

Time Domain Method for the Green Function in Schwarzschild Spacetime

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Green Functions in Black Hole Spacetimes

- The 1st Order self-force can be decomposed as

$$F_{\text{self}}^{\alpha}(z) = F_{\text{inst}}^{\alpha} + F_{\text{hist}}^{\alpha}$$

- The historical part relates to the effects from the part of the worldline *inside* the past light cone

$$h \sim (\text{local terms}) + \lim_{\epsilon \rightarrow 0} \int_{-\infty}^{\tau^{-} - \epsilon} G_{\alpha\beta\alpha'\beta'}(z(\tau), z(\tau')) u^{\alpha'} u^{\beta'} d\tau'$$

- G is the retarded Green Function

Mino, Sasaki, Tanaka, 1997, *Phys. Rev. D* **55**

Quinn, Wald, 1997, *Phys. Rev. D* **56**

Detweiler, Whiting, 2003, *Phys. Rev. D* **67**

Green Functions in Black Hole Spacetimes

- For now, we restrict ourselves to a *scalar* self force, in Schwarzschild

$$(\square_{(4)} - \zeta R)\Phi(x) = -4\pi\rho(x)$$

- This is just a wave equation in curved spacetime, so

$$\Phi(x) = \int G(x, x')\rho(x')\sqrt{-g} d^4x'$$

$$\Rightarrow F_{\text{hist}}^\alpha(z) = q^2 g^{\alpha\beta} \lim_{\epsilon \rightarrow 0^+} \int_{-\infty}^{\tau-\epsilon} \nabla_\beta G(z(\tau), z(\tau')) d\tau'$$

- So we try to solve for a Green function, which will satisfy:

$$\left(\frac{1}{\sqrt{-g}} \partial_\mu (\sqrt{-g} g^{\mu\nu} \partial_\nu) - \zeta R \right) G(x, x') = -4\pi \frac{\delta_4(x - x')}{\sqrt{-g}}$$

Time Domain Numerical Method

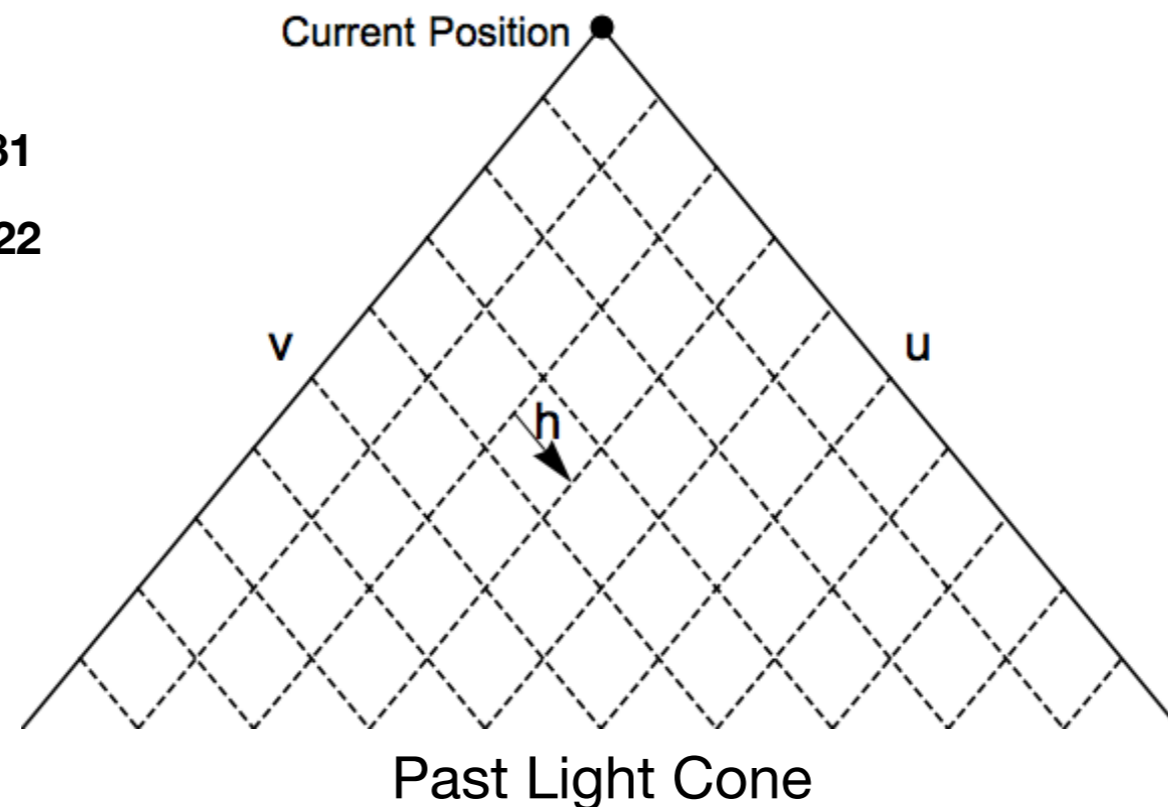
- Inside the past light cone, reduces to a 2D wave equation
- Grid in null coordinates, (u, v)

