

低エネルギー QCD とカイラル有効理論 – 計算ノート –

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注意！

間違いがあるかもしれないので、ご利用は自己責任で。

計算に必要な知識

$$(\gamma_5)^2 = 1$$

$$\bar{q} = (q)^\dagger \gamma_0$$

$$(\gamma_5)^\dagger = \gamma_5$$

$$\{\gamma_\mu, \gamma_5\} = 0$$

$$t = \frac{\tau}{2}$$

$$\tau_a \tau_b = \delta_{ab} + i\epsilon_{abc} \tau_c$$

$$\text{tr} (t_a t_b) = \frac{1}{2} \delta_{ab}$$

ここで t は SU(2) の生成子で最後の式のように規格化されている。 τ は通常のパウリ行列。

page 11 : 射影演算子の性質

$$P_L + P_R = \frac{1}{2}(1 - \gamma_5) + \frac{1}{2}(1 + \gamma_5)$$
$$= 1$$

$$P_L^2 = \frac{1}{2}(1 - \gamma_5) \times \frac{1}{2}(1 - \gamma_5)$$
$$= \frac{1}{4}(1 - \gamma_5 - \gamma_5 + (\gamma_5)^2)$$
$$= \frac{1}{4}(2 - 2\gamma_5)$$
$$= \frac{1}{2}(1 - \gamma_5)$$
$$= P_L$$

$$P_R^2 = \frac{1}{2}(1 + \gamma_5) \times \frac{1}{2}(1 + \gamma_5)$$
$$= \frac{1}{4}(1 + \gamma_5 + \gamma_5 + (\gamma_5)^2)$$
$$= \frac{1}{4}(2 + 2\gamma_5)$$
$$= \frac{1}{2}(1 + \gamma_5)$$
$$= P_R$$

$$P_L P_R = \frac{1}{2}(1 - \gamma_5) \times \frac{1}{2}(1 + \gamma_5)$$
$$= \frac{1}{4}(1 - \gamma_5 + \gamma_5 - (\gamma_5)^2)$$
$$= 0$$

$$P_R P_L = \frac{1}{2}(1 + \gamma_5) \times \frac{1}{2}(1 - \gamma_5)$$
$$= \frac{1}{4}(1 + \gamma_5 - \gamma_5 - (\gamma_5)^2)$$
$$= 0$$

page 12 : 反フェルミオン

$$\bar{q}_L = (P_L q)^\dagger \gamma_0$$
$$= q^\dagger P_L^\dagger \gamma_0$$
$$= q^\dagger \left(\frac{1 + \gamma_5}{2} \right)^\dagger \gamma_0$$
$$= q^\dagger \left(\frac{1 + \gamma_5}{2} \right) \gamma_0$$

$$\begin{aligned}
&= q^\dagger \gamma_0 \left(\frac{1 - \gamma_5}{2} \right) \\
&= \bar{q} P_R
\end{aligned}$$

page 12 : カイラリティ、 γ_5 の固有値

$$\begin{aligned}
\gamma_5 q_L &= \gamma_5 \frac{1}{2} (1 - \gamma_5) q \\
&= \frac{1}{2} (\gamma_5 - 1) q \\
&= -\frac{1}{2} (1 - \gamma_5) q \\
&= -q_L \\
\gamma_5 q_R &= \gamma_5 \frac{1}{2} (1 + \gamma_5) q \\
&= \frac{1}{2} (\gamma_5 + 1) q \\
&= q_R
\end{aligned}$$

page 12 : ラグランジアン

$$\begin{aligned}
\mathcal{L}_{\text{kin}} &= \bar{q} \not{\partial} q \\
&= (\bar{q}_R + \bar{q}_L) \not{\partial} (q_L + q_R) \\
&= \bar{q}_R \not{\partial} q_L + \bar{q}_R \not{\partial} q_R + \bar{q}_L \not{\partial} q_L + \bar{q}_L \not{\partial} q_R \\
&= \bar{q} P_L \not{\partial} P_L q + \bar{q}_R \not{\partial} q_R + \bar{q}_L \not{\partial} q_L + \bar{q} P_R \not{\partial} P_R q \\
&= \bar{q} P_L P_R \not{\partial} q + \bar{q}_R \not{\partial} q_R + \bar{q}_L \not{\partial} q_L + \bar{q} P_R P_L \not{\partial} q \\
&= \bar{q}_L \not{\partial} q_L + \bar{q}_R \not{\partial} q_R \\
\mathcal{L}_{\text{mass}} &= \bar{q} m q \\
&= (\bar{q}_R + \bar{q}_L) m (q_L + q_R) \\
&= \bar{q}_R m q_L + \bar{q}_R m q_R + \bar{q}_L m q_L + \bar{q}_L m q_R \\
&= \bar{q}_R m q_L + \bar{q} P_L m P_R q + \bar{q} P_R m P_L q + \bar{q}_L m q_R \\
&= \bar{q}_R m q_L + \bar{q}_L m q_R
\end{aligned}$$

