

New geometric interpretation of D-branes and DBI action

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Introduction

[Fradkin, Tseytlin '85]

[Abouelsaood, Callan, Nappi, Yost '87]

[Callan, Lovelace, Nappi, Yost '88]

Dirac-Born-Infeld (DBI) action:
the low-energy effective theory of D-brane

$$S_{\text{DBI}} = \int_{\varphi_{\Phi}(\Sigma)} \sqrt{\det(\varphi_{\Phi}^*(g + B) - F)_{ab}} dx^0 \wedge \cdots \wedge dx^p$$

We proposed that

DBI action = Generalization of Nambu-Goto action
in the framework of generalized geometry

It is known that

Scalar fields describing transverse displacements

= **NG bosons** for broken translational symmetries

Broken symmetries are **non-linearly realized** in NG action.

[Low, Manohar '02]

Under T-duality,



We show that

- The gauge field and the scalar fields can be treated on equal footing in the framework of generalized geometry.
- As scalar fields, the gauge field are interpreted as NG boson for broken (constant) B-field gauge transformations.
- The DBI action is invariant under non-linearly realized symmetry for all types of diffeomorphisms and B-field gauge transformations over the target space.

Outline

Introduction

1. What is generalized geometry
2. D-brane (Dirac structure)
3. Adding a metric and a B-field (generalized metric str.)
4. Transformation law
5. Invariance of the DBI action

Summary

1. What is generalized geometry

What is generalized geometry? [Courant '90] [Hitchin '03]

Generalized geometry is extension of (usual) differential geometry.

M : D -dimensional manifold (the target space)

Differential geometry

TM

Diffeomorphism



Generalized Geometry

$$TM = TM \oplus T^*M$$

Diff. and B-field gauge transf.

Lie derivative:

$$\mathcal{L}_{u+\xi}(v + \eta) = \underbrace{\mathcal{L}_u(v + \eta)}_{\text{Diffeomorphism}} - \underbrace{i_v d\xi}_{\text{B-field gauge transf.}}$$

\uparrow
generators

2. D-brane

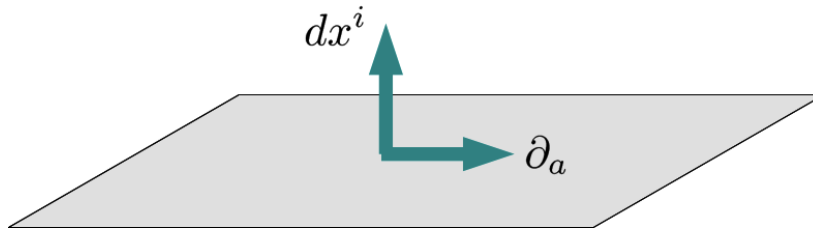
(Dirac structure)

Dp-brane :

(Dirac structure [Courant '90])

A Dp-brane without fluctuations (Φ, A) can be characterized as a subbundle

$$\begin{aligned} L &= \{v^a(x)\partial_a + \xi_i(x)dx^i\} \\ &= \Delta \oplus \text{Ann}(\Delta) \quad \subset TM \end{aligned}$$



Examples of D-branes:

TM : D9-brane

T^*M : D(-1)-brane

(M:10 dim manifold)

Dp-brane with fluctuations

Acting a diffeomorphism and a B-field gauge transformation on L , a D-brane with fluctuations can be represented as a subbundle

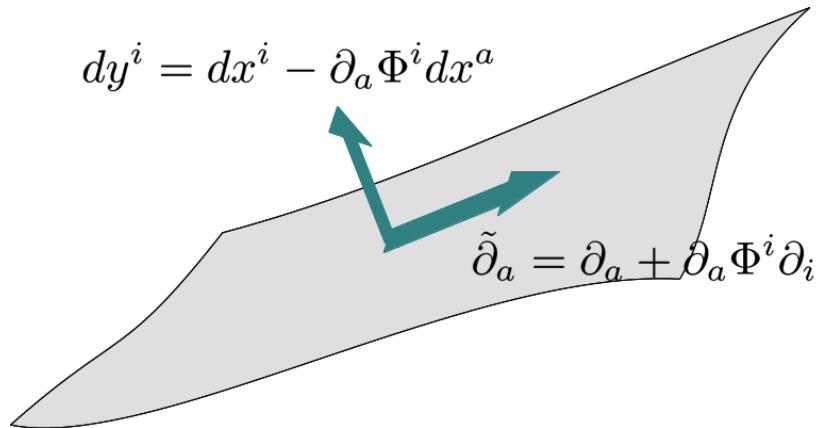
$$L_{\mathcal{F}} = e^{-\mathcal{L}_{\Phi+A}} L \subset \mathbb{T}M$$

$$V_L + \mathcal{F}(V_L) = v^a(x)(\partial_a + \partial_a\Phi^i\partial_i + F_{ab}dx^b) + \xi_i(x)(dx^i - \partial_a\Phi^i dx^a) \in \Gamma(L_{\mathcal{F}})$$

