

A framework for crossover of scaling law using a self-similar solution : dynamical impact of the solid sphere onto the viscoelastic PDMS board.

Hirokazu Maruoka

Deep-Sea Nanoscience Research Group,
Research Center for Bioscience and Nanoscience,
Research Institute for Marine Resource Utilization,
Japan Agency for Marine-Earth Science and Technology (JAMSTEC)
2-15 Natsushima-cho, Yokosuka, Kanagawa 237-0061, Japan
e-mail : maruokah@jamstec.go.jp
TEL : +81-46-867-9422

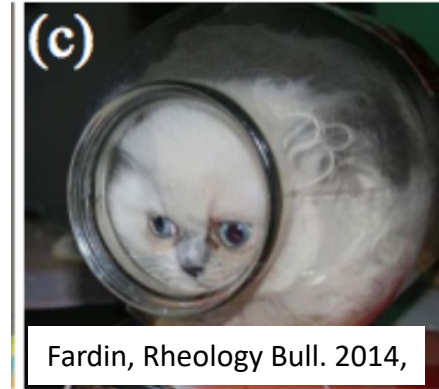
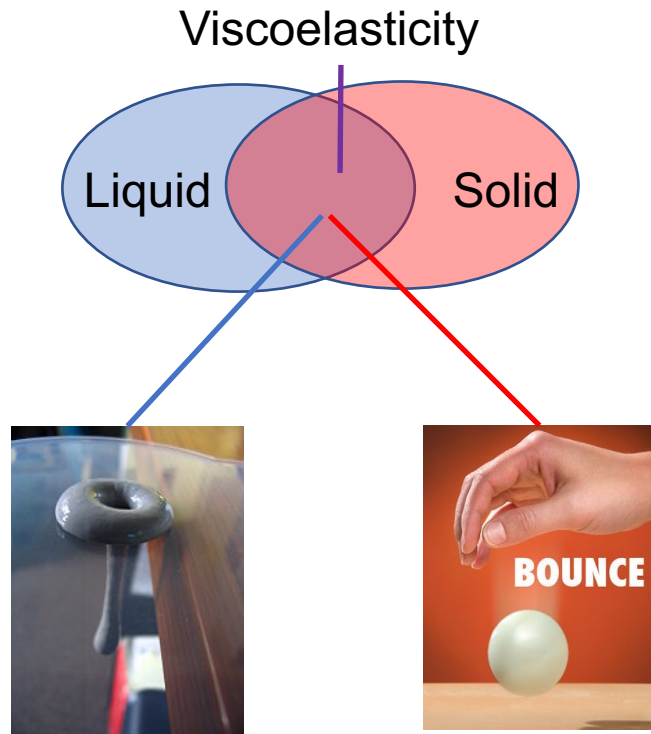


2022/11/01

<https://arxiv.org/abs/2203.00253>

Soft matter : Mixed physical property, Scale-locality.

- **Mixed** physical property



- **Scale-local** behavior



$$\frac{dV}{dT} = \begin{cases} 0 & (\text{De} \gg 1) \\ \frac{\pi d^4 \rho g}{128 \mu} \left(1 + \frac{h}{l}\right) & (\text{De} \sim 1). \end{cases}$$

Parnell, T. *et al.* Eur.J.Phys. (1984)

Time scale 

Crossover of scaling law

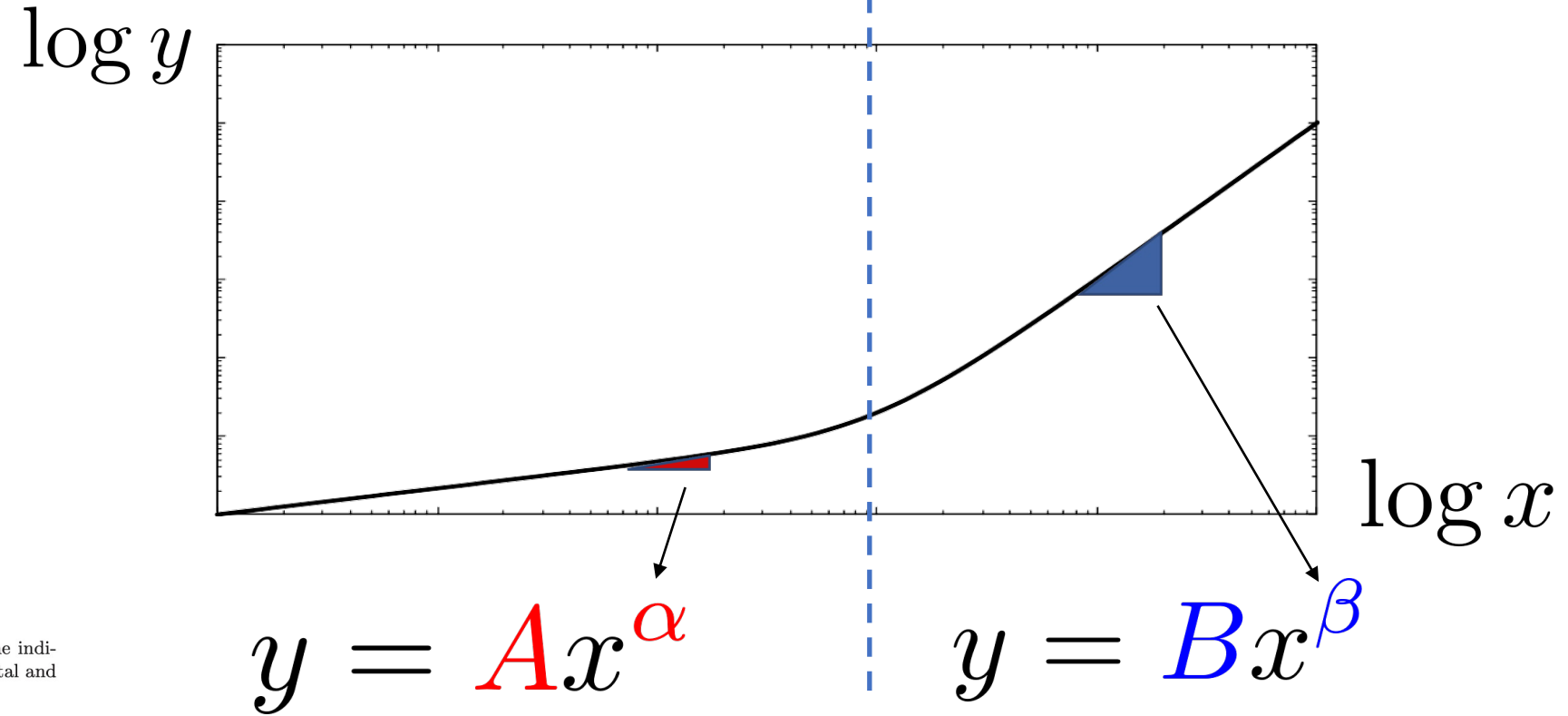
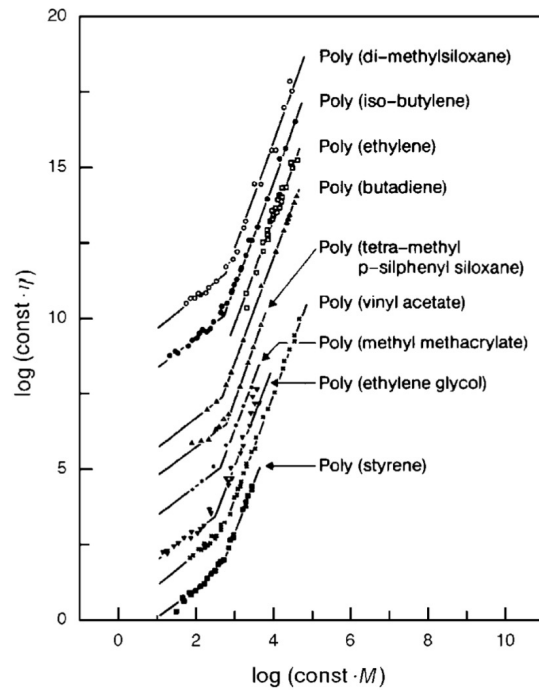
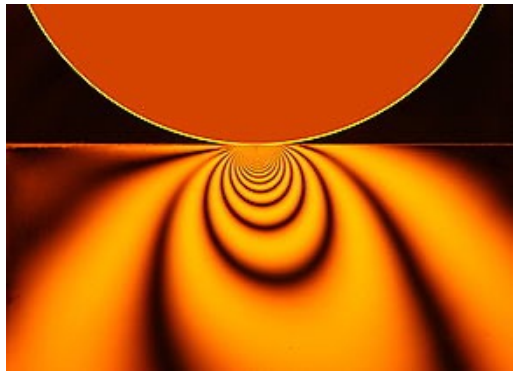
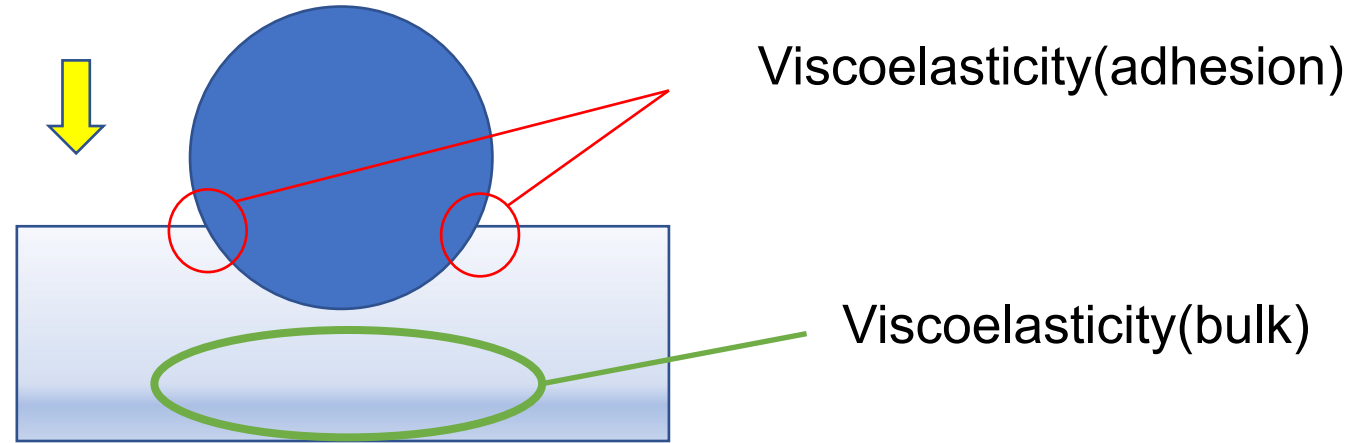
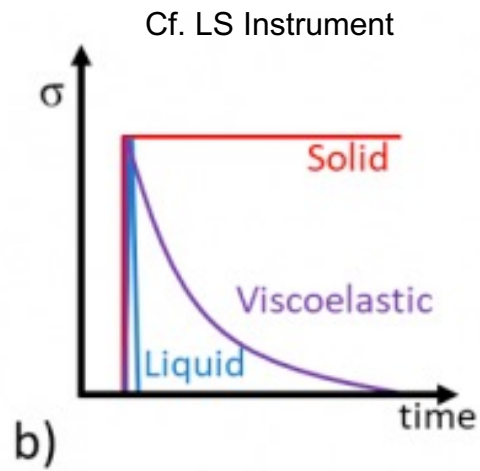