page 14 : 極性、軸性変換の右、左成分

$$\begin{aligned}q_R + q_L &\rightarrow e^{i\theta_V} (q_R + q_L) \\ &= e^{i\theta_V} q_R + e^{i\theta_V} q_L \\ q_R + q_L &\rightarrow e^{i\gamma_5\theta_A} (q_R + q_L) \\ &= e^{i\gamma_5\theta_V} q_R + e^{i\gamma_5\theta_V} q_L \\ &= e^{i\theta_V} q_R + e^{-i\theta_V} q_L\end{aligned}$$

よって

$$\begin{aligned}g_V &= (e^{i\theta_V}, e^{i\theta_V}) \\ g_A &= (e^{i\theta_A}, e^{-i\theta_A})\end{aligned}$$

page 15 : 極性、軸性変換とラグランジアン

反フェルミオン場は、極性変換の下で

$$\begin{aligned}\bar{q} &= (q)^\dagger \gamma_0 \\ &\rightarrow (qe^{i\theta_V})^\dagger \gamma_0 \\ &= \bar{q}e^{-i\theta_V}\end{aligned}$$

となるので (変換パラメーター θ_V は実)、ラグランジアンは極性変換の下で

$$\begin{aligned}\mathcal{L} &= \bar{q}\not{\partial}q + \bar{q}mq \\ &\rightarrow \bar{q}e^{-i\theta_V}\not{\partial}e^{i\theta_V}q + \bar{q}e^{-i\theta_V}me^{i\theta_V}q \\ &= \bar{q}\not{\partial}q + \bar{q}mq \\ &= \mathcal{L}\end{aligned}$$

と不変である。反フェルミオン場の軸性変換は

$$\begin{aligned}\bar{q} &= (q)^\dagger \gamma_0 \\ &\rightarrow (q)^\dagger e^{-i\gamma_5\theta_A} \gamma_0 \\ &= (q)^\dagger \gamma_0 e^{+i\gamma_5\theta_A} \\ &= \bar{q}e^{+i\gamma_5\theta_A}\end{aligned}$$

であるので、ラグランジアンは

$$\begin{aligned}\mathcal{L} &= \bar{q}\not{\partial}q + \bar{q}mq \\ &\rightarrow \bar{q}e^{i\gamma_5\theta_A}\not{\partial}e^{i\gamma_5\theta_A}q + \bar{q}e^{i\gamma_5\theta_A}me^{i\gamma_5\theta_A}q \\ &= \bar{q}\not{\partial}e^{-i\gamma_5\theta_A}e^{i\gamma_5\theta_A}q + \bar{q}e^{2i\gamma_5\theta_A}mq \\ &= \bar{q}\not{\partial}q + \bar{q}e^{2i\gamma_5\theta_A}mq \\ &\neq \mathcal{L}\end{aligned}$$

となる。つまり質量項がある場合は不変でない。

page 18 : 右、左生成子の交換関係

$$\begin{aligned}
 [t_R^a, t_R^b] &= ([t^a, t^b], 0) \\
 &= (if_c^{ab} t^c, 0) \\
 &= if_c^{ab} (t^c, 0) \\
 &= if_c^{ab} t_R^c \\
 [t_L^a, t_L^b] &= (0, [t^a, t^b]) \\
 &= (0, if_c^{ab} t^c) \\
 &= if_c^{ab} (0, t^c) \\
 &= if_c^{ab} t_L^c \\
 [t_R^a, t_L^b] &= (0, 0) \\
 &= 0
 \end{aligned}$$