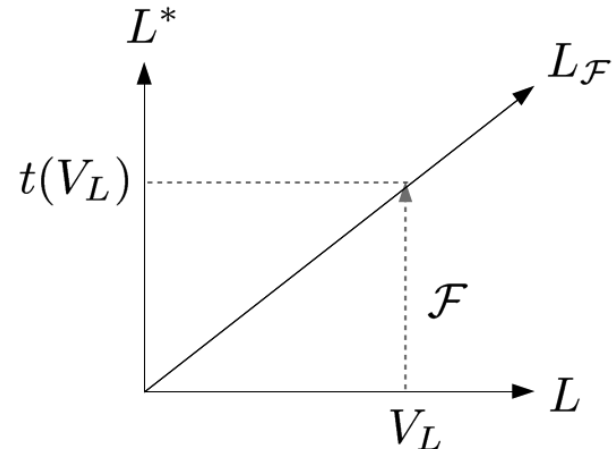
where

$$\mathcal{F} = \frac{1}{2}F_{ab}dx^a \wedge dx^b + \partial_a\Phi^i dx^a \wedge \partial_i : \text{a generalized field strength}$$

Image of $L_{\mathcal{F}}$,



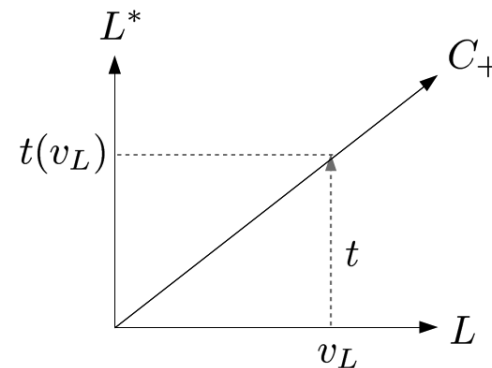
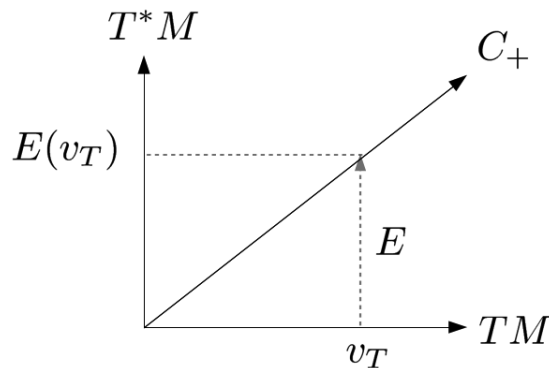
Graph of a map $\mathcal{F} : L \rightarrow L^*$,



3. Adding a metric and a B-field
(generalized metric structure)

Generalized metric

Generalized metric is given by a subbundle $C_+ \subset \mathbb{T}M$ of which sections are described as a graph of $E = g + B : TM \rightarrow T^*M$ or as a graph $t : L \rightarrow L^*$,



Since these graphs represent the same subbundle, we find the relation

$$\begin{aligned} t^{ij} &= E^{ij}, & t_a^j &= -E_{ak} E^{kj}, \\ t^i_b &= E^{ik} E_{kb}, & t_{ab} &= E_{ab} - E_{ak} E^{kl} E_{lb} \end{aligned}$$

These relations are similar to the Buscher rule since T-duality exchanges vector fields and 1-forms.