Fig. 6.13. Molecular weight dependence of the viscosity as observed for the indicated polymers. For better comparison curves are suitably shifted in horizontal and vertical directions. Data from Berry and Fox [71]

$$\eta \sim \begin{cases} M & (M < M_c) \\ M^{3.2-3.6} & (M > M_c) \end{cases}$$

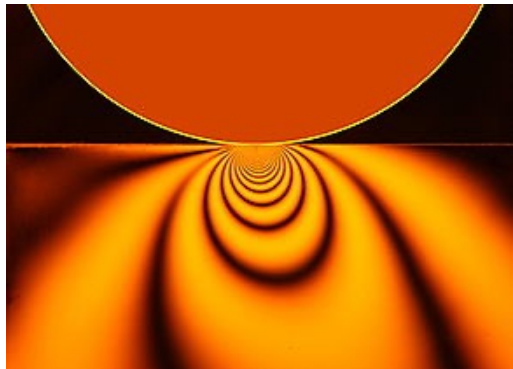
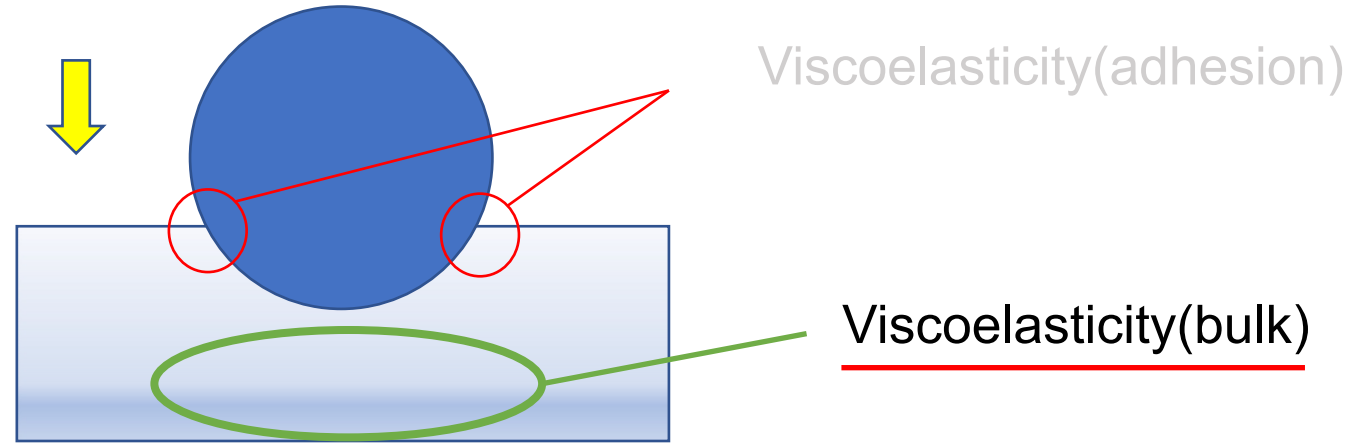
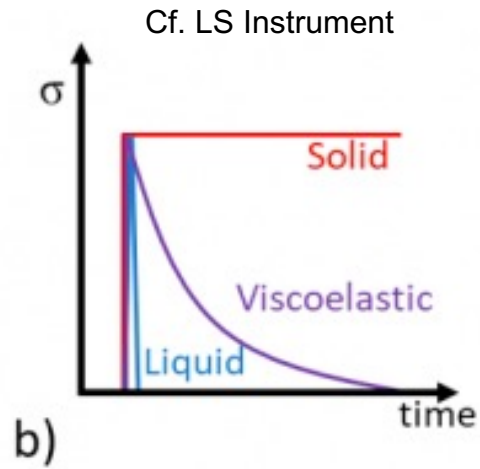
- Crossover of scaling is the process of transition of scaling law by continuous change of scale parameter
- Crossover of scaling law corresponds to **a transition of physical law**

Viscoelasticity on contact mechanics



- Velocity-dependent behaviors derived from viscoelasticity appear.
- The viscoelasticity derived from the adhesion is dominant for contact though here I focus on the viscoelasticity from bulk.

Viscoelasticity on contact mechanics



- Velocity-dependent behaviors derived from viscoelasticity appear.
- The viscoelasticity derived from the adhesion is dominant for contact though here I focus on the viscoelasticity from bulk.

- How do physical phenomena change?
- We have failed to study crossover as continuous process.
- The actual viscoelastic contribution derived from bulk to dynamical impact had been unclear.



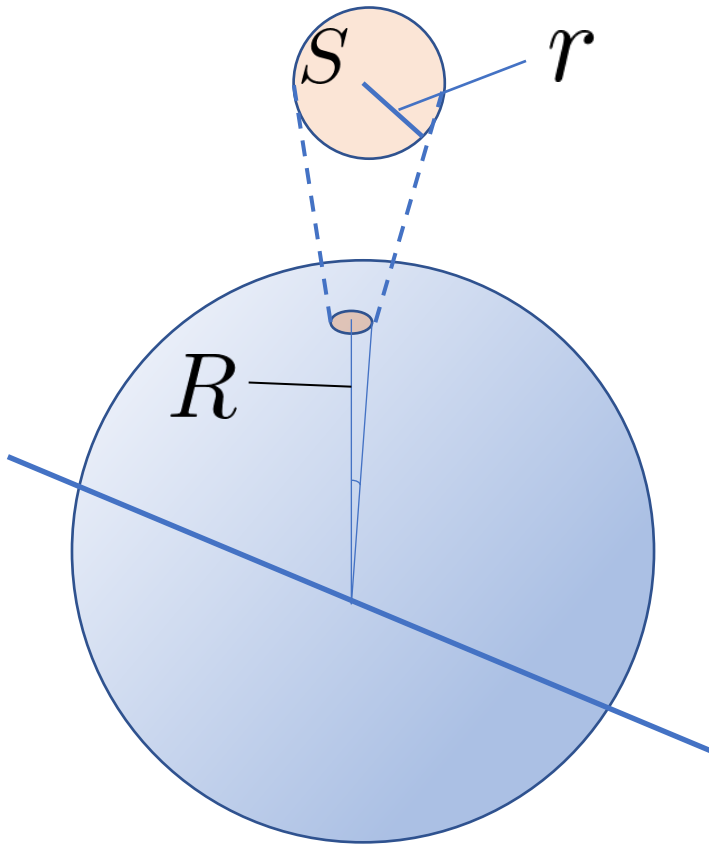
Question to method

- What is a framework of crossover of scaling law?

Question to a phenomenon

- How is the viscoelasticity derived from bulk involved in the dynamical contact?

How the scaling law is formalized: intermediate asymptotics



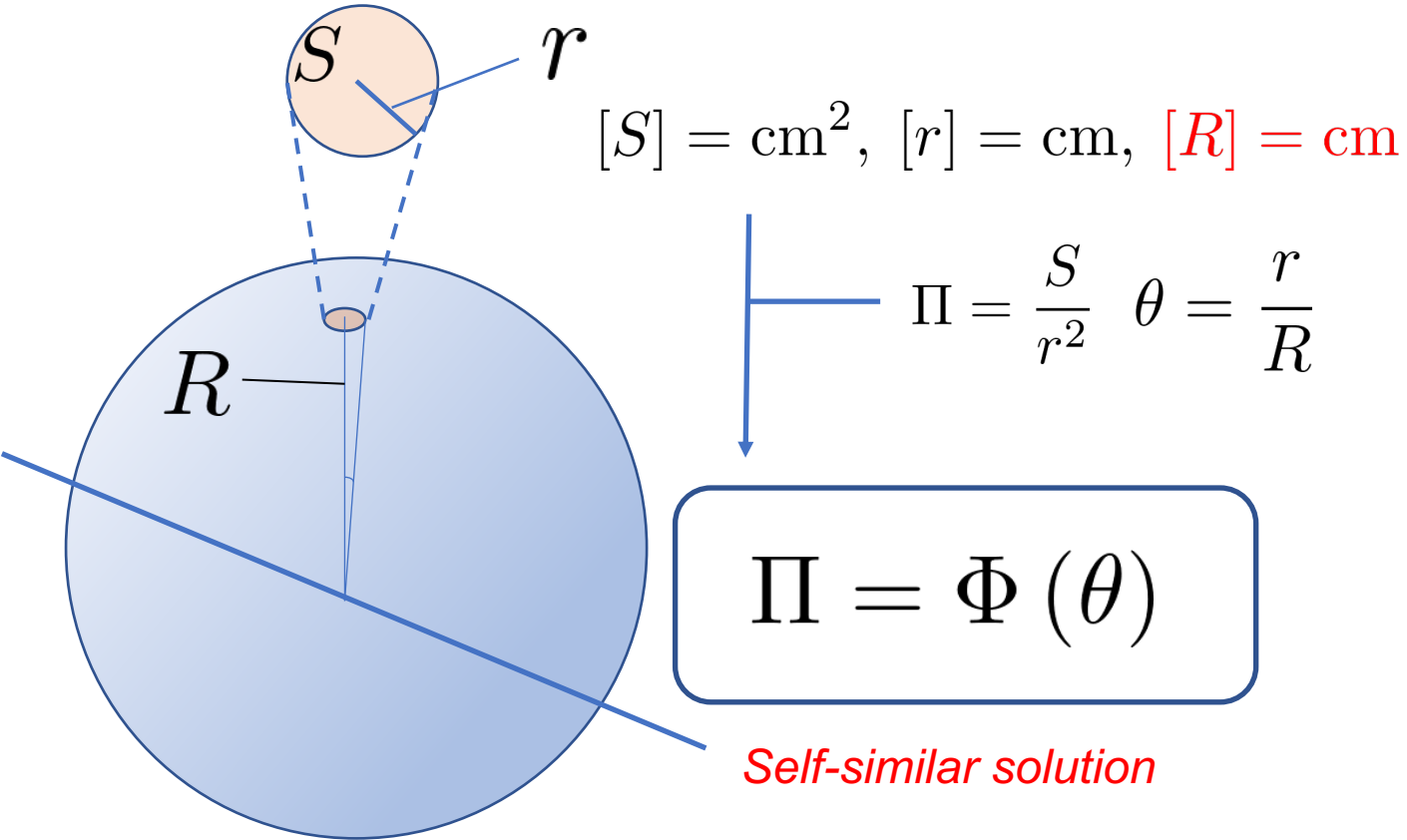
$$S \sim r^\alpha ?$$

Barenblatt, *Scaling* (CUP 2003)