page 18 : 極性、軸性生成子の交換関係

$$\begin{aligned}
 [t_V^a, t_V^b] &= ([t^a, t^b], [t^a, t^b]) \\
 &= (if_c^{ab} t^c, if_c^{ab} t^c) \\
 &= if_c^{ab} (t^c, t^c) \\
 &= if_c^{ab} t_V^c \\
 [t_A^a, t_A^b] &= ([t^a, t^b], [-t^a, -t^b]) \\
 &= (if_c^{ab} t^c, if_c^{ab} t^c) \\
 &= if_c^{ab} (t^c, t^c) \\
 &= if_c^{ab} t_V^c \\
 [t_A^a, t_V^b] &= ([t^a, t^b], [-t^a, t^b]) \\
 &= (if_c^{ab} t^c, -if_c^{ab} t^c) \\
 &= if_c^{ab} (t^c, -t^c) \\
 &= if_c^{ab} t_A^c
 \end{aligned}$$

page 28 : 線形シグマ模型の場のカイラル変換

$\sigma \sim \bar{q}q$ 、 $\pi \sim \bar{q}i\tau\gamma_5q$ 。極性変換の下で

$$\begin{aligned}
 \bar{q}q &\rightarrow \bar{q}(1 - i\theta^V \cdot \tau/2)(1 + i\theta^V \cdot \tau/2)q + \mathcal{O}(\theta^2) \\
 &= \bar{q}q + \mathcal{O}(\theta^2) \\
 \bar{q}i\tau_a\gamma_5q &\rightarrow \bar{q}(1 - i\theta_b^V \tau_b/2)i\tau_a\gamma_5(1 + i\theta_b^V \tau_b/2)q + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q + \bar{q}(-i)\theta_b^V (\tau_b/2)i\tau_a\gamma_5q + \bar{q}i\tau_a\gamma_5i\theta_b^V (\tau_b/2)q + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q + \frac{\theta_b^V}{2} [\bar{q}\tau_b\tau_a\gamma_5q - \bar{q}\tau_a\tau_b\gamma_5q] + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q + \frac{\theta_b^V}{2} [\bar{q}(\delta_{ba} + i\epsilon_{bac}\tau_c)\gamma_5q - \bar{q}(\delta_{ab} + i\epsilon_{abc}\tau_c)\gamma_5q] + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q + \frac{\theta_b^V}{2} [\bar{q}i(-\epsilon_{abc})\tau_c\gamma_5q - \bar{q}i\epsilon_{abc}\tau_c\gamma_5q] + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q - \epsilon_{abc}\theta_b^V \bar{q}i\tau_c\gamma_5q + \mathcal{O}(\theta^2)
 \end{aligned}$$

よって無限少変換 ($\theta_{V,A}$ の 1 次) では

$$\begin{aligned}
 \sigma &\rightarrow \sigma \\
 \pi &\rightarrow \pi - \theta^V \times \pi
 \end{aligned}$$

軸性変換の下で

$$\begin{aligned}
 \bar{q}q &\rightarrow \bar{q}(1 + i\gamma_5\theta^A \cdot \tau/2)(1 + i\gamma_5\theta^A \cdot \tau/2)q + \mathcal{O}(\theta^2) \\
 &= \bar{q}q + \theta^A \cdot [\bar{q}i\gamma_5\tau q] + \mathcal{O}(\theta^2) \\
 \bar{q}i\tau_a\gamma_5q &\rightarrow \bar{q}(1 + i\gamma_5\theta_b^A \tau_b/2)i\tau_a\gamma_5(1 + i\gamma_5\theta_b^A \tau_b/2)q + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q + \frac{\theta_b^V}{2} [-\bar{q}\tau_b\tau_a\gamma_5\gamma_5q - \bar{q}\tau_a\tau_b\gamma_5\gamma_5q] + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q - \frac{\theta_b^V}{2} [\bar{q}(\delta_{ba} + i\epsilon_{bac}\tau_c)q + \bar{q}(\delta_{ab} + i\epsilon_{abc}\tau_c)q] + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_a\gamma_5q - \frac{\theta_a^V}{2} [\bar{q}\gamma_5q] - \frac{\theta_b^V}{2} [\bar{q}i(-\epsilon_{abc})\tau_c\gamma_5q + \bar{q}i\epsilon_{abc}\tau_cq] + \mathcal{O}(\theta^2) \\
 &= \bar{q}i\tau_aq - \frac{\theta_a^V}{2} [\bar{q}q]
 \end{aligned}$$

