Monte Carlo studies of the rotational symmetry breaking in dimensionally reduced matrix models

Takehiro Azuma [Department of Mathematics and Physics, Setsunan University]

Tata Institute of Fundamental Research (TIFR), Aug 16th 2012, 16:00 ~ 17:00 with K.N. Anagnostopoulos and J. Nishimura, arXiv:1009.4504,1108.1534 1

Contents

1	Introduction	2
2	Gaussian toy model	4
3	Single-variable factorization method	8
4	Multi-variable factorization method	17
5	Conclusion	30

1 Introduction

Matrix models as a constructive definition of superstring theory

IKKT model (IIB matrix model)

 \Rightarrow Promising candidate for the constructive definition of superstring theory. Ishibashi, Kawai, Kitazawa and Tsuchiya, hep-th/9612115.

$$S=N\left(-rac{1}{4} ext{tr}\,[A_{\mu},A_{
u}]^2+rac{1}{2} ext{tr}\,ar{\psi}_{lpha}(\Gamma_{\mu})_{lphaeta}[A_{\mu},\psi_{eta}]
ight).$$

- $A_{\mu} \ (10 {
 m d vector}) \ {
 m and} \ \psi_{lpha} \ (10 {
 m d Majorana-Weyl spinor}) \Rightarrow N imes N \ {
 m matrices} \ .$
- Euclidean model after Wick rotation \Rightarrow SO(10) rotational symmetry.

Path integral is finite without cutoff. W. Krauth, H. Nicolai and M. Staudacher, hep-th/9803117, P. Austing and J.F. Wheater hep-th/0103159.

• Recent observation from Gaussian Expansion Method (GEM): J. Nishimura, T. Okubo and F. Sugino, arXiv:1108.1293.

Rotational symmetry breaking $SO(10) \rightarrow SO(3)$.

• After integrating out fermion, $\int d\psi e^{-S_f} = \operatorname{Pf}\mathcal{M}$, where $S_f = \frac{N}{2} \operatorname{tr} \bar{\psi}_{\alpha}(\Gamma_{\mu})_{\alpha\beta} [A_{\mu}, \psi_{\beta}]$, $(\mathcal{M})_{a\alpha,b\beta} = -i f_{abc} (\mathcal{C}\Gamma_{\mu})_{\alpha\beta} A^c_{\mu} = (16(N^2 - 1) \times 16(N^2 - 1) \operatorname{matrix}).$

For the Euclidean model, this Pfaffian is complex in general.

- * Crucial for rotational symmetry breaking. Nishimura and Vernizzi, hep-th/0003223.
- * Difficulty of Monte Carlo simulation.

2 Gaussian toy model

We want to understand the rotational symmetry breaking in the Euclidean IKKT model. Toy model with similarity to the Euclidean IKKT model. Nishimura, hep-th/0108070.

$$S = \underbrace{rac{N}{2} \mathrm{tr} \, A_{\mu}^2}_{=S_b} \underbrace{- ar{\psi}^f_{lpha}(\Gamma_{\mu})_{lphaeta} A_{\mu} \psi^f_{eta}}_{=S_f}
onumber \ \Gamma_1 = \sigma_1 = egin{pmatrix} 0 & 1 \ 1 & 0 \end{pmatrix}, \ \Gamma_2 = \sigma_2 = egin{pmatrix} 0 & -i \ i & 0 \end{pmatrix}, \ \Gamma_3 = \sigma_3 = egin{pmatrix} 1 & 0 \ 0 & -1 \end{pmatrix}, \ \Gamma_4 = i\sigma_4 = egin{pmatrix} i & 0 \ 0 & i \end{pmatrix}.$$

- A_{μ} : $N \times N$ hermitian matrices $(\mu = 1, \dots, 4)$ $\bar{\psi}^{f}_{\alpha}, \psi^{f}_{\alpha}$: *N*-dim vector $(\alpha = 1, 2, f = 1, \dots, N_{f} = (\text{number of flavors}))$ \Rightarrow CPU cost is $O(N^{3})$ (instead of $O(N^{6})$ in the IKKT model)
- SO(4) rotational symmetry.
- No supersymmetry.

