Exploring multipartite steering effect using Bell operators



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Abstract:

Einstein-Podolsky-Rosen (EPR) steering represents quantum correlation intermediate between entanglement and Bell nonlocality. We evaluate the steering ability of the superposition of two non-commuting Bell operators and explore the strong connection between the EPR steering and joint measurability based on the nonlinear steering inequalities. The necessary and sufficient criteria of unsteerability are investigated and demonstrated in the qutrit case.

1. Introduction

Quantum mechanics demonstrates richer correlation structure than classical system.

Separable (product or disentanglement) states: $|0\rangle = |z; +\rangle$, $|1\rangle = |z; -\rangle$ $|\Psi_{\rm S}\rangle = \frac{1}{2}(|0\rangle_A + |1\rangle_A) \otimes (|0\rangle_B + |1\rangle_B)$

Nonlocality



2. LHV and LHS

Bell nonlocality may be explained by a local model

 $p(ab|xy) = \int d\lambda \, q(\lambda) p(a|x,\lambda) p(b|y,\lambda)$

x: Alice's measurement ($x = 0: S_z, x = 1: S_x$) *a*: Outcome of *x* $q(\lambda)$: Some probability distribution

 \rightarrow Local Hidden Variable (LHV) model

Quantum Calculation: $p(ab|xy) = Tr(\rho \Pi_{a|x} \Pi_{b|y})$ Projector to x = a state

Bell inequality (CHSH inequality[4])

Non-separable state: Entangled state (a Bell state)

$$|\Psi\rangle = \frac{1}{\sqrt{2}} (|0\rangle_A \otimes |0\rangle_B + |1\rangle_A \otimes |1\rangle_B$$

$$\begin{split} |\Psi\rangle &= \frac{1}{\sqrt{2}} (|+\rangle_A |+\rangle_B + |-\rangle_A |-\rangle_B) \\ &= \frac{1}{\sqrt{2}} (|x;+\rangle_A |x;+\rangle_B + |x;-\rangle_A |x;-\rangle_B) \end{split}$$

Alice measures $S_z \implies$ Bob's ensemble $|\pm\rangle_B$ measures $S_x \implies$ ensemble $|x;\pm\rangle_B$

Through her measurement, Alice can steer Bob's ensemble!!

3. Multipartite case

How two outcomes *a* and *b* are correlated?

If Alice knows her result, a, then she may make a statement on b with some certainty.

Separable: No correlation.

 $P(a,b) = P_A(a)P_B(b)$ The results of Alice and Bob are independent.

Bell state: 100% correlation.

If Alice observes 0, she is sure that Bob's is 0 too.

Not all entangle states show nonlocality/steering.



 $S = \langle a_0 b_0 \rangle + \langle a_1 b_0 \rangle + \langle a_0 b_1 \rangle - \langle a_1 b_1 \rangle$ $\left(\langle a_x b_y \rangle = \sum_{x} ab \ p(ab|xy), \quad a, b = \pm 1 \right)$ LHV models: $S \leq 2$ QM for Bell state: $S = 2\sqrt{2}$

Steering and LHS

Bob assumes that he has local states σ_{λ}^{B} that depends on the local variable λ . (Local Hidden States: LHS)

Bob can explain the steering phenomenon by a local model if

 $p(ab|xy) = \int d\lambda \, q(\lambda) p(a|x,\lambda) \operatorname{Tr}\left(\Pi_{b|y} \sigma_{\lambda}^{B}\right)$

(Alice arranges a set of σ_{λ}^{B} to convince Bob of steering.)

 \square No such σ_{λ}^{B} and λ : the initial state is *steerable*. Otherwise, *unsteerable*. [2]

 $|W\rangle \propto |00100\cdots 1\rangle + |11101\cdots 0\rangle + \cdots$ An *n*-qubit states W Bob Alice Measurement Measurement k qubits n-k $M_i^{l_j}$ Steer!!

