Yukawa Institute Workshop Strings and Fields "Developments in String Theory and Quantum Field Theory"

Conic D-branes

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Cones are critical

- Conic shapes widely appear in nature
- Cones are critical geometries where the topology changes
 - Merger/fragmentation of liquid
 - Merger/fragmentation of black hole horizon
 - Phase boundary

D3/D7 system

Karch, Katz (2002), Grana, Polchinski (2002), Bertolini et al. (2002)

- Holographic dual to $\mathcal{N} = 2$ SQCD
 - In large N_c limit, a probe D7-brane is embedded in $AdS_5 \times S^5$ geometry
 - Fluctuations of the D7-brane = "meson" excitations
- Phase transition by applying electric fields
 - Dielectric breakdown due to Schwinger effect



Critical embedding in the D3/D7 system

- A phase boundary between the Minkowski embeddings and the BH embeddings
 - Two series of the solutions merge
 - The shape of the D7-brane is conical



Taylor cone

- A hydrodynamic phenomena, which are used in electrospray in material/industrial science
- As an electric field increases the surface of a conductive liquid is sharpening, and at a critical electric field a cone is formed
 - Beyond the critical value, the liquid sprays





Ref. R.Krpoun "Micromachined Electrospray Thrusters for Spacecraft Propulsion" (2009)

Taylor cone

• The first theoretical model of this phenomena is given by Taylor (1964)

G.Taylor Proc. R. Soc. Lond. A 280, 383 (1964)

- He assumed the liquid was a perfect conductor and the cone was formed when the surface tension and the electrostatic stress equilibrated on the liquid surface
- Repulsive forces between the induced charges cancel surface tension forces
- A half-cone angle 49.29° predicted by Taylor is very close to experimental results
 - This angle is determined by a zero of the Legendre polynomial

Can we find something like universal properties for conic D-branes?

RR flux background

- D2-brane in a constant Ramond-Ramond (RR) flux background in flat spacetime
 - The *d*-dim. bulk spacetime

$$g_{\mu\nu}dx^{\mu}dx^{\nu} = -dt^2 + (dx^1)^2 + (dx^2)^2 + d\vec{y}_{d-3}^2$$

- Embedding function

$$y = \phi(\rho)$$
 $\rho = \sqrt{(x^1)^2 + (x^2)^2}$

- RR field

$$C_{\mu}dx^{\mu} = C_0dt = cy\,dt \quad (c = \text{const.})$$

 The action is a DBI action with a coupling to the RR field

$$S = -\mathcal{T}_2 \int dx^0 dx^1 dx^2 \sqrt{-\det(\eta_{ab} + 2\pi\alpha' F_{ab} + \partial_a \phi \partial_b \phi)}$$
$$-\frac{\mathcal{T}_2}{2} \int dx^0 dx^1 dx^2 \ 2\pi\alpha' F_{ab} C_c \epsilon^{abc}$$



Conic solution



 $\theta_{\rm cone} = \arctan \sqrt{2}$

The apex of the cone is located at $\rho = 0$

- This analysis is local
 - The global structure of the D-brane depends on asymptotic boundary conditions.
 - In general, the RR flux does not need to be constant and uniform globally.
- If a cone has been formed at a part of the D2brane, the cone should be locally identified with our solution at that critical point.
 - At the critical point, the apex angle can be uniquely determined.

Other examples

- NSNS flux background
 - Dp-brane in a constant NSNS flux

topology of the cone: $\mathbf{R}_+ imes S^{p-2}$

$$\theta_{\rm cone} = \arctan\sqrt{2(p-2)}$$

- D3/D7
 - Probe D7-brane with worldvolume gauge fields in AdS_5 –Schwarzschild × S^5 topology of the cone: $\mathbf{R}_+ \times S^3$

 $\theta_{\rm cone} = \arctan \sqrt{6}$

The cone angle is unique independent of three parameters (E_i, B_i, r_h)

Universal formula?

- We have three conical D-brane solutions for different external forces and couplings
 - RR flux, NSNS flux, gravitational field (AdS curvature)
- It is expected that the half-cone angle is determined as

$$\theta_{\rm cone} = \arctan\sqrt{2(d_{\rm cone}-1)}$$

topology of the cone: $\mathbf{R}_+ imes S^{d_{\mathrm{cone}}-1}$

- What mechanism determines the angle of conic D-branes?
- Where is the factor of 2 in the square root coming from?