Monte Carlo studies of the rotational symmetry breaking in dimensionally reduced matrix models , Aug. 16th 2012 16:00 \sim 17:00

• Partition function:

$$egin{aligned} Z &= \int dA e^{-S_B} (\det \mathcal{D})^{N_f} = \int dA e^{-S_0} e^{i\Gamma}, ext{ where} \ \mathcal{D} &= \Gamma_\mu A_\mu = egin{pmatrix} A_3 + iA_4 & A_1 - iA_2 \ A_1 + iA_2 & -A_3 + iA_4 \end{pmatrix} = (2N imes 2N ext{ matrices}), \end{aligned}$$

Phase-quenched partition function

$$Z_0 = \int dA e^{-S_0} = \int dA e^{-S_B} |\det \mathcal{D}|^{N_f}.$$

det \mathcal{D} becomes complex conjugate under

$$A_n^P = A_n (n=1,2,3), \,\,\, A_4^P = -A_4.$$

In general, det \mathcal{D} is complex, while det \mathcal{D} is real when $A_4 = 0$.

Monte Carlo simulation of the phase-quenched model

Simulation of the partition function Z_0 with the phase omitted. Observable for probing dimensionality : $T_{\mu\nu} = \frac{1}{N} \operatorname{tr} (A_{\mu}A_{\nu})$. $\lambda_n \ (n = 1, 2, 3, 4)$: eigenvalues of $T_{\mu\nu} \ (\lambda_1 \ge \lambda_2 \ge \lambda_3 \ge \lambda_4)$



Results for r = 1 (left) and r = 2 (right).

$$\langle \lambda_1
angle_0 = \dots = \langle \lambda_4
angle_0 o 1 + rac{r}{2} ext{ (as } N o \infty),$$

 $\langle * \rangle_0 = ($ V.E.V. for the phase-quenched model $Z_0).$

The effect of the phase is crucial for the spontaneous rotational symmetry breaking.

Gaussian expansion analysis up to 9th order:

Okubo, Nishimura and Sugino, hep-th/0412194.



Results for
$$r = 1$$
 $(\tilde{\lambda}_n = \frac{\lambda_n}{\langle \lambda_n \rangle_0} = \frac{\lambda_n}{1 + \frac{r}{2}})$:

- SO(2) ansatz: $\langle \tilde{\lambda}_1 \rangle = \langle \tilde{\lambda}_2 \rangle = 1.4, \, \langle \tilde{\lambda}_3 \rangle = 0.7, \, \langle \tilde{\lambda}_4 \rangle = 0.5.$
- SO(3) ansatz: $\langle \tilde{\lambda}_1
 angle = \langle \tilde{\lambda}_2
 angle = \langle \tilde{\lambda}_3
 angle = 1.17, \, \langle \tilde{\lambda}_4
 angle = 0.5.$
- No constant volume property : $\prod_{n=1}^{4} \langle \tilde{\lambda}_n \rangle \simeq \begin{cases} 0.69 \ (\text{SO}(2) \text{ ansatz}) \\ 0.79 \ (\text{SO}(3) \text{ ansatz}) \end{cases} \neq 1.$
- Comparison of free energy: $F_{SO(2)} = -1.8 < F_{SO(3)} = -1.5 \Rightarrow SO(2)$ vacuum is favored.

Spontaneous breakdown of SO(4) to SO(2) at finite $r\left(=\frac{N_f}{N}\right)$.

3 Single-variable factorization method

Difficulty in simulating complex-action systems:

• Sign problem: Standard reweighting method:

 $\langle \lambda_n
angle = rac{\langle \lambda_n e^{i\Gamma}
angle_0}{\langle e^{i\Gamma}
angle_0} = rac{\langle \lambda_n e^{i\Gamma}
angle_0}{\langle e^{i\Gamma}
angle_0}, ext{ where } \langle *
angle_0 = (ext{ V.E.V. for the phase-quenched model } Z_0).$

(Number of configurations required) $\simeq e^{O(N^2)}$.

