

Introduction to gravitational self-force

Adam Pound

University of Southampton

29 June 2015

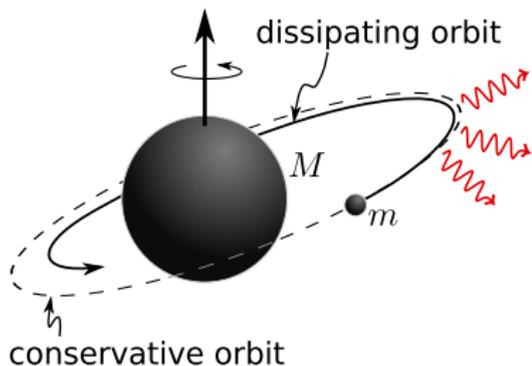
Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

Original motivation: extreme-mass-ratio inspirals (EMRIs)

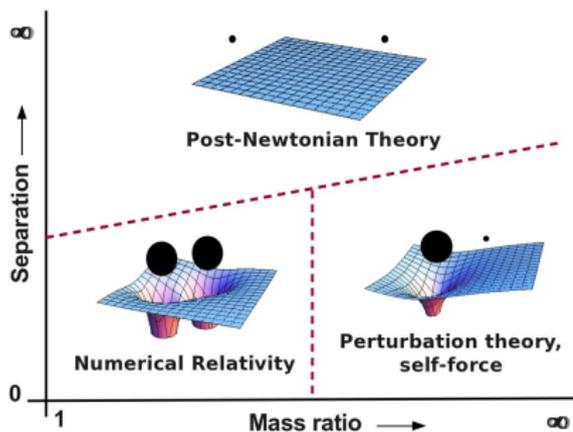


- stellar-mass neutron star or black hole orbits supermassive black hole
- m emits gravitational radiation, loses energy, spirals into M

- waveforms carry very precise information about strong-field dynamics and geometry of spacetime near black hole
- need very accurate model of motion for $\sim M/m \sim 10^5$ orbits—*self-force theory*

Self-force's place in the two-body problem

Binary parameter space



[Leor Barack]

Besides modeling EMRIs, self-force can improve models of ground-based-detector sources

- determine high-order post-Newtonian parameters
- calibrate Effective One Body theory

Also, self-force has surprisingly large domain of validity [Le Tiec et al]
 \Rightarrow can *directly* model IMRIs (and even similar-mass binaries?)

Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

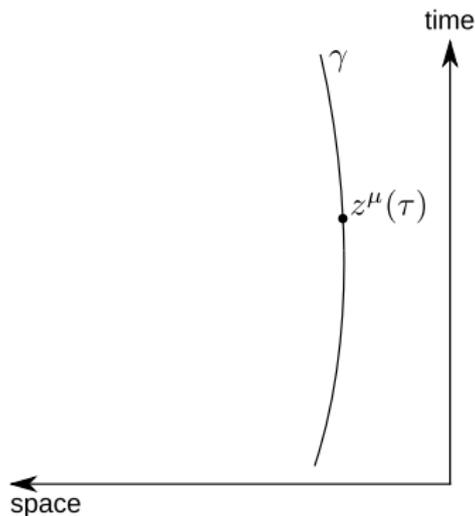
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g + h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



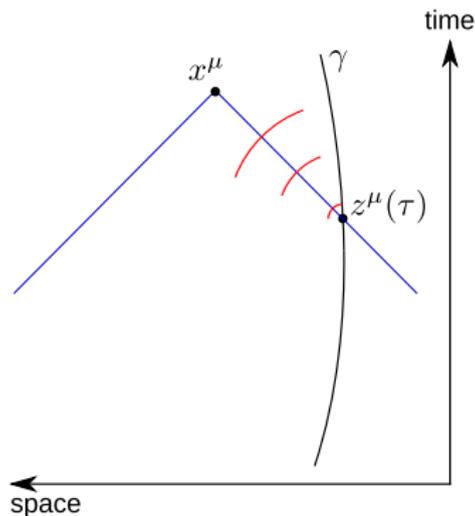
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g+h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



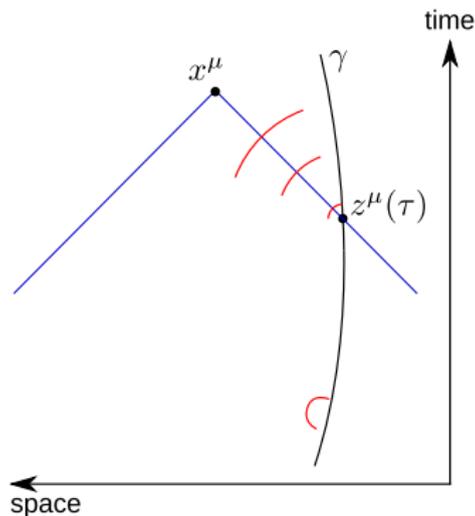
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g+h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



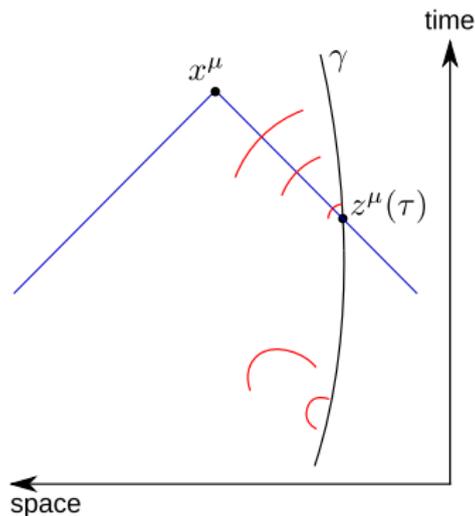
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g + h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



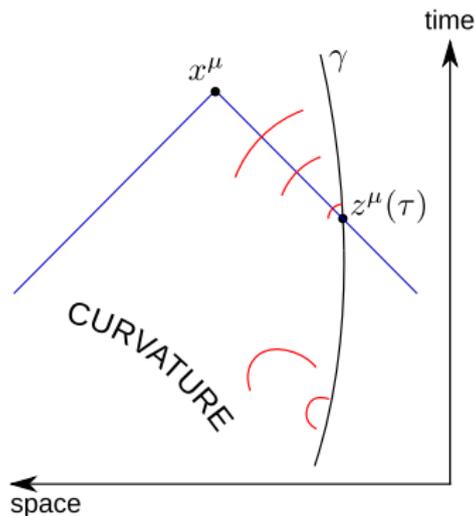
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g+h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