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M}{r^3}\right) G_l = 0$$

Barack, Sago, 2010, *Phys Rev D*, **81**

Lousto, 2005, *Class. Quant. Grav.* **22**

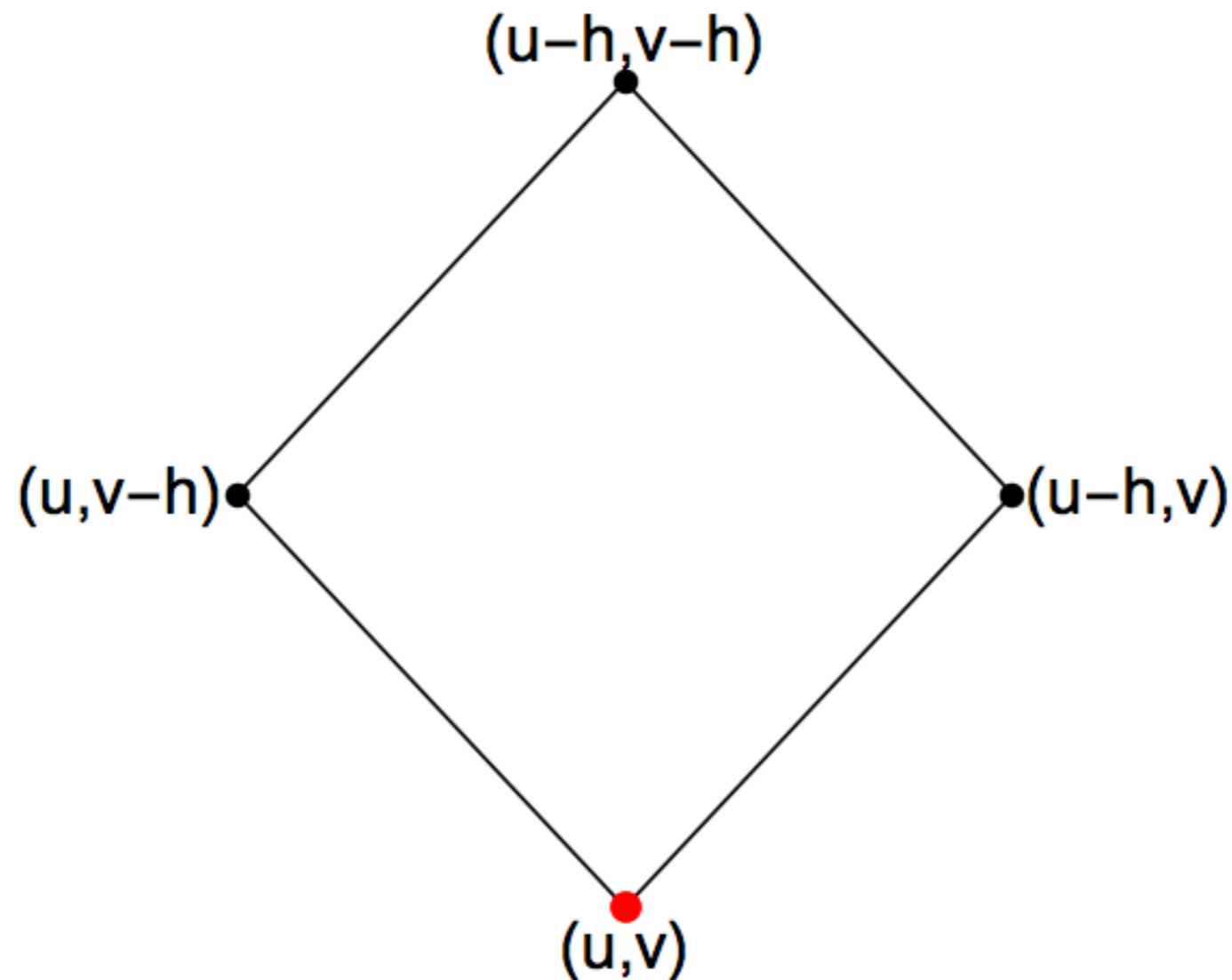
Haas, 2007, *Phys. Rev. D* **75**



Direction of numerical evolution

Time Domain Numerical Method

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M}{r^3}\right) G_l = 0$$



Points needed for 2nd Order in h

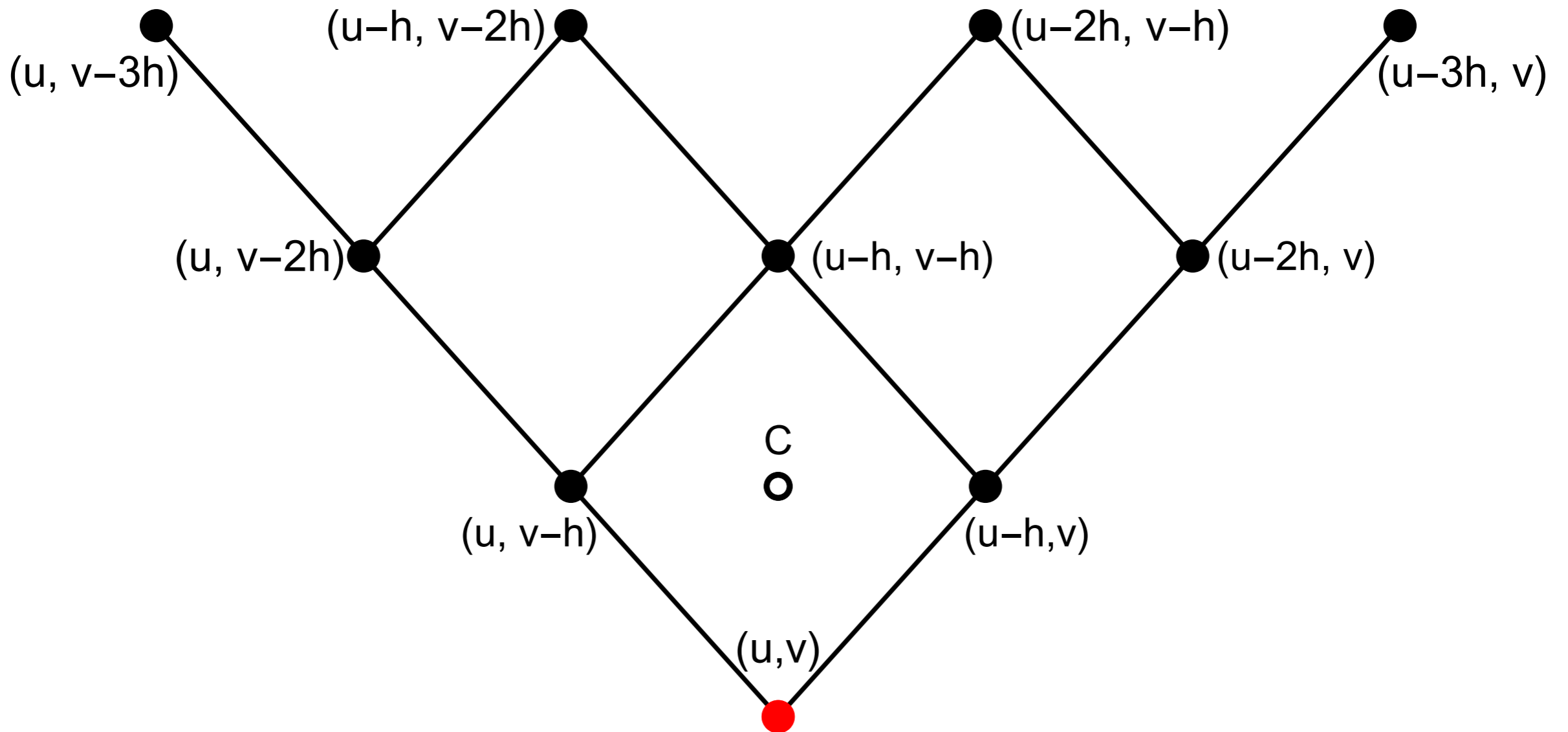
Time Domain Numerical Method

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M}{r^3}\right) G_l = 0$$

$$G_l(u, v) = -G_l(u - h, v - h) + [G_l(u - h, v) + G_l(u, v - h)] \left(1 - \frac{h^2}{2} W(u, v)\right)$$

Time Domain Numerical Method

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M}{r^3}\right) G_l = 0$$



Points needed for 4th Order in h

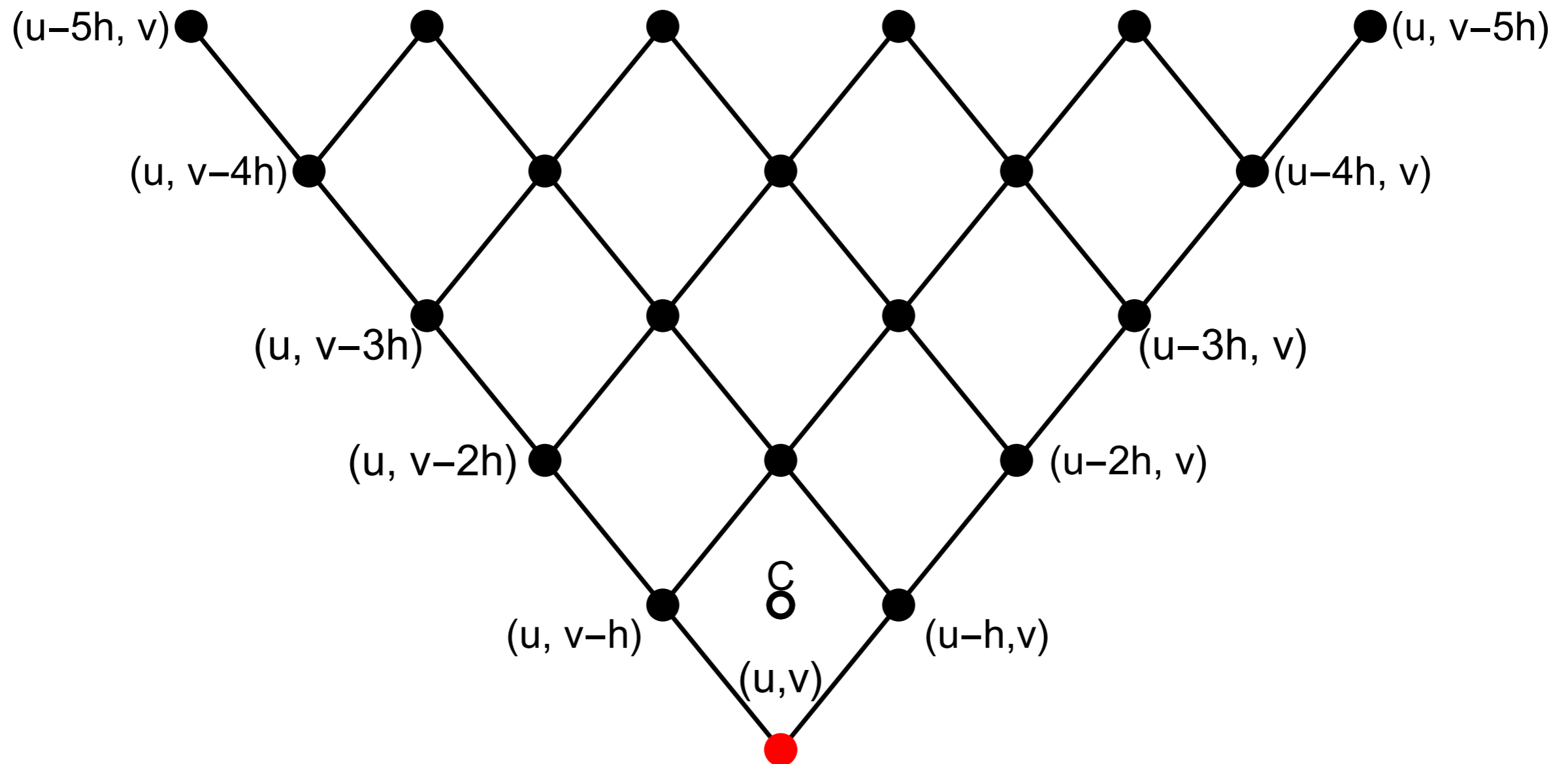
Time Domain Numerical Method

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M}{r^3}\right) G_l = 0$$

$$\begin{aligned} G_l(u, v) = & -G_l(u-h, v-h) + G_l(u, v-h) + G_l(u-h, v) \\ & -\frac{h^2}{24} \left(2W(u, v) \left(-G_l(u-h, v-h) + (G_l(u-h, v) + G_l(u, v-h)) \left(1 - \frac{h^2}{2} W(u, v) \right) \right) \right) \\ & + 10(W(u-h, v-h)G_l(u-h, v-h) + W(u, v-h)G_l(u, v-h) + W(u-h, v)G_l(u-h, v)) \\ & - 4(W(u-2h, v)G_l(u-2h, v) + W(u, v-2h)G_l(u, v-2h)) \\ & + (W(u-3h, v)G_l(u-3h, v) + W(u, v-3h)G_l(u, v-3h) \\ & - W(u-h, v-2h)G_l(u-h, v-2h) - W(u-2h, v-h)G_l(u-2h, v-h)) \end{aligned}$$