Force balance in Newtonian mechanics

- We have two force balance conditions:
 - Normal direction (extrinsic dynamics)
 - Radial direction (intrinsic dynamics)



External

Assuming that the tension is isotropic and its distribution behaves as

$$T_{ss} = T_{rr} \simeq Ar^{\alpha} \quad (r \sim 0) \qquad \theta_{\rm cone} = \arctan\sqrt{\frac{1}{\alpha}}$$

Equations of motion for generic membranes

Extrinsic and intrinsic dynamics

External force $\mathcal{F}^{\mu}=\mathcal{F}^{\mu}_{\mathrm{n}}+\mathcal{F}^{a}_{\mathrm{t}}h_{a}{}^{\mu}$

Induced metric: $h_{ab} \equiv g_{\mu\nu} \partial_a X^{\mu} \partial_b X^{\nu}$

Extrinsic curvature: $-K^{\mu}{}_{ab} \equiv (g^{\mu}{}_{\lambda} - h^{\mu}{}_{\lambda})h_{a}{}^{\nu}\nabla_{\nu}h_{b}{}^{\lambda}$ = $D_{a}D_{b}X^{\mu} + \Gamma^{\mu}{}_{\alpha\beta}D_{a}X^{\alpha}D_{b}X^{\beta}$, Embedding functions: $x^{\mu} = X^{\mu}(y^{a})$

 $T^{ab}K^{\mu}{}_{ab} = -\mathcal{F}^{\mu}_{n},$

 $D_a T^{ab} = \mathcal{F}^b_{+},$

Nambu-Goto brane $T^{ab} = -\sigma h^{ab}$ ($\sigma = \text{const.}$) $\text{Tr}K^{\mu} = 0$ Extremal surface

In general, the energy density is not equal to the tension (negative pressure).

Force balance in curved spacetimes

• A membrane in an "axisymmetric" spacetime Bulk metric: $g_{\mu\nu}dx^{\mu}dx^{\nu} = A_{ij}(\rho,\zeta)dy^{i}dy^{j} + B(\rho,\zeta)(d\rho^{2} + d\zeta^{2}) + C(\rho,\zeta)d\Omega_{d-1}^{2}$ $+ D_{kl}(\rho,\zeta)dw^{k}dw^{l}$

Induced metric on the memebrane:

Embedding functions

 $\zeta = \phi(\rho), w^k = \text{const.}$

$$\begin{split} + \, [1 + \phi'(\rho)^2] \mathsf{B}(\rho, \phi(\rho)) d\rho^2 + \mathsf{C}(\rho, \phi(\rho)) d\Omega_{d-1}^2 \\ \\ \text{Topology of the cone} \ \ \mathbf{R}_+ \times S^{d-1} \end{split}$$

We assume the membrane has an isotropic tension on the cone stress-energy tensor $T_{ab} = \tau_{ab} - \sigma(r_a r_b + s_{ab})$ tension induced metric on the cone $\begin{bmatrix} T^{ab}K^{\mu}{}_{ab} = -\mathcal{F}^{\mu}_{n} \\ D_{a}T^{ab} = \mathcal{F}^{b}_{i} \end{bmatrix} \longrightarrow \frac{\sin\theta}{\sqrt{-AB}} \frac{d}{d\rho}(\sqrt{-A\sigma}\sin\theta) - \sigma\cos\theta n^{\mu}\partial_{\mu}\log(\sqrt{B}C^{(d-1)/2}) + \frac{1}{2\sqrt{B}}\tau^{ij}\partial_{\rho}A_{ij} = 0$

 $h_{ab}dy^a dy^b = \mathsf{A}_{ii}(\rho, \phi(\rho))dy^i dy^j$

If the external force is along the axis of the cone, we can combine two equations.

• If we assume that the bulk spacetime is regular at the membrane (the membrane does not touch event horizons or some singularities) and the tension σ plays a dominant role, then we have

$$(\sin\theta_{\rm cone})^2 \frac{d\sigma}{d\rho} \simeq (d-1)(\cos\theta_{\rm cone})^2 \frac{\sigma}{\rho}$$

• If the tension behaves as $\sigma \sim \rho^{\alpha}$ near the apex of the cone $\rho \sim 0$, the angle of the cone becomes

$$\theta_{\rm cone} = \arctan \sqrt{\frac{d-1}{\alpha}}$$

- The dimension of the spherical part of the cone
- The power of the stress distribution