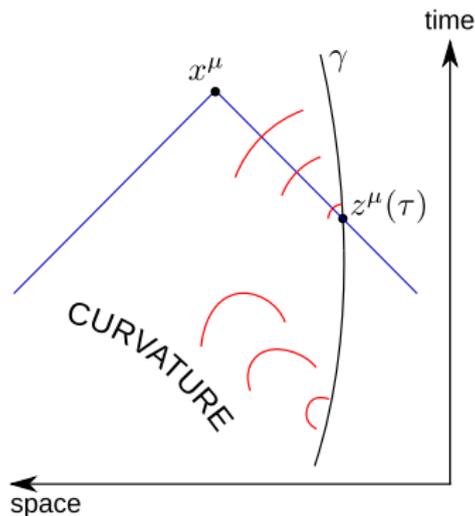
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g+h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



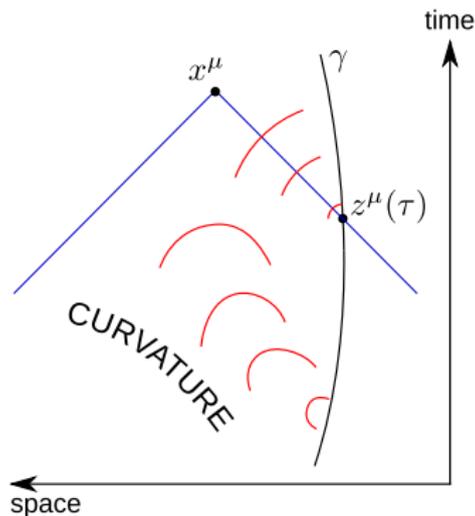
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g+h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



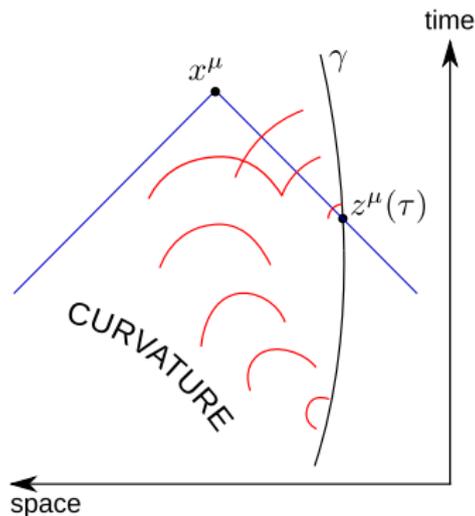
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g+h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



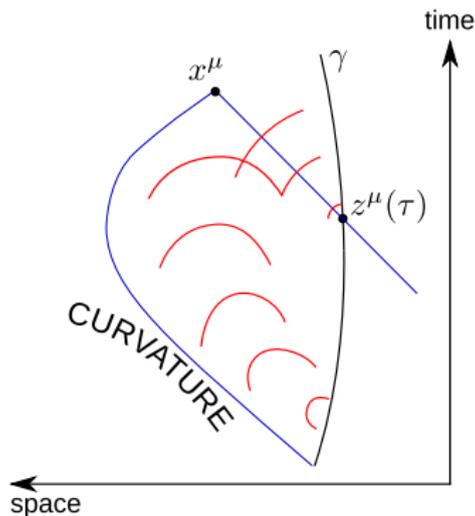
Point particle picture

Linearized theory

- treat m as point particle, with stress-energy $T^{\mu\nu} \sim m\delta^3(x^\rho - z^\rho)$
- write total metric as $g_{\mu\nu} + h_{\mu\nu}$ (e.g., $g_{\mu\nu}$ is metric of M , $h_{\mu\nu}$ is created by m)
- approximate Einstein equation $G_{\mu\nu}[g+h] = 8\pi T_{\mu\nu}$ with linearized EFE $\delta G^{\mu\nu}[h] = 8\pi T^{\mu\nu}$

Tail

- part of perturbation propagates slower than light
- light “cone” bends
 $\therefore h_{\mu\nu}$ depends on past history



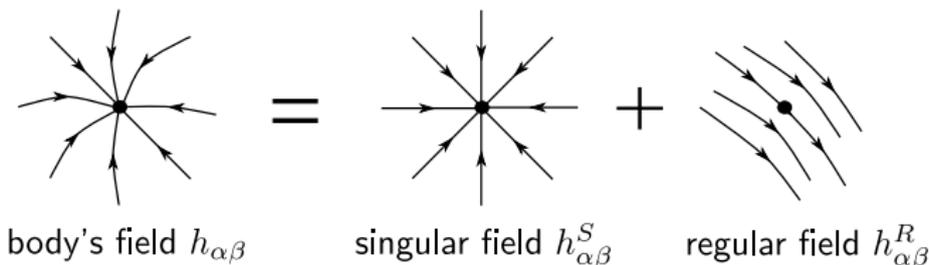
Self-force: geodesic motion in an effective metric

MiSaTaQuWa equation [Mino, Sasaki, Tanaka; Quinn & Wald]

- nonlocal tail acts as potential, exerts force $F^\mu \sim m \nabla^\mu \text{tail}$
- tail isn't nice: non-differentiable, not a solution to a field equation

Generalized equivalence principle [Detweiler & Whiting]

- local field near particle split into two: $h_{\mu\nu}^{(1)} = h_{\mu\nu}^{S(1)} + h_{\mu\nu}^{R(1)}$
- $h_{\mu\nu}^{S(1)} \sim \frac{m}{r} + O(r^0)$; local bound field of particle
- $h_{\mu\nu}^{R(1)} \sim \text{tail} + \text{local terms}$; smooth solution to source-free EFE
- motion is geodesic in effective metric $g_{\mu\nu} + h_{\mu\nu}^{R(1)}$



Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object**
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

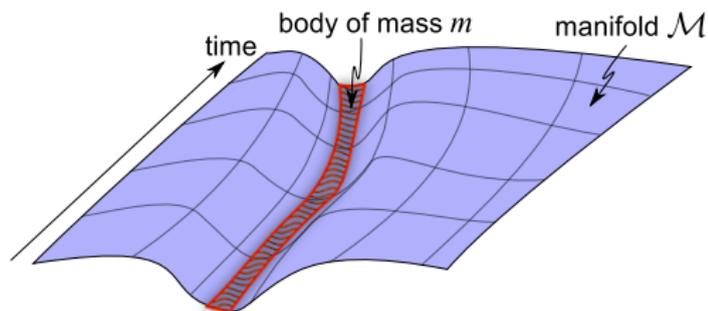
A small extended object moving through spacetime

Fundamental question

how does an object's own gravitational field affect its motion?