• Overlap problem: Discrepancy of a distribution function between the phase-quenched model Z_0 and the full model Z.



Factorization method: An approach to overcome the overlap problem in Monte Carlo simulation.

- K. N. Anagnostopoulos and J. Nishimura, hep-th/0108041,
- J. Ambjorn, K. N. Anagnostopoulos, J. Nishimura and J. J. M. Verbaarschot, hep-lat/0208025.

Factorization property of the distribution function

 $(\tilde{\lambda}_n \stackrel{\text{def}}{=} \lambda_n / \langle \lambda_n \rangle_0$: deviation from $1 \Rightarrow$ effect of the phase)

where

$$C = \langle e^{i\Gamma}
angle_0, ~~
ho_n^{(0)}(x) = \langle \delta(x - ilde{\lambda}_n)
angle_0, ~~w_n(x) = \langle e^{i\Gamma}
angle_{n,x}, \ \langle *
angle_{n,x} = [ext{V.E.V.} ext{ for the partition function } Z_{n,x} = \int dA e^{-S_0} \delta(x - ilde{\lambda}_n)].$$

In fact, $w_n(x) = \langle e^{i\Gamma} \rangle_{n,x} = \langle \cos \Gamma \rangle_{n,x}$ in our model.

Under parity transformation $A_n^P = A_n (n = 1, 2, 3), \ A_4^P = -A_4 \Rightarrow$

- Partition function Z is complex conjugate.
- However, the action S_0 is invariant $\rightarrow C = \langle e^{i\Gamma} \rangle_0 = \langle \cos \Gamma \rangle_0$

$$\bullet \ \lambda_n \ (\text{eigenvalues of} \ T_{\mu\nu} = \frac{1}{N} \text{tr} \ A_\mu A_\nu) \ \text{are also invariant} \ \to w_n(x) = \langle e^{i\Gamma} \rangle_{n,x} = \langle \cos \Gamma \rangle_{n,x}.$$

Simulation of partition function $Z_{n,x} \Rightarrow x$ is trapped at $\tilde{\lambda}_n$.

The system visits the configurations important for full partition function Z. Resolution of overlap problem. In practice, we approximate the partition function $Z_{n,x}$ by

$$Z_{n,V}=\int dA e^{-S_0}e^{-V(\lambda_n)}, ext{ where } V(x)=rac{\gamma}{2}(x-\xi)^2, \hspace{0.2cm} \gamma,\xi= ext{(parameters)}.$$

Monte Carlo evaluation of $ho_n^{(0)}(x)$ and $w_n(x)$:

$$ho_{n,V}(x) \stackrel{ ext{def}}{=} \langle \delta(x- ilde{\lambda}_n)
angle_{n,V} \propto
ho_n^{(0)}(x) \exp(-V(\langle \lambda_n
angle_0 x)).$$

The position of the peak x_p for the distribution function $\rho_{n,V}(x)$:

$$0=rac{\partial}{\partial x}\log
ho_{n,V}(x)=f_n^{(0)}(x)-\langle\lambda_n
angle_0V'(\langle\lambda_n
angle_0x), ext{ where } f_n^{(0)}(x)\stackrel{ ext{def}}{=}rac{\partial}{\partial x}\log
ho_n^{(0)}(x).$$

- ullet Determination of x_p : $ho_{n,V}(x)$ has a sharp peak for large γ
 - $\Rightarrow x_p \text{ is approximated as } x_p \simeq \langle \tilde{\lambda}_n \rangle_{n,V}.$
- Determination of $\rho_n^{(0)}(x)$: Vary ξ , and calculate $f_n^{(0)}(x_p)$ for different x_p . Then, evaluate $\rho_n^{(0)}(x) = \exp\left\{\int_0^x dz f_n^{(0)}(z) + \text{const.}\right\}$.