Time Domain Numerical Method

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M}{r^3}\right) G_l = 0$$



Points needed for 6th Order in h

Time Domain Numerical Method

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M}{r^3}\right) G_l = 0$$

$$\begin{aligned} G_l(u, v) = & -G_l(u-h, v-h) + G_l(u, v-h) + G_l(u-h, v) \\ & -\frac{h^2}{1440} \left(108W(u, v)G_l^{(4)}(u, v) + 371(W(u, v-3h)G_l(u, v-3h) + W(u-3h, v)G_l(u-3h, v))\right) \\ & -154(W(u-4h, v)G_l(u-4h, v) + W(u, v-4h)G_l(u, v-4h)) \\ & +116(W(u-3h, v-h)G_l(u-3h, v-h) + W(u-h, v-3h)G_l(u-h, v-3h)) \\ & +40W(u-2h, v-2h)G_l(u-2h, v-2h) \\ & +27(W(u-5h, v)G_l(u-5h, v) + W(u, v-5h)G_l(u, v-5h)) \\ & -19(W(u-4h, v-h)G_l(u-4h, v-h) + W(u-h, v-4h)G_l(u-h, v-4h)) \\ & -5(W(u-3h, v-2h)G_l(u-3h, v-2h) + W(u-2h, v-3h)G_l(u-2h, v-3h)) \\ & +627(W(u-h, v)G_l(u-h, v) + W(u, v-h)G_l(u, v-h)) \\ & +1032W(u-h, v-h)G_l(u-h, v-h) \\ & -504(W(u-2h, v)G_l(u-2h, v) + W(u, v-2h)G_l(u, v-2h)) \\ & -329(W(u-2h, v-h)G_l(u-2h, v-h) + W(u-h, v-2h)G_l(u-h, v-2h)) \end{aligned}$$

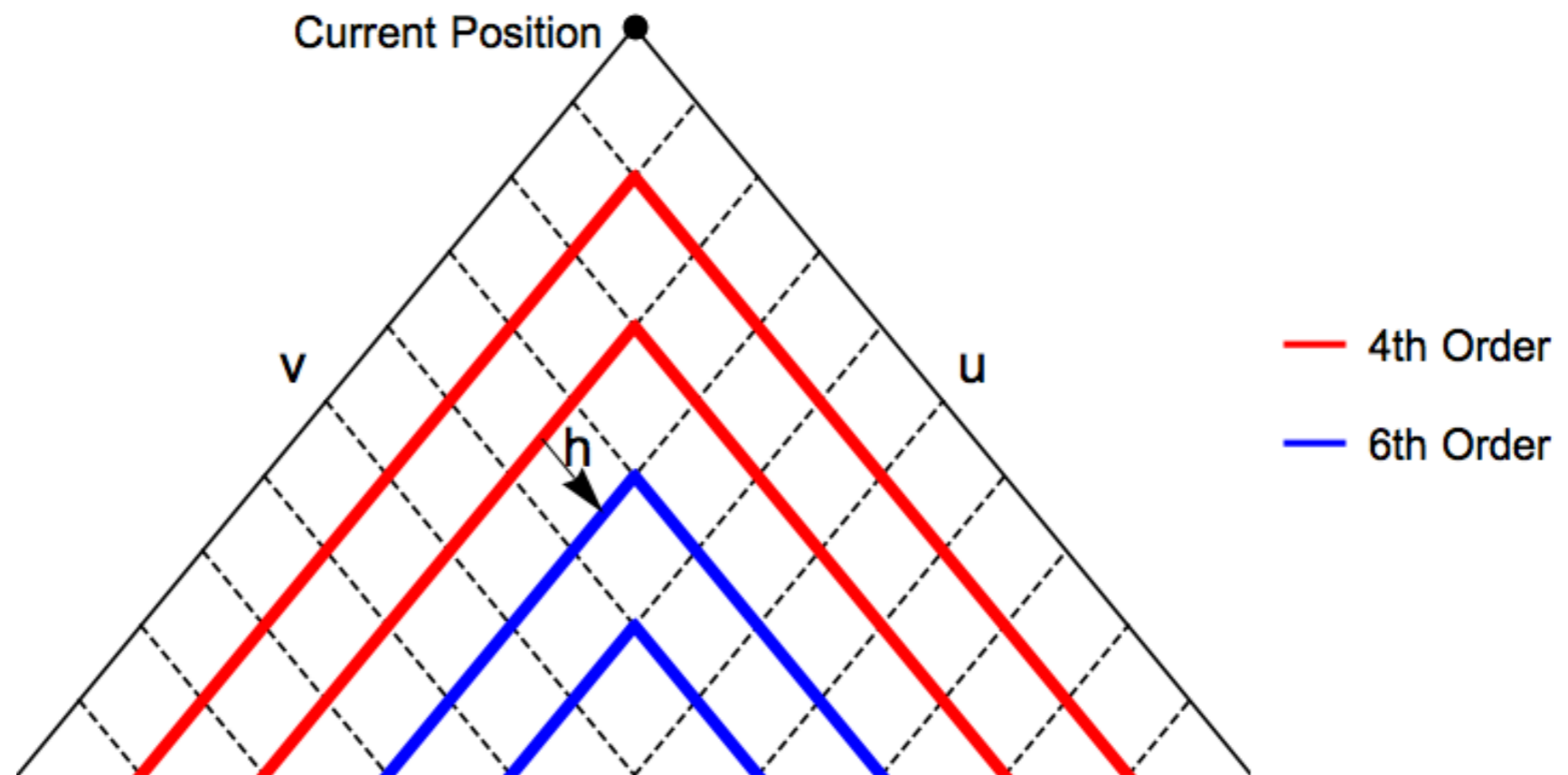
Time Domain Numerical Method

$$-4\partial_{uv}^2 G_l - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M(1-s^2)}{r^3}\right) G_l = 0$$

$$\begin{aligned} G_l(u, v) = & -G_l(u-h, v-h) + G_l(u, v-h) + G_l(u-h, v) \\ & -\frac{h^2}{1440} \left(108W(u, v)G_l^{(4)}(u, v) + 371(W(u, v-3h)G_l(u, v-3h) + W(u-3h, v)G_l(u-3h, v))\right) \\ & -154(W(u-4h, v)G_l(u-4h, v) + W(u, v-4h)G_l(u, v-4h)) \\ & +116(W(u-3h, v-h)G_l(u-3h, v-h) + W(u-h, v-3h)G_l(u-h, v-3h)) \\ & +40W(u-2h, v-2h)G_l(u-2h, v-2h) \\ & +27(W(u-5h, v)G_l(u-5h, v) + W(u, v-5h)G_l(u, v-5h)) \\ & -19(W(u-4h, v-h)G_l(u-4h, v-h) + W(u-h, v-4h)G_l(u-h, v-4h)) \\ & -5(W(u-3h, v-2h)G_l(u-3h, v-2h) + W(u-2h, v-3h)G_l(u-2h, v-3h)) \\ & +627(W(u-h, v)G_l(u-h, v) + W(u, v-h)G_l(u, v-h)) \\ & +1032W(u-h, v-h)G_l(u-h, v-h) \\ & -504(W(u-2h, v)G_l(u-2h, v) + W(u, v-2h)G_l(u, v-2h)) \\ & -329(W(u-2h, v-h)G_l(u-2h, v-h) + W(u-h, v-2h)G_l(u-h, v-2h)) \end{aligned}$$

Initial Conditions

- For higher order, we need data on more than one ‘previous’ null surface



- We use a standard ansatz from BHPT, the Hadamard series

$$G_l = \Theta(-\sigma) \sum_{n=0}^{\infty} U_n \sigma^n \quad \sigma(x, x') = -\frac{1}{2}(\Delta\tau)^2 = -\frac{1}{2}\Delta u \Delta v$$

Initial Conditions

- Can derive transport equations for the U_n 's

$$U_0 = \Delta(x, x') = 1$$

$$-fV_l + 2(\Delta u \partial_u U_1 + \Delta v \partial_v U_1) + 2U_1 = 0$$

$$\square U_n - fV_l U_n + 2(n+1)(\Delta u \partial_u U_{n+1} + \Delta v \partial_v U_{n+1}) + 2(n+1)^2 U_{n+1} = 0$$

- Coefficients independent of t (in Schwarzschild)
- For 4th order, need at least U_5 , for 6th order U_7 , etc.

