

Dirac equation in five-dimensional spherical AdS space-time

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I. Introduction

✓ We provide a detailed discussion on the representation of the angular sector of Dirac field with $SU(2) \times U(1)$ symmetry.

✓ Our analysis applies to asymptotically flat as well as asymptotically AdS and potentially has many application in AdS/CFT context, higher dimensional black holes.

II. Background space time

■ 4+1 dimensional spherically symmetric metric of polar coordinates

$$ds^2 = -f(r)a^2(r)dt^2 + \frac{1}{f(r)}dr^2 + \frac{r^2}{4}(d\theta^2 + d\varphi^2 + d\psi^2 + 2\cos\theta d\varphi d\psi)$$

where
 $0 \leq \theta \leq \pi$,
 $0 \leq \varphi \leq 2\pi$,
 $0 \leq \psi \leq 4\pi$

This metric has symmetry of $SO(4) \cong SU(2)_L \times SU(2)_R$. Then, we can define two invariant one-forms σ_a^L, σ_a^R of $SU(2)$ which satisfy $d\sigma_a^R = 1/2\epsilon^{abc}\sigma_b^R \wedge \sigma_c^R$ and $d\sigma_a^L = -1/2\epsilon^{abc}\sigma_b^L \wedge \sigma_c^L$.

The metric is given by

$$ds^2 = -f(r)a^2(r)dt^2 + \frac{1}{f(r)}dr^2 + \frac{r^2}{4}((\sigma_1^{R,L})^2 + (\sigma_2^{R,L})^2 + (\sigma_3^{R,L})^2)$$

Also, we can define the following Killing vectors $\xi_\alpha^{R,L}$ which satisfy $(\xi_\alpha^{R,L}, \sigma_a^{R,L}) = \delta_{\alpha a}$

$$\begin{aligned} \xi_x^R &= -\sin\psi\partial_\theta + \frac{\cos\psi}{\sin\theta}\partial_\varphi - \cot\theta\cos\psi\partial_\psi & \xi_x^L &= \cos\varphi\partial_\theta + \frac{\sin\varphi}{\sin\theta}\partial_\psi - \cot\theta\sin\varphi\partial_\varphi \\ \xi_y^R &= \cos\psi\partial_\theta + \frac{\sin\psi}{\sin\theta}\partial_\varphi - \cot\theta\sin\psi\partial_\psi & \xi_y^L &= -\sin\varphi\partial_\theta + \frac{\cos\varphi}{\sin\theta}\partial_\psi - \cot\theta\cos\varphi\partial_\varphi \\ \xi_z^R &= \partial_\psi & \xi_z^L &= \partial_\varphi \end{aligned}$$

The invariant one-form of $SU(2)$

$$\begin{aligned} \sigma_1^L &= -\sin\psi d\theta + \cos\psi \sin\theta d\varphi \\ \sigma_2^L &= \cos\psi d\theta + \sin\psi \sin\theta d\varphi \\ \sigma_3^L &= d\psi + \cos\theta d\varphi \\ \sigma_1^R &= \sin\theta d\theta - \cos\theta \sin\theta d\varphi \\ \sigma_2^R &= \cos\theta d\theta + \sin\theta \sin\theta d\varphi \\ \sigma_3^R &= d\psi + \cos\theta d\varphi \end{aligned}$$

Let us define two kinds of angular momenta :

$$L_\alpha^R = i\xi_\alpha^R, L_\alpha^L = i\xi_\alpha^L$$

Commutation relation :

$$\begin{aligned} [L_\alpha^L, L_\beta^L] &= i\epsilon_{\alpha\beta\gamma}L_\gamma^L \\ [L_\alpha^R, L_\beta^R] &= -i\epsilon_{\alpha\beta\gamma}L_\gamma^R \\ [L_\alpha^L, L_\beta^R] &= 0. \end{aligned}$$

In a special case $L^2 = (L^R)^2 = (L^L)^2, L_x^R, L_x^L, L_z^R, L_z^L$ have the common eigenfunction called **Wigner D function**

$$\begin{aligned} L^2 D_{M,K}^l &= l(l+1)D_{M,K}^l \\ L_z^L D_{M,K}^l &= M D_{M,K}^l \\ L_z^R D_{M,K}^l &= K D_{M,K}^l \end{aligned}$$

III. Dirac Hamiltonian

Symmetries of the Dirac Hamiltonian

The Dirac equation in curved space-time : $(e_a^M \gamma^a D_M - m)\Psi = 0$.

