-1} (\partial_r \bar{\phi})(\partial_r \bar{\phi}) < 0$

- $r \partial_r \bar{\phi}$ : fluctuation w.r.t. the “scale transformation”

$$\bar{\phi}((1 + \epsilon)r) \simeq \bar{\phi}(r) + \epsilon r \partial_r \bar{\phi} + \dots$$

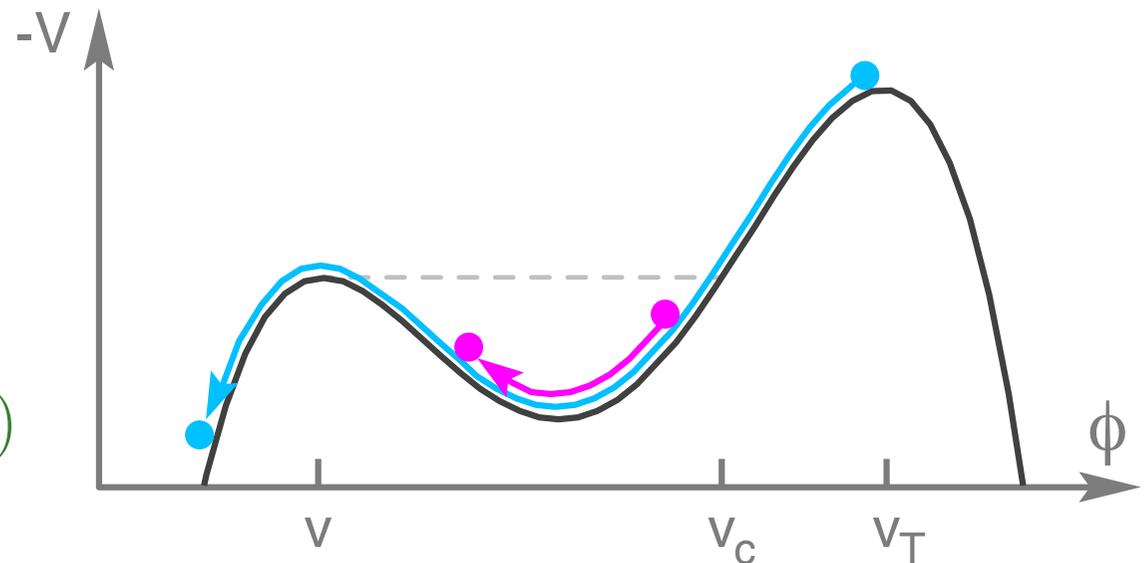
Undershoot-overshoot method to calculate the bounce

$$\partial_r^2 \phi + \frac{D-1}{r} \partial_r \phi - \frac{\partial V}{\partial \phi} = 0$$

2nd term is a “friction,” which disappears as  $r \rightarrow \infty$

There should exist bounce, satisfying  $\bar{\phi}'(0) = 0$  and  $\bar{\phi}(\infty) = v$

- If  $\phi(0) \lesssim v_c$   
 $\Rightarrow$  Undershoot
- If  $\phi(0) \simeq v_T$   
 $\Rightarrow$  Overshoot
- There exists right  $\phi(0)$   
 $\Rightarrow \phi(\infty) = v$



It is not easy to obtain bounce in general

⇒ In particular, more difficulties with multi-fields

There has been various methods and attempts

- Undershoot-overshoot method

- Dilatation maximization

[Claudson, Hall, Hinchliffe ('83)]

- Improved action

[Kusenko ('95); Kusenko, Langacker, Segre ('96); Dasgupta ('96)]

- Squared EoM

[Moreno, M. Quiros, M. Seco ('98); John ('98)]

- Backstep

[Cline, Espinosa, Moore, Riotto ('98); Cline, Moore, Servant ('99)]

- Improved potential  
[Konstandin, Huber ('06); Park ('10)]
- Path deformation  
[Wainwright ('11)]
- Perturbative method  
[Akula, Balazs, White ('16); Athron et al. ('19)]
- Multiple shooting  
[Masoumi, Olum, Shlaer ('16)]
- Tunneling potential  
[Espinosa ('18); Espinosa, Konstandin ('18)]
- Polygon approximation  
[Guada, Maiezza, Nemevsek ('18)]
- Machine learning  
[Jinno ('18); Piscopo, Spannowsky, Waite ('19)]

