"Relativistic Cosmology," YITP in Kyoto, 10th Sep 2014.

Cosmology in generalized Horndeski theories with second-order equations of motion

R. Kase and S. Tsujikawa, Phys.Rev. D90 (2014) 044073

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1. Introduction

Discovery of late-time cosmic acceleration

In 1998, the discovery of late-time cosmic acceleration based on Type Ia supernovae is reported. The source for this acceleration is named dark energy.





Planck+WP+SNLS

Planck+WP+BAO

Planck collaboration arXiv:1303.5076 [astro-ph.CO]

1. Introduction

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Dark energy problem may imply some modification of gravity on large scales.

Unified approach 1: Horndeski Lagrangians

$$\begin{split} L &= \sum_{i=2}^{5} L_i \\ L_2 &= G_2(\chi, Y), \\ L_3 &= G_3(\chi, Y) \Box \chi, \\ L_4 &= G_4(\chi, Y) R - 2G_{4,Y}(\chi, Y) \left[(\Box \chi)^2 - \chi^{;\mu\nu} \chi_{;\mu\nu} \right], \\ L_5 &= G_5(\chi, Y) G_{\mu\nu} \chi^{;\mu\nu} + \frac{1}{3} G_{5,Y}(\chi, Y) \times \text{(field derivatives)}, \\ \text{``;'' covariant derivative} \qquad Y &\equiv \chi_{;\mu} \chi^{;\mu} \qquad G_{i,Y} \equiv \partial G_i / \partial Y \end{split}$$

- •Quintessence and K–essence $G_2 = G_2(\chi, Y)$, $G_3 = 0$, $G_4 = M_{\rm pl}^2/2$, $G_5 = 0$.
- f(R) gravity and Brans–Dicke gravity $G_3 = 0$, $G_4 = F(\chi)$, $G_5 = 0$.
- •Galileon $G_2 = c_2 Y$, $G_3 = c_3/M^3$, $G_4 = M_{\rm pl}^2/2 + c_4 Y^2/M^6$, $G_5 = c_5 Y^2/M^9$.

Horndeski Lagrangians describe the most general scalar-tensor theory with **second-order** equations of motion on the **general** background.

Unified approach 2: Effective Field theory (EFT) on the cosmological background

J. Gleyzes, D. Langlois, F. Piazza, and F. Vernizzi, JCAP 1308, 025 (2013)



A scalar field χ associated with the modification of gravity is absorbed into the constant time hypersurfaces.

Unified approach 2: Effective Field theory (EFT) on the cosmological background

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Horndeski Lagrangians in the EFT language

$$G_{2}(\chi, Y) \to G_{2}(N, t) \quad \left(Y = -\dot{\chi}^{2}/N^{2}\right) \qquad n^{\mu} = -\chi_{;}^{\mu}/\sqrt{-Y}$$

$$G_{3}(\chi, X) \Box \chi \to 2(-Y)^{3/2} F_{3,Y} K - Y F_{3,\chi} \quad \left(G_{3} = F_{3} + 2Y F_{3,Y}\right)$$

$$\vdots \qquad \vdots$$

$$L = A_2(N,t) + A_3(N,t)K + A_4(N,t)(K^2 - S) + B_4(N,t)\mathcal{R} + A_5(N,t)K_3 + B_5(N,t)(\mathcal{U} - K\mathcal{R}/2), (K_3 = 3H(2H^2 - 2KH + K^2 - S) + O(3))$$

The Horndeski theory is a subclass of the EFT of modified gravity.

$$S = \int d^4x \sqrt{-g} L(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}; t)$$

 $K \equiv K^{\mu}{}_{\mu}, \quad \mathcal{S} \equiv K_{\mu\nu}K^{\mu\nu}, \quad \mathcal{R} \equiv \mathcal{R}^{\mu}{}_{\mu}, \quad \mathcal{Z} \equiv \mathcal{R}_{\mu\nu}\mathcal{R}^{\mu\nu}, \quad \mathcal{U} \equiv \mathcal{R}_{\mu\nu}K^{\mu\nu}.$

Horndeski Lagrangians in the EFT language

$$L = A_2(N,t) + A_3(N,t)K + A_4(N,t)(K^2 - S) + B_4(N,t)R + A_5(N,t)K_3 + B_5(N,t)(U - KR/2) ,$$
$$(K_3 = 3H(2H^2 - 2KH + K^2 - S) + O(3))$$

$$L_{4} = G_{4}(\chi, Y) R - 2G_{4,Y}(\chi, Y) [(\Box \chi)^{2} - \chi^{;\mu\nu} \chi_{;\mu\nu}] ,$$

$$L_{5} = G_{5}(\chi, Y) G_{\mu\nu} \chi^{;\mu\nu} + \frac{1}{3} G_{5,Y}(\chi, Y) \times \text{(field derivatives)} ,$$

In the case of Horndeski theories there are the following relations:

$$A_4 = 2YB_{4Y} - B_4, \quad A_5 = -YB_{5Y}/3.$$

Generalized Horndeski theories

$$L = A_2(N, t) + A_3(N, t)K + A_4(N, t)(K^2 - S) + B_4(N, t)\mathcal{R} + A_5(N, t)K_3 + B_5(N, t)(\mathcal{U} - K\mathcal{R}/2), (K_3 = 3H(2H^2 - 2KH + K^2 - S) + O(3))$$