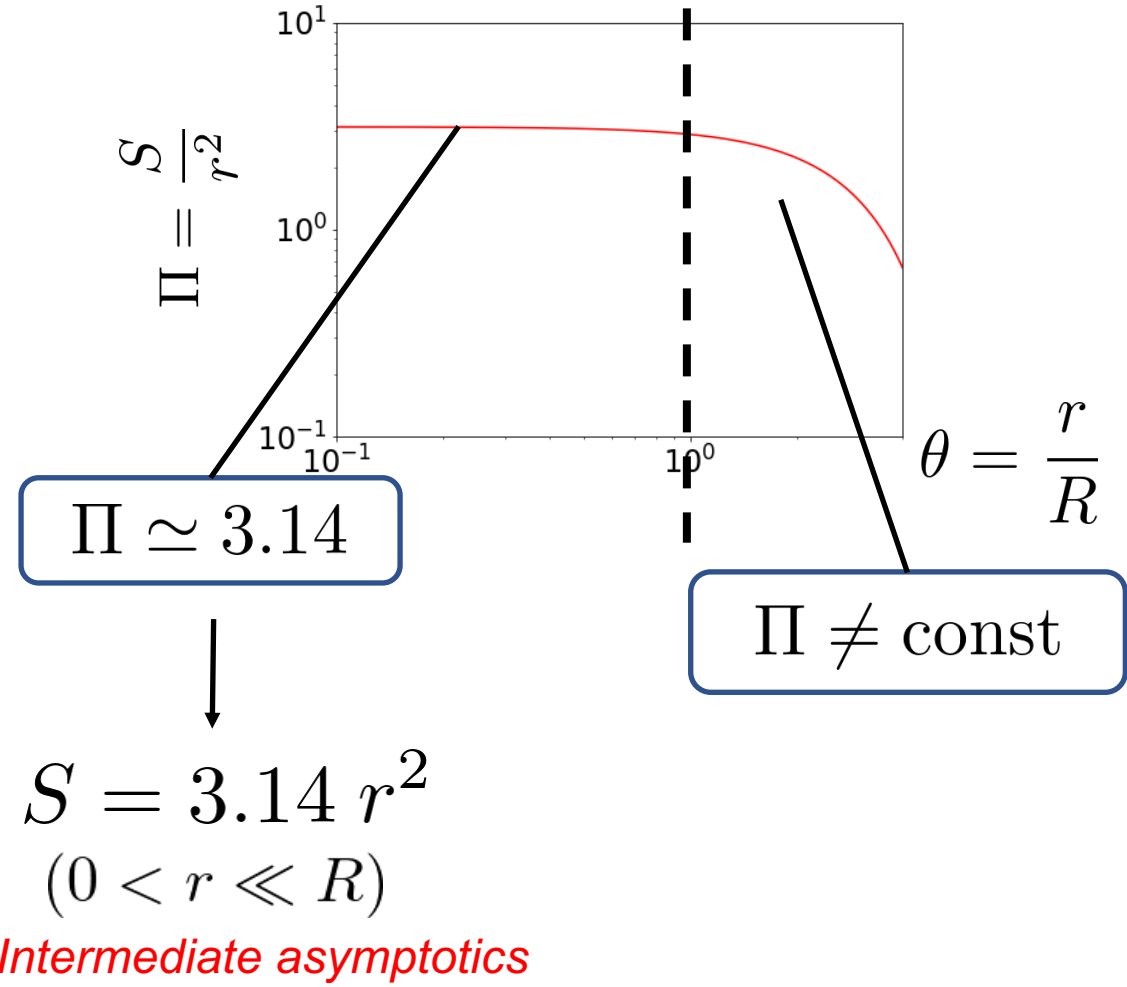
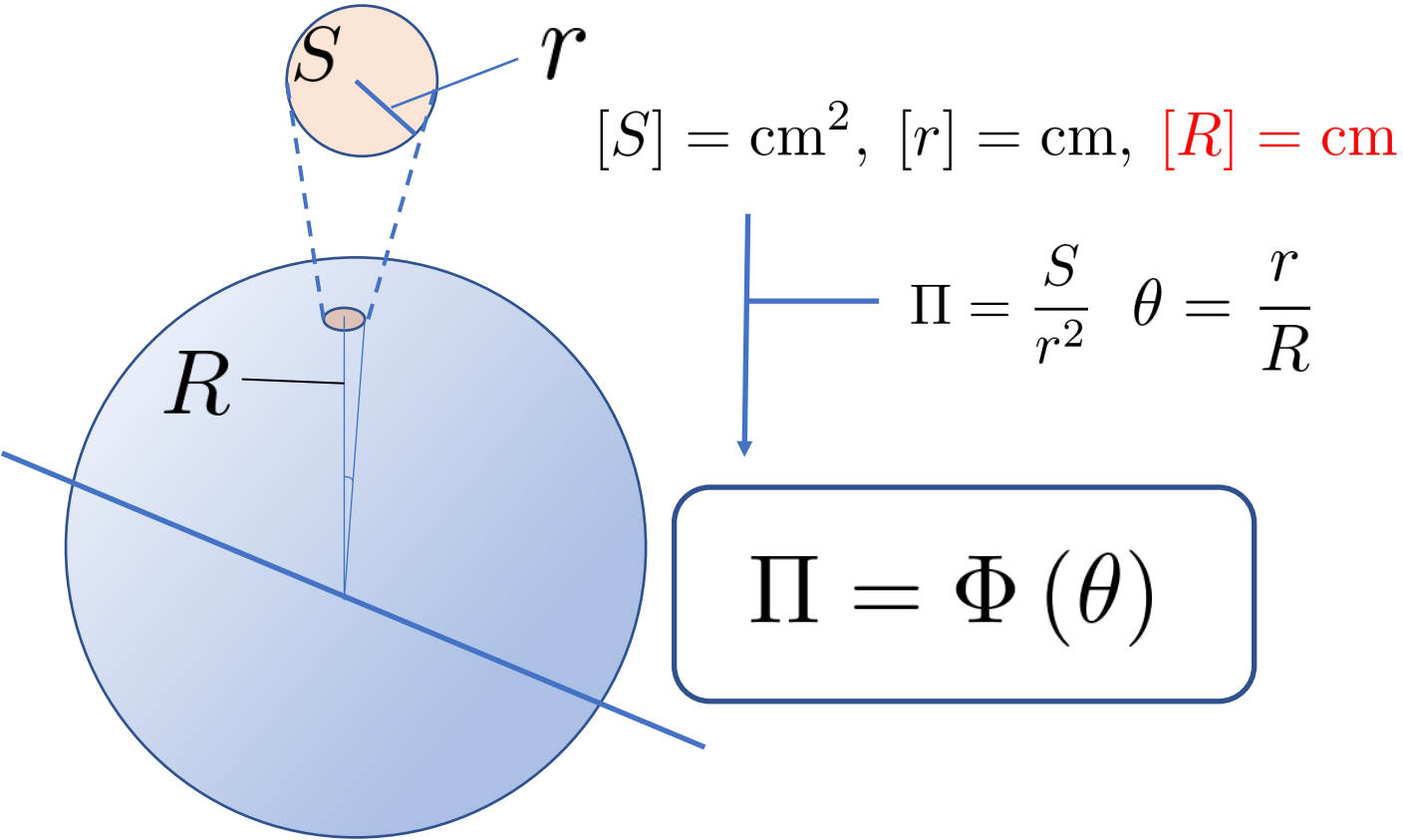
G.I. Barenblatt

How the scaling law is formalized: intermediate asymptotics



Barenblatt, *Scaling* (CUP 2003)

How the scaling law is formalized: intermediate asymptotics



Barenblatt, *Scaling* (CUP 2003)

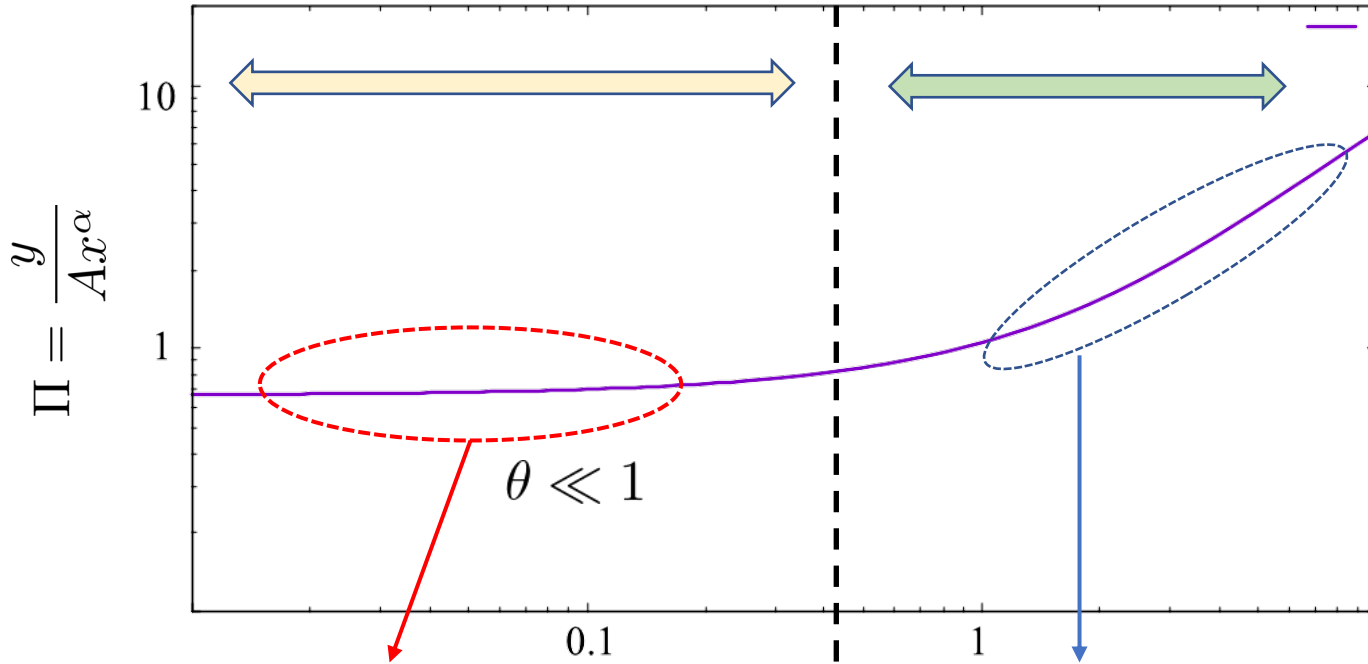
- Intermediate asymptotics** is an asymptotic representation valid in a certain range of physical parameters. → *Convergence of Φ is a condition for a stable scaling law.*

- **Intermediate asymptotic** is an asymptotics representation of a function valid in a certain range of independent variables.
- Ideal gas equation is an intermediate asymptotic in which the volume of molecules b and the molecular interaction a are negligible on a van der Waals equation.

$$p = \frac{nRT}{V - nb} - \frac{an^2}{V^2} \rightarrow \frac{nRT}{V} \quad \left(\frac{an^2}{V} \ll p \ll \frac{RT}{b} \right)$$

A framework for crossover of scaling law

Φ idealized region nonidealized region



$$\Pi = \Phi(\theta)$$

Self-similar solution

$$\theta = \frac{z}{x^\beta}$$

$$\Phi = \text{const}$$

$$\Phi \neq \text{const}$$

$$y = Ax^\alpha$$



$$y = Bx^\beta$$

Intermediate asymptotics

- $\Phi \neq \text{const}$, corresponds to a crossover of scaling law?