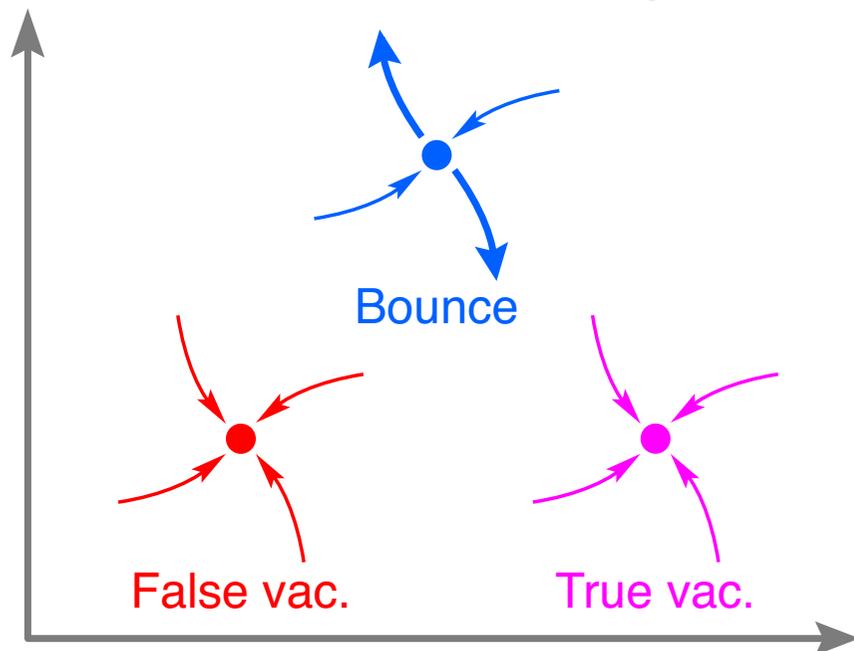
### 3. Bounce from Flow Equation

We want a flow eq. which has bounce as a stable fixed point

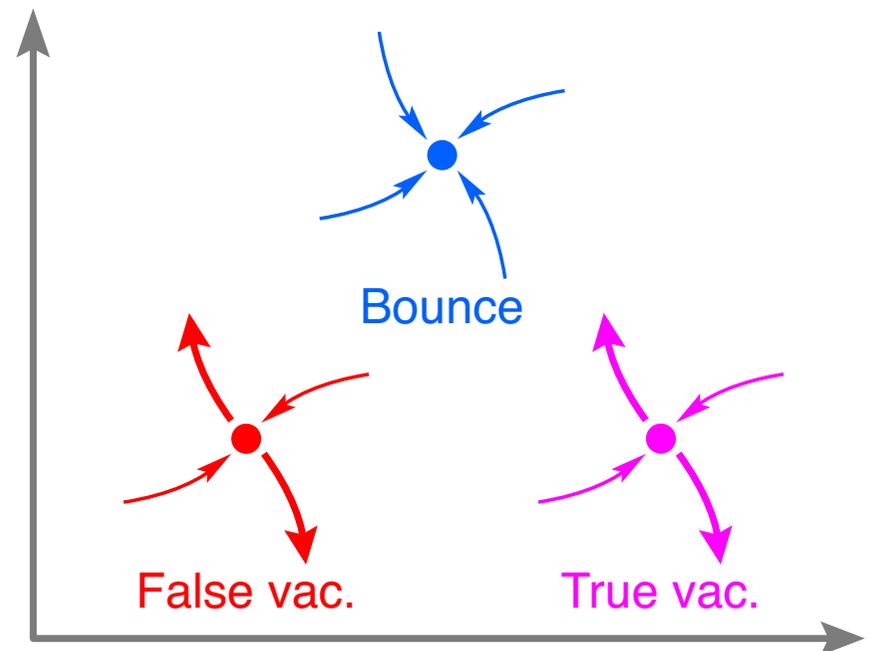
- $\partial_s \Phi(r, s) = \mathcal{G}[\Phi]$
- $\Phi(r, s \rightarrow \infty) = \bar{\phi}(r)$