Initial Conditions

$$U_1(r, r_0) = \frac{(r - r_0)(-M(r + r_0)(s^2 - 1) + rr_0l(l + 1))}{2r^2r_0^2(r^* - r_0^*)}$$

$$U_2(r, r_0) = \frac{(r - r_0)^2(-M(r + r_0)(s^2 - 1) + rr_0l(l + 1))^2}{16r^4r_0^4(r^* - r_0^*)^2}$$

$$+ \frac{(r - r_0)(-M(r + r_0)(s^2 - 1) + l(l + 1)rr_0)}{4r^2r_0^2(r^* - r_0^*)^3}$$

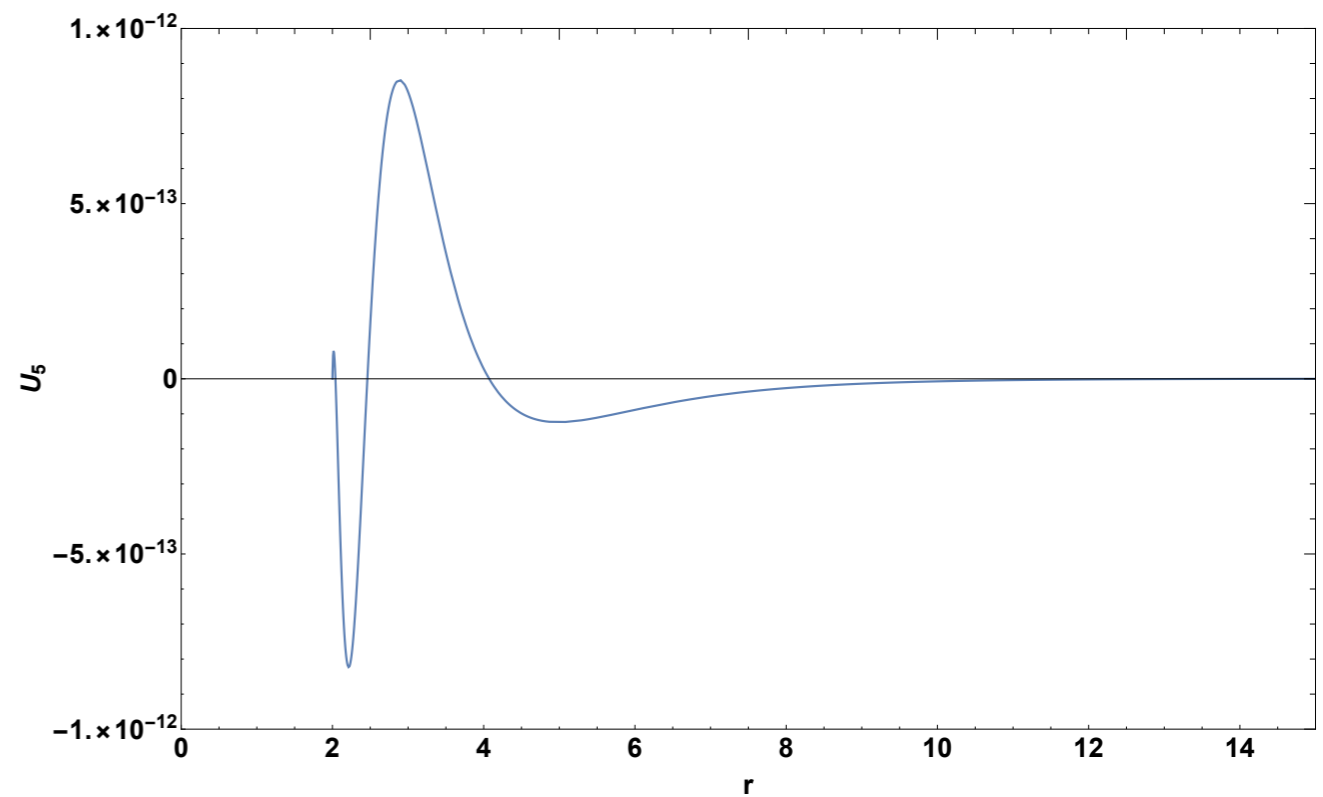
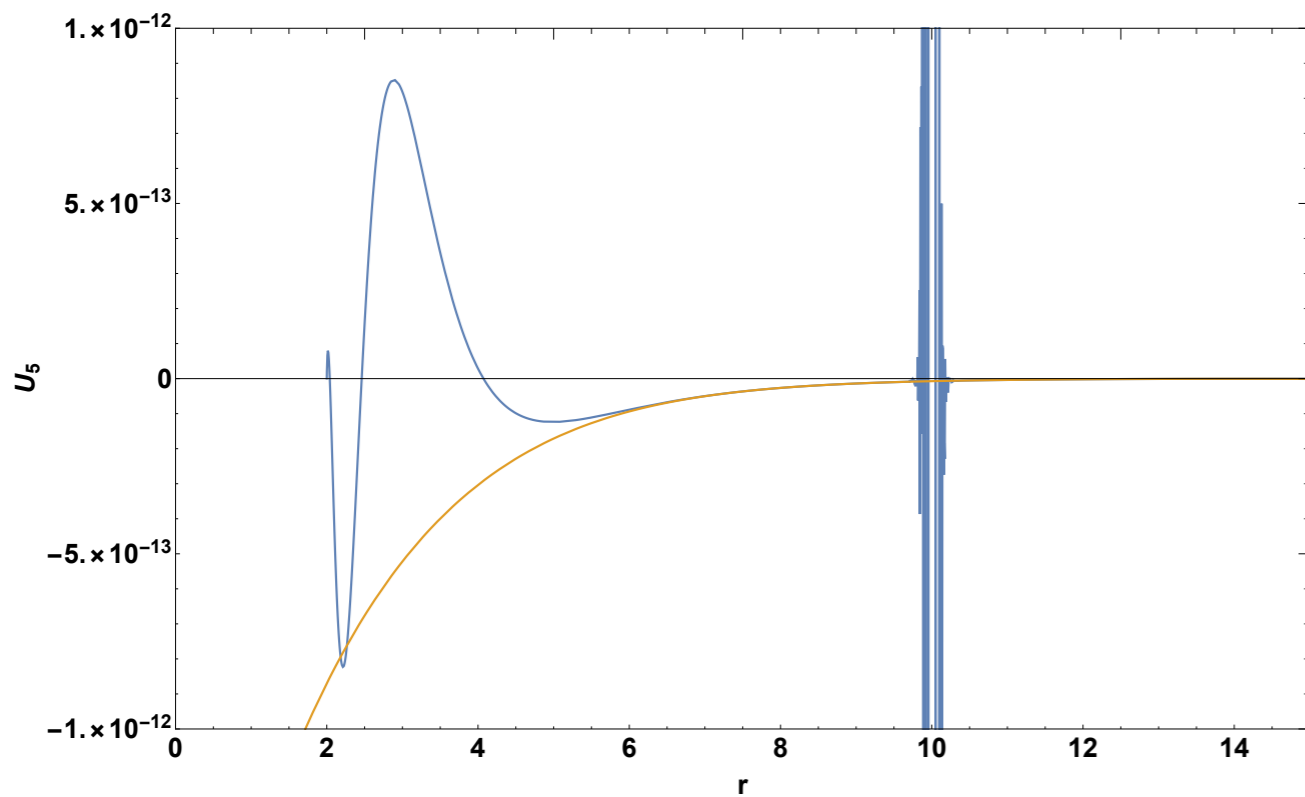
$$- \frac{(-2M + r_0)(l(l + 1)r_0 - 2M(s^2 - 1))}{4r_0^4(r^* - r_0^*)^2}$$

$$- \frac{1}{8(r^* - r_0^*)^2} \left(1 - \frac{2M}{r} \right) \left(\frac{l(l + 1)}{r^2} - \frac{2M(s^2 - 1)}{r^3} \right)$$

$$+ \frac{1}{8(r^* - r_0^*)^2} \left(1 - \frac{2M}{r_0} \right) \left(\frac{l(l + 1)}{r_0^2} - \frac{2M(s^2 - 1)}{r_0^3} \right)$$

Initial Conditions

- We must treat the value of the initial conditions carefully near coincidence



Green Function Derivatives

- For the self-force, also require the derivatives of the Green Function: $\partial_u G$, $\partial_v G$
- For example, for a scalar charge:

$$F_\mu = q \int_{-\infty}^{\tau^-} \nabla_\mu G(z(\tau), z(\tau')) d\tau'$$

- Can use finite differencing or compute directly
- Latter requires values of both derivatives and Green function on previous points in the domain