Regime: small object

- examine spacetime $(\mathcal{M}, g_{\mu\nu})$ containing object of mass m and external lengthscales \mathcal{R}
- seek representation of object's motion when its mass and size are $\ll \mathcal{R}$



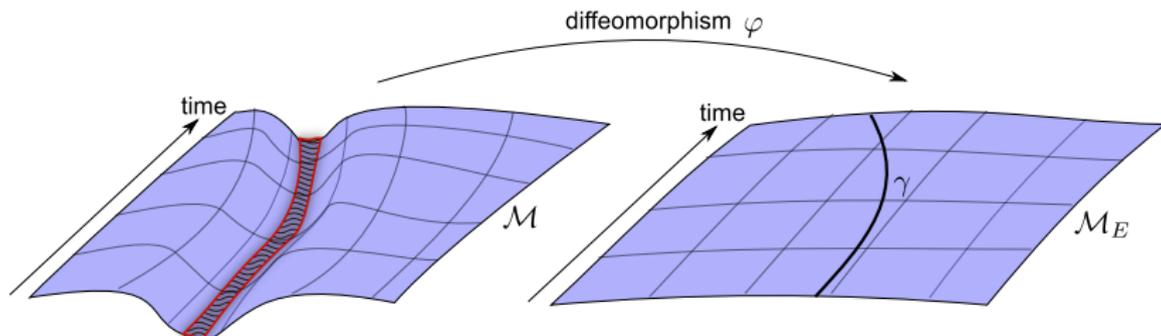
Perturbative description

[Mino, Sasaki, Tanaka; Quinn & Wald; Detweiler & Whiting; Gralla & Wald; Pound; Harte]

- treat object as source of perturbation of external background spacetime $(\mathcal{M}_E, g_{\mu\nu})$:

$$g_{\mu\nu} = g_{\mu\nu} + \epsilon h_{\mu\nu}^{(1)} + \epsilon^2 h_{\mu\nu}^{(2)} + \dots$$

- ϵ counts powers of m
- assume object is compact, so as $m \rightarrow 0$, linear size $\rightarrow 0$ at same rate
- seek representation of motion in $(\mathcal{M}_E, g_{\mu\nu})$



Body in exact spacetime

Representation of motion
in external spacetime

Challenges in applying perturbation theory

Multiple time scales in binary

- orbital period ($\sim M$)
- time over which inspiral occurs ($\sim M^2/m$)

Multiple length scales

- near small object: scale of object's size ($\sim m$)
- everywhere else: scale of external universe ($\sim M$)

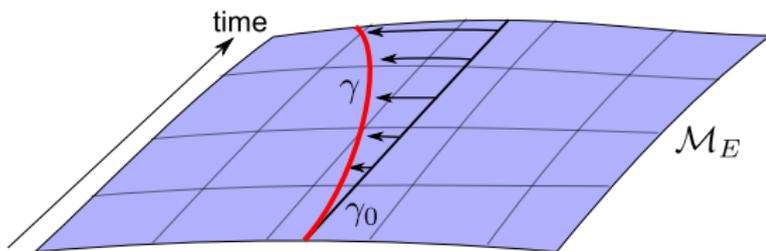
Identifying object's position, spin, higher moments

- point particle not valid in nonlinear field theory such as GR
- how do we capture bulk parameters without worrying about details of object's composition?
- how do we best represent the small object's bulk motion (e.g., identify its "center")?

Long time scales: self-consistent approximation

Worldline

rather than find small corrections to zeroth-order motion, seek worldline $\gamma(\tau, \epsilon)$ that tracks object's bulk motion

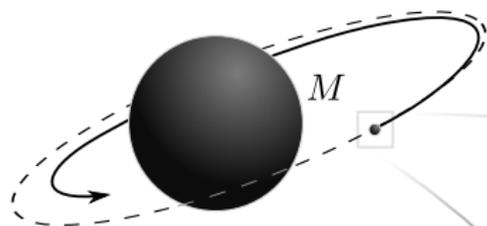


Self-consistent expansion

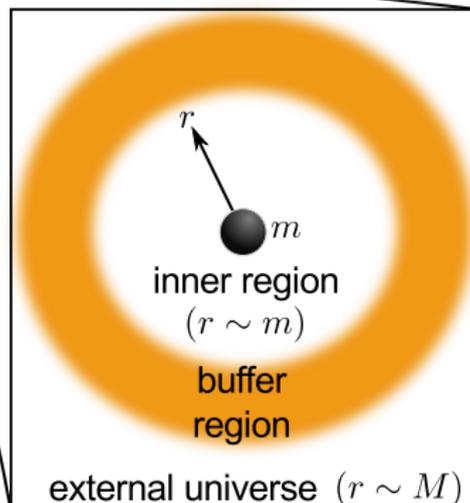
- since $h_{\mu\nu}$ depends on γ , can't expand $h_{\mu\nu}$ in regular power series without also expanding γ
- allow γ to depend on ϵ and assume expansion of form

$$\begin{aligned} \mathfrak{g}_{\mu\nu}(x, \epsilon) &= g_{\mu\nu}(x) + h_{\mu\nu}(x, \epsilon; \gamma) \\ &= g_{\mu\nu}(x) + \epsilon h_{\mu\nu}^{(1)}(x; \gamma) + \epsilon^2 h_{\mu\nu}^{(2)}(x; \gamma) + \dots \end{aligned}$$