Schematic view of the flow on the configuration space

Flow based on the height of S



Flow we want



Flow based on the height of  $\mathcal{S}$

$$\partial_s \Phi(r, s) = F(r, s)$$

$$F \equiv -\frac{\delta \mathcal{S}[\Phi]}{\delta \Phi} = \partial_r^2 \Phi + \frac{D-1}{r} \partial_r \Phi - \frac{\partial V(\Phi)}{\partial \Phi}$$

Behavior of fluctuations around the bounce

$$\Phi(r, s) = \bar{\phi}(r) + \sum_n a_n(s) \chi_n(r)$$

$$\Rightarrow \sum_n \dot{a}_n \chi_n \simeq -\mathcal{M} \sum_n a_n \chi_n = -\sum_n \lambda_n a_n \chi_n$$

$$\Rightarrow \dot{a}_n \simeq -\lambda_n a_n$$

Because of  $\chi_-$ , bounce cannot be a stable fixed point

$\Rightarrow$  This does not work

Flow equation of our proposal, which has a parameter  $\beta$

$$\partial_s \Phi(r, s) = F(r, s) - \beta \langle F|g \rangle g(r)$$

$g(r)$ : some function with  $\langle g|g \rangle = 1$

$$g(r) \equiv \sum_n c_n \chi_n(r)$$

We will see:

With relevant choices of  $g(r)$  and  $\beta$ , the bounce becomes a stable fixed point of our flow equation

For  $\beta \neq 1$ :

$$\partial_s \Phi = 0 \Rightarrow F = 0 \text{ (solution of EoM)}$$

$\Leftrightarrow$  Fixed points do not depend on  $\beta$

Behavior of the fluctuation:  $\Phi(r, s) = \bar{\phi}(r) + \sum_n a_n(s) \chi_n(r)$

$$F(r, s) \simeq -\mathcal{M}(\Phi - \bar{\phi}) = -\sum_m \lambda_m a_m \chi_m$$

$$\langle F | g \rangle \simeq -\sum_m \lambda_m c_m a_m$$

$$\dot{a}_n \simeq -\lambda_n a_n + \beta \sum_m c_n c_m \lambda_m a_m \equiv -\sum_m \Gamma_{nm}(\beta) a_m$$

In the matrix form:

$$\dot{\vec{a}} \simeq -\Gamma(\beta) \vec{a}$$

$$\Gamma(\beta) = (\mathbf{I} - \beta \vec{c} \vec{c}^T) \text{diag}(\lambda_-, \lambda_1, \lambda_2, \dots)$$

Eigenvalues of  $\Gamma$ :  $\gamma_n$  (which are complex in general)

$$\Rightarrow \vec{a} \sim \sum_n \vec{v}_n e^{-\gamma_n s}$$

If  $\operatorname{Re} \gamma_n > 0$  for  $\forall n$ , then  $\vec{a}(s \rightarrow \infty) = 0$

We first study  $\det \Gamma(\beta) = \prod_n \gamma_n$

Notice:  $\det(\mathbf{I} - \beta \vec{c} \vec{c}^T) = 1 - \beta$

$$(\mathbf{I} - \beta \vec{c} \vec{c}^T) \vec{c} = (1 - \beta) \vec{c}$$

$$(\mathbf{I} - \beta \vec{c} \vec{c}^T) \vec{v}_\perp = \vec{v}_\perp, \text{ if } \vec{c}^T \vec{v}_\perp = 0$$

$$\det \Gamma(\beta) = (1 - \beta) \prod_n \lambda_n$$

$\Rightarrow \det \Gamma(\beta) > 0$ , if  $\beta > 1$

$\Rightarrow$  Taking  $\beta > 1$ , real parts of all the eigenvalues of  $\Gamma$  may become positive

Existence proof of  $g(r)$  which realizes  $\text{Re } \gamma_n > 0$  for  $\forall n$

$$g(r) = \chi_-, \text{ i.e., } \vec{c} = (1, 0, 0, \dots)^T$$

$$\Rightarrow \Gamma(\beta) = \text{diag}(1 - \beta, 1, 1, \dots) \text{diag}(\lambda_-, \lambda_1, \lambda_2, \dots)$$