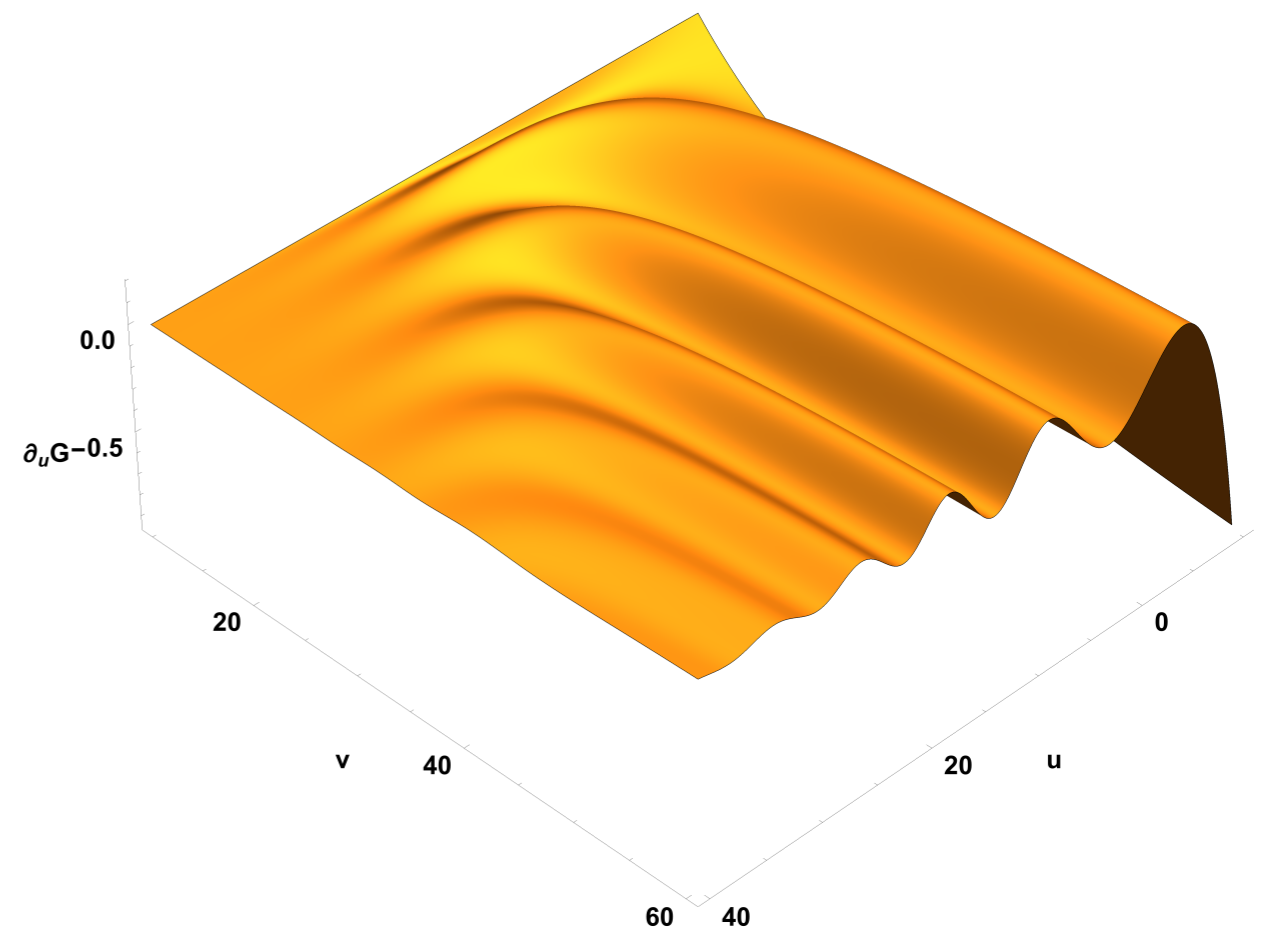
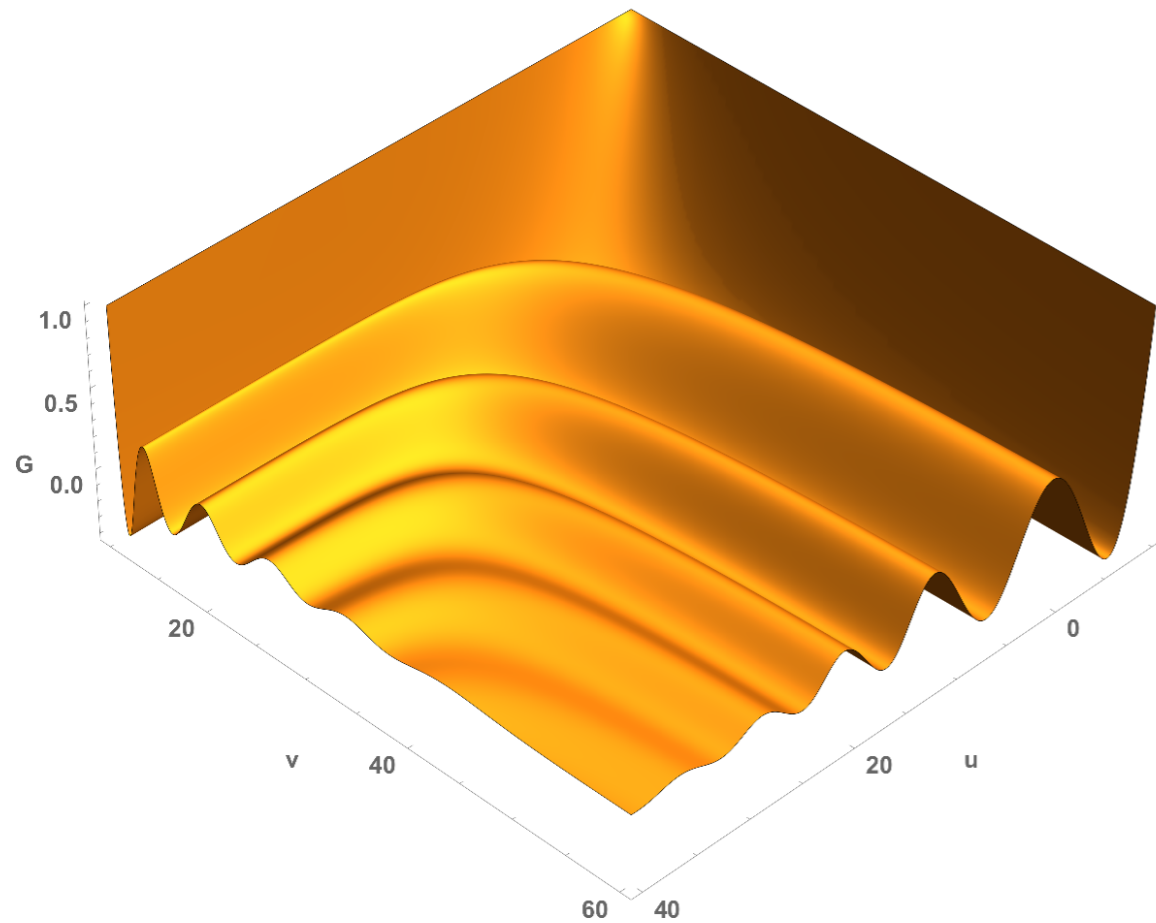
Green Function Derivatives

- For direct computation, start by differentiating the wave equation

$$\begin{aligned} -4\partial_{uv}^2(\partial_u G_l) - \partial_u \left(\left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M(1-s^2)}{r^3}\right) \right) G_l \\ - \left(1 - \frac{2M}{r}\right) \left(\frac{l(l+1)}{r^2} + \frac{2M(1-s^2)}{r^3}\right) \partial_u G_l = 0 \end{aligned}$$

- The first term is the same as before, the second and third are both of familiar form
- We then differentiate the Hadamard series to obtain the necessary initial data
- This requires finding derivatives of the U_n 's, which we have expressions for
- Note that now 2nd order will require U_1 , 4th order U_6 , 6th order U_8 , etc.

