

#### Replica Symmetry Breaking in trajectories of a driven Brownian particle Shin-ichi Sasa and Masahiko Ueda 2015/08/13@Kyoto

JSPS Core-to-Core program 2013-2015 Non-equilibrium dynamics of soft matter and information



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## **PART** I Motivation

## Common-noise induced synchronization

Teramae-Tanaka, PRL, 2004



http://www-waka.ics.es.osakau.ac.jp/~teramae/nis.html

#### What is this ?

Attraction of two independent trajectories by the common noise

Consider a limit-cycle oscillator + noise

and its Replica (with a slightly different initial condition)

#### **Dynamical system theory:**

Nagative Lyapunov exponent (separation ratio of nearby trajectories)

#### **Statistical mechanics of trajectories:**

common noise = quenched disorder

One stable (dominant) trajectory (=configuration in time)

No-independent noise ⇔ T=0

#### Finite temperature T >0

T >0 ⇔ Adding independent noises

- no synchronization
- power-law behavior in T  $\rightarrow$  0

(Teramae-Tanaka, PRL, 2004: Nakao, Arai,Kawamura,PRL, 2007)

## We ask a possibility of the two extensions

common noise = quenched disorder

**T=0** 

one dominant (irregular) trajectory (=configuration in time)

Several dominant (irregular) trajectories (=configuration in time) Clustering in the trajectory space!

h

T>0 fragile of "T=0" behavior against adding independent noises Robust of "T=0" behavior against adding independent noises



#### **R**eplica **S**ymmetry **B**reaking in trajectories



## Is it possible ?

#### In this talk,

#### We study a simple model : a Brownian particle driven by a KPZ field

We provide evidence of RSB in trajectories of the single particle

See Ueda-Sasa, arXiv:1411.1816 to appear in Phys. Rev. Lett. soon

# **PART II**MODEL and OBSERVATION

#### Particle driven by a KPZ field

$$\frac{\partial \phi}{\partial t} = \nu \frac{\partial^2 \phi}{\partial x^2} + \frac{1}{2} \left( \frac{\partial \phi}{\partial x} \right)^2 + v(x,t)$$

 $\langle v(x,t)v(x',t')\rangle = 2B\delta(x-x')\delta(t-t')$ 



$$u(x,t) = -\frac{\partial \phi}{\partial x}(x,t)$$

$$\dot{x}(t) = u(x(t), t)$$

Ref: Chin, Phys. Rev. E, 2002

## Ten independent particles driven by the KPZ field



Ref: Chin, Phys. Rev. E, 2002

arkappa

#### Mechanism





13

X

#### Adding independent noises

$$\frac{\partial \phi}{\partial t} = \nu \frac{\partial^2 \phi}{\partial x^2} + \frac{1}{2} \left( \frac{\partial \phi}{\partial x} \right)^2 + v(x,t)$$

$$\langle v(x,t)v(x',t')\rangle = 2B\delta(x-x')\delta(t-t')$$

$$u(x,t) = -\frac{\partial \phi}{\partial x}(x,t)$$
$$\dot{x}(t) = u(x(t),t) + \underline{\xi}(t)$$
$$\underline{\xi}(t)\xi(t') = 2D\delta(t-t')$$

 $D = \nu$ 

Ref: Drossel and Karder, Phys. Rev. B, 2002

### Ten trajectories from the same initial position



t

#### Single particle diffusion

#### Displacement $\sigma \equiv |x(t) - x(0)|$



#### Super-diffusion

Gaussian

Ref: Drossel and Karder, Phys. Rev. B, 2002

#### **Relative diffusion**

#### Relative distance $d \equiv |x^{(1)} - x^{(2)}|$



normal-diffusion

Non-Gaussian

#### How to detect RSB



overlap  

$$q \equiv \frac{1}{M} \sum_{j=1}^{M} \theta \left( \ell - \left| x^{(1)} (j\Delta t) - x^{(2)} (j\Delta t) \right| \right)$$

$$\ell = 5 \qquad \text{Localization length}$$

Mean field spin glass model (e.g. 3-SK model)

$$P(q) \equiv \mathbb{E}\left[\frac{1}{Z^2} \sum_{\sigma,\sigma'} e^{-\beta H(\sigma) - \beta H(\sigma')} \delta\left(q - q_{\sigma,\sigma'}\right)\right]$$

$$q_{\sigma,\sigma'} \equiv \frac{1}{N} \sum_{i=1}^{N} \sigma_i \sigma'_i$$



P(q) for trajectories  $q \equiv \frac{1}{M} \sum_{j=1}^{M} \theta \left( \ell - \left| x^{(1)}(j\Delta t) - x^{(2)}(j\Delta t) \right| \right)$ 



Clear two peaks!