Gleyzes, Langlois, Piazza, and Vernizzi (GLPV) generalized Horndeski theory in such a way that the coefficients A_4 , A_5 , B_4 , B_5 are not necessarily related to each other. J. Gleyzes, D. Langlois, F. Piazza and F. Vernizzi, arXiv:1404.6495

A_4 , A_5 , B_4 , B_5 : arbitrary functions

Generalized Horndeski theories

$$L = A_2(N, t) + A_3(N, t)K + A_4(N, t)(K^2 - S) + B_4(N, t)\mathcal{R} + A_5(N, t)K_3 + B_5(N, t)(\mathcal{U} - K\mathcal{R}/2), (K_3 = 3H(2H^2 - 2KH + K^2 - S) + O(3))$$

Although GLPV theories go beyond the Horndeski domain,

the number of physical degrees of freedom is same as Horndeski theories.



It is not trivial whether the screening mechanism works sufficiently or not compared to the Horndeski theory.



Kobayashi-san's talk!

Once we go beyond the Horndeski domain, non-trivial modifications to all the propagation speeds of DE/matter fields.

L. Gergely and S. Tsujikawa Phys. Rev. D89 (2014) 064059

2. Background EOMs and GLPV theories

$$\begin{split} S &= \int d^4 x \sqrt{-g} \left[L(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}; t) + \sum_{I=1}^{N-1} P^{(I)}(X_I) \right] \\ ds^2 &= -N^2 dt^2 + h_{ab} (dx^a + N^a dt) (dx^b + N^b dt) \\ \mathbf{BG}: \ \bar{N} = 1 \,, \quad \bar{N}^i = 0 \,, \quad \bar{h}_{ij} = a^2(t) \delta_{ij} \,. \end{split}$$

 $\sum_{I=1}^{N-1} P^{(I)}(X_I)$: in order to model perfect fluids of matter components

Expanding the Lagrangian up to linear order as

e.g.
$$L_N = \partial L / \partial N$$

 $L = \bar{L} + L_N \delta N + L_K \delta K + L_S \delta S + L_R \delta R + L_Z \delta Z + L_U \delta U + \mathcal{O}(2)$

using $K_{ij} = \left(\partial_t h_{ij} - \nabla_i N_j - \nabla_j N_i\right) / (2N)$ with 3D covariant derivative ∇_i

$$S = \int d^4x \sqrt{-\bar{g}} \left[\mathcal{E}^N \delta N + \mathcal{E}^h \delta \sqrt{h} \right]$$

2. Background EOMs and GLPV theories

$$\begin{split} S &= \int d^4 x \sqrt{-g} \left[L(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}; t) + \sum_{I=1}^{N-1} P^{(I)}(X_I) \right] \\ &ds^2 = -N^2 dt^2 + h_{ab} (dx^a + N^a dt) (dx^b + N^b dt) \\ &\mathbf{BG:} \ \bar{N} = 1 \,, \quad \bar{N}^i = 0 \,, \quad \bar{h}_{ij} = a^2(t) \delta_{ij} \,. \end{split}$$

Then the BG EOMs follow as

$$\mathcal{E}^N = 0 \to \bar{L} + L_N - 3H\mathcal{F} = \rho_M$$
$$\mathcal{E}^h = 0 \to \bar{L} - \dot{\mathcal{F}} - 3H\mathcal{F} = -P_M$$

$$\left(\mathcal{F} \equiv L_K + 2HL_{\mathcal{S}}, \quad \rho_M = \sum_{I=1}^{N-1} \left[2X_I P_{X_I}^{(I)} - P^{(I)} \right], \quad P_M = \sum_{I=1}^{N-1} P^{(I)} \right)$$

2. Background EOMs and GLPV theories

$$\begin{split} S &= \int d^4 x \sqrt{-g} \left[L(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}; t) + \sum_{I=1}^{N-1} P^{(I)}(X_I) \right] \\ &ds^2 = -N^2 dt^2 + h_{ab} (dx^a + N^a dt) (dx^b + N^b dt) \\ &\mathbf{BG:} \ \bar{N} = 1 \,, \quad \bar{N}^i = 0 \,, \quad \bar{h}_{ij} = a^2(t) \delta_{ij} \,. \end{split}$$

Applying to the GLPV theories,

$$L = A_2 + A_3 K + A_4 (K^2 - S) + B_4 \mathcal{R} + A_5 K_3 + B_5 (\mathcal{U} - K \mathcal{R}/2) ,$$