The covariant derivative :

$$D_M = \partial_M + \frac{1}{8}\omega_{\mu ab}[\gamma^a, \gamma^b]$$

Gamma matrices :

$$\gamma^0 = i \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \gamma^i = i \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix}, \gamma^5 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Vielbein :

Definition : $g_{MN} = e_a^M e_b^N \eta^{ab}$

The relation between Cartesian coordinate (x, y, z, w) and polar coordinate $(r, \theta, \varphi, \psi)$

$$\begin{pmatrix} \alpha\sqrt{f} \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} \\ \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} \\ \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} \\ \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\cos\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} & \frac{1}{\sqrt{f}}\sin\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} \end{pmatrix} \begin{pmatrix} r \\ r\sin\frac{\theta}{2}\cos\frac{\varphi-\psi}{2} \\ r\sin\frac{\theta}{2}\sin\frac{\varphi-\psi}{2} \\ r\cos\frac{\theta}{2} \end{pmatrix}$$

The Dirac equation can be written as $i\partial_t\Psi = \mathcal{H}\Psi$. Further, we assume that the spinor can be decomposed as an energy eigenequation

$$\Psi(t, x) = e^{iEt} \begin{pmatrix} \chi_1(x) \\ \chi_2(x) \end{pmatrix} \Rightarrow \mathcal{H} \begin{pmatrix} \chi_1 \\ \chi_2 \end{pmatrix} = E \begin{pmatrix} \chi_1 \\ \chi_2 \end{pmatrix} \text{ where } \mathcal{H} = \begin{pmatrix} \sqrt{f}am & -i\tau_\mu p_\mu \\ i\tau_\mu p_\mu & -\sqrt{f}am \end{pmatrix}$$

This Dirac Hamiltonian does not commute with the space time symmetry generators $L_x^L, L_x^R, L_z^L, L_z^R$. The reason is that these operators are the generators of the angular momenta, instead Dirac fields carry a spin. We define following total angular momenta :

$$G_\alpha^R = L_\alpha^R - \frac{1}{2} \begin{pmatrix} \tau_\alpha & 0 \\ 0 & 0 \end{pmatrix}, G_\alpha^L = L_\alpha^L + \frac{1}{2} \begin{pmatrix} 0 & 0 \\ 0 & \tau_\alpha \end{pmatrix} \text{ where } [G_\alpha^R, \mathcal{H}] = [G_\alpha^L, \mathcal{H}] = 0.$$

Angular operator of the Dirac Hamiltonian

The Dirac Hamiltonian has angular operators iD_ϕ, iD_ψ in the non-diagonal part. They are written as :

$$iD_\phi = \begin{pmatrix} L_x^L & \sqrt{2}L_x^R \\ -\sqrt{2}L_x^L & L_x^R \end{pmatrix}, iD_\psi = \begin{pmatrix} -L_z^R & \sqrt{2}L_z^+ \\ -\sqrt{2}L_z^- & L_z^R \end{pmatrix} \text{ where } \begin{aligned} L_x^R &= (iL_x^R \pm L_y^R)/\sqrt{2} \\ L_x^L &= (iL_x^L \pm L_y^L)/\sqrt{2} \end{aligned}$$

The spinorial harmonics can be obtained by using $SU(2)$ Clebsch-Gordan coefficients $C_{IM\frac{1}{2}\sigma^3}^{GMG_1}, C_{IK\frac{1}{2}\sigma^3}^{GMG_2}$.

$$|i\rangle_l = \sum_{M\sigma^3} C_{IM\frac{1}{2}\sigma^3}^{GMG_1} |lMK\rangle_{\sigma^3}, |i\rangle_r = \sum_{K\sigma^3} C_{IK\frac{1}{2}\sigma^3}^{GMG_2} |lMK\rangle_{\sigma^3}$$