Small length scales: matched asymptotic expansions



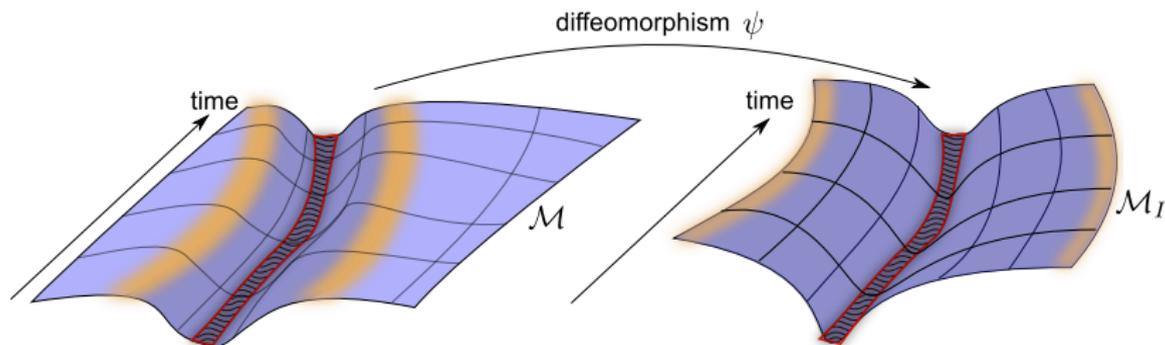
- define buffer region by $m \ll r \ll \mathcal{R}$
- because $m \ll r$, can treat mass as small perturbation of external background
- because $r \ll \mathcal{R}$, can extract information about small object



Matched asymptotic expansions: the *inner expansion*

Zoom in on object

- use scaled coords $\tilde{r} \sim r/\epsilon$ to keep size of object fixed, send other distances to infinity as $\epsilon \rightarrow 0$
- unperturbed object defines background spacetime $g_{I\mu\nu}$ in inner expansion
- buffer region at asymptotic infinity $r \gg m$
 \Rightarrow can define multipole moments without integrals over object



Position at first order: self-consistent definition

Mass dipole about γ

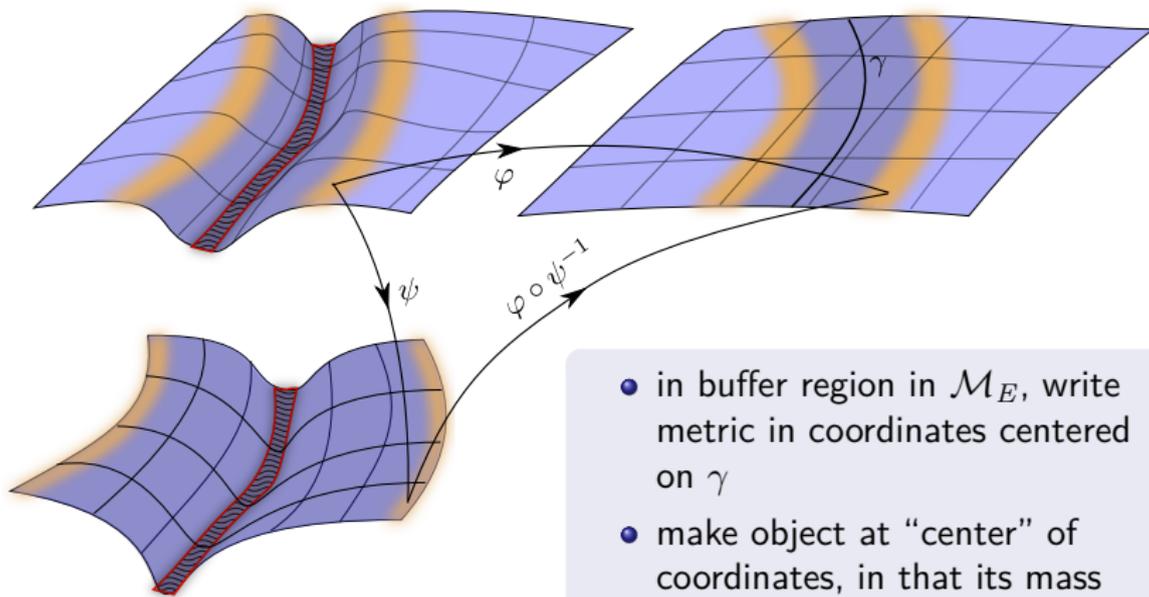
We want to find worldline γ for which $M^\mu = 0$

- work in coordinates centered on unspecified γ
- calculate mass dipole M^μ of inner background $g_{I\mu\nu}$
- first-order acceleration of γ : whatever ensures $M^\mu \equiv 0$

Position in self-consistent expansion (continued)

Enforce a relationship between the expansions

...to define a worldline for all time, even for black hole



- in buffer region in \mathcal{M}_E , write metric in coordinates centered on γ
- make object at “center” of coordinates, in that its mass dipole vanishes in \mathcal{M}_I

Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

Solving the EFE in buffer region

Expansion for small r

- in coordinates centered on γ , allow all negative powers of r in $h_{\mu\nu}^{(n)}$
- but inner expansion must not have negative powers of ϵ
 \Rightarrow most negative power of r in $\epsilon^n h_{\mu\nu}^{(n)}$ is $\frac{\epsilon^n}{r^n} = \frac{\epsilon^n}{\epsilon^n \tilde{r}^n} = \frac{1}{\tilde{r}^n}$

Therefore

$$h_{\mu\nu}^{(n)} = \frac{1}{r^n} h_{\mu\nu}^{(n,-n)} + r^{-n+1} h_{\mu\nu}^{(n,-n+1)} + r^{-n+2} h_{\mu\nu}^{(n,-n+2)} + \dots$$

Information from inner expansion

- $1/\tilde{r}^n$ terms arise from asymptotic expansion of zeroth-order background in inner expansion
 $\Rightarrow h_{\mu\nu}^{(n,-n)}$ is determined by multipole moments of isolated object

Form of solution in buffer region

What appears in the solution?