Another definition of the generalized metric

We introduce the operation $G : \mathbb{T}M \rightarrow \mathbb{T}M$ given by

$$G = \begin{pmatrix} -Bg^{-1} & g^{-1} \\ g - Bg^{-1}B & g^{-1}B \end{pmatrix} \quad [\text{Gualtieri '03}]$$

Then $C_{\pm} = \text{Ker}(1 \mp G)$

1. Restriction of G to $L_{\mathcal{F}}$ gives the induced metric on $L_{\mathcal{F}}$:

$$s_{\mathcal{F}} = s - (a - \mathcal{F})s^{-1}(a - \mathcal{F}) \in \Gamma(L_{\mathcal{F}}^* \otimes L_{\mathcal{F}}^*)$$

2. Restriction of G to C_+ gives a bulk metric:

$$g \in \Gamma(T^*M \otimes T^*M)$$

s : symmetric part of t

a : anti-symmetric part of t

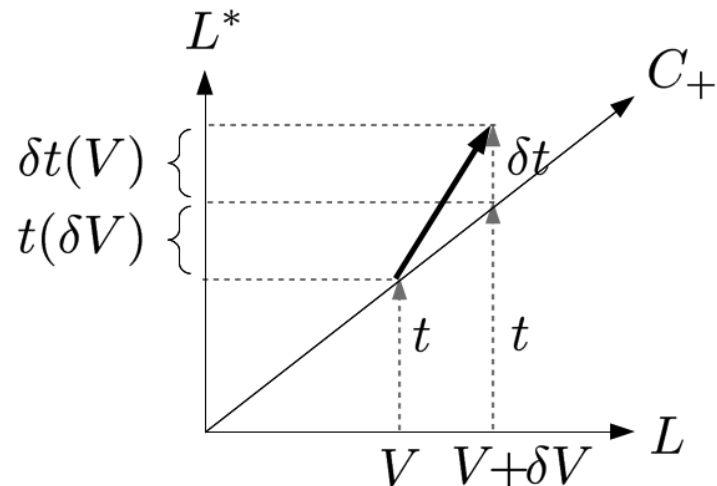
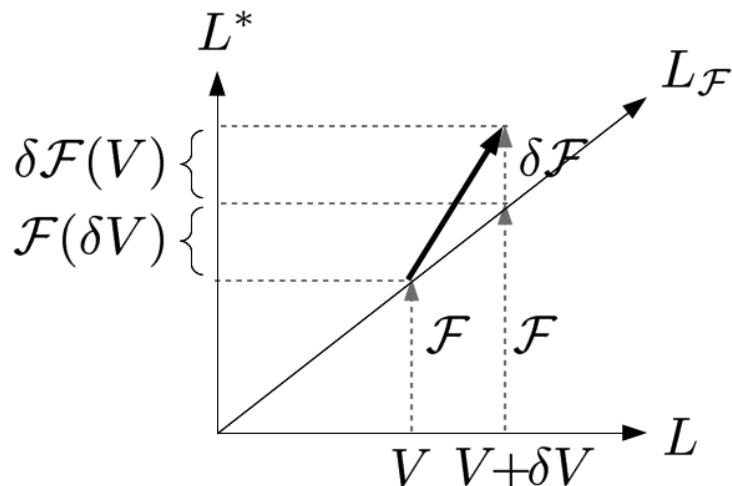
4. Transformation law

Transformation law

Consider an infinitesimal transformation of a diffeomorphism and a B-field gauge transformation generated by

$$\begin{aligned}\epsilon &= \epsilon_{\parallel} + \epsilon_{\perp} = \epsilon^a \partial_a + \epsilon^i \partial_i \\ \Lambda &= \Lambda_{\parallel} + \Lambda_{\perp} = \Lambda_a dx^a + \Lambda_i dx^i\end{aligned}$$

The transformation law for the tensor $\mathcal{F} \in \Gamma(L^* \otimes L^*)$ and $t \in \Gamma(L^* \otimes L^*)$ can be found as the transformation of the subbundles $L_{\mathcal{F}}$ and C_+ .



Transformation law:

$$\begin{aligned}
\delta \mathcal{F}_{ab} &= -\epsilon^M \partial_M \mathcal{F}_{ab} - \partial_a \epsilon^c \mathcal{F}_{cb} - \mathcal{F}_{ac} \partial_b \epsilon^c - \partial_{[a} \Lambda_{k]} \mathcal{F}_b^k + \mathcal{F}_a^k \partial_{[k} \Lambda_{b]} \\
&\quad - \mathcal{F}_a^k \partial_k \epsilon^c \mathcal{F}_{cb} + \mathcal{F}_{ac} \partial_k \epsilon^c \mathcal{F}_b^k - \mathcal{F}_a^k \partial_{[k} \Lambda_{l]} \mathcal{F}_b^l + \partial_{[a} \Lambda_{b]} \\
\delta \mathcal{F}_a^j &= -\delta \mathcal{F}_a^j = -\epsilon^M \partial_M \mathcal{F}_a^j - \partial_a \epsilon^c \mathcal{F}_c^j + \mathcal{F}_a^k \partial_k \epsilon^j - \mathcal{F}_a^k \partial_k \epsilon^c \mathcal{F}_c^j + \partial_a \epsilon^j
\end{aligned}$$