Strategy

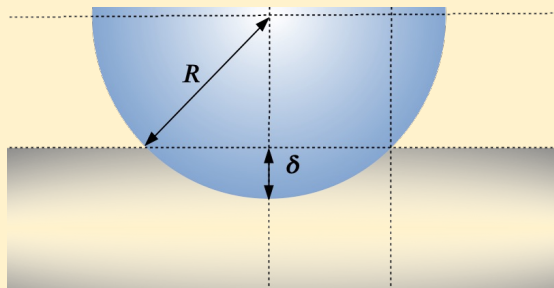
- A stability of scaling laws can be understood by intermediate asymptotics. The convergence of self-similar solution to a finite limit gives the asymptotic expression of scaling law.

$$\lim_{\theta \rightarrow 0} \Phi(\theta) = \text{const} \quad \longleftrightarrow \quad y = Ax^\alpha \quad (\theta \ll 1)$$

- Incomplete convergence of scaling law generates the transition of scaling law?

$$\Phi(\theta) \neq \text{const} \quad \longleftrightarrow \quad y = Ax^\alpha \longrightarrow Bx^\gamma \quad ?$$

- What is a self-similar solution that describes the transition from elastic impact to viscoelastic impact?

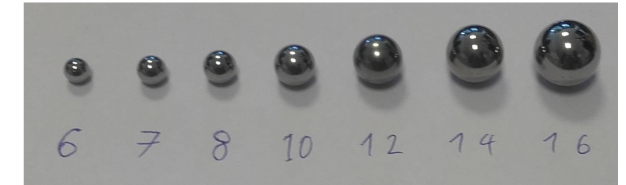
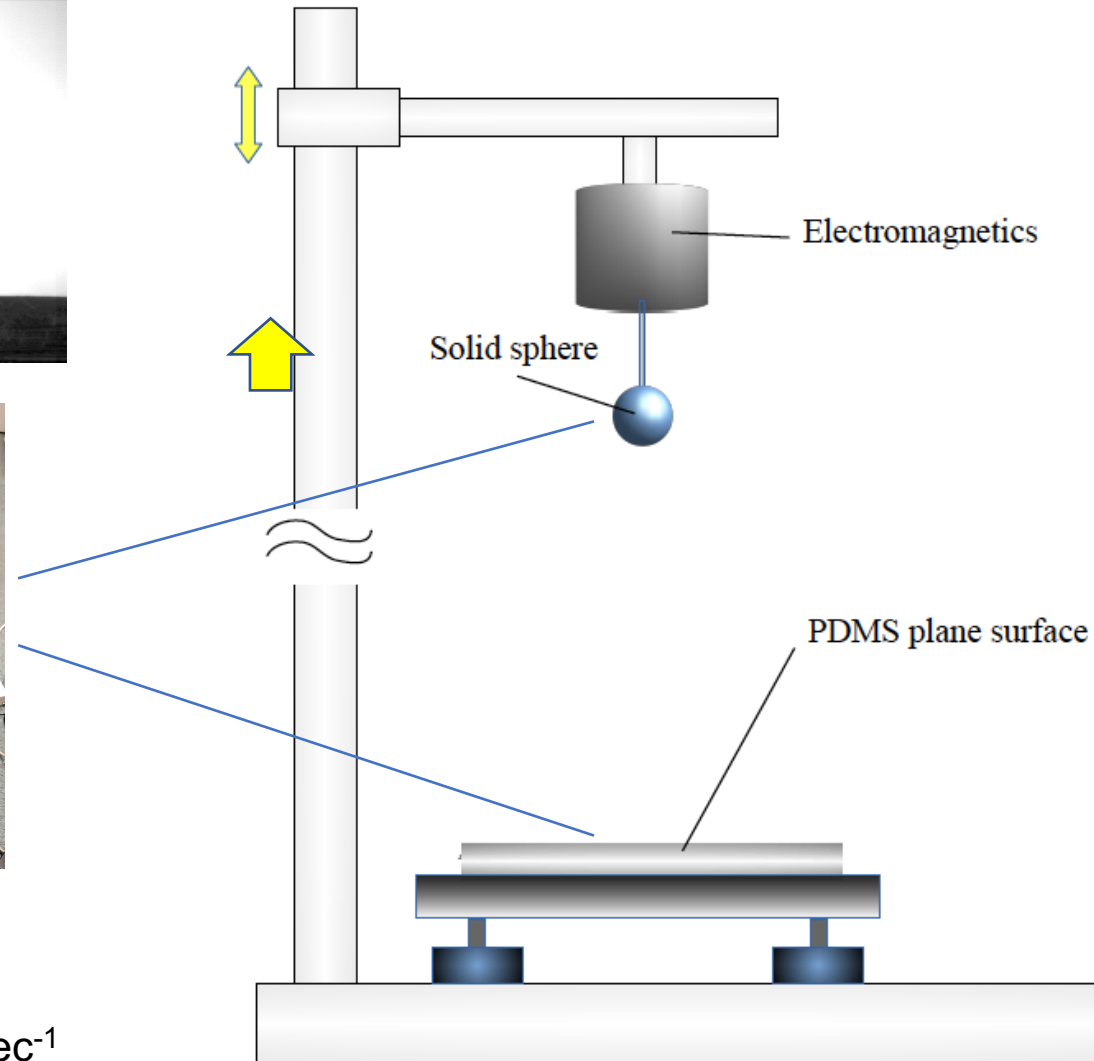


$$\Psi = \Phi(Z) \quad ?$$

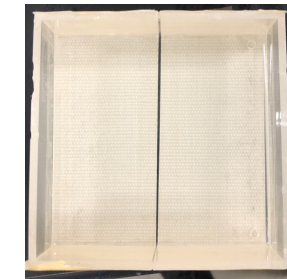
Experimental set up



High speed camera
(FASTCAM SA1.1)
Frame rate = 10000 f sec⁻¹



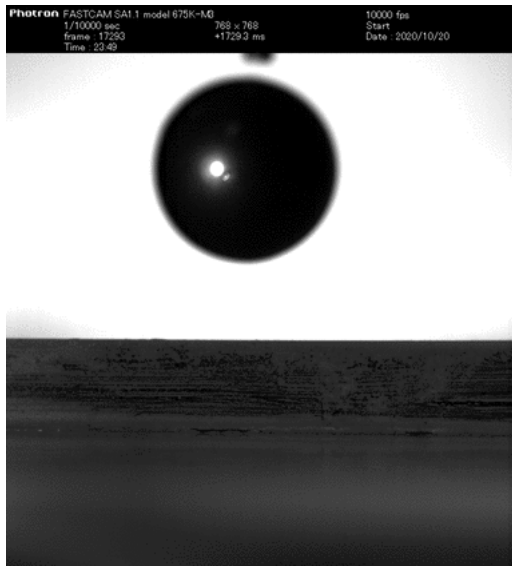
$\rho = 7800 \text{ kg/m}^3$
 $R = 3.0, 4.0, 5.0, 7.0, 8.0 \text{ mm}$



Polydimethylsiloxane

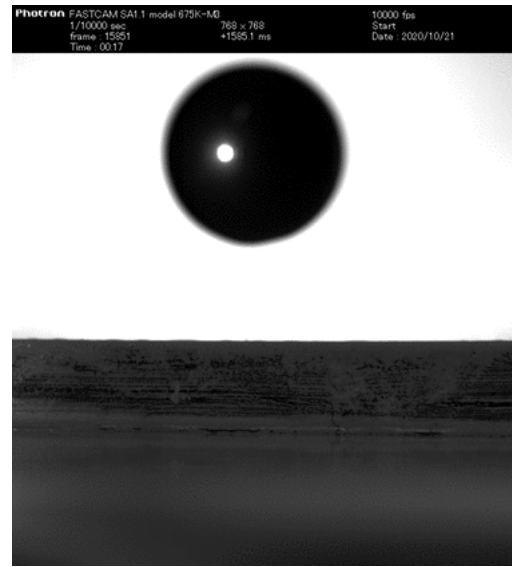
$E \approx 0.78 \text{ MPa}$
 $\mu = 141 \text{ Pa}\cdot\text{s}$

Dynamical impact of sphere on R = 8.0 mm



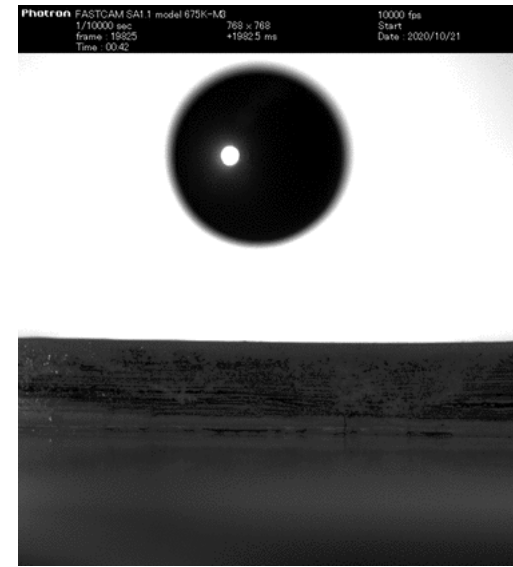
R = 8.0 mm
 $V_i = 390$ mm/s
 $\rho = 7800$ kg/m³