よって無限少変換では

$$\begin{aligned}
 \sigma &\rightarrow \sigma + \theta^A \cdot \pi \\
 \pi &\rightarrow \pi - \theta^A \sigma
 \end{aligned}$$

page 29 : カイラル不変量

極性変換の下で

$$\begin{aligned}\sigma^2 + \boldsymbol{\pi} \cdot \boldsymbol{\pi} &\rightarrow \sigma^2 + (\boldsymbol{\pi} - \boldsymbol{\theta}^V \times \boldsymbol{\pi}) \cdot (\boldsymbol{\pi} - \boldsymbol{\theta}^V \times \boldsymbol{\pi}) \\ &= \sigma^2 + \boldsymbol{\pi} \cdot \boldsymbol{\pi} - \boldsymbol{\pi} \cdot \boldsymbol{\theta}^V \times \boldsymbol{\pi} - \boldsymbol{\theta}^V \times \boldsymbol{\pi} \cdot \boldsymbol{\pi} + \mathcal{O}(\theta^2) \\ &= \sigma^2 + \boldsymbol{\pi} \cdot \boldsymbol{\pi} - \boldsymbol{\theta}^V \cdot (\boldsymbol{\pi} \times \boldsymbol{\pi}) - (\boldsymbol{\pi} \times \boldsymbol{\pi}) \cdot \boldsymbol{\theta}^V + \mathcal{O}(\theta^2) \\ &= \sigma^2 + \boldsymbol{\pi} \cdot \boldsymbol{\pi} + \mathcal{O}(\theta^2)\end{aligned}$$

軸性変換の下で

$$\begin{aligned}\sigma^2 + \boldsymbol{\pi} \cdot \boldsymbol{\pi} &\rightarrow (\sigma + \boldsymbol{\theta}^A \cdot \boldsymbol{\pi})^2 + (\boldsymbol{\pi} - \boldsymbol{\theta}^A \boldsymbol{\sigma}) \cdot (\boldsymbol{\pi} - \boldsymbol{\theta}^A \boldsymbol{\sigma}) \\ &= \sigma^2 + 2\boldsymbol{\sigma} \boldsymbol{\theta}^A \cdot \boldsymbol{\pi} + \boldsymbol{\pi} \cdot \boldsymbol{\pi} - \boldsymbol{\pi} \cdot \boldsymbol{\theta}^A \boldsymbol{\sigma} - \boldsymbol{\theta}^A \boldsymbol{\sigma} \cdot \boldsymbol{\pi} + \mathcal{O}(\theta^2) \\ &= \sigma^2 + \boldsymbol{\pi} \cdot \boldsymbol{\pi} + \mathcal{O}(\theta^2)\end{aligned}$$

page 30 : 線形シグマ模型の真空

$$\begin{aligned}\frac{\partial V(\phi)}{\partial \phi} &= \mu^2 \phi + \frac{\lambda}{6} \phi^3 \\ &= \phi \left(\mu^2 + \frac{\lambda}{6} \phi^2 \right) \\ &= 0\end{aligned}$$

これを満たすのは

$$\begin{cases} \phi = 0 \\ \phi = \sqrt{-\frac{6\mu^2}{\lambda}} \end{cases}$$

page 31 : 自発的に対称性の破れた線形シグマ模型 (スライドの「場の一次は落とす」は間違い)

$\sigma = \tilde{\sigma} + \langle \sigma \rangle$ と書きなおして整理 :

$$\begin{aligned}\mathcal{L}_{\text{kin}} &= \frac{1}{2} \partial_\mu (\tilde{\sigma} + \langle \sigma \rangle) \partial^\mu (\tilde{\sigma} + \langle \sigma \rangle) + \frac{1}{2} \partial_\mu \boldsymbol{\pi} \cdot \partial^\mu \boldsymbol{\pi} \\ &= \frac{1}{2} \partial_\mu \tilde{\sigma} \partial^\mu \tilde{\sigma} + \frac{1}{2} \partial_\mu \boldsymbol{\pi} \cdot \partial^\mu \boldsymbol{\pi} \\ \mathcal{L}_{\text{mass}} &= -\frac{\mu^2}{2} [(\tilde{\sigma} + \langle \sigma \rangle)(\tilde{\sigma} + \langle \sigma \rangle) + \boldsymbol{\pi} \cdot \boldsymbol{\pi}] \\ &= -\frac{\mu^2}{2} \tilde{\sigma}^2 - \frac{\mu^2}{2} \boldsymbol{\pi} \cdot \boldsymbol{\pi} - \mu^2 \langle \sigma \rangle \tilde{\sigma} + (\text{const}) \\ \mathcal{L}_{\text{int}} &= -\frac{\lambda}{4!} [(\tilde{\sigma} + \langle \sigma \rangle)(\tilde{\sigma} + \langle \sigma \rangle) + \boldsymbol{\pi} \cdot \boldsymbol{\pi}]^2\end{aligned}$$