A guideline to choose  $g(r)$

$\Rightarrow$  We should take  $g(r)$  with sizable  $c_-$

$$g(r) \equiv \sum_n c_n \chi_n(r) \text{ with } \sum_n c_n^2 = 1$$

Our choice:  $g(r) \propto r \partial_r \Phi(r, s)$

- $\langle (r \partial_r \bar{\phi}) | \mathcal{M} (r \partial_r \bar{\phi}) \rangle = -(D - 2) \int_0^\infty dr r^{D-1} (\partial_r \bar{\phi})(\partial_r \bar{\phi})$
- Empirically, it works well (see the numerical results)

If  $\Phi(s \rightarrow \infty, r)$  goes to a stable fixed point with  $\beta > 1$

1.  $\Phi(s \rightarrow \infty, r)$  is a solution of EoM

2.  $\Phi(s \rightarrow \infty, r)$  satisfies the BCs relevant for the bounce

3.  $\Phi(s \rightarrow \infty, r)$  cannot be the false or true vacuum

$\Leftrightarrow$  Real parts of the eigenvalues of  $\Gamma(\beta > 1)$  are all positive because  $\Phi(s \rightarrow \infty, r)$  is stable against fluctuations

$\Leftrightarrow \det\Gamma(\beta = 0) < 0$ , so the fluctuation operator around  $\Phi(s \rightarrow \infty, r)$  has a negative eigenvalue

$\Leftrightarrow$  For the fluctuation operator around the false or true vacuum,  $\det\Gamma(\beta = 0) > 0$

$\Rightarrow$  Thus,  $\Phi(s \rightarrow \infty, r)$  is a bounce

## 4. Numerical Analysis

We considered single- and double scalar cases:

- Single-scalar case:

$$V^{(1)} = \frac{1}{4}\phi^4 - \frac{k_1 + 1}{3}\phi^3 + \frac{k_1}{2}\phi^2$$

– False vacuum:  $\phi = 0$

– True vacuum:  $\phi = 1$

- Double-scalar case:

$$V^{(2)} = (\phi_x^2 + 5\phi_y^2) [5(\phi_x - 1)^2 + (\phi_y - 1)^2] + k_2 \left( \frac{1}{4}\phi_y^4 - \frac{1}{3}\phi_y^3 \right)$$

