

# Self-force: Foundations and formalism

Abraham Harte

Max Planck Institute for Gravitational Physics  
Albert Einstein Institute  
Golm, Germany

June 27, 2016

19th Capra Meeting  
Meudon

- 1 What is the self-force? What is it not?
- 2 The problem of motion
- 3 Detweiler-Whiting: What and why?

# What is the self-force?



What is the (net) force that something exerts on itself?

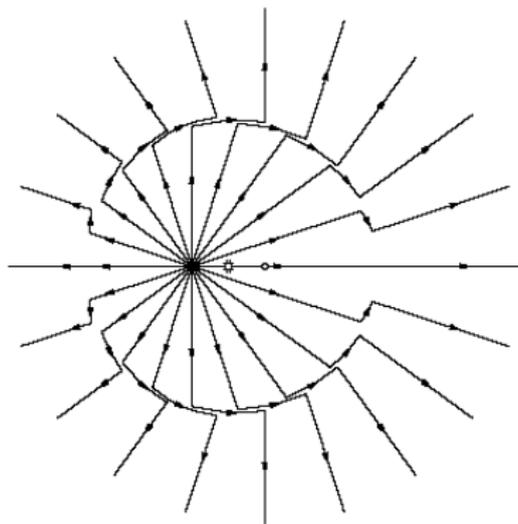
What is the (net) force that something can exert on itself?

A bit vague.

But you know it when you see it. . .

# Radiation reaction

Objects coupled to long-range fields can radiate.



They must move in reaction to emitted energy, momentum, etc.

# Radiation reaction II



# Not only radiation reaction

Momentum carried by radiation implies a (self-) force:

- This can sometimes be used to calculate said force.
- But objects don't really "care" what's happening to fields far away from them: It's indirect.

Also, there can be nonradiative self-forces. . .

# What is the self-force not?

Sometimes (misleadingly!) identified with

- Radiation reaction
- 2-body problem, esp. small mass ratios
- Black hole perturbation theory

These are special cases. . .

Self-force is just one aspect of the general problem of motion

But it's an interesting and often challenging aspect.

Look at the general problem of motion...

# Approaches to motion problems

Consider a compact clump of matter interacting with long-range fields (charged solid in Maxwell EM, star in GR, ...)

- 1 Either **compute “everything”** (numerics)
  - *Many inputs*: detailed matter model, initial and boundary conditions
  - *Complicated output*: detailed density, velocity, temperature fields
  - “Complete”
  - **Describes only very specific systems**
- 2 ...or **focus only on a few “bulk” or “external” quantities** (CM etc.)
  - *Simple input*
  - *Simple output*: center of mass, spin, ...
  - Not complete
  - **Can describe large classes of systems simultaneously**

# Internal and external variables in celestial mechanics

Ordinary celestial mechanics makes “PDEs  $\rightarrow$  ODEs:”

## External (or bulk) variables

Center of mass positions  
Linear momenta  
Angular momenta

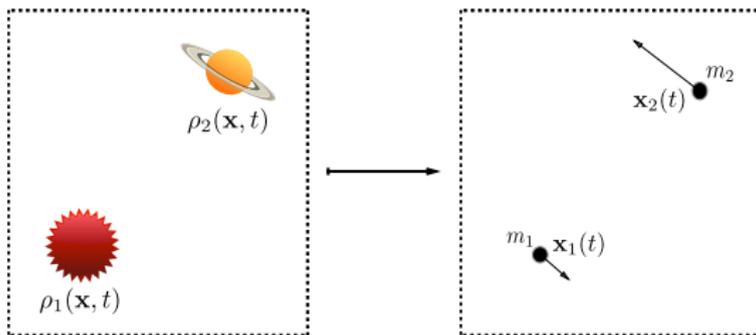
## Internal variables

Density distributions  
Internal velocities  
Thermodynamic variables

*Focus on the external variables.*

## Example: Newtonian $N$ -body problem

$N$  points in  $\mathbb{R}^3$ , described only by their positions and (constant) masses. Positions evolve via simple **ODEs**, not **PDEs**.



Tremendous (and useful) simplification over the full continuum mechanics. Derivation is well-understood.

Can this be repeated in electromagnetism, GR, ...?

## A question

In what sense is it true that  $D\dot{z}^a/ds = 0$  for freely-falling masses?

Clearly true in *some* limits.