- put expansion into n th-order wave equation, solve order by order in r
- expand each $h_{\mu\nu}^{(n,p)}$ in spherical harmonics (wrt angles on sphere around $r = 0$)
- given a worldline γ , the solution at all orders is fully characterized by
 - 1 object's multipole moments (and corrections thereto): $\sim \frac{Y^{\ell m}}{r^{\ell+1}}$
 - 2 smooth solutions to vacuum wave equation: $\sim r^\ell Y^{\ell m}$
- everything else made of (linear or nonlinear) combinations of the above

Self field and regular field

- multipole moments define $h_{\mu\nu}^{S(n)}$; interpret as bound field of object
- smooth homogeneous solutions define $h_{\mu\nu}^{R(n)}$; free radiation, determined by global boundary conditions

Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

First and second order solutions

First order

- $h_{\mu\nu}^{(1)} = h_{\mu\nu}^{S(1)} + h_{\mu\nu}^{R(1)}$
- $h_{\mu\nu}^{S(1)} \sim 1/r + O(r^0)$ defined by mass monopole m
- $h_{\mu\nu}^{R(1)}$ is undetermined homogenous solution regular at $r = 0$
- evolution equations: $\dot{m} = 0$ and $a_{(0)}^\mu = 0$
(where $\frac{D^2 z^\mu}{d\tau^2} = a_{(0)}^\mu + \epsilon a_{(1)}^\mu + \dots$)

Second order

- $h_{\mu\nu}^{(2)} = h_{\mu\nu}^{S(2)} + h_{\mu\nu}^{R(2)}$
- $h_{\mu\nu}^{S(2)} \sim 1/r^2 + O(1/r)$ defined by
 - 1 monopole correction δm
 - 2 mass dipole M^μ (set to zero)
 - 3 spin dipole S^μ
- evolution equations: $\dot{S}^\mu = 0$, $\delta \dot{m} = \dots$, and $a_{(1)}^\mu = \dots$

Equation of motion

MiSaTaQuWa-Mathisson-Papapetrou equation

$$a_{(1)}^{\alpha} = -\frac{1}{2} (g^{\alpha\delta} + u^{\alpha} u^{\delta}) \left(2h_{\delta\beta;\gamma}^{R(1)} - h_{\beta\gamma;\delta}^{R(1)} \right) u^{\beta} u^{\gamma} + \frac{1}{2m} R^{\alpha}{}_{\beta\gamma\delta} u^{\beta} S^{\gamma\delta}$$

- self-force (due to regular field) + Papapetrou spin-force
- together with $\dot{m} = 0$ and $\dot{S}^{\mu\nu} = 0$
- through order ϵ , small object moves as a test body in $g_{\mu\nu} + h_{\mu\nu}^R$

Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

Why second order?

Modeling EMRIs

- inspiral occurs very slowly, on time scale $t \sim 1/m$
 - neglecting second-order self-force leads to error in acceleration
 $\delta a^\mu \sim m^2$
 \Rightarrow error in position $\delta z^\mu \sim m^2 t^2$
 \Rightarrow after time $t \sim 1/m$, error $\delta z^\mu \sim 1$
- \therefore accurately describing orbital evolution requires second-order force

Modeling IMRIs and similar-mass binaries

- second-order self-force should yield highly accurate model for IMRIs
- will fix terms quadratic in mass in post-Newtonian and Effective One Body theory

Position at second order: mass-centered gauges

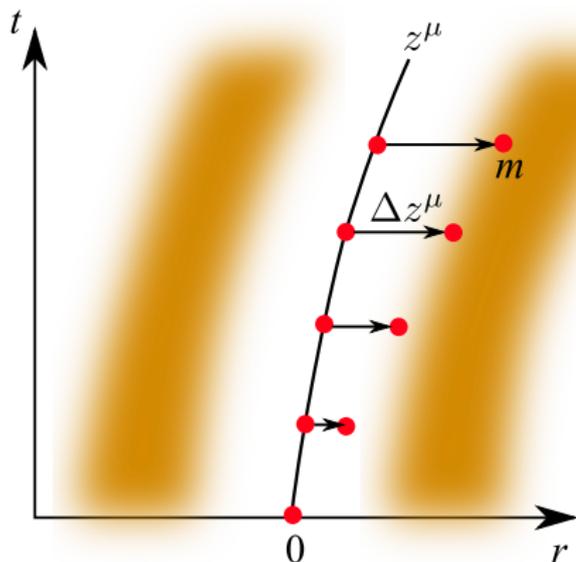
Problem

- mass dipole moment defined for asymptotically flat spacetimes
- beyond zeroth order, inner expansion is not asymptotically flat

Solution

- find gauge in which field is manifestly mass-centered on γ
- define position in other gauges by referring to transformation to that mass-centered gauge

Position at second order [Pound]



- start in gauge mass-centered on z^μ
- demand that transformation to practical (e.g., Lorenz) gauge does not move z^μ
- i.e., insist $\Delta z^\mu = 0$
- ensures worldline in the two gauges is the same

Self-consistent equation of motion [Pound]

Neglecting object's spin and quadrupole moment,

$$\frac{D^2 z^\mu}{d\tau^2} = \frac{1}{2} (g^{\mu\nu} + u^\mu u^\nu) (g_\nu{}^\rho - h_\nu^{\text{R}\rho}) (h_{\sigma\lambda;\rho}^{\text{R}} - 2h_{\rho\sigma;\lambda}^{\text{R}}) u^\sigma u^\lambda + O(\epsilon^3)$$

- here $h_{\mu\nu}^{\text{R}} = \epsilon h_{\mu\nu}^{\text{R}(1)} + \epsilon^2 h_{\mu\nu}^{\text{R}(2)}$

Generalized equivalence principle

- z^μ satisfies geodesic equation in $g_{\mu\nu} + h_{\mu\nu}^{\text{R}}$
- recall: here $g_{\mu\nu} + h_{\mu\nu}^{\text{R}}$ is a “physical” field in the sense of satisfying vacuum EFE
- extends results of Detweiler-Whiting to second order

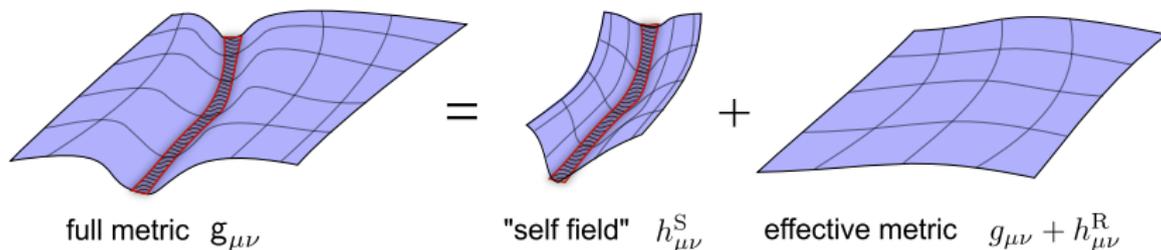
Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field**
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