Mettalic ball



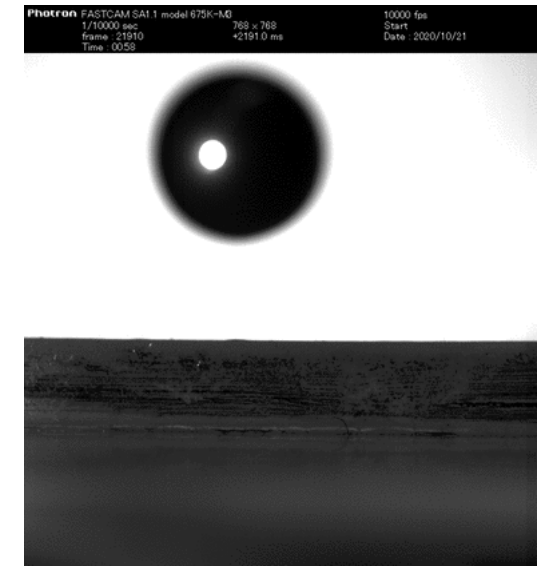
R = 8.0 mm
 $V_i = 750$ mm/s
 $\rho = 7800$ kg/m³

Mettalic ball



R = 8.0 mm
 $V_i = 1290$ mm/s
 $\rho = 7800$ kg/m³

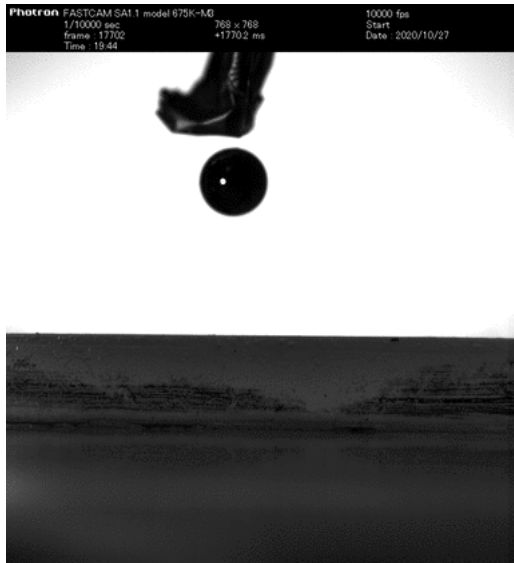
Mettalic ball



R = 8.0 mm
 $V_i = 2302$ mm/s
 $\rho = 7800$ kg/m³

Mettalic ball

Dynamical impact of sphere on $v_i = 400$ mm/s



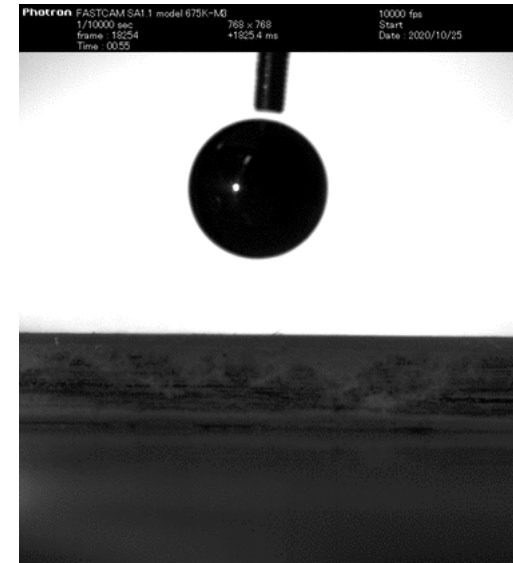
$R = 3.0$ mm
 $V_i = 471$ mm/s
 $\rho = 7800$ kg/m³

Mettalic ball



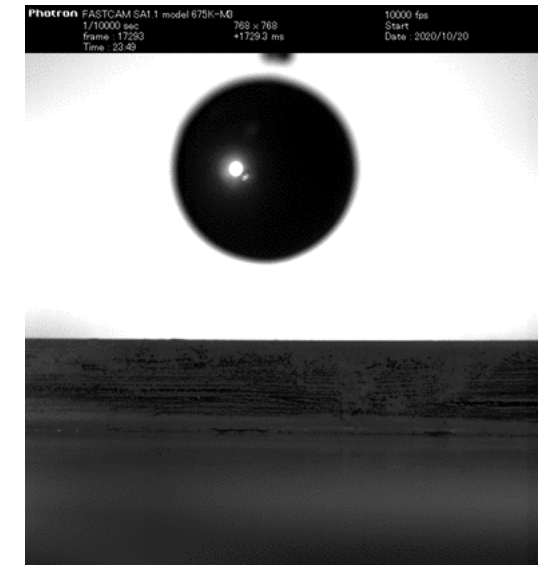
$R = 4.0$ mm
 $V_i = 430$ mm/s
 $\rho = 7800$ kg/m³

Mettalic ball



$R = 6.0$ mm
 $V_i = 369$ mm/s
 $\rho = 7800$ kg/m³

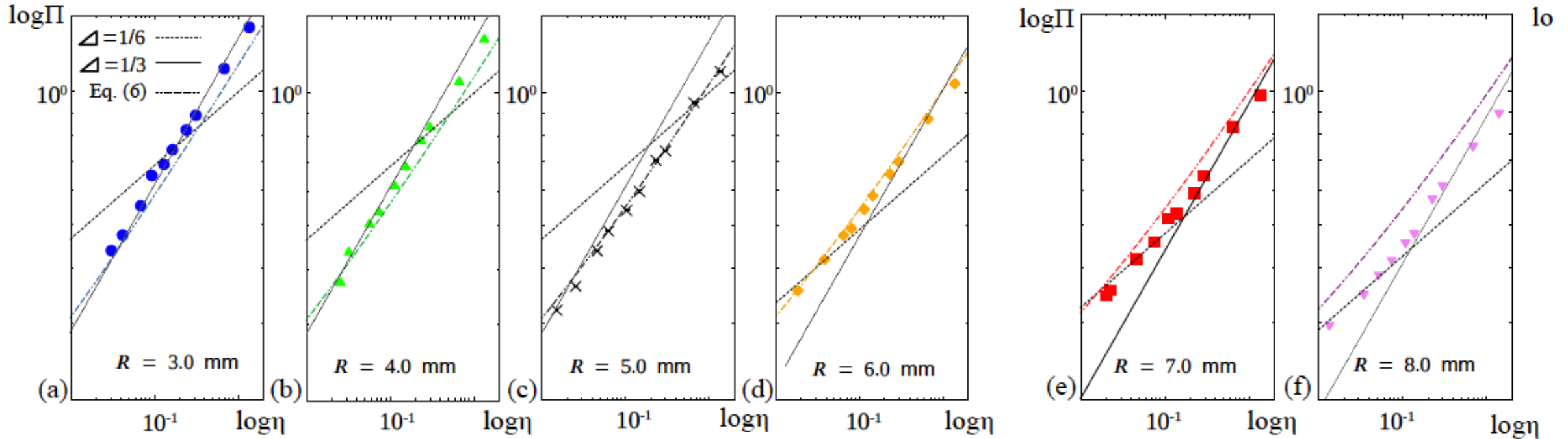
Mettalic ball



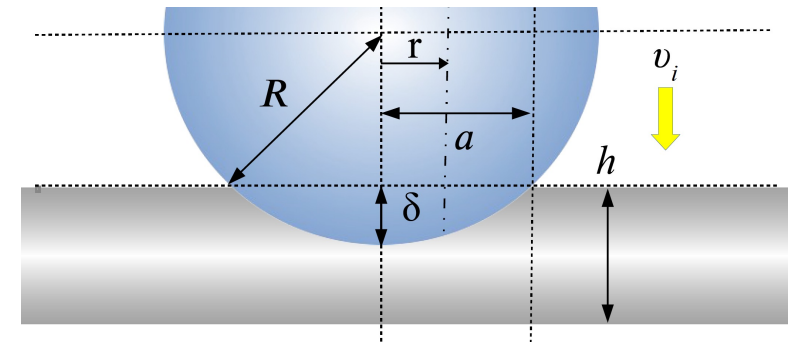
$R = 8.0$ mm
 $V_i = 390$ mm/s
 $\rho = 7800$ kg/m³

Mettalic ball

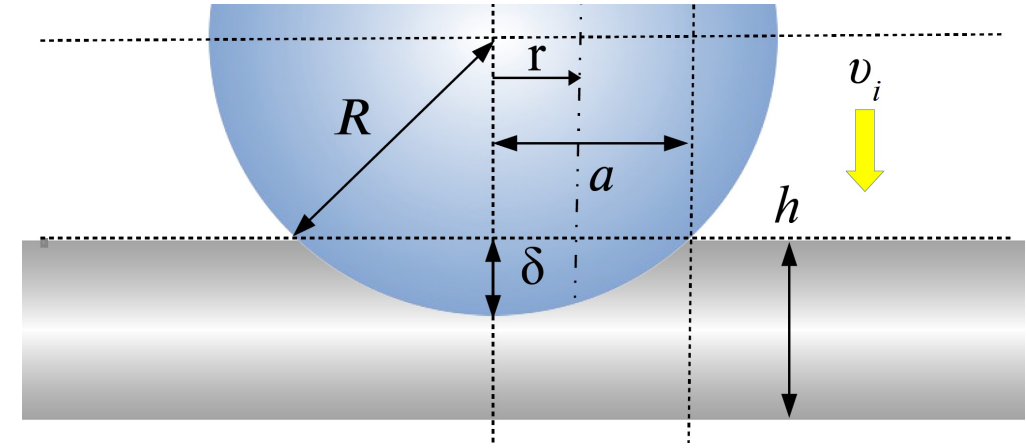
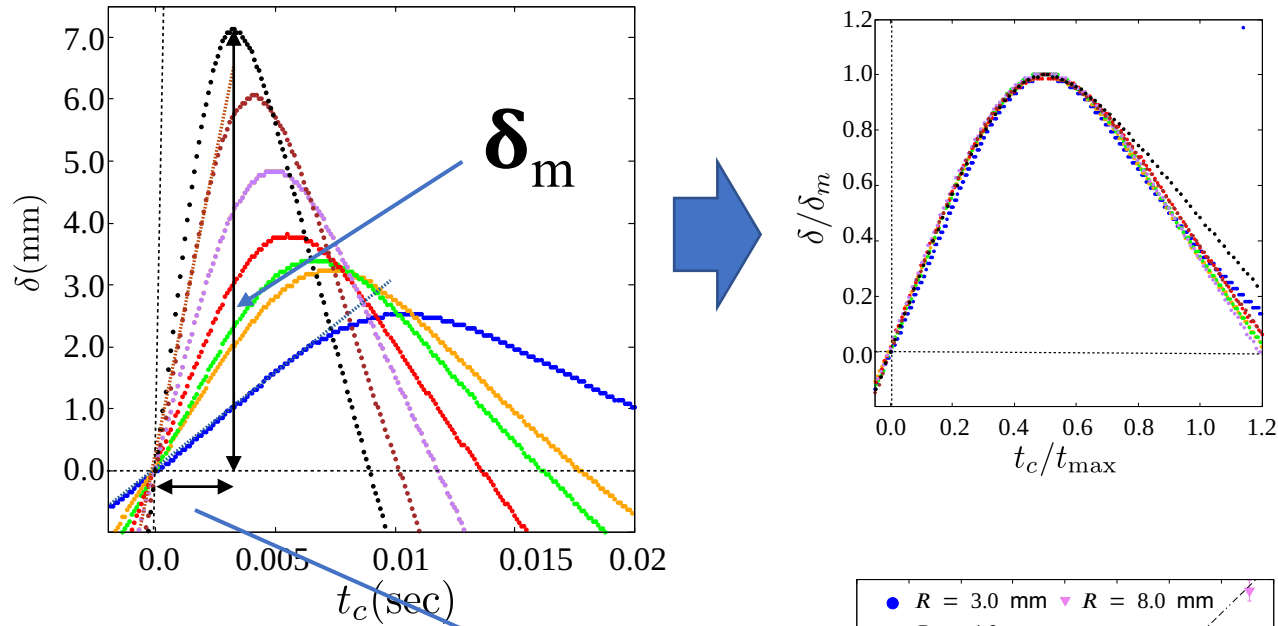
The maximum deformations and the impact velocities