Monte Carlo evaluation of $\langle \tilde{\lambda}_n \rangle$

 $w_n(x)>0 \Rightarrow \langle ilde{\lambda}_n
angle$ is the minimum of $\mathcal{F}_n(x)$:

$${\mathcal F}_n(x) = (ext{free energy density}) = -rac{1}{N^2}\log
ho_n(x)$$

 $egin{aligned} ext{We solve } \mathcal{F}'_n(x) &= 0, ext{ namely } rac{1}{N^2} f_n^{(0)}(x) = -rac{d}{dx} \left\{ rac{1}{N^2} \log w_n(x)
ight\}. \ ext{Both } rac{1}{N^2} \log w_n(x) ext{ and } rac{1}{N^2} f_n^{(0)}(x) ext{ scale at large } N ext{ as} \ &rac{1}{N^2} \log w_n(x) o \Phi_n(x), \ \ rac{1}{N^2} f_n^{(0)}(x) o F_n(x) \end{aligned}$



Monte Carlo studies of the rotational symmetry breaking in dimensionally reduced matrix models , Aug. 16th 2012 16:00 \sim 17:00

$(ext{Behavior of } \Phi_n(x))$

Asymptotic behavior of $\Phi_n(x) = \frac{1}{N^2} \log w_n(x)$ at $x \ll 1$ and $x \gg 1$. When we fix the *n*-th largest eigenvalue \rightarrow

• $x \ll 1$ (n = 2, 3, 4): (5 - n) directions are shrunk

 \Rightarrow (n-1)-dimensional configuration

- $x \gg 1$ (n = 1, 2, 3): (4 n) directions are shrunk
 - \Rightarrow *n*-dimensional configuration

Fermion determinant det \mathcal{D} is complex conjugate under

$$A_n^P = A_n (n=1,2,3), \,\,\, A_4^P = -A_4$$

 $\Omega_d = (d\text{-dim. configuration such that } A_{d+1} = A_{d+2} = \cdots A_4 = 0 \text{ after a certain SO}(4) \text{ rotation})$ 3-dimensional configuration $\Omega_3 \Rightarrow$ Fermion determinant is real.

J. Nishimura and G. Vernizzi, hep-th/0003223.

For *d*-dimensional configuration Ω_d ,

$$rac{\partial^n \Gamma}{\partial A^{a_1}_{\mu_1}\cdots \partial A^{a_n}_{\mu_n}}=0 \,\, ext{for} \,\, n=1,\cdots,3-d$$

(Up to (3 - d)-order perturbation \Rightarrow configuration $\in \Omega_3$)

Expected power behaviors:

$$\Phi_n(x) \propto \left\{egin{array}{l} c_{n,0} x^{5-n} + \cdots & (x \ll 1, n=2,3,4) \ rac{d_{n,0}}{x^{4-n}} + \cdots & (x \gg 1, n=1,2,3) \end{array}
ight.$$

 $(*) \ x \ {
m has \ the \ order \ of \ the \ eigenvalues \ of \ } T_{\mu
u} = rac{1}{N} {
m tr} \ (A_\mu A_
u).$

.

Monte Carlo studies of the rotational symmetry breaking in dimensionally reduced matrix models , Aug. 16th 2012 16:00 \sim 17:00



Double-peak structure of $\rho_n(x)$ for n = 2, 3Three solutions of $\frac{d}{dx} \log \rho_n(x) = 0$ $(\underbrace{x_s}_{\text{maximum}} < \underbrace{x_b}_{\text{minimum}} < \underbrace{x_l}_{\text{maximum}})$. Which peak is higher?

$$\Delta_n \ = \ rac{1}{N^2} (\log
ho_n(x_l) - \log
ho_n(x_s)) = (\Phi_n(x_l) - \Phi_n(x_s)) + \int_{x_s}^{x_l} dx rac{1}{N^2} f_n^{(0)}(x)$$

Summary of the result for r = 1:

\boldsymbol{n}	x_s	x_l	Δ_n	SO(2) (GEM)	SO(3) (GEM)
1		2.14(1)	_	1.4	1.17
2	0.49(1)	$\underbrace{1.317(1)}_{\rm SO(2)}$	0.33(2)	1.4	1.17
3	$\underbrace{\underbrace{0.62(2)}_{\mathrm{SO}(2)}}$	$\underbrace{1.11(2)}_{\mathrm{SO}(3)}$	0.11(4)	0.7	1.17
4	$\underbrace{\underbrace{0.71(5)}_{\mathrm{SO}(3)}}$	_	_	0.5	0.5

• $\langle \tilde{\lambda}_1 \rangle > \langle \tilde{\lambda}_2 \rangle > 1 > \langle \tilde{\lambda}_4 \rangle \rightarrow SO(4)$ rotational symmetry breaking due to the effect of phase (it is subtle whether Δ_3 is positive or negative).

• $\langle \tilde{\lambda}_1 \rangle \simeq 2.14(1)$ is far from $\langle \tilde{\lambda}_1 \rangle_{\text{GEM}} \simeq 1.4 \rightarrow \text{still remaining overlap problem.}$ $w_1(x)$ comes from the configuration $\langle \tilde{\lambda}_1 \rangle > 1 > \langle \tilde{\lambda}_2 \rangle > \langle \tilde{\lambda}_3 \rangle > \langle \tilde{\lambda}_4 \rangle \rightarrow$ $w_1(x)$ is underestimated.

4 Multi-variable factorization method

Still remaining overlap problem (e.g. $\langle \tilde{\lambda}_{n=1} \rangle$). We constrain the observables $\Sigma = \{\mathcal{O}_k | k = 1, 2, \cdots, n\}$. Observables are normalized as $\tilde{\mathcal{O}}_k = \frac{\mathcal{O}_k}{\langle \mathcal{O}_k \rangle_0}$, where $\langle \cdots \rangle_0 = (V.E.V.$ for the phase-quenched partition function Z_0).

Generalized distribution function $ho(x_1,\cdots,x_n)=\Big\langle\prod_{k=1}^n\delta(x_k- ilde{\mathcal{O}}_k)\Big
angle$ factorizes as

$$egin{aligned} &
ho(x_1,\cdots,x_n) \stackrel{ ext{def}}{=} \langle \prod_{k=1}^n \delta(x_k- ilde{\mathcal{O}}_k)
angle \stackrel{ ext{reweighting}}{=} rac{\langle \prod_{k=1}^n \delta(x- ilde{\mathcal{O}}_n)e^{i\Gamma}
angle_0}{\langle e^{i\Gamma}
angle_0} \ &= rac{1}{\langle e^{i\Gamma}
angle_0} imes \langle \prod_{k=1}^n \delta(x_k- ilde{\mathcal{O}}_k)
angle_0 imes \langle \prod_{k=1}^n \delta(x_k- ilde{\mathcal{O}}_k) e^{i\Gamma}
angle_0} \ &= rac{1}{\langle e^{i\Gamma}
angle_0} imes \langle \prod_{k=1}^n \delta(x_k- ilde{\mathcal{O}}_k)
angle_0 imes \langle \prod_{k=1}^n \delta(x_k- ilde{\mathcal{O}}_k)
angle_0 \ &= rac{1}{C}
ho^{(0)}(x_1,\cdots,x_n) \ &= rac{1}{C}
ho^{(0)}(x_1,\cdots,x_n) w(x_1,\cdots,x_n), \ & ext{where} \ &
ho^{(0)}(x_1,\cdots,x_n) \ &= \left\langle \prod_{k=1}^n \delta(x_k- ilde{\mathcal{O}}_k)
ight
angle_0, \ &w(x_1,\cdots,x_n) = \langle e^{i\Gamma}
angle_{x_1,\cdots,x_n}. \ &\langle \cdots
angle_{x_1,\cdots,x_n} = ext{V.E.V. for partition function} \ &Z_{x_1,\cdots,x_n} = \int dAe^{-S_0} \prod_{k=1}^n \delta(x_k- ilde{\mathcal{O}}_k). \end{aligned}$$