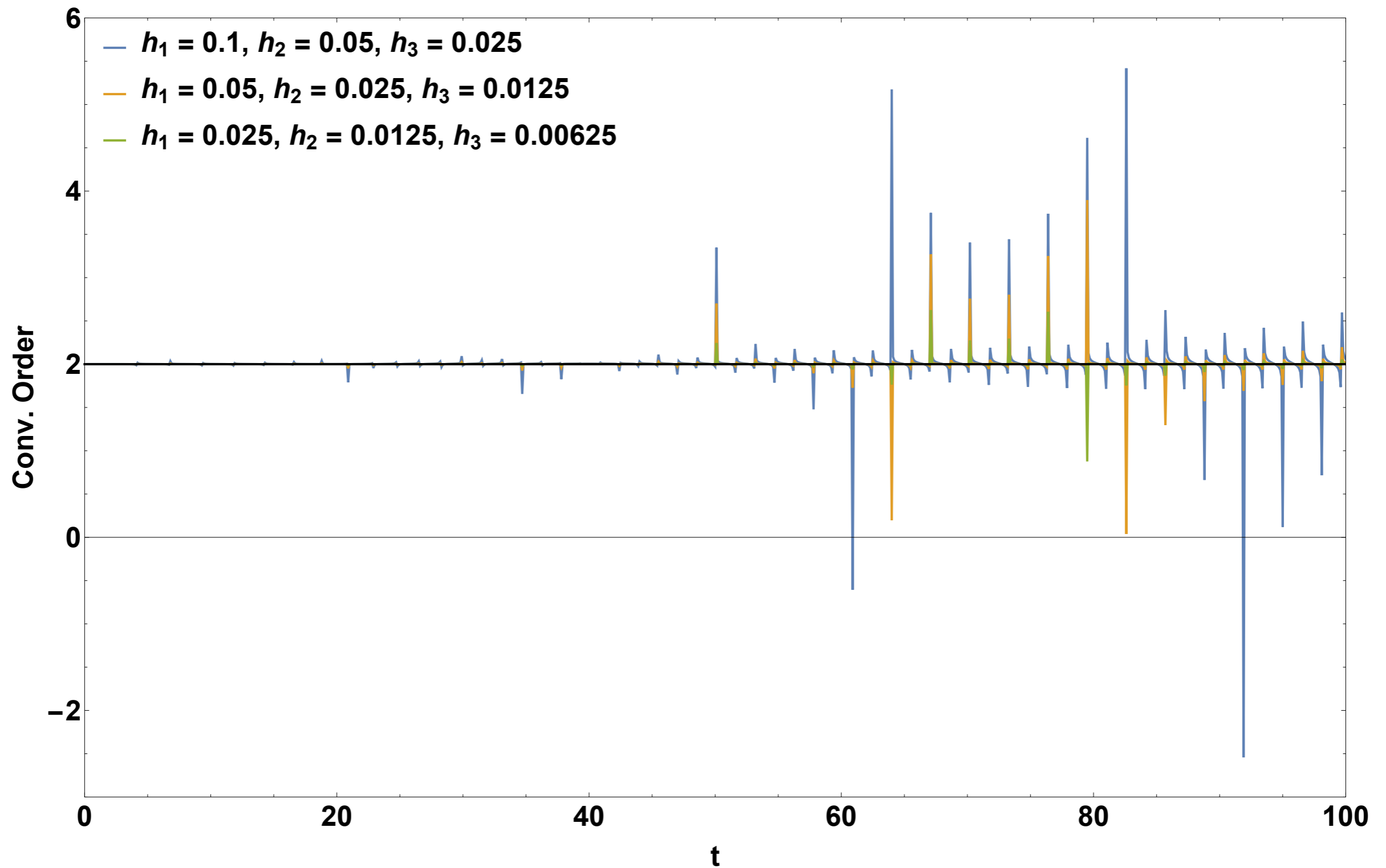
Results



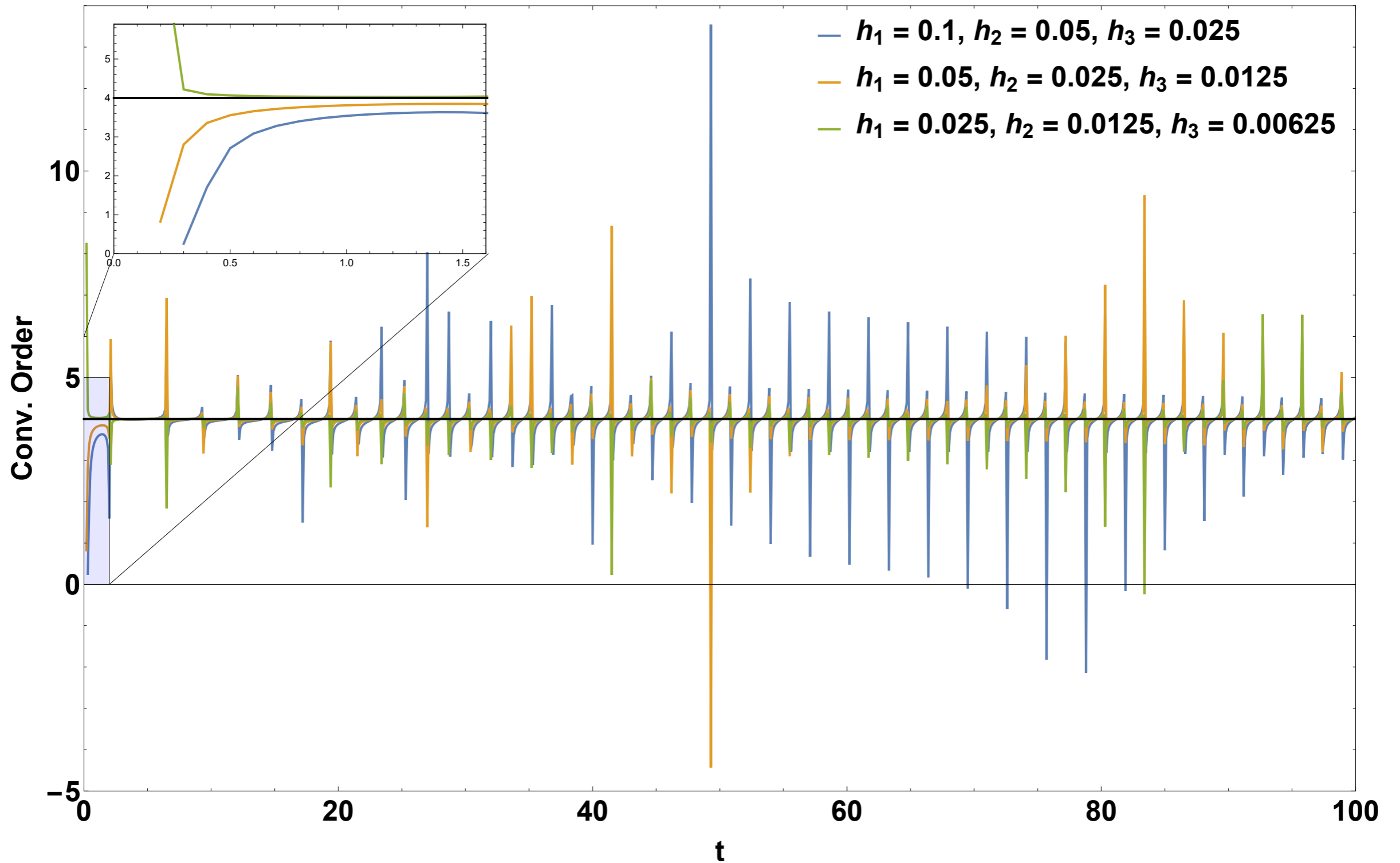
- Mathematica implementation of 2nd and 4th order algorithms for G and both derivatives
- Algorithms valid for scalar, electromagnetic and gravitational perturbations to background

- Extension to higher orders straightforward (6th started)
- C code implementation of the above