$$\Pi = \frac{\delta_m}{R} \quad \eta = \frac{\rho v_i^2}{E}$$

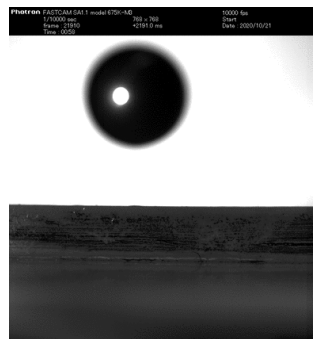


Time evolution of deformation on the impacts

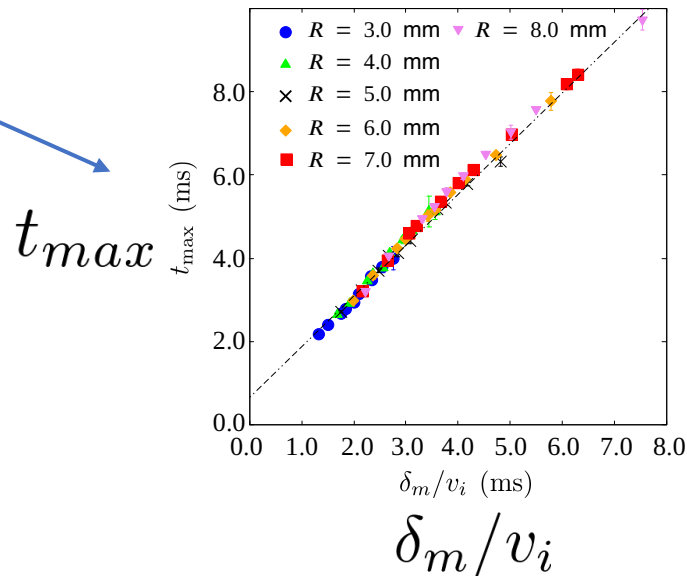


$$\Pi = \frac{\delta}{R}, \quad \kappa = \frac{h}{R}, \quad \eta = \frac{\rho v^2}{E}, \quad \theta = \frac{\mu}{E^{1/2} \rho^{1/2} R},$$

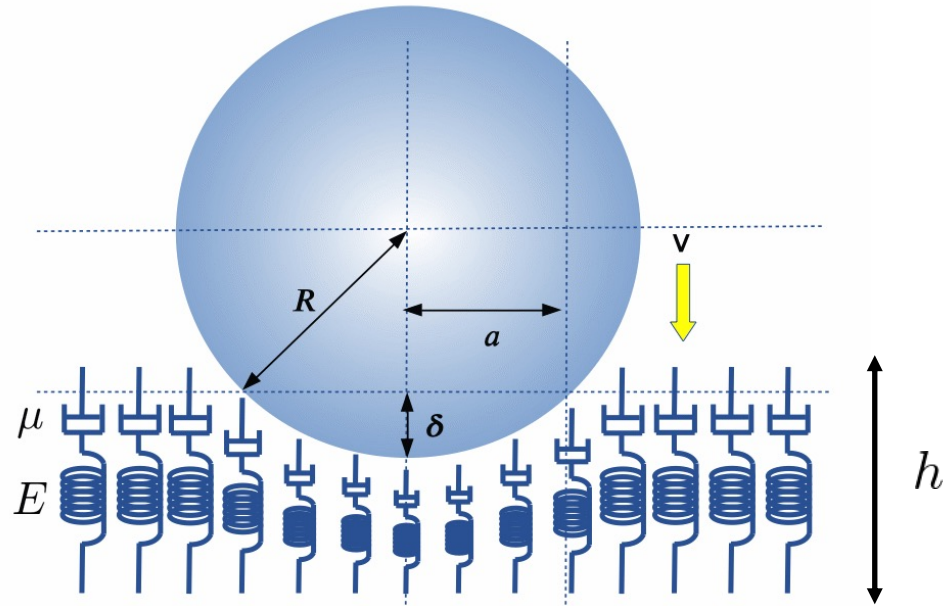
- The similarities of the attractors of deformations is found.
- A scaling relation between the contact times and the impact velocities.



$R = 8.0$ mm
 $V_i = 2302$ mm/s



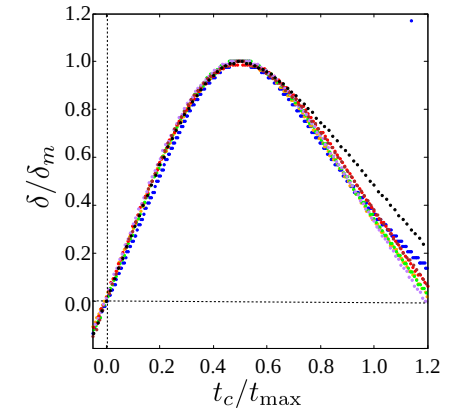
Maxwell Viscoelastic Foundation model



$$\sigma + \frac{\mu}{E} \frac{d\sigma}{dt} = \mu \frac{d\epsilon}{dt}$$

σ : stress
 ϵ : strain

$$\frac{d\delta}{dt} = v_i$$



$$E_{MVF} = \frac{\phi \mu \pi R \delta_m^2}{h} \frac{d\delta}{dt} \left[1 - e^{-\frac{E}{\mu} t_c} \right]$$

Maxwell Viscoelastic Foundation model

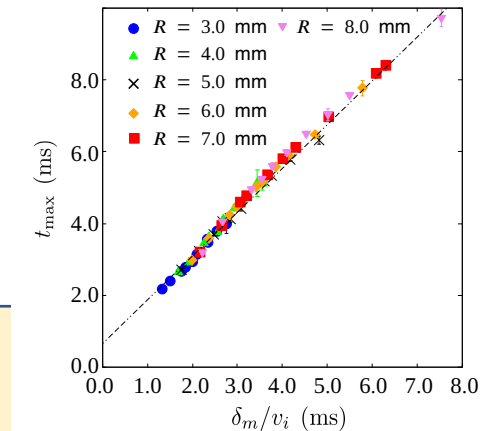
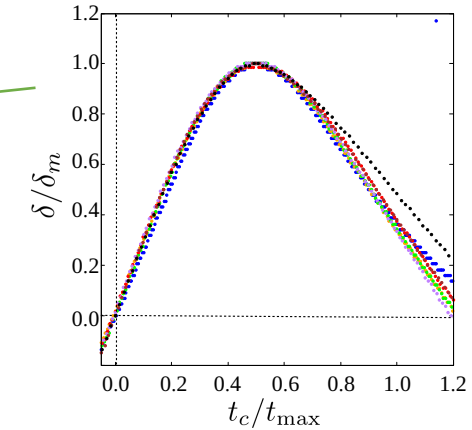
$$E_{MVF} = \frac{\phi\mu\pi R\delta_m^2}{h} \frac{d\delta}{dt} \left[1 - e^{-\frac{E}{\mu}t_c} \right]$$

$$\frac{d\delta}{dt} = v_i \quad t_c = \frac{\delta_m}{v_i}$$

$$E_{MVF} \xrightarrow{Et_c/\mu \ll 1} \frac{\phi\mu\pi R\delta_m^2}{h} v_i \cdot \frac{E\delta_m}{\mu v_i} \simeq \frac{\phi E\pi R\delta_m^3}{h} \simeq E_{el}$$

$$Z = \frac{Et_c}{\mu}$$

- $Z \ll 1$ corresponds to elastic energy estimation
- $Z \sim 1$ corresponds to viscoelastic energy estimation



- Step 1 • Start from a scaling law valid in a idealized region:

$$y = Ax^\alpha$$

- Step 2 • Define the dimensionless number composed of the scaling law:

$$\Pi = \frac{y}{Ax^\alpha}$$

- Step 3 • Construct a self-similar solution by identifying an interfering dimensionless number:

$$\Pi = \Phi(\theta)$$

Dimensionless number of a scaling law in idealized region:

Interfering dimensionless number

$$\theta = \frac{z}{x^\beta}$$

The procedure to construct a self-similar solution

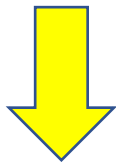
Step 1 : Start from a scaling law in a idealized region

CGR solution

$$\Pi = \text{const} \left(\frac{\kappa}{\phi} \right)^{1/3} \eta^{1/3}$$

$$\Pi = \frac{\delta_m}{R}, \quad \kappa = \frac{h}{R}, \quad \eta = \frac{\rho v_i^2}{E}, \quad \theta = \frac{\mu}{E^{1/2} \rho^{1/2} R}$$

Chastel et al., J. Fluid Mech., 2016.



Step 2 : define a dimensionless number composed of the scaling.