$$\begin{aligned}
\delta t_{ab} &= -\epsilon^M \partial_M t_{ab} - \partial_a \epsilon^c t_{cb} - t_{ac} \partial_b \epsilon^c + \partial_{[k} \Lambda_{a]} t_b^k + t_a^k \partial_{[k} \Lambda_{b]} \\
&\quad - t_a^k \partial_k \epsilon^c t_{cb} + t_{ac} \partial_k \epsilon^c t_b^k - t_a^k \partial_{[k} \Lambda_{l]} t_b^l + \partial_{[a} \Lambda_{b]}
\end{aligned}$$

$$\begin{aligned}
\delta t_a^j &= -\epsilon^M \partial_M t_a^j - \partial_a \epsilon^c t_c^j + t_a^k \partial_k \epsilon^j + \partial_{[k} \Lambda_{a]} t^{kj} \\
&\quad - t_a^k \partial_k \epsilon^c t_c^j + t_{ac} \partial_k \epsilon^c t^{kj} - t_a^k \partial_{[k} \Lambda_{l]} t^{lj} + \partial_a \epsilon^j
\end{aligned}$$

$$\begin{aligned}
\delta t^i_b &= -\epsilon^M \partial_M t^i_b + \partial_k \epsilon^i t_b^k - t^i_c \partial_b \epsilon^c + t^{ik} \partial_{[k} \Lambda_{b]} \\
&\quad - t^{ik} \partial_k \epsilon^c t_{cb} + t^i_c \partial_k \epsilon^c t_b^k - t^{ik} \partial_{[k} \Lambda_{l]} t_b^l - \partial_b \epsilon^i
\end{aligned}$$

$$\begin{aligned}
\delta t^{ij} &= -\epsilon^M \partial_M t^{ij} + \partial_k \epsilon^i t^{kj} + t^{ik} \partial_k \epsilon^j \\
&\quad - t^{ik} \partial_k \epsilon^c t_c^j + t^i_c \partial_k \epsilon^c t^{kj} - t^{ik} \partial_{[k} \Lambda_{l]} t^{lj}
\end{aligned}$$

$$\begin{aligned}
\delta \mathcal{F}_{ab} &= -\epsilon^M \partial_M \mathcal{F}_{ab} - \partial_a \epsilon^c \mathcal{F}_{cb} - \mathcal{F}_{ac} \partial_b \epsilon^c - \partial_{[a} \Lambda_{k]} \mathcal{F}_b^k + \mathcal{F}_a^k \partial_{[k} \Lambda_{b]} \\
&\quad - \mathcal{F}_a^k \partial_k \epsilon^c \mathcal{F}_{cb} + \mathcal{F}_{ac} \partial_k \epsilon^c \mathcal{F}_b^k - \mathcal{F}_a^k \partial_{[k} \Lambda_{l]} \mathcal{F}_b^l + \partial_{[a} \Lambda_{b]} \\
\delta \mathcal{F}_a^j &= -\delta \mathcal{F}_a^j = -\epsilon^M \partial_M \mathcal{F}_a^j - \partial_a \epsilon^c \mathcal{F}_c^j + \mathcal{F}_a^k \partial_k \epsilon^j - \mathcal{F}_a^k \partial_k \epsilon^c \mathcal{F}_c^j + \partial_a \epsilon^j
\end{aligned}$$

This transformation law can be rewritten as

$$\begin{aligned}
\delta \mathcal{F}_{ab} &= \tilde{\partial}_{[a} \delta A_{b]} - \delta \Phi^k \partial_k \mathcal{F}_{ab} \\
\delta \mathcal{F}_a^j &= -\delta \mathcal{F}_a^j = \tilde{\partial}_a \delta \Phi^j
\end{aligned}$$

We can read the non-linear transformation law :

$$\begin{aligned}
\delta A_a &= \Lambda_a - \epsilon^c F_{ca} + \Lambda_k \partial_a \Phi^k \\
\delta \Phi^i &= \epsilon^i - \epsilon^c \partial_c \Phi^i
\end{aligned}$$

(Φ^i, A_a) can be interpreted as NG bosons for $\epsilon^i = \text{const.}$ and $\Lambda_a = \text{const.}$

4. Invariance of the DBI action

In this section, we prove invariance of the DBI action under the full diffeomorphisms and B-field gauge transformations on the target space.