Evaluation of the observables $\langle \tilde{\mathcal{O}}_k \rangle$:

Peak of the distribution function $ho(x_1, \cdots, x_n)$

 \Rightarrow solution of the saddle-point equation

$$rac{d}{dx_k}\log
ho^{(0)}(x_1,\cdots,x_n)=-rac{d}{dx_k}\log w(x_1,\cdots,x_n)$$

Set of observables in Gaussian toy model:

- Single-variable factorization method: $\Sigma = \{\mathcal{O}_1 = \lambda_n\}$ for n = 1, 2, 3, 4 separately.
- Multi-variable factorization method: $\Sigma = \{\mathcal{O}_k = \lambda_k | k = 1, 2, 3, 4\}$ simultaneously. Partition function to simulate:

$$Z_{x_1,x_2,x_3,x_4}=\int dA\,e^{-S_0}\,\prod_{k=1}^4\delta(x_k- ilde\lambda_k),$$

Distribution function:

$$ho(x_1,x_2,x_3,x_4) \ = \ \Big\langle \prod_{k=1}^4 \delta(x_k- ilde{\lambda}_k) \Big
angle.$$

SO(3) vacuum

Solutions which satisfy $x_1 = x_2 = x_3 > 1 > x_4$. Result of Gaussian Expansion Method: $\langle \tilde{\lambda}_1 \rangle = \langle \tilde{\lambda}_2 \rangle = \langle \tilde{\lambda}_3 \rangle = 1.17, \ \langle \tilde{\lambda}_4 \rangle = 0.5 \ (r = 1).$

Minimum of the free energy density $\mathcal{F}(x)$

$$egin{aligned} &rac{\partial}{\partial \zeta}
ho_{\mathrm{SO}(3)}^{(0)}(x,y) = -rac{\partial}{\partial \zeta}w_{\mathrm{SO}(3)}(x,y) & (\zeta=x,y) \;, ext{ where } \ &
ho_{\mathrm{SO}(3)}^{(0)}(x,y) =
ho^{(0)}(x,x,x,y) \;, \ &w_{\mathrm{SO}(3)}(x,y) = w(x,x,x,y) \;, \end{aligned}$$

 $igl(ext{Calculation of } \langle ilde{\lambda}_{n=3}
angle ext{ at } r=1 igr) igr)$

Calculation of $\langle \tilde{\lambda}_{n=3} \rangle$ for fixed $\langle \tilde{\lambda}_{n=4} \rangle = 0.5$.

$$rac{1}{\mathrm{V}^2} f^{(0)}_{\mathrm{SO}(3),x}(x,y) = -rac{\partial}{\partial x} \Phi_{\mathrm{SO}(3)}(x,y),$$

where $f_{{
m SO}(3),x}^{(0)}(x,y)=rac{\partial}{\partial x}\log
ho_{{
m SO}(3)}^{(0)}(x,y) ext{ and } \Phi_{{
m SO}(3)}(x,y)=rac{1}{N^2}\log w_{{
m SO}(3)}(x,y).$

Scaling behavior of the phase:





SO(2) vacuum

Solutions which satisfy $x_1 = x_2 > 1 > x_3 > x_4$. Result of Gaussian Expansion Method: $\langle \tilde{\lambda}_{1,2} \rangle = 1.4, \, \langle \tilde{\lambda}_3 \rangle = 0.7, \, \langle \tilde{\lambda}_4 \rangle = 0.5 \, (r = 1).$

Minimum of the free energy density $\mathcal{F}(x)$

$$egin{aligned} &rac{\partial}{\partial \zeta}
ho_{\mathrm{SO}(2)}^{(0)}(x,y,z) = -rac{\partial}{\partial \zeta}w_{\mathrm{SO}(2)}(x,y,z) & (\zeta=x,y,z) \;, ext{ where } \ &
ho_{\mathrm{SO}(2)}^{(0)}(x,y,z) =
ho^{(0)}(x,x,y,z) \;, \ &w_{\mathrm{SO}(2)}(x,y,z) = w(x,x,y,z) \;, \end{aligned}$$