Effective interior metric

From self-field to singular field

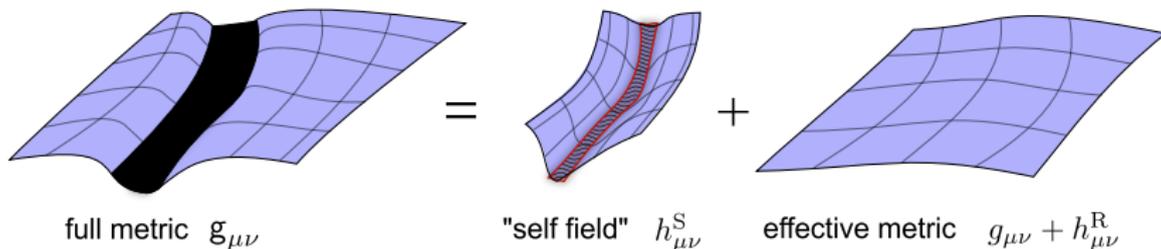
- $h_{\mu\nu}^S$ and $h_{\mu\nu}^R$ derived only in buffer region
- simply extend them to all $r > 0$ (and $r = 0$, for $h_{\mu\nu}^R$)
- does not change field in buffer region or beyond



Effective interior metric

From self-field to singular field

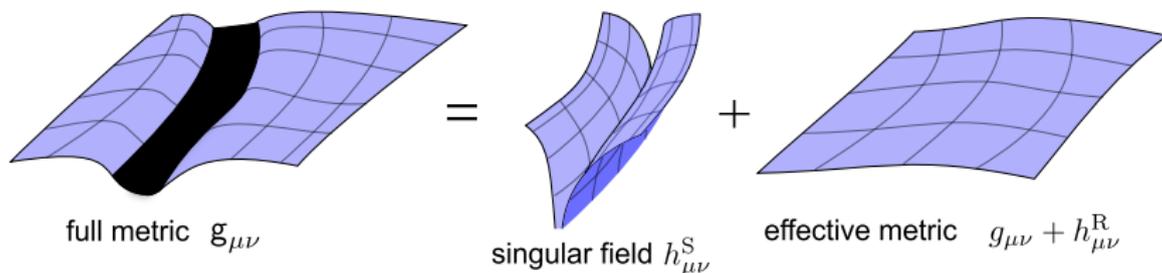
- $h_{\mu\nu}^S$ and $h_{\mu\nu}^R$ derived only in buffer region
- simply extend them to all $r > 0$ (and $r = 0$, for $h_{\mu\nu}^R$)
- does not change field in buffer region or beyond



Effective interior metric

From self-field to singular field

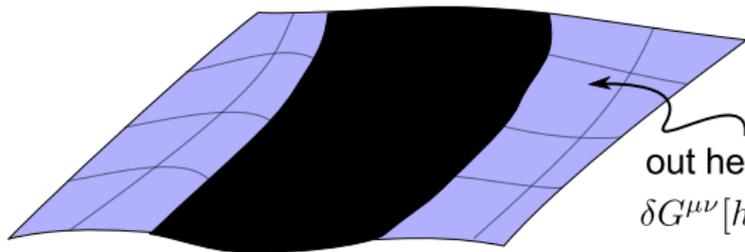
- $h_{\mu\nu}^S$ and $h_{\mu\nu}^R$ derived only in buffer region
- simply extend them to all $r > 0$ (and $r = 0$, for $h_{\mu\nu}^R$)
- does not change field in buffer region or beyond



Obtaining global solution

Puncture/effective source scheme

- define $h_{\mu\nu}^{\mathcal{P}}$ as small- r expansion of $h_{\mu\nu}^{\mathcal{S}}$ truncated at finite order in r
- define $h_{\mu\nu}^{\mathcal{R}} = h_{\mu\nu} - h_{\mu\nu}^{\mathcal{P}} \simeq h_{\mu\nu}^{\mathcal{R}}$



in here, solve

$$\delta G^{\mu\nu}[h_{\rho\sigma}^{\mathcal{R}(2)}] = -\delta^2 G^{\mu\nu}[h_{\rho\sigma}^{(1)}] - \delta G^{\mu\nu}[h_{\rho\sigma}^{\mathcal{P}(2)}]$$

out here, solve

$$\delta G^{\mu\nu}[h_{\rho\sigma}^{(2)}] = -\delta^2 G^{\mu\nu}[h_{\rho\sigma}^{(1)}]$$

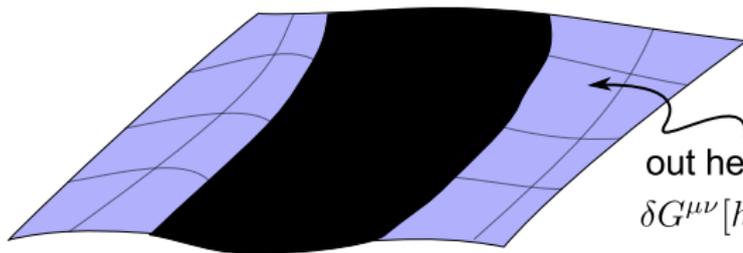
The point...

- to calculate effective metric “inside” object and full metric everywhere else, all you need is $h_{\mu\nu}^{\mathcal{S}}$ found in buffer region

Obtaining global solution

Puncture/effective source scheme

- define $h_{\mu\nu}^{\mathcal{P}}$ as small- r expansion of $h_{\mu\nu}^{\mathcal{S}}$ truncated at finite order in r
- define $h_{\mu\nu}^{\mathcal{R}} = h_{\mu\nu} - h_{\mu\nu}^{\mathcal{P}} \simeq h_{\mu\nu}^{\mathcal{R}}$



in here, solve

$$\delta G^{\mu\nu}[h_{\rho\sigma}^{\mathcal{R}(2)}] = -\delta^2 G^{\mu\nu}[h_{\rho\sigma}^{(1)}] - \delta G^{\mu\nu}[h_{\rho\sigma}^{\mathcal{P}(2)}]$$

out here, solve

$$\delta G^{\mu\nu}[h_{\rho\sigma}^{(2)}] = -\delta^2 G^{\mu\nu}[h_{\rho\sigma}^{(1)}]$$

The point...