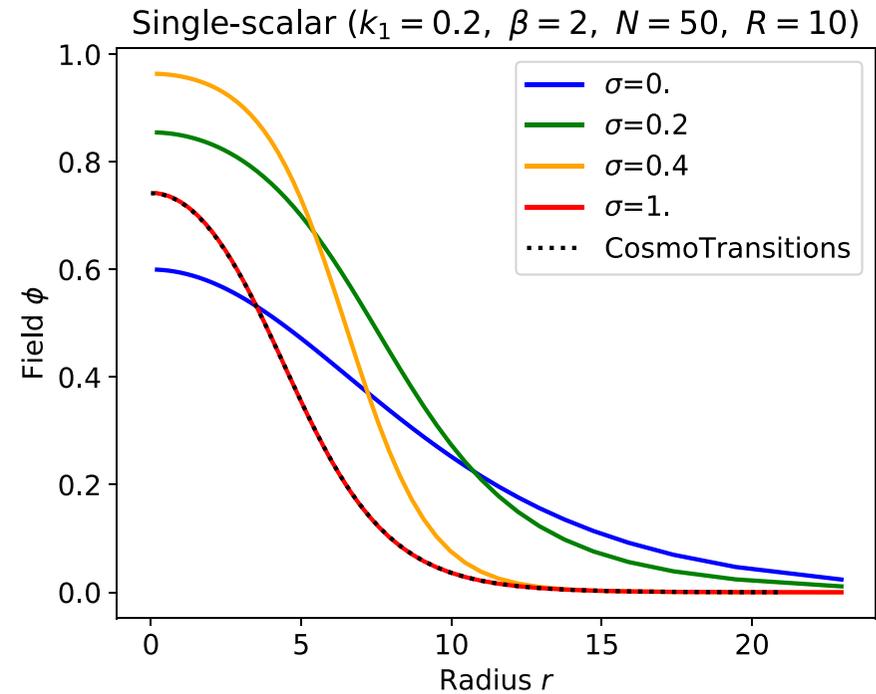
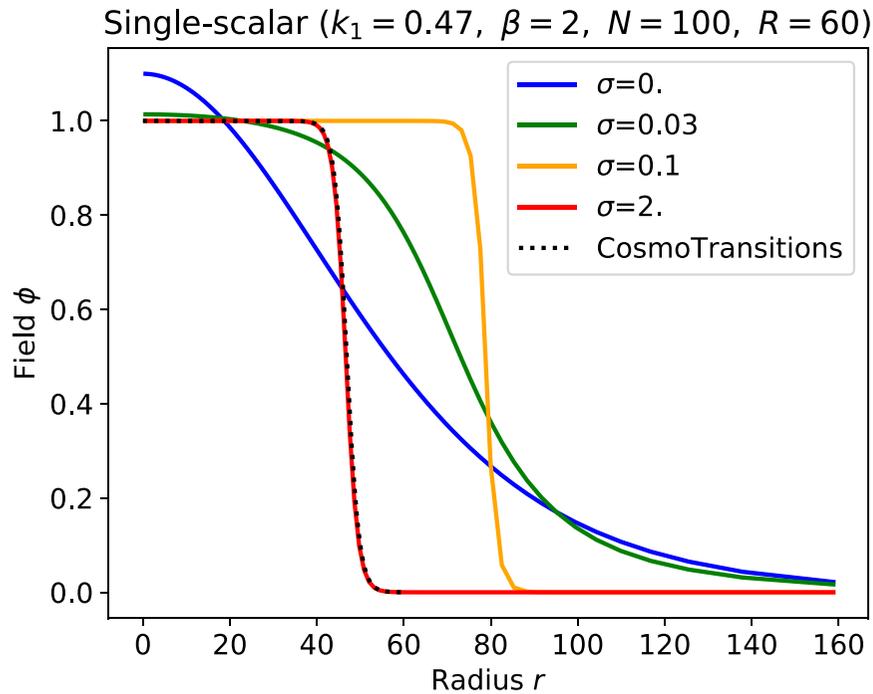
– False vacuum:  $(\phi_x, \phi_y) = (0, 0)$

– True vacuum:  $(\phi_x, \phi_y) = (1, 1)$

- We compare our results with those of CosmoTransitions  
[Wainwright]