$$\begin{aligned}
&= -\frac{\lambda}{4!}[\tilde{\sigma}^2 + 2\langle\sigma\rangle\tilde{\sigma} + \langle\sigma\rangle^2 + \boldsymbol{\pi} \cdot \boldsymbol{\pi}]^2 \\
&= -\frac{\lambda}{4!}[\tilde{\sigma}^4 + 4\langle\sigma\rangle^2\tilde{\sigma}^2 + \langle\sigma\rangle^4 + (\boldsymbol{\pi} \cdot \boldsymbol{\pi})(\boldsymbol{\pi} \cdot \boldsymbol{\pi}) \\
&\quad + 4\tilde{\sigma}^2\langle\sigma\rangle\tilde{\sigma} + 2\tilde{\sigma}^2\langle\sigma\rangle^2 + 2\tilde{\sigma}^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad + 4\langle\sigma\rangle\tilde{\sigma}\langle\sigma\rangle^2 + 4\langle\sigma\rangle\tilde{\sigma}\boldsymbol{\pi} \cdot \boldsymbol{\pi} + 2\langle\sigma\rangle^2\boldsymbol{\pi} \cdot \boldsymbol{\pi}] \\
&= -\frac{\lambda}{4!}[4\langle\sigma\rangle^3\tilde{\sigma} + 6\langle\sigma\rangle^2\tilde{\sigma}^2 + 2\langle\sigma\rangle^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad + 4\langle\sigma\rangle\tilde{\sigma}^3 + \tilde{\sigma}^4 + 4\langle\sigma\rangle\tilde{\sigma}\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad + 2\tilde{\sigma}^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} + (\boldsymbol{\pi} \cdot \boldsymbol{\pi})(\boldsymbol{\pi} \cdot \boldsymbol{\pi})] + (\text{const}) \\
&= -\frac{\lambda}{6}\langle\sigma\rangle^3\tilde{\sigma} - \frac{\lambda}{4}\langle\sigma\rangle^2\tilde{\sigma}^2 - \frac{\lambda}{12}\langle\sigma\rangle^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad - \frac{\lambda}{6}\langle\sigma\rangle\tilde{\sigma}^3 - \frac{\lambda}{24}\tilde{\sigma}^4 - \frac{\lambda}{6}\langle\sigma\rangle\tilde{\sigma}\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad - \frac{\lambda}{12}\tilde{\sigma}^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} - \frac{\lambda}{24}(\boldsymbol{\pi} \cdot \boldsymbol{\pi})(\boldsymbol{\pi} \cdot \boldsymbol{\pi}) + (\text{const})
\end{aligned}$$

全て加えると

$$\begin{aligned}
\mathcal{L} &= \frac{1}{2}\partial_\mu\tilde{\sigma}\partial^\mu\tilde{\sigma} + \frac{1}{2}\partial_\mu\boldsymbol{\pi} \cdot \partial^\mu\boldsymbol{\pi} - \frac{\mu^2}{2}\tilde{\sigma}^2 - \frac{\mu^2}{2}\boldsymbol{\pi} \cdot \boldsymbol{\pi} - \mu^2\langle\sigma\rangle\tilde{\sigma} \\
&\quad - \frac{\lambda}{6}\langle\sigma\rangle^3\tilde{\sigma} - \frac{\lambda}{4}\langle\sigma\rangle^2\tilde{\sigma}^2 - \frac{\lambda}{12}\langle\sigma\rangle^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad - \frac{\lambda}{6}\langle\sigma\rangle\tilde{\sigma}^3 - \frac{\lambda}{24}\tilde{\sigma}^4 - \frac{\lambda}{6}\langle\sigma\rangle\tilde{\sigma}\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad - \frac{\lambda}{12}\tilde{\sigma}^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} - \frac{\lambda}{24}(\boldsymbol{\pi} \cdot \boldsymbol{\pi})(\boldsymbol{\pi} \cdot \boldsymbol{\pi}) + (\text{const}) \\
&= \frac{1}{2}\partial_\mu\tilde{\sigma}\partial^\mu\tilde{\sigma} + \frac{1}{2}\partial_\mu\boldsymbol{\pi} \cdot \partial^\mu\boldsymbol{\pi} - \left(\frac{\mu^2}{2} + \frac{\lambda}{4}\langle\sigma\rangle^2\right)\tilde{\sigma}^2 \\
&\quad - \left(\mu^2 + \frac{\lambda}{6}\langle\sigma\rangle^2\right)\boldsymbol{\pi} \cdot \boldsymbol{\pi} - \left(\mu^2 + \frac{\lambda}{6}\langle\sigma\rangle^2\right)\langle\sigma\rangle\tilde{\sigma} \\
&\quad - \frac{\lambda}{6}\langle\sigma\rangle\tilde{\sigma}^3 - \frac{\lambda}{24}\tilde{\sigma}^4 - \frac{\lambda}{6}\langle\sigma\rangle\tilde{\sigma}\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad - \frac{\lambda}{12}\tilde{\sigma}^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} - \frac{\lambda}{24}(\boldsymbol{\pi} \cdot \boldsymbol{\pi})(\boldsymbol{\pi} \cdot \boldsymbol{\pi}) + (\text{const})
\end{aligned}$$