The explicit form of the angular basis

$$\begin{aligned} |0\rangle_l &= \sqrt{\frac{G+K}{2G}} D_{0,0}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \sqrt{\frac{G-K}{2G}} D_{0,0}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} & |2\rangle_l &= \sqrt{\frac{G+M+\frac{1}{2}}{2G}} D_{2,0}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} - \sqrt{\frac{G-M+\frac{1}{2}}{2G}} D_{2,0}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ |1\rangle_l &= -\sqrt{\frac{G-K+1}{2G+2}} D_{1,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \sqrt{\frac{G+K+1}{2G+2}} D_{1,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} & |3\rangle_l &= -\sqrt{\frac{G-M+\frac{1}{2}}{2G+2}} D_{3,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} - \sqrt{\frac{G+M+\frac{1}{2}}{2G+2}} D_{3,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ |0\rangle_r &= \sqrt{\frac{G-M}{2G}} D_{0,0}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \sqrt{\frac{G+M}{2G}} D_{0,0}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} & |2\rangle_r &= -\sqrt{\frac{G-K+\frac{1}{2}}{2G}} D_{2,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \sqrt{\frac{G+K+\frac{1}{2}}{2G}} D_{2,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ |1\rangle_r &= \sqrt{\frac{G+M+1}{2G+2}} D_{1,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} - \sqrt{\frac{G-M+1}{2G+2}} D_{1,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} & |3\rangle_r &= -\sqrt{\frac{G-K+\frac{1}{2}}{2G+2}} D_{3,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} - \sqrt{\frac{G+K+\frac{1}{2}}{2G+2}} D_{3,-1}^{G-\frac{1}{2},M} \begin{pmatrix} 0 \\ 0 \end{pmatrix} \end{aligned}$$

These angular basis satisfy $G_3^R \begin{pmatrix} |i\rangle_r \\ |i'\rangle_r \end{pmatrix} = K \begin{pmatrix} |i\rangle_r \\ |i'\rangle_r \end{pmatrix}, G_3^L \begin{pmatrix} |i\rangle_l \\ |i'\rangle_l \end{pmatrix} = M \begin{pmatrix} |i\rangle_l \\ |i'\rangle_l \end{pmatrix}, G^2 \begin{pmatrix} |i\rangle_r \\ |i'\rangle_l \end{pmatrix} = -G(G+1) \begin{pmatrix} |i\rangle_r \\ |i'\rangle_l \end{pmatrix}$.

Parity of angular basis

Parity transformation : $(r, \theta, \varphi, \psi) \rightarrow (r, 2\pi - \theta, \varphi + \pi, \psi - \pi)$ The parity of the angular basis is defined according to the parity of the upper component $|i\rangle_n$

Parity of Wigner D function:

$$\begin{aligned} D_{R,M}^R(\varphi, -\theta, \psi) &= (-1)^{K-M} D_{R,M}^R(\varphi, \theta, \psi) \\ D_{R,M}^R(\varphi, \theta \pm 2n\pi, \psi) &= (-1)^{2n} D_{R,M}^R(\varphi, \theta, \psi) \\ D_{R,M}^R(\varphi \pm n\pi, \theta, \psi) &= (-1)^{\pm 2nK} D_{R,M}^R(\varphi, \theta, \psi) \\ D_{R,M}^R(\varphi, \theta, \psi \pm n\pi) &= (-1)^{\pm 2nM} D_{R,M}^R(\varphi, \theta, \psi) \end{aligned}$$

parity even spinors : $|0\rangle_r, |1\rangle_r$

parity odd spinors : $|2\rangle_r, |3\rangle_r$

IV. The radial equation

The eigenfunction Ψ can be separated by the angular basis and radial part such as $\Psi^{(i)} = \begin{pmatrix} \mathcal{F}_i(r)|i\rangle_r \\ \mathcal{G}_i(r)|i'\rangle_l \end{pmatrix}$.

It is well-known that by eliminating the lower ("the smaller") component, one can obtain the Schrödinger-like radial equations for the positive eigenvalues

$$a^2 f^2 \mathcal{F}_i'' + P_1 \mathcal{F}_i' + \left(P_0^a - P_0^b (G_i - 2) - \frac{a^2 f}{r^2} G_i (G_i - 2) \right) \mathcal{F}_i = 0.$$

Similarly, for the negative eigenvalues, the equations are obtained by eliminating the smaller (in this case, upper) component

$$a^2 f^2 \mathcal{G}_i'' + Q_1 \mathcal{G}_i' + \left(Q_0^a - Q_0^b (G_i - 2) - \frac{a^2 f}{r^2} G_i (G_i - 2) \right) \mathcal{G}_i = 0.$$

Where $G_0 = 2G + 1, G_1 = -G_0, G_2 = -2G, G_3 = 2G + 2, P_0^a, P_0^b, P_1, Q_0^a, Q_0^b, Q_1$ are polynomials of the metric functions.