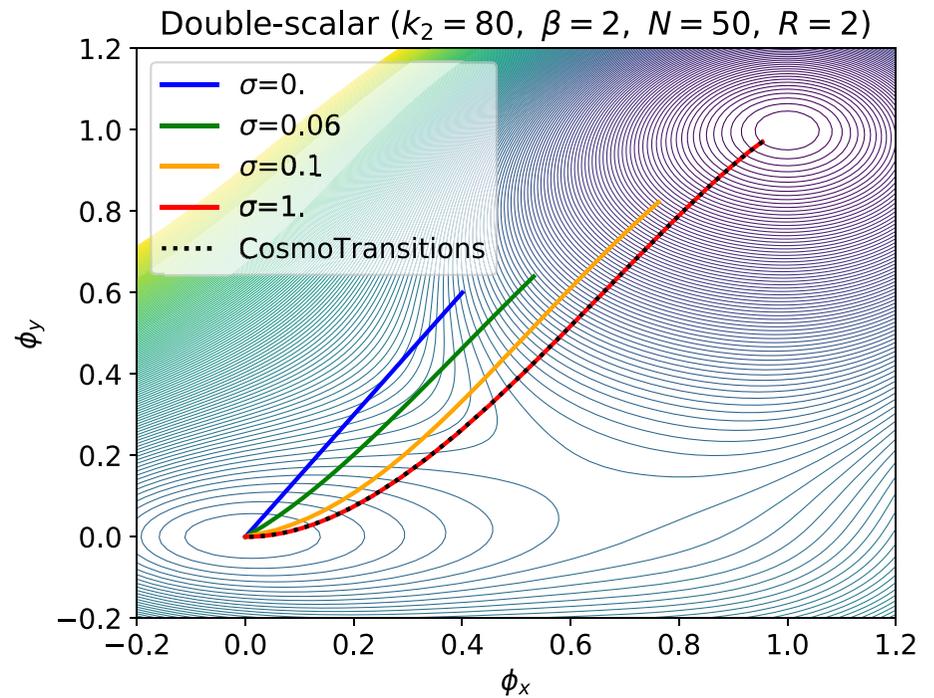
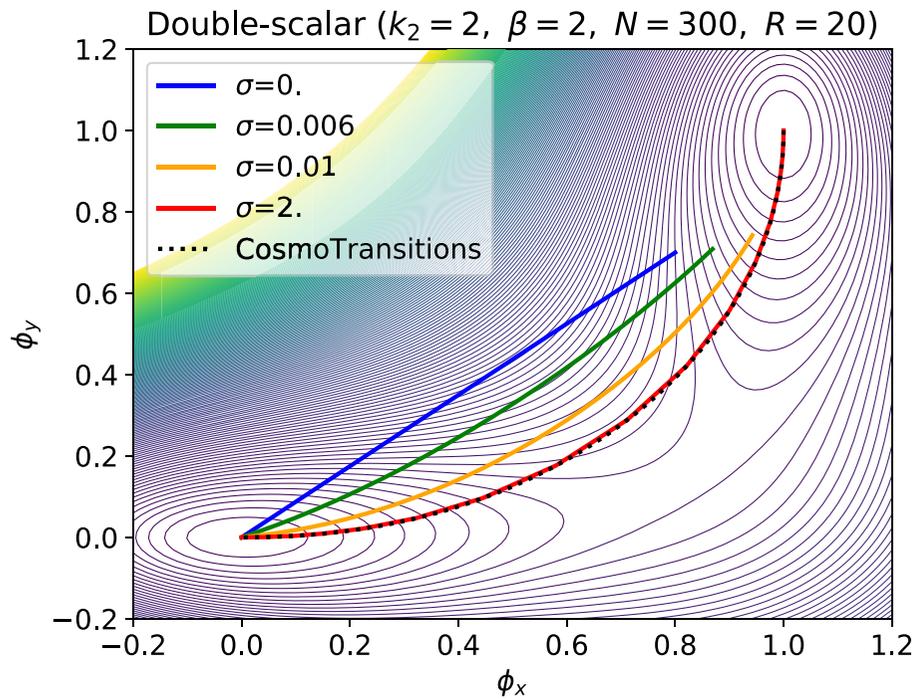
## Single-scalar case (with $D = 3$ )

- Left: thin-wall (model 1a)
- Right: thick-wall (model 1b)



## Double-scalar case (with $D = 3$ )

- Left: thin-wall (model 2a)
- Right: thick-wall (model 2b)



## Bounce action $\mathcal{S}[\bar{\phi}]$

Model	Our Result	CosmoTransitions
1a	1092.5	1092.8
1b	6.6298	6.6490
2a	1769.1	1767.7
2b	4.4567	4.4661

- Our results well agree with those of CosmoTransitions
- Bounce configuration (and its action) can be precisely calculated by using flow equation
- Compared to CosmoTransitions, our method gives better accuracy for the behavior of  $\bar{\phi}(r \rightarrow \infty)$

## Another approach

[Coleman, Glaser, Martin ('78); Sato ('19)]

1. Determine the configuration  $\bar{\varphi}(r; \mathcal{P})$  which minimizes  $\mathcal{S}$  on the hypersurface with constant  $\mathcal{P}$

$$\mathcal{P} \equiv \int d^D x V$$

Flow equation:

$$\partial_s \Phi(r, s) = F - \xi[\Phi] \frac{\partial V}{\partial \Phi}$$

At the fixed point:  $\bar{\varphi}(r; \mathcal{P}) = \Phi(r, s \rightarrow \infty)$