- to calculate effective metric “inside” object and full metric everywhere else, all you need is $h_{\mu\nu}^{\mathcal{S}}$ found in buffer region

Particles and punctures

A particle at linear order

can show that the linear field $h_{\mu\nu}^1$ is identical to one sourced by a point mass m moving on γ

\Rightarrow *exactly recover the point particle picture*

A puncture at any order

the field outside the object, and the object's bulk motion, can be computed by *replacing the object with a puncture equipped with a set of multipole moments*

\Rightarrow generalizes the idea of a point particle

(A note on “regularization”: we never introduce divergent quantities that have to be regularized—every quantity is finite at every step of every calculation)

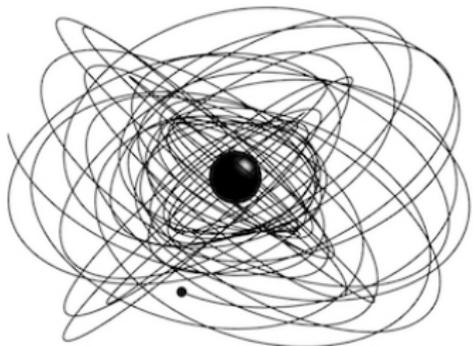
Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

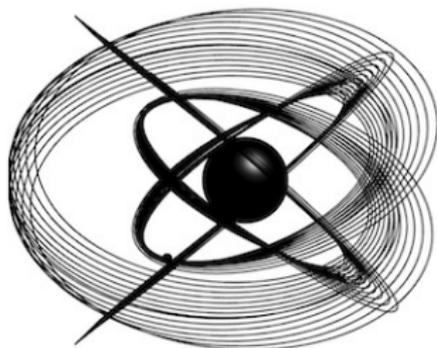
Geodesics in Kerr



[Steve Drasco]

- geodesic characterized by three constants of motion:
 - 1 energy E
 - 2 angular momentum L_z
 - 3 Carter constant Q , related to orbital inclination

- E , L_z , Q related to frequencies of r , ϕ , and θ motion
- *resonances* occur when two frequencies have a rational ratio



[Steve Drasco]

Hierarchy of self-force models [Hinderer & Flanagan]

- when self-force is accounted for, E , L_z , and Q evolve with time
- on an inspiral timescale $t \sim \frac{M^2}{m}$, the phase of the gravitational wave has an expansion

$$\phi = \frac{M}{m} \left[\phi_0 + \frac{m}{M} \phi_1 + O\left(\frac{m^2}{M^2}\right) \right]$$

- a model that gets ϕ_0 right is probably enough for signal detection in many cases
- a model that gets both ϕ_0 and ϕ_1 is enough for parameter extraction
- passage through resonances complicates the expansion, but post-adiabatic requirements are unaltered

Hierarchy of self-force models

[Hinderer & Flanagan]

Adiabatic order

is accounted for, E , L_z , and Q evolve with time
 determined by
 • averaged dissipative piece of F_1^μ , the phase of the gravitational wave

$$\phi = \frac{M}{m} \phi_0 + \frac{m}{M} \phi_1 + O\left(\frac{m^2}{M^2}\right)$$

- a model that gets ϕ_0 right is probably enough for signal detection in many cases
- a model that gets both ϕ_0 and ϕ_1 is enough for parameter extraction
- passage through resonances complicates the expansion, but post-adiabatic requirements are unaltered

Hierarchy of self-force models

[Hinderer & Flanagan]

Adiabatic order

determined by

- averaged dissipative piece of F_1^μ

Post-adiabatic order

determined by

- averaged dissipative piece of F_2^μ
- conservative piece of F_1^μ
- oscillatory dissipative piece of F_1^μ

$$\phi = \frac{M}{m} \left[\phi_0 + \frac{m}{M} \phi_1 + O\left(\frac{m^2}{M^2}\right) \right]$$

- a model that gets ϕ_0 right is probably enough for signal detection in many cases
- a model that gets both ϕ_0 and ϕ_1 is enough for parameter extraction
- passage through resonances complicates the expansion, but post-adiabatic requirements are unaltered

Orbital evolution

- adiabatic evolution schemes in Kerr already devised and implemented (modulo resonances) [Mino, Drasco et al, Sago et al]
 - also, complete inspirals simulated in Schwarzschild including full F_1^μ
 - should soon be possible in Kerr
 - but still need F_2^μ for accurate post-adiabatic inspiral

[Warburton et al 2011, image courtesy of Warburton]

Outline

- 1 Motivation
- 2 Motion of a point particle
- 3 Motion of a small extended object
- 4 Equation of motion at first and second order
 - First-order equation of motion
 - Second-order equation of motion
- 5 Computing the field
- 6 Modeling binaries (i.e., concrete results)
 - EMRIs
 - Other binaries

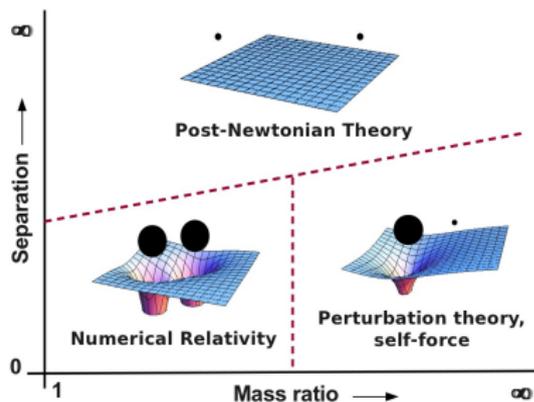
Improving other binary models

PN and EOB models have been improved using data for *conservative* effects of the self-force (computed by “turning off” dissipation)

- orbital precession [Barack et al.]
- ISCO shift [Barack and Sago, Isoyama et al.]
- Detweiler’s redshift invariant $\frac{dt}{d\tau^R}$ on circular orbits [Detweiler, Shah et al., Dolan and Barack]
- averaged redshift $\left\langle \frac{dt}{d\tau^R} \right\rangle$ on eccentric orbits [Barack et al., van de Meent & Shah]