 $\begin{array}{l} \hline \text{Calculation of } \langle \tilde{\lambda}_{n=2} \rangle \text{ at } r=1 \\ \text{Calculation of } \langle \tilde{\lambda}_{n=2} \rangle \text{ for fixed } \langle \tilde{\lambda}_{n=3} \rangle = 0.7 \text{ and } \langle \tilde{\lambda}_{n=4} \rangle = 0.5. \\ & \quad \frac{1}{N^2} f_{\mathrm{SO}(2),x}^{(0)}(x,y=0.7,z=0.5) = -\frac{\partial}{\partial x} \Phi_{\mathrm{SO}(2)}(x,y=0.7,z=0.5), \\ \text{where } f_{\mathrm{SO}(2),x}^{(0)}(x,y,z) = \frac{\partial}{\partial x} \log \rho_{\mathrm{SO}(2)}^{(0)}(x,y,z) \text{ and } \Phi_{\mathrm{SO}(2)}(x,y,z) = \frac{1}{N^2} \log w_{\mathrm{SO}(2)}(x,y,z). \end{array}$

Scaling behavior of the phase:

$$\Phi_{{
m SO}(2)}(x,y=0.7,z=0.5)\sim - ilde{d}_1x^{-2}+ ilde{d}_2x^{-2.5}$$



Numerical Result: $\langle \tilde{\lambda}_{n=2} \rangle = 1.373(2)$, (GEM result $\langle \tilde{\lambda}_{n=2} \rangle_{\text{GEM}} = 1.4$).





Summary of the result for r = 1:

ansatz	SO(3)			$\mathrm{SO}(2)$		
method	single-obs.	multi-obs.	GEM	single-obs.	multi-obs.	GEM
$\langle ilde{oldsymbol{\lambda}}_1 angle$			1.17			1.4
$\langle ilde{oldsymbol{\lambda}}_2 angle$			1.17	1.317(1)	1.373(2)	1.4
$\langle ilde{oldsymbol{\lambda}}_3 angle$	1.11(2)	1.151(2)	1.17	0.62(2)	0.649(4)	0.7
$\langle ilde{oldsymbol{\lambda}}_4 angle$	0.71(5)	0.59(2)	0.5	not available	0.551(2)	0.5

Comparison of the free energy

We evaluate $\Delta = -\mathcal{F}_{\mathrm{SO}(3)} + \mathcal{F}_{\mathrm{SO}(2)} = rac{1}{N^2} \{\log
ho(ec{x}_{\mathrm{SO}(3)}) -
ho(ec{x}_{\mathrm{SO}(2)})\}.$

• $\Delta < 0 \Rightarrow SO(2)$ vacuum dominates. $\Delta > 0 \Rightarrow SO(3)$ vacuum dominates.

$$egin{aligned} &ullet ec{x}_{\mathrm{SO}(3)} = (X', X', X', Y'), & X' \simeq 1.17, & Y' \simeq 0.5. \ &ec{x}_{\mathrm{SO}(2)} = (X, X, Y, Z), & X \simeq 1.4, & Y \simeq 0.7, & Z = 0.5. \end{aligned}$$

This is rewritten as



Is there any more overlap problem?

Observables to constrain: $\Sigma = \{\mathcal{O}_k = \lambda_k | k = 1, 2, 3, 4\}$. Is this enough?

$$egin{aligned} ext{Partition function } Z_\mathcal{O} &= \int dA e^{-S_0} \delta(x- ilde{\mathcal{O}}) \prod_{n=1}^4 \delta(x_n- ilde{\lambda}_n) \ (ext{here we constrain } \Sigma &= \{\mathcal{O},\lambda_1,\cdots,\lambda_4\}). \end{aligned}$$