 $A_2 - 6H^2A_4 - 12H^3A_5 + 2\dot{\chi}^2 \left(A_{2Y} + 3HA_{3Y} + 6H^2A_{4Y} + 6H^3A_{5Y}\right) = \rho_M,$ $A_2 - 6H^2A_4 - 12H^3A_5 - \dot{A}_3 - 4\dot{H}A_4 - 4H\dot{A}_4 - 12H\dot{H}A_5 - 6H^2\dot{A}_5 = -P_M.$

$$\mathcal{F} \equiv L_K + 2HL_S, \quad \rho_M = \sum_{I=1}^{N-1} \left[2X_I P_{X_I}^{(I)} - P^{(I)} \right], \quad P_M = \sum_{I=1}^{N-1} P^{(I)} \right)$$

$$S = \int d^4x \sqrt{-g} \left[L(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}; t) + \sum_{I=1}^{N-1} P^{(I)}(X_I) \right]$$
$$ds^2 = -N^2 dt^2 + h_{ab} (dx^a + N^a dt) (dx^b + N^b dt)$$
$$N = 1 + \delta N, \quad N_i = \partial_i \psi \equiv \partial \psi / \partial x^i ,$$
$$h_{ij} = a^2(t) e^{2\zeta} \hat{h}_{ij} , \quad \hat{h}_{ij} = \delta_{ij} + \gamma_{ij} + \gamma_{il} \gamma_{lj} / 2 , \quad \det \hat{h} = 1 .$$

Expanding the Lagrangian up to second order as

$$L = \overline{L} + L_N \delta N + L_K \delta K + L_S \delta S + L_R \delta R + L_Z \delta Z + L_U \delta U + \frac{1}{2} \left(\delta N \frac{\partial}{\partial N} + \delta K \frac{\partial}{\partial K} + \delta S \frac{\partial}{\partial S} + \delta R \frac{\partial}{\partial R} + \delta U \frac{\partial}{\partial U} \right)^2 L + O(3),$$

using $K_{ij} = \left(\partial_t h_{ij} - \nabla_i N_j - \nabla_j N_i\right) / (2N)$ and integrating by parts...

$$S = \int d^4x \sqrt{-g} \left[L(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}; t) + \sum_{I=1}^{N-1} P^{(I)}(X_I) \right]$$
$$ds^2 = -N^2 dt^2 + h_{ab} (dx^a + N^a dt) (dx^b + N^b dt)$$
$$N = 1 + \delta N, \quad N_i = \partial_i \psi \equiv \partial \psi / \partial x^i,$$
$$h_{ij} = a^2(t) e^{2\zeta} \hat{h}_{ij}, \quad \hat{h}_{ij} = \delta_{ij} + \gamma_{ij} + \gamma_{il} \gamma_{lj} / 2, \quad \det \hat{h} = 1.$$

$$\begin{aligned} \mathcal{L}_{2} &= a^{3} \bigg\{ \frac{1}{2} (2L_{N} + L_{NN} - 6HW + 12H^{2}L_{S})\delta N^{2} + \bigg[\mathcal{W} \left(3\dot{\zeta} - \frac{\partial^{2}\psi}{a^{2}} \right) - 4(\mathcal{D} + \mathcal{E}) \frac{\partial^{2}\zeta}{a^{2}} \bigg] \delta N \\ &+ 4L_{S} \dot{\zeta} \frac{\partial^{2}\psi}{a^{2}} - 6L_{S} \dot{\zeta}^{2} + 2\mathcal{E} \frac{(\partial\zeta)^{2}}{a^{2}} + \sum_{I=1}^{N-1} \bigg[(2\dot{\phi}_{I}^{2}P_{X_{I}X_{I}}^{(I)} - P_{X_{I}}^{(I)}) (\dot{\phi}_{I}^{2}\delta N^{2} - 2\dot{\phi}_{I}\dot{\delta\phi}_{I}\delta N + \dot{\delta\phi}_{I}^{2}) \\ &- 6\dot{\phi}_{I} P_{X_{I}}^{(I)} \zeta \dot{\delta\phi}_{I} - 2\dot{\phi}_{I} P_{X_{I}}^{(I)} \delta\phi_{I} \frac{\partial^{2}\psi}{a^{2}} + P_{X_{I}}^{(I)} \frac{(\partial\delta\phi_{I})^{2}}{a^{2}} \bigg] \bigg\}, \end{aligned}$$

Varying this Lagrangian density with respect to δN and $\partial^2 \psi$, we obtain the Hamiltonian and momentum constraints. Inserting them back...

$$\mathcal{L}_2 = a^3 \left(\dot{\vec{\mathcal{X}}^t} \mathbf{K} \dot{\vec{\mathcal{X}}} - \frac{1}{a^2} \partial_j \vec{\mathcal{X}}^t \mathbf{G} \partial_j \vec{\mathcal{X}} - \vec{\mathcal{X}}^t \mathbf{B} \dot{\vec{\mathcal{X}}} - \vec{\mathcal{X}}^t \mathbf{M} \vec{\mathcal{X}} \right) ,$$
$$\vec{\mathcal{X}}^t = \left(\zeta, \delta \phi_1 / M_{\rm pl}, \cdots, \delta \phi_{N-1} / M_{\rm pl} \right) .$$

No-ghost conditions

In order to avoid ghost instabilities, the matrix $oldsymbol{K}$ must be positive definite.