Stress-energy tensor of the various D-branes

- D2-brane in the RR flux $T^{0}_{0} = -\frac{1}{\sqrt{1 - (C_{0}[\phi])^{2}}}, \quad T^{\theta}_{\theta} = T^{r}_{r} = -\sqrt{1 - (C_{0}[\phi])^{2}} \quad \mathbf{R}_{+} \times S^{1}$
- Dp-brane in the NSNS flux isotropic tension $T^{0}_{0} = T^{1}_{1} = -\frac{1}{\sqrt{1-c^{2}\phi^{2}}}, \quad T^{r}_{r} = -\sqrt{1-c^{2}\phi^{2}}, \quad T^{m}_{n} = -\sqrt{1-c^{2}\phi^{2}}\delta^{m}_{n}$ $\mathbf{R}_{+} \times S^{p-2}$
- D7-brane in AdS₅ × S⁵ $T^{0}{}_{0} = -\frac{1}{\sigma}(1 + \frac{\mathbf{B}^{2}}{g^{2}}), \quad T^{0}{}_{i} = \frac{1}{\sigma}\frac{1}{g^{2}h}\epsilon_{ijk}E^{j}B^{k}, \quad T^{i}{}_{0} = -\frac{1}{\sigma}\frac{1}{g^{2}}\epsilon^{ijk}E_{j}B_{k},$ $T^{i}{}_{j} = -\frac{1}{\sigma}\left[(1 - \frac{\mathbf{E}^{2}}{g^{2}h})\delta^{i}{}_{j} + \frac{1}{g^{2}}(h^{-1}E^{i}E_{j} + B^{i}B_{j})\right],$ $T^{r}{}_{r} = -\sigma, \quad T^{m}{}_{n} = -\sigma\delta^{m}{}_{n} \text{ isotropic tension } \mathbf{R}_{+} \times S^{3}$ $\left(\sigma^{2} \equiv 1 - \frac{1}{g^{2}}(h^{-1}\mathbf{E}^{2} - \mathbf{B}^{2}) - \frac{1}{g^{4}h}(\mathbf{E}\cdot\mathbf{B})^{2}, \quad h(u) \equiv \left(\frac{u^{4} - r_{h}^{4}/4}{u^{4} + r_{h}^{4}/4}\right)^{2}, \quad g(u) \equiv \frac{1}{2\pi\alpha'R^{2}}\frac{u^{4} + r_{h}^{4}/4}{u^{2}}\right)$

Mechanism for the conic Dbranes

- When the isotropic tension vanishes, a cone is formed.
- The angle of the cone is universally determined by the dimension of the cone and the power of the distribution of the tension.
 - For the conic D-branes, the power is ¹/₂ independent of the background fields, which comes from the square root of the DBI action

$$\theta_{\rm cone} = \arctan\sqrt{2(d_{\rm cone}-1)}$$

topology of the cone: ${f R}_+ imes S^{d_{
m cone}-1}$

Summary

- We found various conic D-brane solutions, whose cone angles obey an universal formula
 - The cone is formed at a critical point where the brane tension is canceled
- In general, the cone angles are determined by simply the local force balance
 - It is expected that many conic D-branes other than our limited examples exist and our formula is valid
- Beyond the critical value, what happens?
 - Spray solution? Funnel solution?



NSNS flux background

- Dp-brane in a constant NSNS flux in flat spacetime
 - Bulk spacetime

$$g_{\mu\nu}dx^{\mu}dx^{\nu} = -dt^{2} + d\vec{x}_{p}^{2} + d\vec{y}_{d-p}^{2}$$
$$= -dt^{2} + dx_{1}^{2} + d\rho^{2} + \rho^{2}d\Omega_{p-2}^{2} + d\vec{y}_{d-p}^{2}$$

- NSNS field

$$B_{\mu\nu}dx^{\mu} \wedge dx^{\nu} = 2cy\,dt \wedge dx_1, \quad H_{01y} = c\,(\text{const.})$$

- Embedding function $y = \phi(\rho)$
- The action is given by DBI action

$$S = -\mathcal{T}_{p} \int dx^{p+1} x \sqrt{-\det(\eta + B + \partial\phi\partial\phi)}$$

= $-\mathcal{T}_{p} \int dx^{0} dx^{1} d\rho V_{p-2} \rho^{p-2} \sqrt{(1 + (d\phi/d\rho)^{2})(1 - B_{01}^{2})}$

In contrast to the case of RR flux, no additional coupling term exists.