But interesting regimes require being precise about

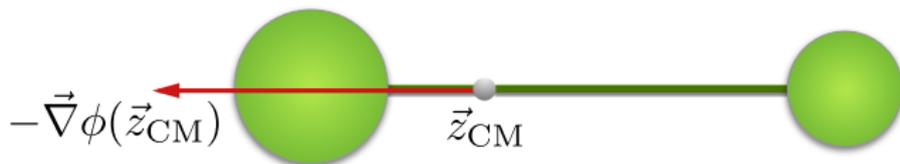
- 1  $z(s)$ ,
- 2  $D/ds$ .

# Nontrivial even in Newtonian gravity

Using  $z(s) \rightarrow \vec{z}_{\text{CM}}(t)$ ,

$$\frac{D\dot{z}^a}{ds} = 0 \quad \longrightarrow \quad \frac{d^2\vec{z}_{\text{CM}}}{dt^2} = -\vec{\nabla}\phi(\vec{z}_{\text{CM}}).$$

But this is false even for an isolated body:



Self-fields require  $\phi(\vec{z}_{\text{CM}})$  to be replaced by something else  
[adding higher moments doesn't help]

Self-gravitating Newtonian masses can be described by replacing  $\phi(\vec{z}_{\text{CM}}) \rightarrow \phi_{\text{ext}}(\vec{z}_{\text{CM}})$  in the test body equation.

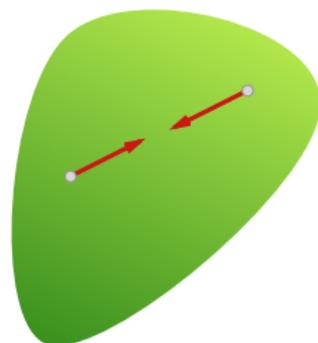
A body  $\mathcal{B}$  moves in an “effective field”  $\phi_{\text{ext}}$  which is *nonlocally related* to the physical one:

$$\begin{aligned}
 \phi_{\text{ext}}[\phi; \mathcal{B}] &= \phi - \phi_{\text{self}} \\
 &= \phi - \left( - \int_{\mathcal{B}} \frac{\rho(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3\vec{x}' \right) \\
 &= \phi - \left( - \frac{1}{4\pi} \int_{\mathcal{B}} \frac{\nabla'^2 \phi}{|\vec{x} - \vec{x}'|} d^3\vec{x}' \right) \\
 &= \frac{1}{4\pi} \oint_{\partial\mathcal{B}} \left[ \vec{\nabla}' \phi' \left( \frac{1}{|\vec{x} - \vec{x}'|} \right) - \phi' \vec{\nabla}' \left( \frac{1}{|\vec{x} - \vec{x}'|} \right) \right] \cdot d\vec{S}'
 \end{aligned}$$

# Why? I. No self-force

This works because  $\phi_{\text{self}}$  exerts no net force (or torque):

$$\begin{aligned}\vec{F}_{\text{self}} &= - \int_{\mathcal{B}} d^3\vec{x} \rho \vec{\nabla} \phi_{\text{self}} \\ &= - \int_{\mathcal{B}} d^3\vec{x} \rho \vec{\nabla} \int_{\mathcal{B}} d^3\vec{x}' \rho' G(\vec{x}, \vec{x}') \\ &= - \frac{1}{2} \int_{\mathcal{B}} d^3\vec{x} \int_{\mathcal{B}} d^3\vec{x}' \rho \rho' (\vec{\nabla} + \vec{\nabla}') G(\vec{x}, \vec{x}') \\ &= - \frac{1}{2} \int_{\mathcal{B}} d^3\vec{x} \int_{\mathcal{B}} d^3\vec{x}' \rho \rho' \mathcal{L}_{\vec{0}} G(\vec{x}, \vec{x}') \rightarrow 0 \\ &= 0.\end{aligned}$$



Everything cancels.

## Why? II. $\phi_{\text{ext}}$ varies slowly

If bodies are well-separated,

$$\begin{aligned}\vec{F} &= \vec{F}_{\text{ext}} + \vec{F}_{\text{self}} \xrightarrow{0} \\ &= - \int_{\mathcal{B}} d^3\vec{x}\rho \vec{\nabla} \phi_{\text{ext}} \\ &= - \int_{\mathcal{B}} d^3\vec{x}\rho \vec{\nabla} (\phi_{\text{ext}}^{\text{CM}} + \dots) \\ &= -m \vec{\nabla} \phi_{\text{ext}}^{\text{CM}} + (\text{quadrupole}) + \dots\end{aligned}$$

Slow variation implies that

The point particle limit of  $\vec{\nabla} \phi_{\text{ext}}$  exists, even at  $\vec{z}_{\text{CM}}$ .