Peak of the distribution function $\rho(x_1, x_2, x_3, x_4, x) = \langle \delta(x - \tilde{\mathcal{O}}) \prod_{k=1}^{4} \delta(x_k - \tilde{\lambda}_k) \rangle$. $\rho_{\mathcal{O}}(x) = \rho(X = 1.4, X = 1.4, Y = 0.7, Z = 0.5, x) \text{ (with } x_1, \cdots, x_4 \text{ fixed at GEM results).}$

Saddle-point equation: $\frac{d}{dx} \frac{1}{N^2} \log \rho_{\mathcal{O}}^{(0)}(x) = -\frac{d}{dx} \frac{1}{N^2} \log w_{\mathcal{O}}(x)$, where $\rho_{\mathcal{O}}^{(0)}(x) = \langle \delta(x - \mathcal{O}) \rangle_{X,X,Y,Z}$ (VEV of partition function $Z_{X,X,Y,Z} = \int dA e^{-S_0} \delta(X - \tilde{\lambda}_1) \delta(X - \tilde{\lambda}_2) \delta(Y - \tilde{\lambda}_3) \delta(Z - \tilde{\lambda}_4)$.) $w_{\mathcal{O}}(x) = \langle e^{i\Gamma} \rangle_{\mathcal{O}}$ (VEV of partition function $Z_{\mathcal{O}}$ with $x_1 = x_2 = X, x_3 = Y, x_4 = Z$).

Do the peaks of $ho_{\mathcal{O}}^{(0)}(x)$ and $ho_{\mathcal{O}}(x)$ match? We consider $\mathcal{O} = -\frac{1}{N} \mathrm{tr} \, [A_{\mu}, A_{
u}]^2.$ Simulation with $\tilde{\lambda}_n$ fixed at GEM result of SO(2) ansatz $\langle \tilde{\lambda}_{1,2} \rangle = 1.4, \langle \tilde{\lambda}_3 \rangle = 0.7, \langle \tilde{\lambda}_4 \rangle = 0.5 \ (r = 1).$ $w_{\mathcal{O}}(x) \to 1 \text{ as } x \to 0.$ $([A_{\mu}, A_{\nu}] \to 0 \text{ as } x \to 0 \Rightarrow \text{ diagonal configurations become dominant.}$ For $A_{\mu} = \text{diag}(\alpha_{\mu}^{(1)}, \cdots, \alpha_{\mu}^{(N)})$, we have $\det \mathcal{D} = \prod_{i=1}^{N} \left(\sum_{\mu=1}^{4} (\alpha_{\mu}^{(i)})^2 \right) \geqq 0.)$ Asymptotic behavior: $\frac{1}{N^2} \log w_{\mathcal{O}}(x) = -c_{n,0}x^2 + c_{n,1}x^{2.5} + \cdots.$

- Peak of $\rho_{\mathcal{O}}^{(0)}(x)$: Solution of $\frac{1}{N^2} \frac{d}{dx} \log \rho_{\mathcal{O}}^{(0)}(x) = 0 \Rightarrow x \simeq 0.92$.
- Peak of $\rho_{\mathcal{O}}(x)$: Solution of $\frac{1}{N^2} \frac{d}{dx} \log \rho_{\mathcal{O}}^{(0)}(x) = -\frac{1}{N^2} \frac{d}{dx} \log w_{\mathcal{O}}(x) \Rightarrow x \simeq 0.85(3)$. Systematic error is around $10\% \Rightarrow$ there is only a small overlap problem left.



5 Conclusion

Monte Carlo simulation of the toy model with similarity to the Euclidean IKKT model. Factorization method to overcome "overlap problem".

- Phase of the fermion determinant \Rightarrow crucial for rotational symmetry breaking.
- VEV's $\langle \tilde{\lambda}_n \rangle \Rightarrow \text{consistent with the GEM.}$

(Future problems)

Monte Carlo Simulation of the IKKT model Anagnostopoulos, T. A. and Nishimura, in progress Effect of supersymmetry on dynamical generation of spacetime.

Application of factorization method to wider range of science.