Firstly we define the DBI action as an integral over the target space M as

$$S_{\text{DBI}} = \int_M \mathcal{L}_{\text{DBI}} \delta^{(D-p-1)}(x^i - \Phi^i(x^a)) dx^0 \wedge \cdots \wedge dx^{D-1}$$
$$\mathcal{L}_{\text{DBI}} = \det^{\frac{1}{4}} g \det^{\frac{1}{4}} s_{\mathcal{F}}$$

This action can be rewritten as a well-known form

$$S_{\text{DBI}} = \int_{\Sigma} \sqrt{\det(\varphi_{\Phi}^*(g + B) - F)_{ab}} dx^0 \wedge \cdots \wedge dx^p$$

The proof of this relation are found in our paper.

Transformation rule:

$$\left\{ \begin{array}{l} \delta \sqrt{\det s_{\mathcal{F}}} = -\epsilon^M \partial_M \sqrt{\det s_{\mathcal{F}}} + \sqrt{\det s_{\mathcal{F}}} \{ -\partial_c \epsilon^c + \partial_k \epsilon^k - 2\mathcal{F}_c^k \partial_k \epsilon^c \} \\ \delta \sqrt{\det g} = -\epsilon^M \partial_M \sqrt{\det g} + \sqrt{\det g} \{ -\partial_M \epsilon^M \} \end{array} \right.$$

$$\delta \mathcal{L}_{\text{DBI}} = -\epsilon^M \partial_M \mathcal{L}_{\text{DBI}} - (\partial_c \epsilon^c + \partial_c \Phi^k \partial_k \epsilon^c) \mathcal{L}_{\text{DBI}}.$$

The delta function is transformed as a density to

$$\begin{aligned} & \delta[\delta^{(D-p-1)}(x^i - \Phi^i)] \\ &= -\epsilon^M \partial_M [\delta^{(D-p-1)}(x^i - \Phi^i)] - (\partial_k \epsilon^k - \partial_k \epsilon^c \partial_c \Phi^k) \delta^{(D-p-1)}(x^i - \Phi^i). \end{aligned}$$

Combining these transformation laws, we get

$$\delta \left[\mathcal{L}_{\text{DBI}} \delta^{(D-p-1)}(x^i - \Phi^i) \right] = -\partial_M \left[\epsilon^M \mathcal{L}_{\text{DBI}} \delta^{(D-p-1)}(x^i - \Phi^i) \right]$$

total derivative

Interpretation as determinant bundles

$$\begin{aligned}\sqrt{\det g} \, dx^0 \wedge \cdots \wedge dx^{D-1} &\in \Gamma(\det(T^* M)) \\ \sqrt{\det s_{\mathcal{F}}} \, dx^0 \wedge \cdots \wedge dx^p \wedge \partial_{p+1} \wedge \cdots \wedge \partial_{D-1} &\in \Gamma(\det(L^*))\end{aligned}$$

The determinant bundle of each structures are decomposed as

$$\begin{aligned}\det(T^* M) &= \det(\Delta^*) \otimes \det(\text{Ann}(\Delta)), \\ \det(L^*) &= \det(\Delta^*) \otimes \det(\text{Ann}^*(\Delta)) = \det(\Delta^*) \otimes \det^{-1}(\text{Ann}(\Delta))\end{aligned}$$

Then

$$\det(T^* M) \otimes \det(L^*) = \det^2(\Delta^*) \otimes \det(\text{Ann}(\Delta)) \otimes \det^{-1}(\text{Ann}(\Delta))$$

Therefore the DBI Lagrangian can be characterized as a volume form over a D-brane world-volume as

$$\mathcal{L}_{\text{DBI}} dx^0 \wedge \cdots \wedge dx^p \in \Gamma(\det \Delta)$$

Summary

- D-branes are described as a subbundle (Dirac structure), where scalar fields and a gauge field can be treated on an equal footing.
- As the scalar fields, the gauge fields are interpreted as NG boson for broken B-field gauge transformations.
- We show that the DBI action is invariant under non-linearly realized symmetry.

Open questions

How can we extend these arguments to the following cases?

- Non-Abelian gauge theory
- Ramond-Ramond coupling (especially for A-roof genus)
- The relation with non-geometric fluxes
- M2, M5-brane