V. The plane wave in flat case

Flat space-time $a(r) = 1, f(r) = 1$

The radial equations :

$$r^2 \mathcal{F}_i'' + r \mathcal{F}_i' + \mathcal{F}_i (r^2 (E^2 - m^2) - G_i^2) = 0$$

The solution :

$$\mathcal{F}_i = \frac{J(kr)}{r}$$

The complete basis sets $\{\Xi_i\} = \{u_i\}, \{v_i\}$

$$u_a = N_k \begin{pmatrix} i\omega_{E_k}^+ \frac{J_{2G+1}(kr)}{r} |0\rangle_r \\ -\omega_{E_k}^- \frac{J_{2G+1}(kr)}{r} |2\rangle_l \end{pmatrix} v_a = N_k \begin{pmatrix} i\omega_{E_k}^+ \frac{J_{2G+1}(kr)}{r} |2\rangle_r \\ -\omega_{E_k}^- \frac{J_{2G}(kr)}{r} |0\rangle_l \end{pmatrix}$$

$$u_b = N_k \begin{pmatrix} i\omega_{E_k}^+ \frac{J_{2G+2}(kr)}{r} |1\rangle_r \\ -\omega_{E_k}^- \frac{J_{2G+1}(kr)}{r} |3\rangle_l \end{pmatrix} v_b = N_k \begin{pmatrix} i\omega_{E_k}^+ \frac{J_{2G+1}(kr)}{r} |3\rangle_r \\ -\omega_{E_k}^- \frac{J_{2G+2}(kr)}{r} |1\rangle_l \end{pmatrix}$$

$|0\rangle_r, |1\rangle \sim |3\rangle_r, |l\rangle$: Angular basis
 $J_l(r)$: Bessel function
 k : Eigenvalue of momentum
 N_k : Normalization constant
 $\omega_{E_k, > 0}, \omega_{E_k, < 0} = \text{sgn}(E_k)$,
 $\omega_{E_k, > 0}, \omega_{E_k, < 0} = \frac{k}{E_k + m}$

VI. The normal mode in AdS

A. The analytical study

Massless case

AdS vacuum $a(r) = 1, f(r) = 1 + \frac{r^2}{l^2}$

The asymptotic behaviors

• origin $F_i = a_1 r^{G_i-2} + a_2 r^{-G_i}$ • infinity $F_i = \frac{c_1}{r^3} + \frac{c_2}{r^2}$

Change the variable and the function :

$$\frac{r}{l} = \sqrt{\frac{1}{x^2} - 1}, \mathcal{F}_i(x) = x^3(1-x)^{\frac{G_i-2}{2}}(1+x)^{-\frac{G_i+1}{2}} H(x)$$

The equation :

$$(1-x^2)H'' + (1-2G_i-x)H' + \epsilon^2 H = 0$$

The normalizability condition

$$\epsilon_2 = 0$$

The regularity conditions

$$\begin{cases} a_1 = 0 & \text{for } G_i > 2 \\ a_2 = 0 & \text{for } G_i < 0 \end{cases}$$

$$\int r^3 dr \mathcal{F}_i^2 < \infty$$

$$\Leftrightarrow r^3 \mathcal{F}_i^2 \text{ is faster than } r^{-1}$$

$$\Leftrightarrow \mathcal{F}_i \text{ is faster than } r^{-2}$$

The solution

$$H(x) = {}_2F_1(E, -E, G_i, \frac{1-x}{2}) \text{ for } G_i = 3$$

$E = 3.725, 5.65, 7.62, 9.6$

Massive case

The asymptotic behavior

• origin $F_\infty = A_\infty r^{-2-m} + B_\infty r^{-2+m}$ • infinity $F_i = A_0 r^{G_i-2} + B_0 r^{-G_i}$

Change the variable and the function

$$\mathcal{F}_i(x) = x^{m+2}(1-x)^{\frac{G_i-2}{2}}(1+x)^{\frac{G_i-1}{2}} H(x)$$

The equation

$$x(1-x^2)(E+x+m)H'' + P_3 H' + P_2 H = 0$$

P_3, P_2 are polynomial of x .

The normalizability condition $B_\infty, m \geq 1$

The regularity conditions $\begin{cases} A_0 = 0 & \text{for } G_i > 2 \\ B_0 = 0 & \text{for } G_i < 0 \end{cases}$

The solution

$$C_p^{m+G_i+p-\frac{1}{2}} H(x) = P_p^{m-\frac{1}{2}, G_i} (1-2x^2) + x P_{p-1}^{m+1/2, G_i} (1-2x^2)$$

$$E_{2p} = G_i + m + 2p \quad p : \text{integer}$$

B. The numerical study

A reason of performing numerical study

If one obtain the smaller component of the solutions, we should use following relations,

$$\mathcal{G}_i |i'\rangle_l = \frac{i\tau_\mu p_\mu}{E + a\sqrt{f}m} \mathcal{F}_i |i\rangle_r \text{ for } E > 0, \quad \mathcal{F}_i |i'\rangle_r = \frac{i\tau_\mu p_\mu}{|E| + a\sqrt{f}m} \mathcal{G}_i |i\rangle_l \text{ for } E < 0.$$

But, it is tedious task to compute analytically. So, we numerically solve the equations and obtain the smaller component. Also, we check the validity of our obtained analytical results.