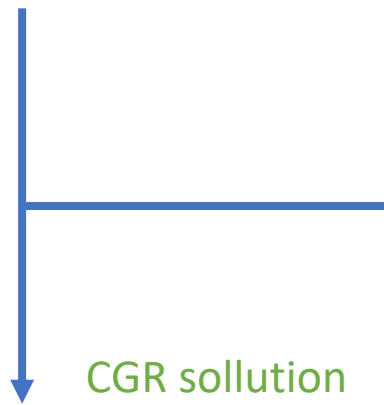
$$\Psi = \frac{\phi}{\kappa} \frac{\Pi^3}{\eta}$$

The procedure to construct a self-similar solution

$$\frac{2}{3} = \Pi^2 \theta \frac{\phi}{\kappa} \frac{1}{\eta^{1/2}} \left[1 - \exp \left(-\frac{\Pi}{\theta \eta^{1/2}} \right) \right]$$

$$\Pi = \frac{\delta_m}{R}, \quad \kappa = \frac{h}{R}, \quad \eta = \frac{\rho v_i^2}{E}, \quad \theta = \frac{\mu}{E^{1/2} \rho^{1/2} R}$$

Step 3 : construct a self-similar solution by identifying an interfering dimensionless:



CGR solution

$$\Psi = \frac{\phi}{\kappa} \frac{\Pi^3}{\eta}$$

$$Z = \frac{\Pi}{\theta \eta^{1/2}}$$

$$\Psi = \frac{2}{3} \frac{Z}{[1 - \exp(-Z)]}$$

The interfering dimensionless number: *A inverse Deborah number.*

The self-similar solution

The hierarchical structure of self-similarity

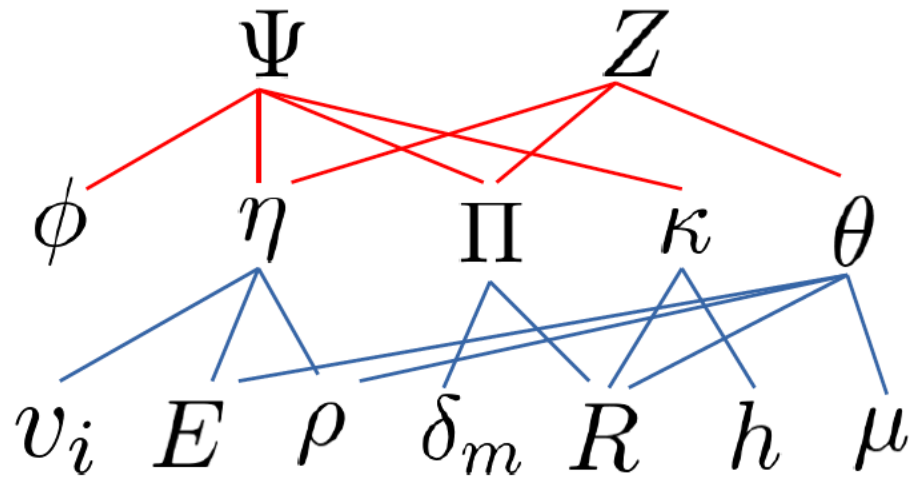
$$\Psi = \frac{\phi \Pi^3}{\kappa \eta} = \frac{\delta^3 E \phi}{R^2 \rho v^2 h}$$

$$Z = \frac{\Pi}{\theta \eta^{1/2}} = \frac{E \delta}{\mu v}$$

$$\Psi = \frac{2}{3} \frac{Z}{1 - \exp(-Z)} \xrightarrow{Z \rightarrow 0} \frac{2}{3} \iff \Pi = \left(\frac{2\kappa}{3\phi} \right)^{1/3} \eta^{1/3}$$

CGR solution

elastic
kinetic \iff viscous
elastic



Self-similarity of the second class

$$\Psi = \Phi(Z)$$

Dynamics of element

Self-similarity of the first class

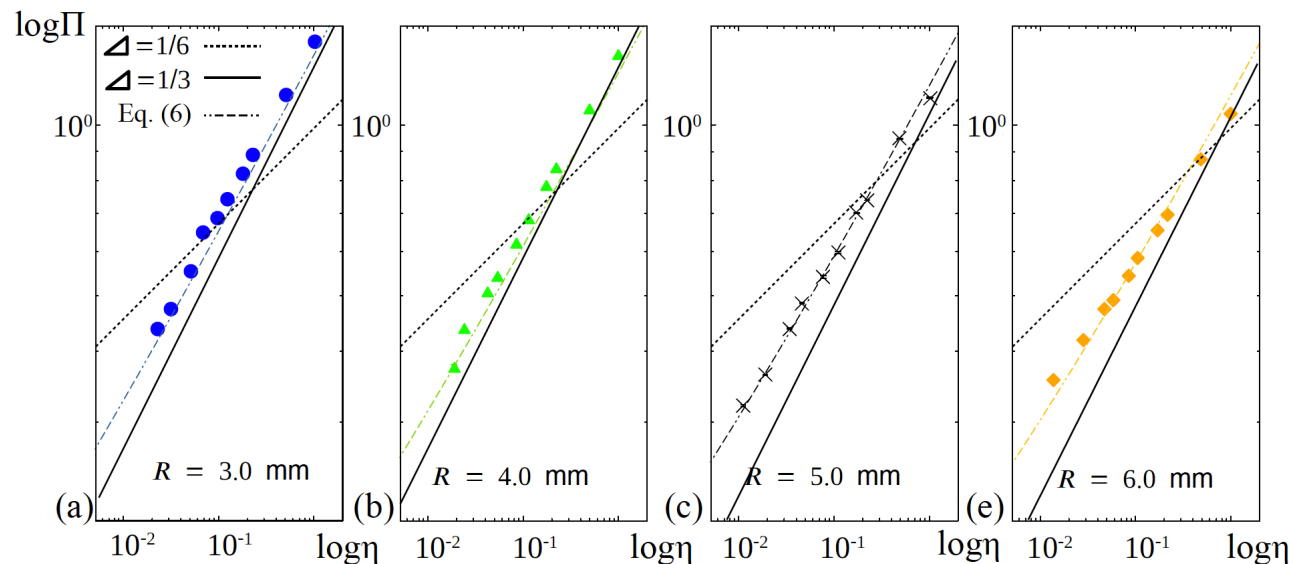
$$\Pi = \Phi(\phi, \kappa, \theta, \eta)$$

Dimensionless parameters

Physical quantity

$$\delta_m = f(R, h, \phi, \rho, \mu, E, v_i) \quad \text{Physical quantity}$$

Hierarchical structure of self-similarity



$$\Psi = \frac{\phi \Pi^3}{\kappa \eta} = \frac{\delta^3 E \phi}{R^2 \rho v^2 h} = \frac{\text{elastic}}{\text{kinetic}}$$

$$Z = \frac{\Pi}{\theta \eta^{1/2}} = \frac{E \delta}{\mu v} = \frac{\text{viscous}}{\text{elastic}}$$



small

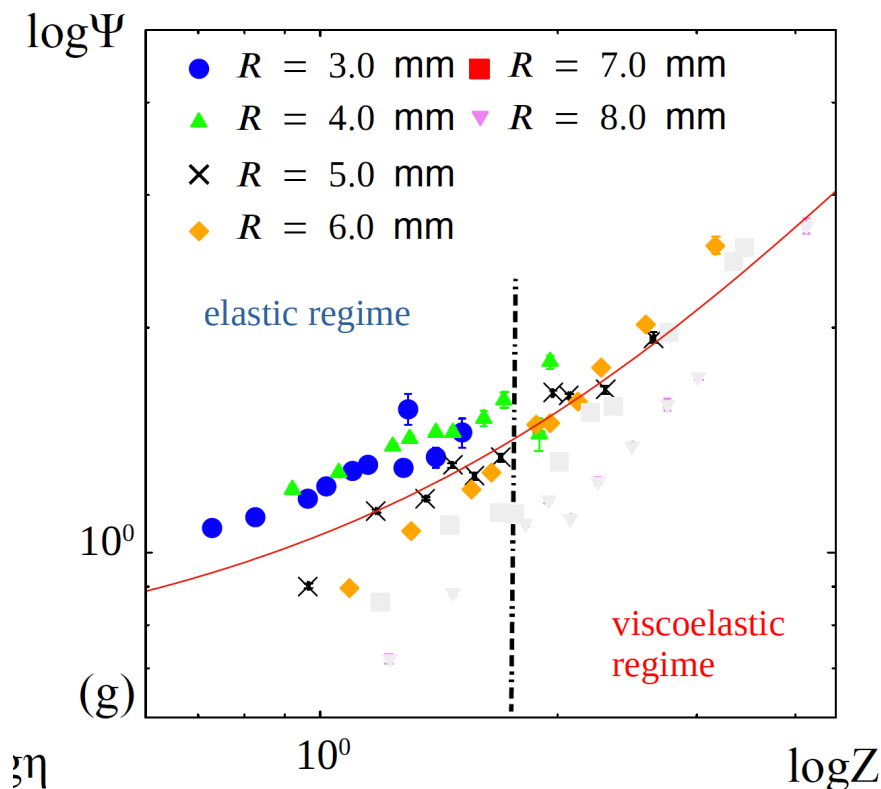
large

elastic

viscoelastic

$$\Psi = \frac{2}{3} \frac{Z}{[1 - \exp(-Z)]}$$

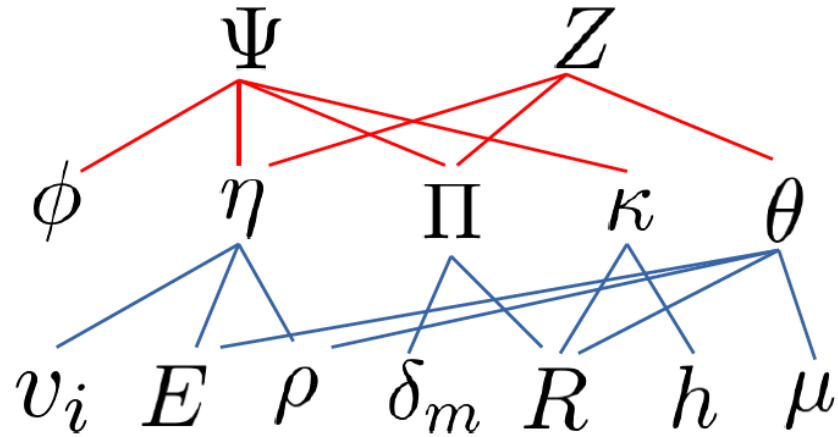
$$\Pi = \frac{\kappa}{54 \phi \theta^2} + \left(\frac{\kappa^2}{486 \phi^2 \theta^3} \right)^{\frac{1}{3}} \eta^{\frac{1}{6}} + \left(\frac{2\kappa}{3\phi} \right)^{\frac{1}{3}} \eta^{\frac{1}{3}}$$