- spin precession [Dolan et al.]
- quadrupolar and octupolar self-tides [Dolan et al, Damour and Bini]

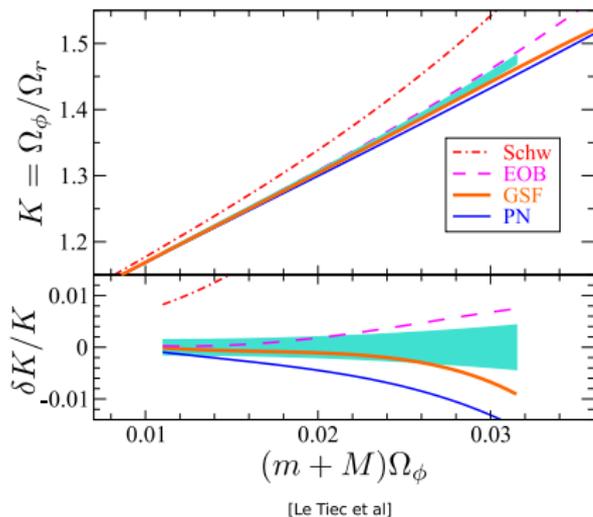
Binary parameter space



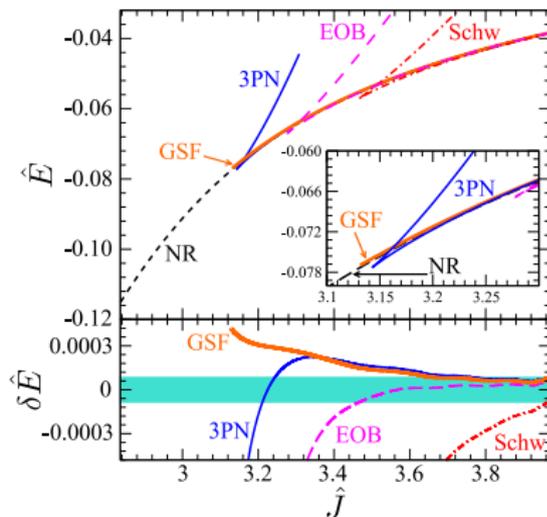
[Leor Barack]

Using SF to *directly* model other binariesComparisons for **equal-mass** binaries

Orbital precession



Gravitational binding energy



- SF results use “mass symmetrized” model: $\frac{m}{M} \rightarrow \frac{mM}{(m+M)^2}$
- with mass-symmetrization, second-order self-force might be able to directly model even similar-mass binaries

Calculations performed as of 2005

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓		
	generic	✓		
Kerr	circular			
	generic (w/o resonances)			
	generic (w/ resonances)			

Calculations performed as of 2006

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓		
	generic	✓		
Kerr	circular	✓		
	generic (w/o resonances)			
	generic (w/ resonances)			

Calculations performed as of 2007

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓	✓	
	generic	✓		
Kerr	circular	✓		
	generic (w/o resonances)			
	generic (w/ resonances)			

Calculations performed as of 2009

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓	✓	
	generic	✓		
Kerr	circular	✓		
	generic (w/o resonances)	✓		
	generic (w/ resonances)			

Calculations performed as of 2010

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓	✓	
	generic	✓	✓	
Kerr	circular	✓		
	generic (w/o resonances)	✓		
	generic (w/ resonances)			

Calculations performed as of 2012

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓	✓	
	generic	✓	✓	
Kerr	circular	✓	✓	
	generic (w/o resonances)	✓		
	generic (w/ resonances)			

Calculations performed as of 2015

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓	✓	<i>underway</i>
	generic	✓	✓	
Kerr	circular	✓	✓	
	generic (w/o resonances)	✓	<i>underway</i>	
	generic (w/ resonances)	<i>underway</i>	<i>underway</i>	

Calculations performed as of ????

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓	✓	<i>underway</i>
	generic	✓	✓	
Kerr	circular	✓	✓	
	generic (w/o resonances)	✓	<i>underway</i>	
	generic (w/ resonances)	<i>underway</i>	<i>underway</i>	holy grail

Conclusion

Formalism: motion of a small object

- in principle, no obstacle to going to arbitrary order
- through second order in its mass, a nonspinning compact object moves on a geodesic in a vacuum geometry $g_{\mu\nu} + h_{\mu\nu}^{\text{R}}$
- $h_{\mu\nu}^{\text{R}}$ can be computed by replacing the object with an analytically known puncture

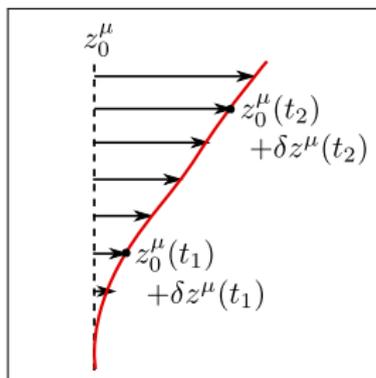
Status of binary modeling

- wealth of numerical results at first order
- calculations at second order are underway [Wednesday talks]
- second-order equations have so far neglected spin and quadrupole moment of object—need to include them through second order for accurate modeling

Using the local self-force in evolution

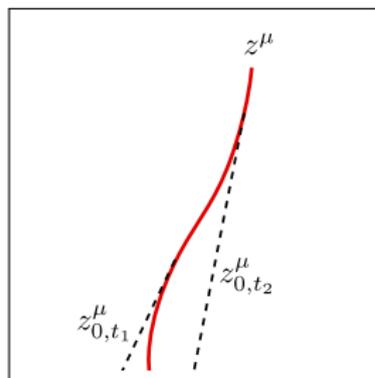
Gralla-Wald

- source of $h_{\mu\nu}^1$ moves on Kerr geodesic z_0^μ
- calculate shift δz^μ relative to z_0^μ
- error grows large with time



Geodesic-source + osculation

- at each t , source moves on instantaneously tangential geodesic $z_{0,t}^\mu$
- error $\sim (m/M)^2$



Self-consistent [Pound]

- source moves on the accelerated orbit z^μ
- only been implemented in scalar field model