The Newtonian  $\phi \rightarrow \phi_{\text{ext}}$  suggests that in GR, **objects fall on geodesics which are *not* determined by  $\nabla_a$** . Use some “effective external” connection  $\nabla_a \rightarrow \hat{\nabla}_a$  instead:

$$\frac{\hat{D}\dot{z}^a}{ds} = 0 \quad \text{with} \quad \frac{\hat{D}}{ds} = \dot{z}^b \hat{\nabla}_b \neq \dot{z}^b \nabla_b$$

This *can* be vacuous:

- For *any*  $z^\mu(s)$ , there exist  $\Gamma_{\nu\lambda}^\mu$  st  $\ddot{z}^\mu + \Gamma_{\nu\lambda}^\mu \dot{z}^\nu \dot{z}^\lambda = 0$ .
- Infinitely many possible connections and infinitely many sources...

But it can be useful when coupled with a “nice,” precisely-defined  $\hat{\nabla}_a$ .

# An organizing principle

In many contexts, self-force results are usefully summarized by

Detweiler-Whiting scheme [Detweiler & Whiting (2002)]

- 1 Start with test-body equation of motion
- 2 Replace all potentials/metrics by  $\phi \rightarrow \hat{\phi} := \phi - \phi_S$  for some *particular*  $\phi_S$

Direct analog of the Newtonian result, no reference to boundary conditions or initial conditions.

# Very general!

Equivalent representations exist in special cases, but nothing else works so broadly and simply:

- Exact for **Newtonian gravity & electrostatics** [??]
- **Point charges** in SR [Dirac (1938)]
- **Point particles** coupled to scalar, EM, linearized gravity in curved backgrounds [Detweiler & Whiting (2002)]
- Small masses through **2nd order in GR** [Pound (2009-)]
- Exact for **general extended bodies** in scalar, EM, GR [AIH (2008-)]
- Exact for **spin DOFs** for general extended bodies [AIH (2008-)]
- **All dimensions** (with some modification) [AIH, Taylor, Flanagan (2016)]

# Examples

Self-force in GR:

$$\frac{D}{ds}\dot{z}^a = 0 \quad \longrightarrow \quad \frac{\hat{D}}{ds}\dot{z}^a = 0$$

Self-torque in GR:

$$\frac{D}{ds}S_a = 0 \quad \longrightarrow \quad \frac{\hat{D}}{ds}S_a = 0$$

Electric charge:

$$m\ddot{z}^a = qF^a{}_b\dot{z}^b \quad \longrightarrow \quad m\ddot{z}^a = q\hat{F}^a{}_b\dot{z}^b$$

Also works with all higher multipole moments. . .

# Making this precise

None of this is useful without specifying the maps  $\phi \mapsto \hat{\phi}$ :

- 1 Always **nonlocal**:  $\hat{\phi}(x)$  depends on  $\phi$  away from  $x$ .  
 $\hookrightarrow$  Use **propagators**  $G_S(x, y, \dots)$
- 2 Usually **linear**:  $\hat{\phi} = \phi - \phi_S[\phi]$  with  $\phi_S[\phi]$  linear.  
 $\hookrightarrow$  **2-point** propagators  $G_S(x, y)$ :

$$\phi_S(x) = \int G_S(x, y) \rho(y) dy$$

- 3 Usually **nonvacuum**  $\rightarrow$  **vacuum**:  $\square \hat{\phi} = 0$  despite  $\square \phi \neq 0$ .  
 $\hookrightarrow$  Use *some* **Green function**

# Why vacuum fields?

Sufficient to “imply” slow variations:

No singularities in the point particle limit

Singularity propagation theorems [Hörmander, ...] for hyperbolic PDEs  
⇒ singularities move along along null geodesics.

No singularities in initial data mean **no singularities anywhere**.

Other possibilities do exist. . .

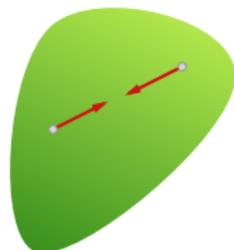
# Is that it?