Conic solution

 In this case there is a critical point at which the Lagrangian density vanishes.

 $\mathcal{L}[\phi(\rho)] = \rho^{p-2} \sqrt{(1 + (d\phi/d\rho)^2)(1 - B_{01}^2)}$ $= \rho^{p-2} \sqrt{(1 + (d\phi/d\rho)^2)(1 - c^2\phi^2)}$

The equation of motion becomes singular when $\phi(\rho) = 1/c$

 Near this critical point, we can obtain conic solution in a similar manner

$$\phi(\rho) = \frac{1}{c} - \frac{1}{\sqrt{2(p-2)}}\rho + \cdots \qquad \qquad \begin{array}{l} \text{Half-cone angle} \\ \theta_{\text{cone}} = \arctan\sqrt{2(p-2)} \end{array}$$

Induced metric: $h_{ab}dx^a dx^b = -dt^2 + dx_1^2 + (1 + \phi'^2)d\rho^2 + \rho^2 d\Omega_{p-2}^2$ Topology of the cone: $\mathbf{R}_+ \times S^{p-2}$

D3/D7 system

- Probe D7-brane with worldvolume gauge field in the AdS_5 -Schwarzschild × S^5 geometry
 - Bulk metric:

$$\begin{split} g_{\mu\nu}dx^{\mu}dx^{\nu} &= \frac{1}{R^2}\frac{u^4 + r_{\rm h}^4/4}{u^2}[-h(u)dt^2 + d\vec{x}_3^2] + \frac{R^2}{u^2}(du^2 + u^2d\Omega_5^2) \\ h(u) &\equiv \left(\frac{u^4 - r_{\rm h}^4/4}{u^4 + r_{\rm h}^4/4}\right)^2 \qquad \qquad du^2 + u^2d\Omega_5^2 = d\rho^2 + dw^2 + \rho^2d\Omega_3^2 + w^2d\psi^2 \\ r_{\rm h} \text{ is a horizon radius in the usual Schwarzschild coordinates} \qquad \qquad (u^2 = w^2 + \rho^2) \end{split}$$

- Embedding functions: $w = L(\rho), \psi = \text{const.}$
- Worldvolume gauge field: $F_{0i} = E_i$, $F_{ij} = e_{ijk}B_k$
- DBI action

$$S = -\mathcal{T}_{7} \int d^{8}x \sqrt{-\det(g_{ab} + 2\pi\alpha' F_{ab})} \propto \int d^{4}x \rho^{3} \sqrt{\xi(1 + (L'(\rho))^{2})}$$
$$\xi \equiv \left(\frac{u^{4} + r_{h}^{4}/4}{u^{4}}\right)^{4} h(u) - \left(\frac{2\pi\alpha' R^{2}(u^{4} + r_{h}^{4}/4)}{u^{6}}\right)^{2} (\mathbf{E}^{2} - h(u)\mathbf{B}^{2}) - \left(\frac{2\pi\alpha' R^{2}}{u^{2}}\right)^{4} (\mathbf{E} \cdot \mathbf{B})^{2}$$

Conic solution

- When the electric field increases, there exists a critical electric field at which the Lagrangian density vanishes
 - Critical embedding, which is the phase boundary between two series of solutions: BH and Minkowski embeddings

$$\begin{split} L(\rho) &= L_{\rm c} - \frac{1}{\sqrt{6}}\rho + \cdots & \begin{array}{l} \text{Half-cone angle} \\ \theta_{\rm cone} &= \arctan\sqrt{6} \\ \\ h_{ab}dy^a dy^b &= \frac{1}{R^2} \frac{(\rho^2 + L^2)^2 + r_{\rm h}^4/4}{\rho^2 + L^2} [-h(u)dt^2 + dx_i^2] + \frac{R^2}{\rho^2 + L^2} [(1 + L'^2)d\rho^2 + \rho^2 d\Omega_3^2] \\ \\ \end{array} \\ \end{split}$$
Topology of the cone: $\mathbf{R}_+ \times S^3$

The cone angle is unique independent of three parameters (E_i, B_i, r_h)



Phase transition by applying electric fields Karch, O'Bannon (2007)

• Schwinger effect

Erdmenger, Meyer, Shock (2007) Albash, Filev, Johnson, Kundu (2007)



Beyond the critical electric field, an effective horizon emerges on the brane The electric current becomes non-zero value = Schwinger effect