Under the tensor no-ghost condition, $L_{S} > 0$, it follows that...

$$K_{11} = \frac{2L_{\mathcal{S}}}{\mathcal{W}^2} \left(g_2 + \frac{8L_{\mathcal{S}}}{M_{\rm pl}^2} \sum_{I=2}^N \dot{\phi}_{I-1}^2 K_{II} \right),$$

$$K_{II} = \left[2\dot{\phi}_{I-1}^2 P_{X_{I-1}X_{I-1}}^{(I-1)} - P_{X_{I-1}}^{(I-1)} \right] M_{\rm pl}^2,$$

$$K_{1I} = K_{I1} = -\frac{4L_{\mathcal{S}}\dot{\phi}_{I-1}}{M_{\rm pl}\mathcal{W}} K_{II},$$

$$g_2 = 4L_{\mathcal{S}}(2L_N + L_{NN}) + 3(L_{KN} + 2HL_{\mathcal{S}N})^2 > 0,$$

$$2\dot{\phi}_I^2 P_{X_I X_I}^{(I)} - P_{X_I}^{(I)} > 0 \qquad (I = 1, 2, \cdots, N - 1).$$

$$\mathcal{L}_2 = a^3 \left(\dot{\vec{\mathcal{X}}^t} \mathbf{K} \dot{\vec{\mathcal{X}}^t} - \frac{1}{a^2} \partial_j \vec{\mathcal{X}}^t \mathbf{G} \partial_j \vec{\mathcal{X}} - \vec{\mathcal{X}}^t \mathbf{B} \dot{\vec{\mathcal{X}}^t} - \vec{\mathcal{X}}^t \mathbf{M} \vec{\mathcal{X}} \right) ,$$
$$\vec{\mathcal{X}}^t = \left(\zeta, \delta \phi_1 / M_{\rm pl}, \cdots, \delta \phi_{N-1} / M_{\rm pl} \right) .$$

Propagation speeds

In the limit of a large wave number, $det (\omega^2 K - k^2 G/a^2) = 0$. Introducing the scalar sound speed $\omega^2 = c_s^2 k^2/a^2$, it follows that

$$\begin{split} \prod_{I=1}^{N} \left(c_s^2 - c_{s\mathrm{H}I}^2 \right) &= -\frac{8L_{\mathcal{S}}}{g_2} \left(\frac{\mathcal{C}_3 \mathcal{W}}{16L_{\mathcal{S}}^2} + 1 \right) \times \\ & \sum_{I=2}^{N} \left[\dot{\phi}_{I-1}^2 P_{X_{I-1}}^{(I-1)} \left\{ 2c_s^2 + c_{s\mathrm{H}I}^2 \left(\frac{\mathcal{C}_3 \mathcal{W}}{16L_{\mathcal{S}}^2} - 1 \right) \right\} \prod_{J \neq I, J \geq 2}^{N} (c_s^2 - c_{s\mathrm{H}J}^2) \right], \\ \text{where,} \\ & c_{s\mathrm{H}1}^2 = \frac{\mathcal{W}^2}{2L_{\mathcal{S}}g_2} \left[G_{11} + \frac{16L_{\mathcal{S}}^2}{\mathcal{W}^2} \sum_{I=2}^{N} \dot{\phi}_{I-1}^2 P_{X_{I-1}}^{(I-1)} \right], \quad c_{s\mathrm{H}I}^2 = \frac{P_{X_{I-1}}^{(I-1)}}{P_{X_{I-1}}^{(I-1)} - 2\dot{\phi}_{I-1}^2 P_{X_{I-1}X_{I-1}}^{(I-1)}}. \end{split}$$

$$\mathcal{L}_2 = a^3 \left(\dot{\vec{\mathcal{X}}^t} \mathbf{K} \dot{\vec{\mathcal{X}}} - \frac{1}{a^2} \partial_j \vec{\mathcal{X}}^t \mathbf{G} \partial_j \vec{\mathcal{X}} - \vec{\mathcal{X}}^t \mathbf{B} \dot{\vec{\mathcal{X}}} - \vec{\mathcal{X}}^t \mathbf{M} \vec{\mathcal{X}} \right) ,$$
$$\vec{\mathcal{X}}^t = \left(\zeta, \delta \phi_1 / M_{\rm pl}, \cdots, \delta \phi_{N-1} / M_{\rm pl} \right) .$$

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$$\begin{split} \prod_{I=1}^{N} \left(c_{s}^{2} - c_{s\mathrm{H}I}^{2} \right) &= -\frac{8L_{\mathcal{S}}}{g_{2}} \left(\frac{\mathcal{C}_{3}\mathcal{W}}{16L_{\mathcal{S}}^{2}} + 1 \right) \times \\ \sum_{I=2}^{N} \left[\dot{\phi}_{I-1}^{2} P_{X_{I-1}}^{(I-1)} \left\{ 2c_{s}^{2} + c_{s\mathrm{H}I}^{2} \left(\frac{\mathcal{C}_{3}\mathcal{W}}{16L_{\mathcal{S}}^{2}} - 1 \right) \right\} \prod_{J \neq I, J \geq 2}^{N} (c_{s}^{2} - c_{s\mathrm{H}J}^{2}) \right], \\ \text{where,} \\ c_{s\mathrm{H}1}^{2} &= \frac{\mathcal{W}^{2}}{2L_{\mathcal{S}}g_{2}} \left[G_{11} + \frac{16L_{\mathcal{S}}^{2}}{\mathcal{W}^{2}} \sum_{I=2}^{N} \dot{\phi}_{I-1}^{2} P_{X_{I-1}}^{(I-1)} \right], \quad c_{s\mathrm{H}I}^{2} &= \frac{P_{X_{I-1}}^{(I-1)}}{P_{X_{I-1}}^{(I-1)} - 2\dot{\phi}_{I-1}^{2} P_{X_{I-1}}^{(I-1)}}. \end{split}$$