No! **Nonsingular behavior is not sufficient.**

(actually meaningless for *individual* physical systems)

Also need something for which  $F_a[\phi_S]$  is “ignorable”

Generalize the cancellations of Newton’s 3rd law. . .



$$F[\phi_S] \sim 0$$

↪ More complicated than Newtonian:  $F_S = F[\phi_S] \neq 0$ ,  
but it's nevertheless ignorable.

## Renormalization

One can define  $\phi_S$  so that  $F_S$  may be absorbed into (finite!) redefinitions of mass, spin, ...

# Renormalization: An example

Consider a small charged particle with retarded BCs in flat spacetime [Abraham-Lorentz-Dirac]:

$$m\ddot{z}_a = qF_{ab}^{\text{ext}}\dot{z}^b + \frac{2}{3}q^2P_{ab}\ddot{z}^b - \delta m\ddot{z}_a$$
$$(m + \delta m)\ddot{z}_a = q(F_{ab}^{\text{ext}} + \frac{4}{3}q\dot{z}_{[a}\ddot{z}_{b]})\dot{z}^b$$

Define  $\hat{m}$  and  $\hat{F}_{ab}$  s.t.

$$\hat{m}\ddot{z}_a = q\hat{F}_{ab}\dot{z}^b$$

## Final definition for $\phi_S$

$G_S(x, y)$  defines field per charge at  $x$  **due to**  $y$ . Demand that

- 1 This is a Green function: **Slow variation**
- 2  $G_S(x, y) = G_S(y, x)$ : **Reciprocity**
- 3  $G_S(x, y) = 0$  if  $x, y$  are timelike-separated: **Locality**

These imply that  $G_S$  is constructed quasilocally from  $g_{ab}$ .

### Detweiler-Whiting Green function

$$G_S = U\delta(\sigma) + V\Theta(\sigma)$$

# Final Detweiler-Whiting scheme

- 1 Compute physical field  $\phi$ .
- 2 Use  $G_S$  to determine  $\hat{\phi}$ .
- 3 Plug  $\hat{\phi}$  into test-body equations.

This isolates an appropriate “effective external field”

Using DW metric perturbation in linearized GR [with retarded BCs](#),

$$\frac{\hat{D}\dot{z}^a}{ds} = 0$$

turns into [Detweiler & Whiting (2002)]

$$\frac{\bar{D}\dot{z}^a}{ds} = \frac{1}{2}P^{ab}(h_{bcd}^{\text{tail}} - 2h_{cdb}^{\text{tail}})\dot{z}^c\dot{z}^d,$$

with

$$h_{cab}^{\text{tail}} = 4m \lim_{\epsilon \rightarrow 0^+} \int_{-\infty}^{\tau - \epsilon} \bar{\nabla}_c G_{aba'b'}^{\text{ret}} \dot{z}^{a'} \dot{z}^{b'} d\tau'.$$

Using DW metric perturbation in linearized GR [with retarded BCs](#),

$$\frac{\hat{D}S_a}{ds} = 0$$

turns into [AIH (2012)]

$$\frac{\bar{D}S_a}{ds} = -2m\dot{z}^b\dot{z}^c\bar{R}_{abc}{}^dS_d + \frac{1}{2}\dot{z}^bS^c(h_{cab}^{\text{tail}} - 2h_{(ab)c}^{\text{tail}}).$$

## Different derivations:

### Perturbative

GR: [Pound, Gralla, Wald, . . .]

Electromagnetism: [Many!]

- Black holes ok
- Closer to “practical” things
- **Complicated calculations**
- **Difficult to modify**

### Nonperturbative

[AIH, Flanagan, Taylor]

- Exact
- General toolbox
- Physical intuition
- Easy calculations
- **No black holes**
- **Still need to solve field eqns**

Also various heuristic motivations. . .

# Summary

Laws of motion (including self-interaction) can be summarized by subtracting appropriate  $S$ -fields from physical fields.

- 1 The effects of  $\phi_S$  can all be absorbed into local redefinitions.
- 2 What remains is slowly varying—even in a point particle limit—and therefore has the same effect as the external field acting on a test body.

None of this depends on point particles or singularities. . .

# Some comments

- ① Self-force is one aspect of the problem of motion
- ② It's more about what *doesn't matter* than what does.
- ③ Still haven't talked about solving field equations [**Hard!**]

- 1 Computational tools, phenomenology, etc.
- 2 New interesting observables
- 3 Nonperturbative methods and nonlinearity
- 4 Self-interaction in other theories
  - For which types of theories do similar results hold?
  - Other physical systems (fluid mechanics, ...)