Multipartite criteria of unsteerability

Task function

 $F^{(n,k)}(W) = \sqrt{\langle B_k^+ B_{n-k} \rangle^2 + \langle B_k^+ B_{n-k}' \rangle^2 + \sqrt{\langle B_k^- B_{n-k} \rangle^2 + \langle B_k^+ B_{n-k}' \rangle^2}$

LHV-LHS model

 $p(ab|\mathcal{M}\mathcal{M}') = \int d\lambda \, q(\lambda) \, p(a|\mathcal{M}, \lambda) \mathrm{Tr}(\mathcal{M}'_b \sigma_\lambda)$

For n –qutrit system $|\psi\rangle \sim |201102 \cdots 2\rangle$ An *n*-qutrit states Bell operators for qutrits [6] $M_{n}^{k} = \frac{1}{3} \left[(X + \alpha^{2}Y)^{n} + \omega^{2k} (X + \omega\alpha^{2}Y)^{n} + \omega^{k} (X + \omega^{2}\alpha^{2}Y)^{n} \right]$ $X = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \qquad Y = \begin{pmatrix} 0 & 0 & \alpha^{-2} \\ \alpha & 0 & 0 \\ 0 & \alpha & 0 \end{pmatrix}, \qquad \alpha = e^{\frac{2\pi i}{9}}, \qquad \omega = \alpha^3$

(Qutrit version of Mermin inequalities are derived.)

Task function $R^{(n,k)} = \frac{1}{3} \sum_{j=0}^{2} \left| \sum_{l=0}^{2} \left\langle M_{k}^{j} M_{n-k}^{l} \right\rangle^{2} \right|$

The upper bound for LHV-LHS model



Numerical evaluation: I.h.s / r.h.s

n — k	1	2	3
3	0.88 / 0.86	1.089 / 0.844	
4	1.440 / 1.213	1.761 / 1.721	2.177 / 1.477

n-qubit Klyshko-Bell operators [5]
$$B_n = B_{n-1}B_1^+ + B_{n-1}'B_1^- \qquad B_1^{\pm} = \frac{B_1 \pm B_1'}{2}$$

$$B_{n} = B_{n-1}B_{1}^{+} + B_{n-1}^{\prime}B_{1}^{-}$$

$$B_{1}^{\pm} = \frac{-1 - -1}{2}$$

$$B_{1}^{\pm} = \frac{-1 - -1}{2}$$

$$B_{1}^{\pm} = B_{1}^{-}B_{1}^{\pm}$$
(Choose $B_{1} = \sigma_{x}, B_{1}^{\prime} = \sigma^{y}$

Bell inequalities and multipartite nonlocality $B_2 = \frac{1}{2}(B_1B_1 + B_1B_1' + B_1'B_1 - B_1'B_1') = \frac{S}{2}$ (CHSH operator)

References

[1] L.-Y. Hsu, S. Kawamoto "Exploring multipartite steering effect using Bell operators," in submission. [2] H. Wiseman, S. J. Jones, A. Doherty, PRL98, 140402 [3] R. Uola, et al., "Quantum Steering," arXiv: 1903.06663 [4] J.F. Clauser, M.A. Horne, A. Shimony, and R.A. Holt, PRL23, 880

[5] J.-D. Bancal, C. Branciard, N. Gisin, S. Pironio, PRL103, 090503 [6] J. Lawrence, PRA95, 042123

Alice:
$$\mathcal{M} = \{M_1^{i_1}, \cdots, M_k^{i_k}\}, \quad a = \{o_1^{i_1}, \cdots, o_k^{i_k}\}$$

Bob:
$$\mathcal{M}' = \{\Pi_{o|M}\}$$
: Set of projectors for Bob

W is unsteerable

$$F^{(n,k)}(W) \le R_{n-k} \equiv 2^{\frac{n-k-1}{2}}$$

(Also related to Joint Measurability)

A fully entangled state (GHZ state):

$$\left|\psi_{n}^{\theta}\right\rangle = \frac{1}{\sqrt{2}}\left(\left|00\cdots0\right\rangle + e^{i\theta}\left|11\cdots1\right\rangle\right)$$

The task function takes the maximum value, $F^{(n,k)}(\psi_n^{\theta}) = R_n$

I.h.s is evaluated for qutrit GHZ states

$$|\Psi_k\rangle = \frac{1}{\sqrt{3}} [|0\cdots 0\rangle + \alpha^k |1\cdots 1\rangle + \alpha^{2k} |2\cdots 2\rangle]$$

r.h.s (max.) is realized for a uniform distribution.

4.Conclusion

- We have considered EPR steering inequalities for multipartite case by using Bell-type operators.
- For a bipartition of multi-qubits, we find a rather simple task function that judges a given state is steerable or not.
- A generalization of multi-qutrit case is considered and the derived steering inequality is evaluated numerically.