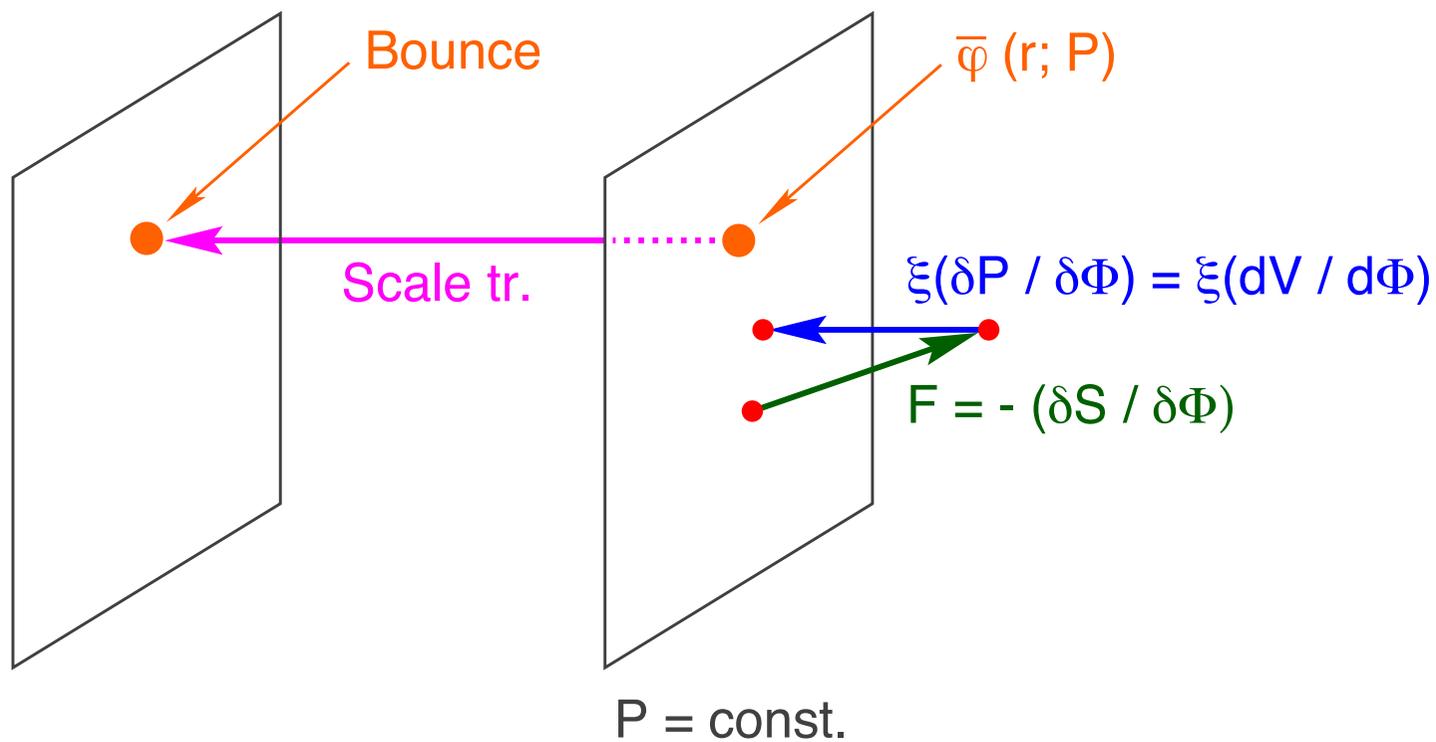
$$\partial_r^2 \bar{\varphi} + \frac{D-1}{r} \partial_r \bar{\varphi} - \lambda^2 \frac{\partial V}{\partial \bar{\varphi}} = 0$$

$$\lambda^2 = \xi[\Phi(s \rightarrow \infty)] + 1$$

2. Use scale transformation:

$$\partial_{r'}^2 \bar{\varphi}(r; \mathcal{P}) + \frac{D-1}{r'} \partial_{r'} \bar{\varphi}(r; \mathcal{P}) - \frac{\partial V}{\partial \bar{\varphi}} = 0 \quad r' = \lambda r$$

$$\Rightarrow \bar{\phi}(r) = \bar{\varphi}(\lambda^{-1} r, \mathcal{P})$$



## 5. Summary

We proposed a new method to calculate the bounce

- Our method is based on the gradient flow
- The bounce is obtained by solving the flow equation
- It can be easily implemented into numerical code

To-do list:

- Application to BSM models (in particular, SUSY)  
[Gunion, Haber, Sher; Casas, Lleyda, Munoz; Kusenko, Langacker, Segre; Camargo-Molina et al.; Chowdhury et al.; Blinov and Morrissey; Endo, Moroi, Nojiri; Endo, Moroi, Nojiri, Shoji; ...]
- Making a public code (?)

Please use our method, if you find any good application