$$\mathcal{L}_2 = a^3 \left(\dot{\vec{\mathcal{X}}^t} \mathbf{K} \dot{\vec{\mathcal{X}}^t} - \frac{1}{a^2} \partial_j \vec{\mathcal{X}}^t \mathbf{G} \partial_j \vec{\mathcal{X}} - \vec{\mathcal{X}}^t \mathbf{B} \dot{\vec{\mathcal{X}}^t} - \vec{\mathcal{X}}^t \mathbf{M} \vec{\mathcal{X}} \right) ,$$
$$\vec{\mathcal{X}}^t = \left(\zeta, \delta \phi_1 / M_{\rm pl}, \cdots, \delta \phi_{N-1} / M_{\rm pl} \right) .$$

Propagation speeds

In the limit of a large wave number, $det (\omega^2 K - k^2 G/a^2) = 0$. Introducing the scalar sound speed $\omega^2 = c_s^2 k^2/a^2$, it follows that

If the deviation from the Horndeski domain is small...

$$\begin{aligned} \mathcal{C}_{3} &= \mathcal{C}_{3}^{\mathrm{H}} \left(1 + \delta \mathcal{C}_{3} \right) \,, \quad c_{s1}^{2} = c_{s\mathrm{H}1}^{2} + \delta c_{s1}^{2} \,, \quad c_{sI}^{2} = c_{s\mathrm{H}I}^{2} + \delta c_{sI}^{2} \,, \quad (I = 2, 3, \cdots, N) \,. \\ \delta c_{s1}^{2} &\simeq \sum_{I=2}^{N} \xi_{I-1} \,\delta \mathcal{C}_{3} \,\, \left(\xi_{I} \equiv \frac{16L_{\mathcal{S}} \dot{\phi}_{I}^{2} P_{X_{I}}^{(I)}}{g_{2}} \right) \,, \\ \delta c_{sI}^{2} &\simeq -\frac{c_{s\mathrm{H}I}^{2}}{2(c_{s\mathrm{H}I}^{2} - c_{s\mathrm{H}1}^{2} - \delta c_{s1}^{2})} \xi_{I-1} \delta \mathcal{C}_{3}^{2} \,\, (I = 2, 3, \cdots, N) \,. \end{aligned}$$

$$\mathcal{L}_2 = a^3 \left(\dot{\vec{\mathcal{X}}^t} \mathbf{K} \dot{\vec{\mathcal{X}}} - \frac{1}{a^2} \partial_j \vec{\mathcal{X}}^t \mathbf{G} \partial_j \vec{\mathcal{X}} - \vec{\mathcal{X}}^t \mathbf{B} \dot{\vec{\mathcal{X}}} - \vec{\mathcal{X}}^t \mathbf{M} \vec{\mathcal{X}} \right) ,$$
$$\vec{\mathcal{X}}^t = \left(\zeta, \delta \phi_1 / M_{\rm pl}, \cdots, \delta \phi_{N-1} / M_{\rm pl} \right) .$$

Propagation speeds

In the limit of a large wave number, $det (\omega^2 K - k^2 G/a^2) = 0$. Introducing the scalar sound speed $\omega^2 = c_s^2 k^2/a^2$, it follows that

As we will see later $\xi_{I-1} \gg 1$, $\delta C_3 \ll 1$ realize for the covariantized version of Galileon model.

$$\delta c_{s1}^2 \simeq \sum_{I=2}^N \xi_{I-1} \, \delta \mathcal{C}_3 \sim \mathcal{O}(1) \,,$$

$$\delta c_{sI}^2 \simeq -\frac{c_{sHI}^2}{2(c_{sHI}^2 - c_{sH1}^2 - \delta c_{s1}^2)} \xi_{I-1} \delta \mathcal{C}_3^2 \ll 1 \,.$$

 $L = A_2 + A_3 K + A_4 (K^2 - S) + B_4 R + A_5 K_3 + B_5 (U - K R/2) ,$

(A) Covariant Galileon

A. Nicolis, R. Rattazzi, E. Tricherini (2009)C. Deffayet, G. Esposito-Farese, A. Vikman (2009)

$$A_{2} = \frac{c_{2}}{2}Y, \quad A_{3} = \frac{c_{3}}{3M^{3}}(-Y)^{3/2}, \quad A_{4} = -\frac{M_{\rm pl}^{2}}{2} - \frac{3c_{4}}{4M^{6}}Y^{2}, \quad A_{5} = \frac{c_{5}}{2M^{9}}(-Y)^{5/2},$$
$$B_{4} = \frac{M_{\rm pl}^{2}}{2} - \frac{c_{4}}{4M^{6}}Y^{2}, \quad B_{5} = -\frac{3c_{5}}{5M^{9}}(-Y)^{5/2}.$$