Scale transformation $x' = A^\alpha x$

Self-similar solution

Scale invariance



$$\Psi = \frac{2}{3} \frac{Z}{1 - \exp(-Z)}$$

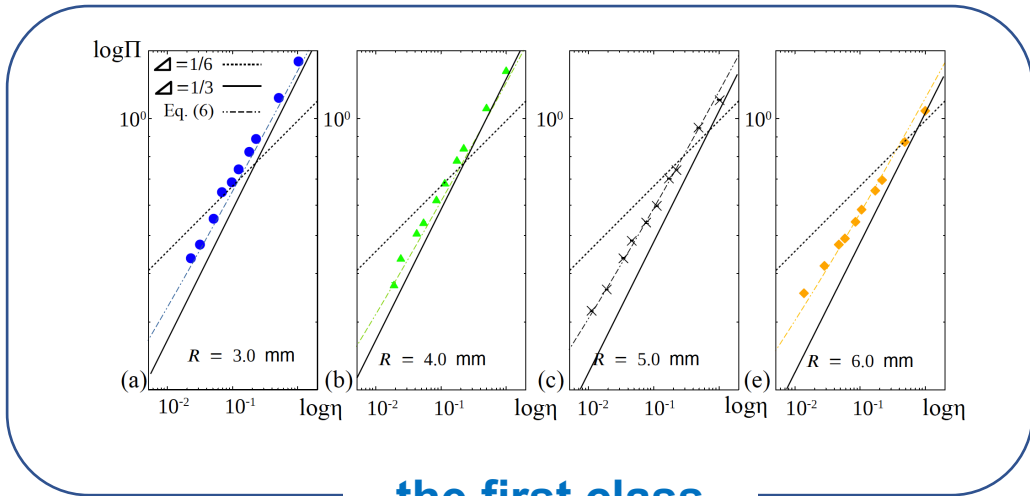
×

$$\frac{\Pi^3 \phi}{\kappa \eta} = \frac{2}{3} \frac{\frac{\Pi}{\theta \eta^{1/2}}}{1 - \exp\left(-\frac{\Pi}{\theta \eta^{1/2}}\right)}$$

○

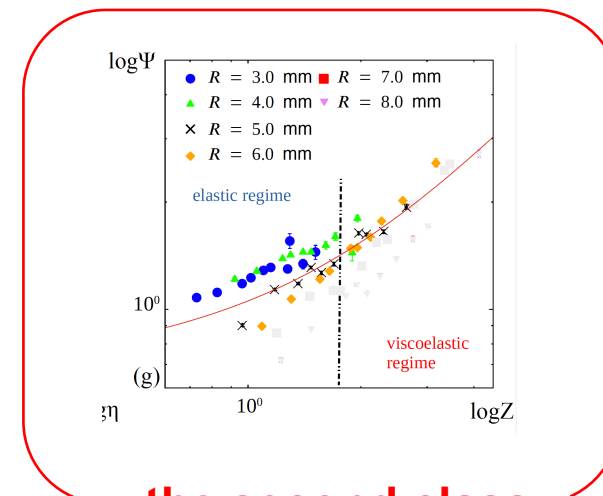
$$\frac{\delta_m^3 E \phi}{R^2 h \rho v_i^2} = \frac{2}{3} \frac{\frac{E \delta_m}{\mu v_i}}{1 - \exp\left(-\frac{E \delta_m}{\mu v_i}\right)}$$

○



the first class

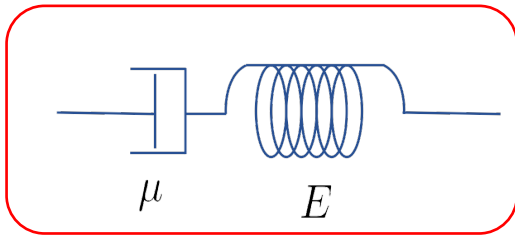
• Scaling behavior



the second class

- Dynamical balance
- Scale dependence

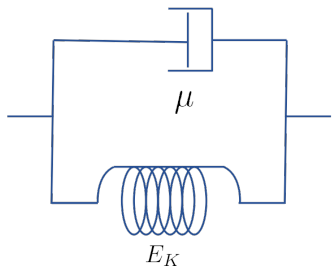
Maxwell model



$$\sigma + \frac{\mu}{E} \frac{d\sigma}{dt} = \mu \frac{d\epsilon}{dt}$$

$$E_{MVF} = \frac{\pi\mu\phi R\delta^2}{h} \frac{d\delta}{dt} \left[1 - \exp\left(-\frac{Et_c}{\mu}\right) \right]$$

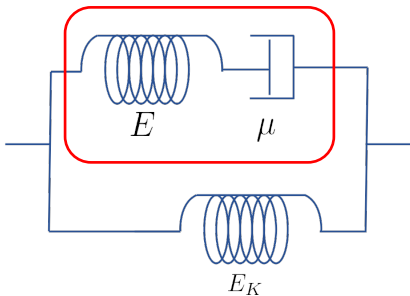
Kelvin Voigt model



$$\sigma = E_K \epsilon + \mu \frac{d\epsilon}{dt}$$

$$E_{KV} = \frac{\phi\pi E_K R\delta^3}{3h} + \frac{\phi\mu\pi R\delta^2}{h} \frac{d\delta}{dt}$$

Zener model



$$\frac{\mu}{E} \frac{d\sigma}{dt} = -\sigma + E_K \epsilon + \mu \left(\frac{E_K}{E} + 1 \right) \frac{d\epsilon}{dt}$$

$$E_Z = \frac{\phi\pi E_K R\delta^3}{3h} + \frac{\phi\mu\pi R\delta^2}{h} \frac{d\delta}{dt} \left[1 - \exp\left(-\frac{Et_c}{\mu}\right) \right]$$

Perturbation solution

$$\Pi = \frac{\kappa}{54\phi\theta^2} + \left(\frac{\kappa^2}{486\phi^2\theta^3} \right)^{\frac{1}{3}} \eta^{\frac{1}{6}} + \left(\frac{2\kappa}{3\phi} \right)^{\frac{1}{3}} \eta^{\frac{1}{3}}$$

$$\Pi = \sqrt{\frac{2\kappa}{3\phi\theta}} \eta^{\frac{1}{4}} - \frac{\kappa}{9\phi\theta^2}$$

$$E \ll E_K$$



$$E \gg E_K$$

$$\Pi = (3K^3 - 2K^2) \frac{\kappa}{54\phi\theta^2} + K^{\frac{5}{3}} \left(\frac{\kappa^2}{486\phi^2\theta^3} \right)^{\frac{1}{3}} \eta^{\frac{1}{6}} + K^{\frac{1}{3}} \left(\frac{2\kappa}{3\phi} \right)^{\frac{1}{3}} \eta^{\frac{1}{3}}$$

crossover



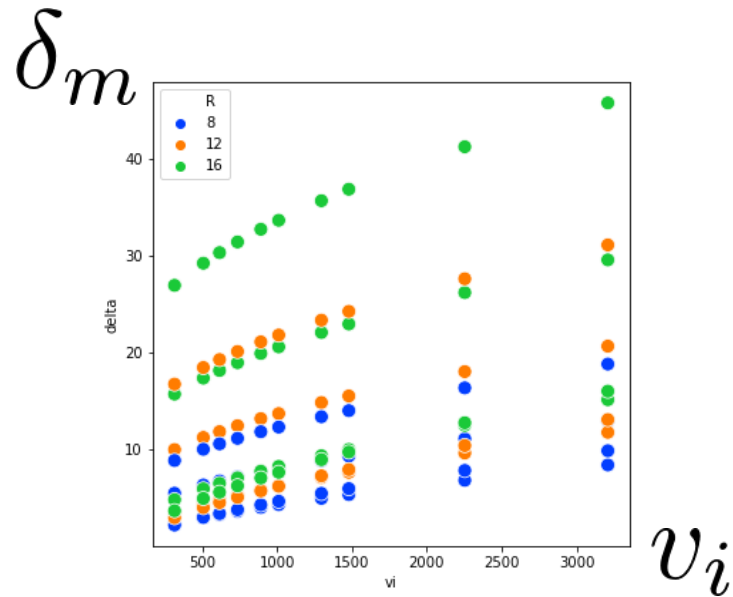
Conclusions for method

- There exists a self-similar solution on crossover of scaling law : the crossover is generated by another dimensionless number.
- A scale-variant function Φ drives the scale dependent behavior : the hierarchical structure is essential for crossover to estimate the stability of intermediate asymptotics.

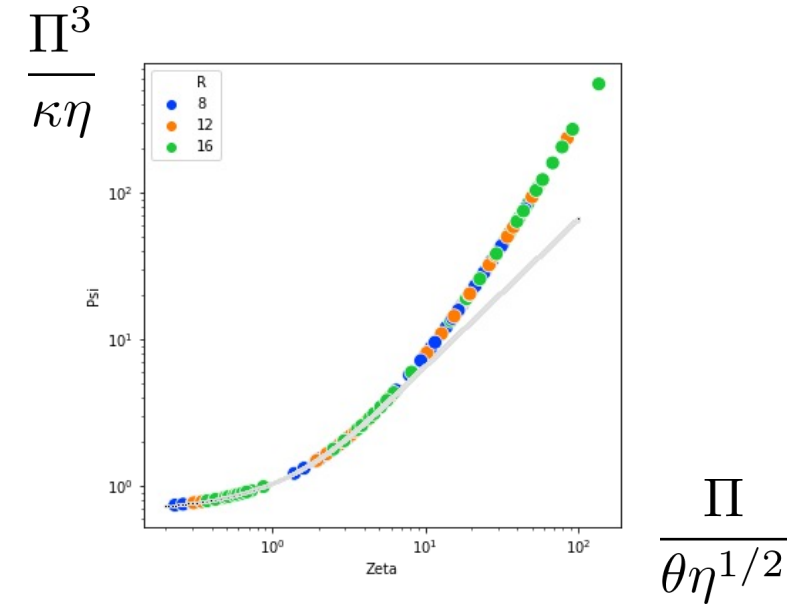
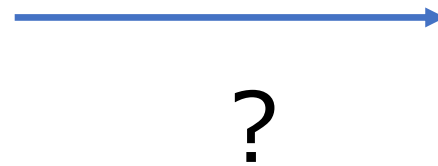
Conclusion for the phenomenon

- From the experimental observations, we found that the similar attractor of deformation : it gives the scaling law $d\delta/dt = v_i$ and $t_c = \delta_m/v_i$, which simplifies the calculation.
- Time-dependently, the energy E_{MVF} changes its form, giving rise to a crossover
- Maxwell element, serial connection of a dash pot and a spring, is necessary for crossover of scaling law

- Do we have a data driven algorithm to find a data collapse?



$$\delta_m = f(R, h, \phi, \rho, \mu, E, v_i)$$



$$\frac{\Pi^3}{\kappa\eta} = \Phi\left(\frac{\Pi}{\theta\eta^{1/2}}\right)$$

$$\frac{\Pi^3}{\kappa\eta} = \Phi\left(\frac{\Pi}{\theta^{\alpha_1} \kappa^{\alpha_2} \eta^{\alpha_3}}\right)$$

$$I = I(\alpha_1, \alpha_2, \alpha_3)$$