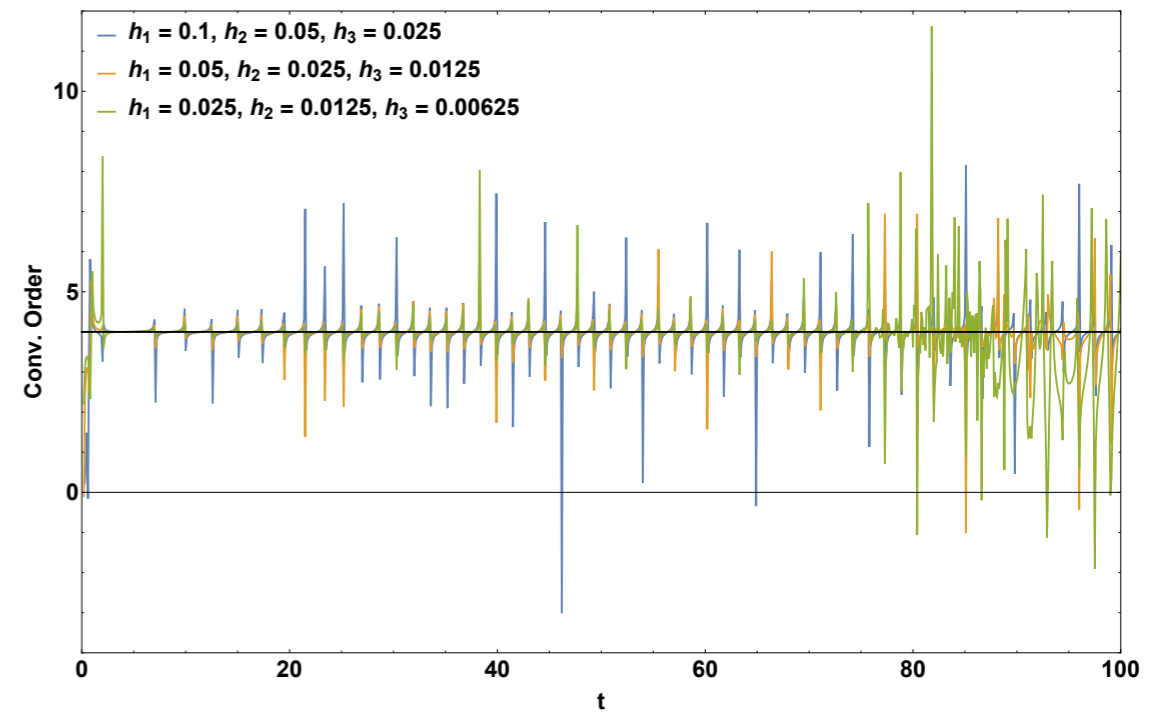
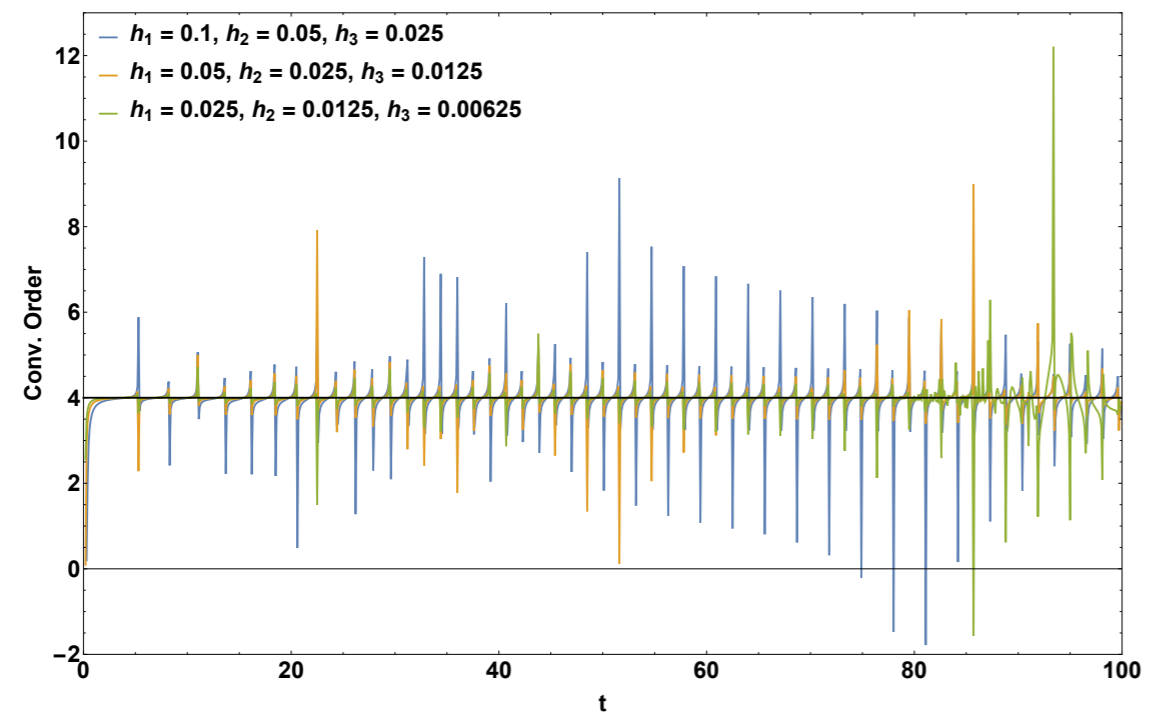
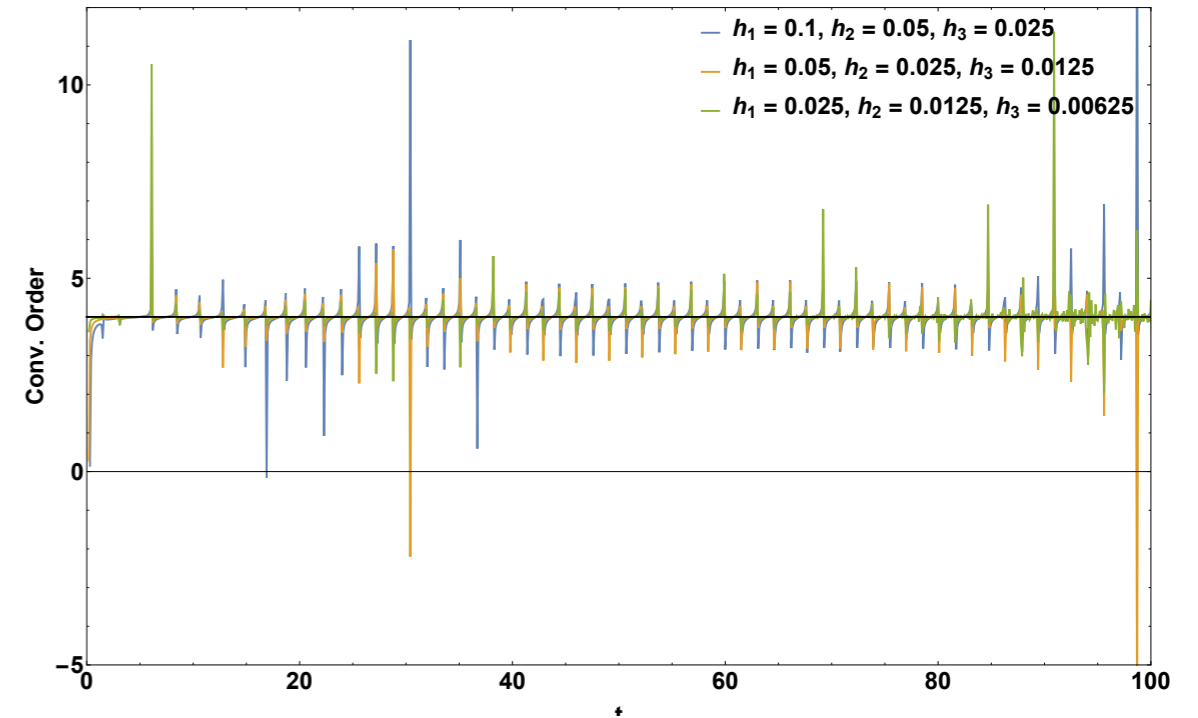
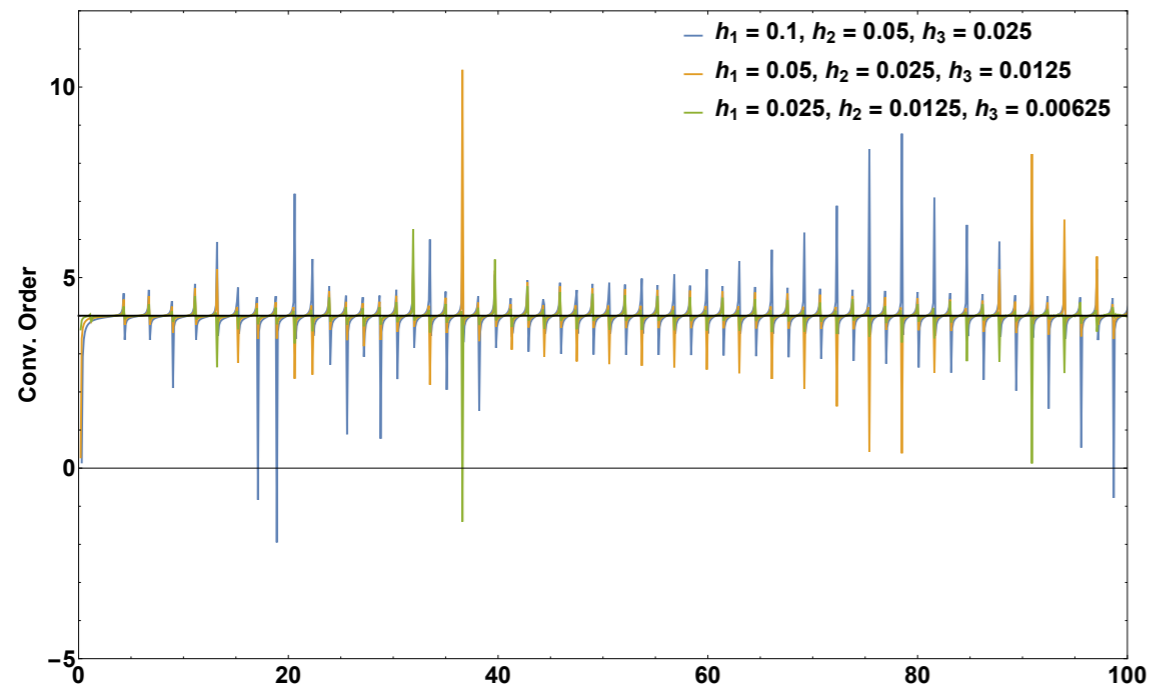
Results