(B) Covariantized Galileon

The covariantized version of the Minkowski Galileon obtained by replacing partial derivatives with covariant derivatives (outside the Horndeski domain). Adding the Einstein-Hilbert term it follows that

$$A_{2} = \frac{c_{2}}{2}Y, \quad A_{3} = \frac{c_{3}}{3M^{3}}(-Y)^{3/2}, \quad A_{4} = -\frac{M_{\rm pl}^{2}}{2} - \frac{3c_{4}}{4M^{6}}Y^{2}, \quad A_{5} = \frac{c_{5}}{2M^{9}}(-Y)^{5/2},$$
$$B_{4} = \frac{M_{\rm pl}^{2}}{2}, \quad B_{5} = 0.$$

 $L = A_2 + A_3 K + A_4 (K^2 - S) + B_4 R + A_5 K_3 + B_5 (U - K R/2) ,$

(A) Covariant Galileon

A. Nicolis, R. Rattazzi, E. Tricherini (2009)C. Deffayet, G. Esposito-Farese, A. Vikman (2009)

$$A_{2} = \frac{c_{2}}{2}Y, \quad A_{3} = \frac{c_{3}}{3M^{3}}(-Y)^{3/2}, \quad A_{4} = -\frac{M_{\text{pl}}^{2}}{2} - \frac{3c_{4}}{4M^{6}}Y^{2}, \quad A_{5} = \frac{c_{5}}{2M^{9}}(-Y)^{5/2},$$

$$B_{4} = \frac{M_{\text{pl}}^{2}}{2} - \frac{c_{4}}{4M^{6}}Y^{2}, \quad B_{5} = -\frac{3c_{5}}{5M^{9}}(-Y)^{5/2}.$$
Since $\bar{\mathcal{R}}_{\mu\nu} = 0$, these two models cannot be distinguished at the BG level.

The covariantized version of the Minkowski Galileon obtained by replacing partial derivatives with covariant derivatives (outside the Horndeski domain). Adding the Einstein-Hilbert term it follows that

$$A_{2} = \frac{c_{2}}{2}Y, \quad A_{3} = \frac{c_{3}}{3M^{3}}(-Y)^{3/2}, \quad A_{4} = -\frac{M_{\rm pl}^{2}}{2} - \frac{3c_{4}}{4M^{6}}Y^{2}, \quad A_{5} = \frac{c_{5}}{2M^{9}}(-Y)^{5/2},$$
$$B_{4} = \frac{M_{\rm pl}^{2}}{2}, \quad B_{5} = 0.$$

$$\begin{split} 3M_{\rm pl}^2H^2 &= \rho_{\rm DE} + \rho_M \;, \\ 3M_{\rm pl}^2H^2 + 2M_{\rm pl}^2\dot{H} = -P_{\rm DE} - P_M \;, \\ \rho_{\rm DE} &= -\frac{1}{2}c_2\dot{\chi}^2 + \frac{3c_3H\dot{\chi}^3}{M^3} - \frac{45c_4H^2\dot{\chi}^4}{2M^6} + \frac{21c_5H^3\dot{\chi}^5}{M^9} \;, \\ P_{\rm DE} &= -\frac{1}{2}c_2\dot{\chi}^2 - \frac{c_3\dot{\chi}^2\ddot{\chi}}{M^3} + \frac{3c_4\dot{\chi}^3}{2M^6} \left[8H\ddot{\chi} + (3H^2 + 2\dot{H})\dot{\chi} \right] - \frac{3c_5H\dot{\chi}^4}{M^9} \left[5H\ddot{\chi} + 2(H^2 + \dot{H})\dot{\chi} \right] \;. \end{split}$$

Matter components



BG evolution

$$r_1 \equiv \frac{\dot{\chi}_{\rm dS} H_{\rm dS}}{\dot{\chi} H}, \quad r_2 \equiv \frac{H}{H_{\rm dS}} \left(\frac{\dot{\chi}}{\dot{\chi}_{\rm dS}}\right)^5,$$

- There is the dS point at $r_1 = r_2 = 1$.
- The tracker solution $(r_1 = 1)$ is in tension with the observational data.
- The late-time tracking solution $(r_1^{\text{ini}} \ll 1)$ is consistent with the observational data.



S. Nesseris, A. De Felice and S. Tsujikawa, Phys. Rev. D 82, 124054 (2010)

Evolution of the propagation speed along the late-time tracking

(A) Covariant Galileon

$$c_{s1}^{2} = \begin{cases} \frac{1}{40} (\Omega_{r} + 1) & [(i) \ r_{1} \ll 1, \ r_{2} \ll 1], \\ \frac{8 + 10\alpha - 9\beta + \Omega_{r}(2 + 3\alpha - 3\beta)}{3(2 - 3\alpha + 6\beta)} & [(ii) \ r_{1} = 1, \ r_{2} \ll 1], \\ \frac{(\alpha - 2\beta)(4 + 15\alpha^{2} - 48\alpha\beta + 36\beta^{2})}{2(2 + 3\alpha - 6\beta)(2 - 3\alpha + 6\beta)} & [(iii) \ r_{1} = 1, \ r_{2} = 1]. \end{cases}$$

Under the no-ghost conditions,

$$L_{S} > 0 \qquad \qquad \beta > 0 \qquad \qquad c_{2}x_{dS}^{2} = 6 + 9\alpha - 12\beta \\ -2 < 3(\alpha - 2\beta) < 2 \qquad c_{3}x_{dS}^{3} = 2 + 9\alpha - 9\beta$$

the above propagation speed of sound is positive in any regime.