ここで $\langle\sigma\rangle = \sqrt{-6\mu^2/\lambda}$ を代入すると

$$\begin{aligned}
\mathcal{L} &= \frac{1}{2}\partial_\mu\tilde{\sigma}\partial^\mu\tilde{\sigma} + \frac{1}{2}\partial_\mu\boldsymbol{\pi} \cdot \partial^\mu\boldsymbol{\pi} - \left(\frac{\mu^2}{2} - \frac{3\mu^2}{2}\right)\tilde{\sigma}^2 \\
&\quad - \frac{\lambda}{6}\sqrt{-\frac{6\mu^2}{\lambda}}\tilde{\sigma}^3 - \frac{\lambda}{24}\tilde{\sigma}^4 - \frac{\lambda}{6}\sqrt{-\frac{6\mu^2}{\lambda}}\tilde{\sigma}\boldsymbol{\pi} \cdot \boldsymbol{\pi} \\
&\quad - \frac{\lambda}{12}\tilde{\sigma}^2\boldsymbol{\pi} \cdot \boldsymbol{\pi} - \frac{\lambda}{24}(\boldsymbol{\pi} \cdot \boldsymbol{\pi})(\boldsymbol{\pi} \cdot \boldsymbol{\pi}) + (\text{const}) \\
&= \frac{1}{2}\partial_\mu\tilde{\sigma}\partial^\mu\tilde{\sigma} + \frac{1}{2}\partial_\mu\boldsymbol{\pi} \cdot \partial^\mu\boldsymbol{\pi} + \mu^2\tilde{\sigma}^2 \\
&\quad - \sqrt{-\frac{\lambda\mu^2}{6}}\tilde{\sigma}^3 - \frac{\lambda}{24}\tilde{\sigma}^4 - \sqrt{-\frac{\lambda\mu^2}{6}}\tilde{\sigma}\boldsymbol{\pi} \cdot \boldsymbol{\pi}
\end{aligned}$$

$$-\frac{\lambda}{12}\tilde{\sigma}^2\boldsymbol{\pi}\cdot\boldsymbol{\pi}-\frac{\lambda}{24}(\boldsymbol{\pi}\cdot\boldsymbol{\pi})(\boldsymbol{\pi}\cdot\boldsymbol{\pi})+(\text{const})$$

注) 場の一次の項はキャンセルして消えるので、スライドの「場の一次は落とす」は間違い。一方で、ラグランジアンの変数項は物理に影響がないので落とす。

page 35 : カイラルラグランジアンの運動項

$$\begin{aligned}\mathcal{L} &= a\text{Tr}(\partial_\mu U^\dagger\partial^\mu U) \\ &= a\text{Tr}[\partial_\mu(1-i\sqrt{2}\pi/f+\dots)\partial^\mu(1+i\sqrt{2}\pi/f+\dots)] \\ &= a\frac{2}{f^2}\text{Tr}[\partial_\mu\pi\partial^\mu\pi] \\ &= a\frac{2}{f^2}\text{Tr}[\partial_\mu\pi_a\sqrt{2}t_a\partial^\mu\pi_b\sqrt{2}t_b] \\ &= a\frac{4}{f^2}\partial_\mu\pi_a\partial^\mu\pi_b\text{Tr}[t_at_b] \\ &= a\frac{4}{f^2}\partial_\mu\pi_a\partial^\mu\pi_b\frac{\delta_{ab}}{2} \\ &= a\frac{2}{f^2}\partial_\mu\boldsymbol{\pi}\cdot\partial^\mu\boldsymbol{\pi}\end{aligned}$$

この係数が 1/2 になるためには

$$\begin{aligned}a\frac{2}{f^2} &= \frac{1}{2} \\ a &= \frac{f^2}{4}\end{aligned}$$