The numerical method

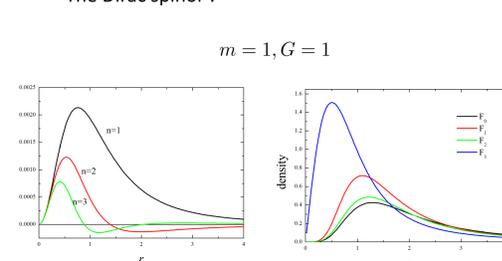
(Naoki Watanabe, <http://www.cms.phys.s.u.tokyo.ac.jp/~naoki/CIPINTRO/CIP/index.html>)

For the numerical analysis, we employ a scheme based on simple first order perturbation, which is quite efficient for the present eigenvalue problem. The method is summarized:

- We employ the rescaling of the coordinate $r \rightarrow \frac{y}{1-y}$.
- We assume an eigenvalue E_0 , and solve the equation for $\mathcal{F}_i(y)$ from $y = 0$ to an intermediate matching point $y = y_{\text{fit}}$ by using the standard Runge Kutta method.
- We match the asymptotic solution F_∞ with the value of the solution $F_i(y)$ at y_{fit} by multiplying a factor α : $\alpha F_\infty(y_{\text{fit}}) \equiv F_i(y_{\text{fit}})$.
- We introduce an arbitrary δ -functional potential at an intermediate value y_{fit} :
$$V_\delta(y) := -\frac{[F_i'(y_{\text{fit}})]_{y_{\text{fit}}=0}^{y_{\text{fit}}+0}}{F_i(y_{\text{fit}})} \delta(y - y_{\text{fit}}).$$
 Because, the eigenfunction is continuous at the matching point if the δ -functional potential exists, but its derivative is not. Therefore the correction in terms of the first order perturbation
$$\Delta E = \int \frac{y^3 dy}{(1-y)^5} F_i^*(y) V_\delta(y) F_i(y) = -\frac{y_{\text{fit}}^3}{(1-y_{\text{fit}})^5} [F_i'(y_{\text{fit}})]_{y_{\text{fit}}=0}^{y_{\text{fit}}+0} F_i(y_{\text{fit}})$$
 efficiently improves the eigenvalue, i.e., the eigenfunction.
- We repeat the process 2-4. If the analysis reaches the correct eigenfunction, it no longer has discontinuity at all and the computation is successfully terminated.

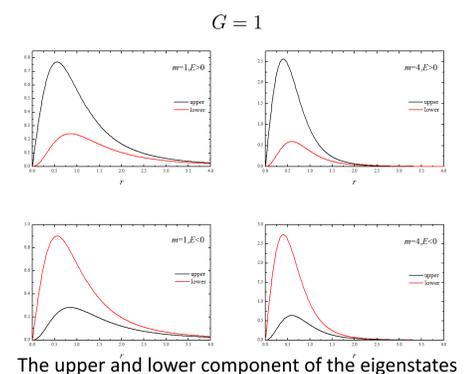
The numerical results

The Dirac spinor :



The four first eigenstates for $|0\rangle_r$.

The densities of ground state of $|0\rangle_r, |1\rangle_r, |2\rangle_r, |3\rangle_r$.



The upper and lower component of the eigenstates

The energy spectrum :

	$n = 0$	$n = 1$	$n = 2$
\mathcal{F}_0	4.00000003	6.00000008	8.00000015
\mathcal{G}_0	-5.00000024	-7.00000069	-9.00000107
\mathcal{F}_1	5.00000003	7.00000038	9.00000095
\mathcal{G}_1	-4.00000004	-6.00000009	-8.00000017
\mathcal{F}_2	2.00000002	4.00000004	6.00000010
\mathcal{G}_2	-3.00000003	-5.00000006	-7.00000011
\mathcal{F}_3	3.00000004	5.00000008	7.00000015
\mathcal{G}_3	-2.00000001	-4.00000004	-6.00000007