A. De Felice and S. Tsujikawa, Phys. Rev. Lett. 105, 111301 (2010)

Evolution of the propagation speed along the late-time tracking

(B) Covariantized Galileon

$$c_{s1}^{2} = \begin{cases} \frac{1}{40} (3\Omega_{r} - 1) & [(i) \ r_{1} \ll 1, \ r_{2} \ll 1], \\ \frac{16 - 15(\alpha - 2\beta) + \Omega_{r}(4 - 3\alpha + 6\beta)}{6(2 - 3\alpha + 6\beta)} & [(ii) \ r_{1} = 1, \ r_{2} \ll 1], \\ \frac{\alpha - 2\beta}{2 + 3\alpha - 6\beta} & [(iii) \ r_{1} = 1, \ r_{2} = 1]. \end{cases}$$

In the regime (i), the propagation speed become negative during the matter dominated epoch!!

• Evolution of the propagation speed along the late-time tracking

(B) Covariantized Galileon



In order to include the Horava gravity and its extension in the EFT framework, we need to add extra terms to the EFT Lagrangian as a essential building block.



X. Gao arXiv:1406.0822

• Projectable Horava–Lifshitz gravity ($\delta N = 0$)

$$L = \frac{M_{\rm pl}^2}{2} \left[\mathcal{S} - \lambda K^2 + \mathcal{R} - M_{\rm pl}^{-2} \left(g_2 \mathcal{R}^2 + g_3 \mathcal{Z} \right) - M_{\rm pl}^{-4} \left(g_4 \mathcal{Z}_1 + g_5 \mathcal{Z}_2 \right) \right] \\ \left(\mathcal{Z} \equiv \mathcal{R}_{\mu\nu} \mathcal{R}^{\mu\nu} , \quad \mathcal{Z}_1 \equiv \nabla_i \mathcal{R} \nabla^i \mathcal{R} , \quad \mathcal{Z}_2 \equiv \nabla_i \mathcal{R}_{jk} \nabla^i \mathcal{R}^{jk} \right)$$

The terms \mathcal{Z}_1 , \mathcal{Z}_2 allow the z = 3 scaling characterized by the transformation $t \to c^3 t$ and $x^i \to cx^i$.

The theory is power-counting renormalizable.

However, in this theory, the no-ghost condition and the condition to avoid a Laplacian instability cannot be satisfied at the same time. Moreover there is the strong coupling problem in the deep IR regime.

In order to include the Horava gravity and its extension in the EFT framework, we need to add extra terms to the EFT Lagrangian as a essential building block.

D. Blas, O. Pujolas and S. Sibiryakov, (2010)

X. Gao arXiv:1406.0822

Gao's talk!

• Non-projectable Horava-Lifshitz gravity ($\delta N \neq 0$)

In the non-projectable extended version of the Horava gravity, the acceleration vector $a_{\nu} = n^{\lambda}n_{\nu;\lambda} = \nabla_{\nu}\ln N$ does not vanish. In this case one can consider the Lagrangian

$$\begin{split} L_{\mathcal{V}_3} &= -\frac{1}{2M_{\rm pl}^2} \left(g_4 \mathcal{Z}_1 + g_5 \mathcal{Z}_2 + \eta_4 \alpha_4 + \eta_5 \alpha_5 + \cdots \right) \,, \\ L_{\mathcal{V}_2} &= -\frac{1}{2} \left(g_2 \mathcal{R}^2 + g_3 \mathcal{Z} + \eta_2 \alpha_2 + \eta_3 \alpha_3 + \cdots \right) \,, \\ L_{\mathcal{V}_1} &= \frac{M_{\rm pl}^2}{2} \left(\mathcal{R} + \eta_1 \alpha_1 \right) \,, \quad \begin{array}{l} \alpha_1 \equiv a_i a^i \,, \quad \alpha_2 \equiv a_i \Delta a^i \,, \quad \alpha_3 \equiv \mathcal{R} \nabla_i a^i \,, \\ \alpha_4 \equiv a_i \Delta^2 a^i \,, \quad \alpha_5 \equiv \Delta \mathcal{R} \nabla_i a^i \,, \end{array}$$

 $L_{\mathcal{V}_3}$, $L_{\mathcal{V}_2}$, $L_{\mathcal{V}_1}$ are invariant under z = 3, 2, 1 rescaling, respectively.

$$S = \int d^4x \sqrt{-g} L\left(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}, \mathcal{Z}_1, \mathcal{Z}_2, \alpha_1, \cdots, \alpha_5; t\right)$$

RK and S. Tsujikawa, arXiv:1409.1984

$$K \equiv K^{\mu}{}_{\mu}, \quad \mathcal{S} \equiv K_{\mu\nu}K^{\mu\nu}, \quad \mathcal{R} \equiv \mathcal{R}^{\mu}{}_{\mu}, \quad \mathcal{Z} \equiv \mathcal{R}_{\mu\nu}\mathcal{R}^{\mu\nu}, \\ \mathcal{U} \equiv \mathcal{R}_{\mu\nu}K^{\mu\nu}, \mathcal{Z}_{1} \equiv \nabla_{i}\mathcal{R}\nabla^{i}\mathcal{R}, \quad \mathcal{Z}_{2} \equiv \nabla_{i}\mathcal{R}_{jk}\nabla^{i}\mathcal{R}^{jk}, \\ \alpha_{1} \equiv a_{i}a^{i}, \quad \alpha_{2} \equiv a_{i}\Delta a^{i}, \quad \alpha_{3} \equiv \mathcal{R}\nabla_{i}a^{i}, \quad \alpha_{4} \equiv a_{i}\Delta^{2}a^{i}, \quad \alpha_{5} \equiv \Delta\mathcal{R}\nabla_{i}a^{i}, \end{cases}$$