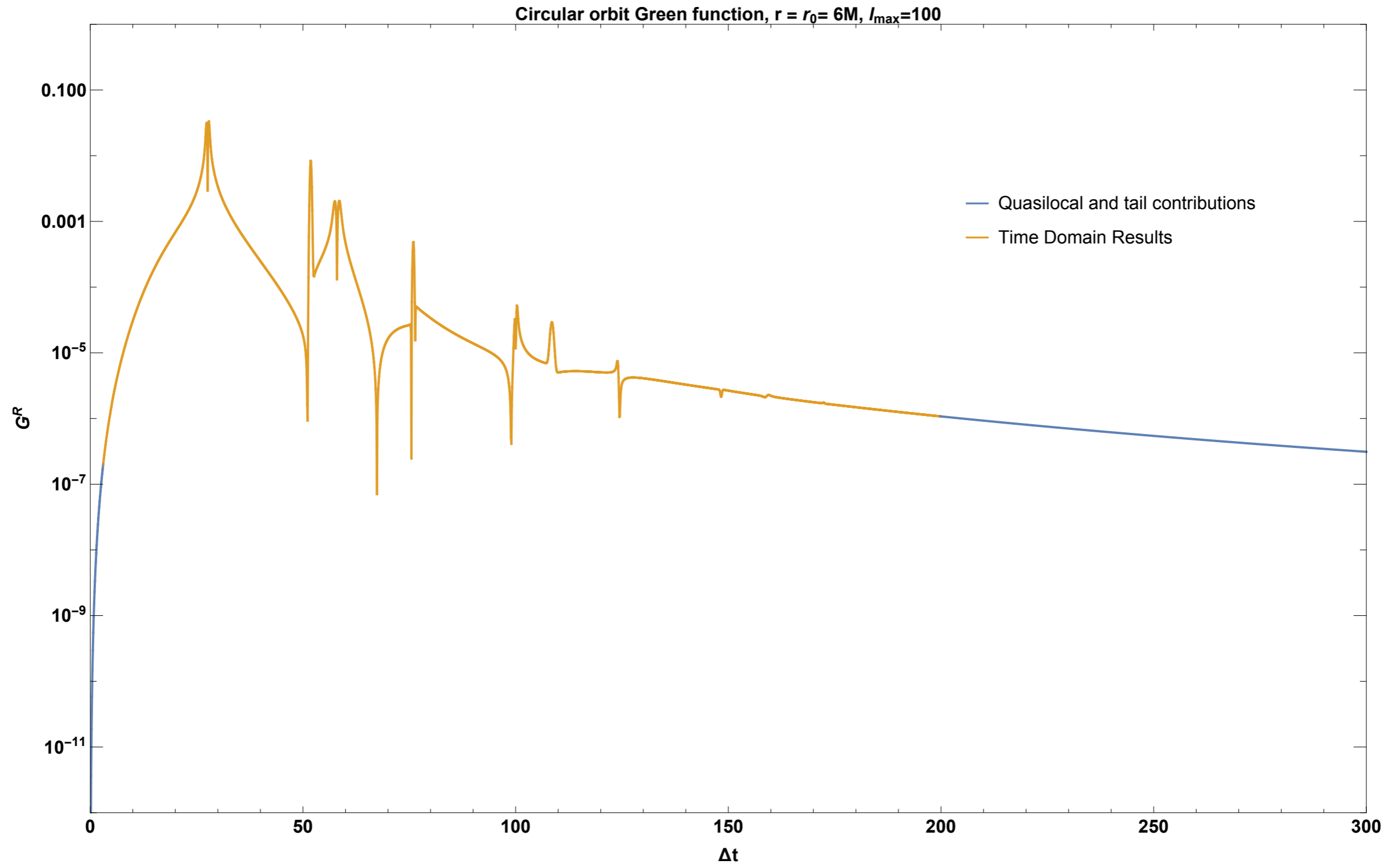
Results



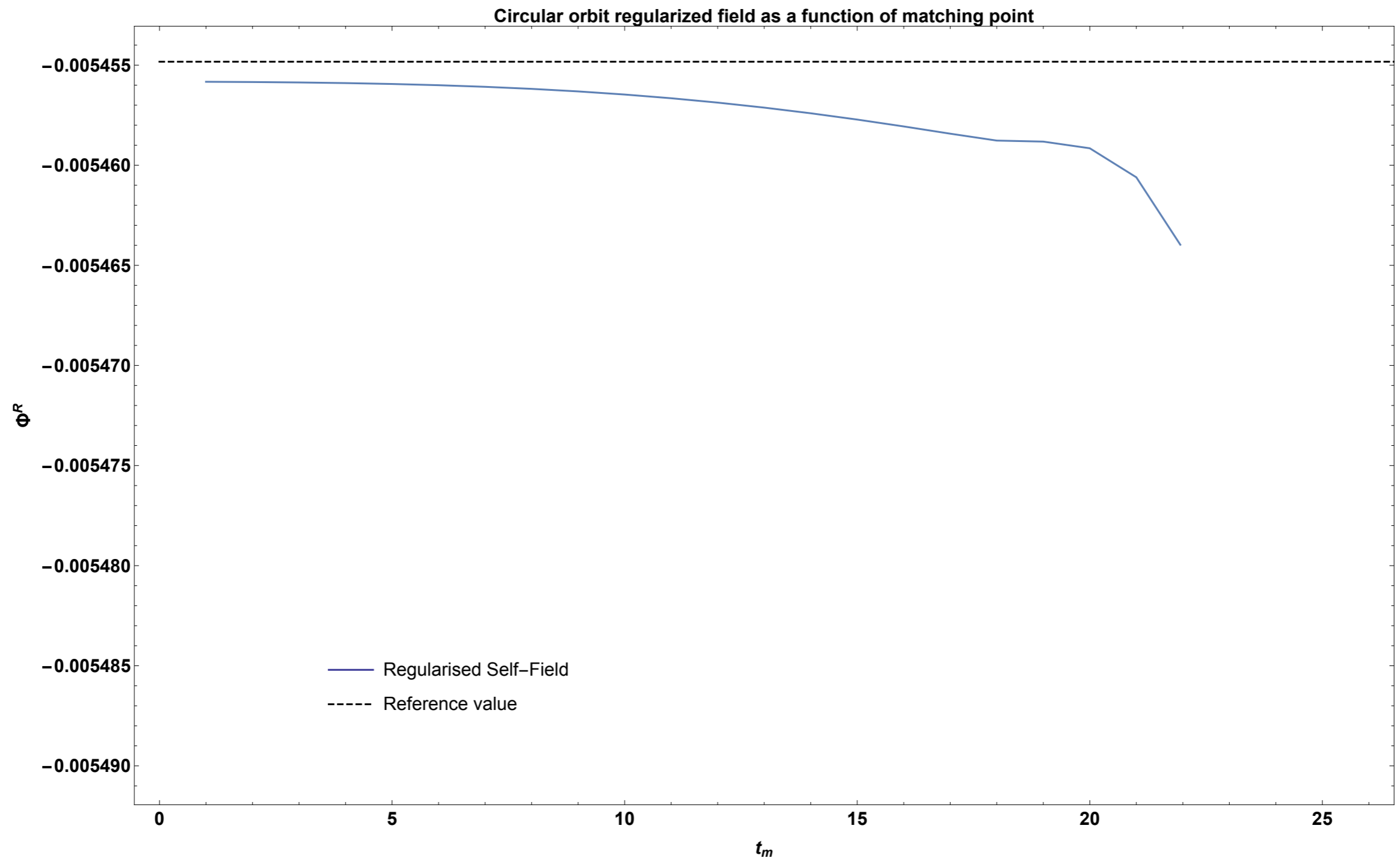
Results



Results



Results



Future Work

- Scalar self-force
- Gravitational self-force
- Higher order schemes (in progress)
- Variety of orbits, bound and unbound
- Mixed second derivatives - Derivatives with respect to both the base point and field point (in progress)
- Input into Surrogate Model(s)
- Extension to Kerr

To name a few things...

**Thank you
Questions?**

Bonus Slide 1

From 4D to 2D

- Simplification to 2D is done through a number of straightforward steps

1. Tortoise Coordinate

$$r_* = r + 2M \log \left(\frac{r}{2M} - 1 \right) \quad \frac{dr}{dr_*} = 1 - \frac{2M}{r} = f$$

$$(*) \rightarrow -\frac{\partial^2 G}{\partial t^2} + \frac{\partial^2 G}{\partial r_*^2} + \frac{2f}{r} \frac{\partial G}{\partial r_*} + \frac{f}{r^2} \nabla_{\Omega_2}^2 G = \frac{-4\pi}{r^2} \delta_2(x^A - x^{A'}) \delta_{\Omega_2}(x^a, x^{a'})$$

2. Conformal Transformation

$$\hat{g}_{\mu\nu}(t, r_*, \theta, \phi) = \frac{g_{\mu\nu}(t, r_*, \theta, \phi)}{r^2} \quad G = \frac{1}{rr'} \hat{G}$$

$$(*) \rightarrow -\frac{\partial^2 \hat{G}}{\partial t^2} + \frac{\partial^2 \hat{G}}{\partial r_*^2} + \frac{f}{r^2} \left(\nabla_{\Omega_2}^2 - \frac{2M}{r} \right) \hat{G} = -4\pi \delta_2(x^A - x^{A'}) \delta_{\Omega_2}(x^a, x^{a'})$$

3. Spherical Harmonic Decomposition

$$\hat{G}(x, x') = \frac{1}{4\pi} \sum_{l=0}^{\infty} (2l+1) G_l(x^A, x^{A'}) P_l(\cos \gamma)$$

$$(*) \rightarrow -\frac{\partial^2 G_l}{\partial t^2} + \frac{\partial^2 G_l}{\partial r_*^2} - f \left(\frac{l(l+1)}{r^2} + \frac{2M(1-s^2)}{r^3} \right) G_l = -4\pi \delta_2(x^A - x^{A'})$$

4. Null Coordinates

$$u = t - r_* \quad v = t + r_* \quad g_{\mu\nu}(u, v) = -\frac{1}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$(*) \rightarrow -4 \frac{\partial^2 G_l}{\partial u \partial v} - f \left(\frac{l(l+1)}{r^2} + \frac{2M(1-s^2)}{r^3} \right) G_l = -4\pi \delta_2(x^A - x^{A'})$$

Bonus Slide 2

Kerr

- A number of significant issues posed by transition to Kerr:
 - Cannot fully separate angular coordinates
 - Initial conditions more complex
 - Reformulation of the problem
- But essentially the same steps as for Schwarzschild
- First of the above has been solved previously for similar problems
- Third may require exploring a number of coordinate systems
- Starting with Bardeen-Press-Teukolsky, then moving on to Teukolsky

Bonus Slide 3

Other To-Dos

- Mixed second derivatives - Derivatives with respect to both the base point and field point
 - Necessary for computing stress-energy
 - Also possibly useful for 2nd-Order Osculating Elements
- Experiment with hyperboloidal coordinates
 - Possibly obtain the global Green function
- Hyperbolic scatterings
 - Potential comparisons with Post-Minkowskian methods
- Zoom-whirls
 - Building on discussions from Monday
- Arbitrary precision using GSL
 - Improves C codes robustness to numerical roundoff errors
- Applications to QFT in curved spacetime
- Self-consistent evolution