Other terms such, e.g. $\mathcal{R}_i^j \mathcal{R}_j^k \mathcal{R}_k^i$, can be taken into account, but they are irrelevant to scalar linear perturbations on the flat FLRW background.

$$S = \int d^4x \sqrt{-g} L(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}, \mathcal{Z}_1, \mathcal{Z}_2, \alpha_1, \cdots, \alpha_5; t)$$

RK and S. Tsujikawa, arXiv:1409.1984

Expanding the EFT Lagrangian up to second order, we derived

- BG EOMs,
- EOMs for linear perturbations,
- stability conditions.

We also applied our general results to

- Horndeski theories,
- GLPV theories,
- Projectable Horava-Lifshitz gravity,
- Non-projectable Horava-Lifshitz gravity.

$$S = \int d^4x \sqrt{-g} L\left(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}, \mathcal{Z}_1, \mathcal{Z}_2, \alpha_1, \cdots, \alpha_5; t\right)$$

RK and S. Tsujikawa, arXiv:1409.1984

• Projectable Horava–Lifshitz gravity ($\delta N = 0$)

$$L = \frac{M_{\rm pl}^2}{2} \left[\mathcal{S} - \lambda K^2 + \mathcal{R} - M_{\rm pl}^{-2} \left(g_2 \mathcal{R}^2 + g_3 \mathcal{Z} \right) - M_{\rm pl}^{-4} \left(g_4 \mathcal{Z}_1 + g_5 \mathcal{Z}_2 \right) \right]$$

$$\mathcal{L}_2 = M_{\rm pl}^2 a^3 \left(\frac{3\lambda - 1}{\lambda - 1} \dot{\zeta}^2 - \zeta \mathcal{O}\zeta \right)$$

 $\mathcal{O} \equiv \Delta + \frac{\Delta^2}{M_2^2} - \frac{\Delta^3}{M_3^4}, \quad \Delta \equiv \nabla^i \nabla_i, \quad M_2^2 \equiv M_{\rm pl}^2 (8g_2 + 3g_3)^{-1}, \quad M_3^4 \equiv M_{\rm pl}^4 (8g_4 + 3g_5)^{-1}.$

which coincides with the results in K. Koyama and F. Arroja, JHEP 1003, 061 (2010), S. Mukohyama, Class. Quant. Grav. 27, 223101 (2010).

$$S = \int d^4x \sqrt{-g} L\left(N, K, \mathcal{S}, \mathcal{R}, \mathcal{Z}, \mathcal{U}, \mathcal{Z}_1, \mathcal{Z}_2, \alpha_1, \cdots, \alpha_5; t\right)$$

RK and S. Tsujikawa, arXiv:1409.1984

• Non-projectable Horava-Lifshitz gravity $\delta N \neq 0$

$$L = \frac{M_{\rm pl}^2}{2} \left[\mathcal{S} - \lambda K^2 + \mathcal{R} + \eta_1 \alpha_1 - M_{\rm pl}^{-2} \left(g_2 \mathcal{R}^2 + g_3 \mathcal{Z} + \eta_2 \alpha_2 + \eta_3 \alpha_3 \right) - M_{\rm pl}^{-4} \left(g_4 \mathcal{Z}_1 + g_5 \mathcal{Z}_2 + \eta_4 \alpha_4 + \eta_5 \alpha_5 \right) \right]$$

In the IR regime, on the Minkowski BG,

$$\mathcal{L}_2 = M_{\rm pl}^2 \frac{3\lambda - 1}{\lambda - 1} \left[\dot{\zeta}^2 - c_s^2 (\partial \zeta)^2 \right] \quad \left(c_s^2 = \frac{\lambda - 1}{3\lambda - 1} \frac{2 - \eta_1}{\eta_1} \right)$$

which coincides with the results in D. Blas, O. Pujolas and S. Sibiryakov, Phys. Rev. Lett. 104, 181302 (2010)

5. Conclusions

- We studied the cosmology of an extended version of Horndeski theories with second-order equations of motion on the flat FLRW background in the presence of multiple scalar fields associated with matter fluids.
- Expanding the action up to second order, we derived the background equations of motion, equations of motion for linear perturbations and stability conditions.
- Although the Background dynamics in Horndeski theories and GLPV theories are same, they can be distinguished at the perturbation level.
- The theories beyond Horndeski induce non-trivial modifications to all the propagation speeds of N scalar fields.
- We applied our general results to the covariant Galileon (a class of Horndeski theories) and the *covariantized* Galileon model (a class of GLPV theories).
 We showed that the propagation speed of the dark energy field become negative during the matter dominated epoch in the latter model.