1-RSB ?



#### This may be a numerical artifact....

### This may come from a finite size effect.....

## PART III

### Theoretical analysis

### Statistical mechanics of trajectories

Probability measure of trajectory  $\, x \,$ 

 $\mathcal{P}[x|x(0) = x_0, \phi] = \frac{1}{Z_0} e^{-\frac{1}{4D} \int_0^\tau dt \left[ \dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t) \right]^2 + \frac{1}{2} \int_0^\tau dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}$ 

A(x) Quantity depending on trajectory

$$\begin{split} \langle A \rangle_{\phi} &\equiv \int \mathcal{D}x \mathcal{P}(x | x_0, \phi) A(x) \\ \text{average over trajectories} \\ \langle A \rangle &= \int \mathcal{D}\phi \mathcal{P}(\phi) \langle A \rangle_{\phi} \\ \text{average over the velocity field} \end{split}$$

#### Trick –I

$$\mathcal{P}[x|x(0) = x_0, \phi] = \frac{1}{Z_0} e^{-\frac{1}{4D} \int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} + \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \left[\dot{x}(t) + \frac{\partial \phi}{\partial x}(x(t), t)\right]^2} - \frac{1}{2} \int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}{\int_0^{\tau} dt \frac{\partial^2 \phi}{\partial x^2}(x(t), t)}$$

#### Trick-II

$$\mathcal{P}\left[x|x(\tau) = x_{0},\phi\right] = \frac{1}{Z_{0}}e^{-\frac{1}{4D}\int_{0}^{\tau}dt\left[\dot{x}(t)^{2}+2\frac{d}{dt}\phi(x(t),t)-2\frac{\partial\phi}{\partial t}(x(t),t)\right]} \\ \times e^{-\frac{1}{4D}\int_{0}^{\tau}dt\left\{\left[\frac{\partial\phi}{\partial x}(x(t),t)\right]^{2}+2D\frac{\partial^{2}\phi}{\partial x^{2}}(x(t),t)\right\}} \\ = \frac{1}{Z_{0}}e^{-\frac{1}{2D}[\phi(x(\tau),\tau)-\phi(x(0),0)]-\frac{1}{4D}\int_{0}^{\tau}dt\left[\dot{x}(t)^{2}-2v(x(t),t)\right]} \\ = \frac{1}{Z_{0}}e^{-\frac{1}{2D}[\phi(x_{0},\tau)-\text{const.}]-\frac{1}{4D}\int_{0}^{\tau}dt\left[\dot{x}(t)^{2}-2v(x(t),t)\right]}$$

#### Trick-II

$$\mathcal{P}\left[x|x(\tau) = x_{0},\phi\right] = \frac{1}{Z_{0}}e^{-\frac{1}{4D}\int_{0}^{\tau} dt \left[\dot{x}(t)^{2} + 2\frac{d}{dt}\phi(x(t),t) - 2\frac{\partial\phi}{\partial t}(x(t),t)\right]} \\ \times e^{-\frac{1}{4D}\int_{0}^{\tau} dt \left\{ \left[\frac{\partial\phi}{\partial x}(x(t),t)\right]^{2} + 2D\frac{\partial^{2}\phi}{\partial x^{2}}(x(t),t) \right\}} \\ = \frac{1}{Z_{0}}e^{-\frac{1}{2D}[\phi(x(\tau),\tau) - \phi(x(0),0)] - \frac{1}{4D}\int_{0}^{\tau} dt \left[\dot{x}(t)^{2} - 2v(x(t),t)\right]} \\ = \frac{1}{Z_{0}}e^{-\frac{1}{2D}[\phi(x_{0},\tau) - \text{const.}] - \frac{1}{4D}\int_{0}^{\tau} dt \left[\dot{x}(t)^{2} - 2v(x(t),t)\right]}$$

### Equilibrium Statistical Mechanics of Directed Polymer in RP!

#### A Study on DP in RP

**G.** Parisi, J. Phys. France 51 1595-1606 (1990) On the replica approach to random directed polymers in two dimensions

$$\begin{split} \psi(\epsilon) &\equiv \lim_{\tau \to \infty} \tau^{-1} \log \left\langle e^{\tau \epsilon q} \right\rangle \\ \left\langle q \right\rangle_{\epsilon} &\equiv \frac{\partial}{\partial \epsilon} \psi(\epsilon) \end{split} \quad \text{Expected value in } \end{split}$$

c-generating function of overlap

Expected value in the biased ensemble



#### Numerical Study on DP in RP

M. Mezard, J. Phys. France 51 1831-1846 (1990) On the glassy nature of random directed polymers in two dimensions

It supported Parisi's result, but for the discretized model

We carefully studied



### Tentative conclusion - conjecture -

Equilibrium ensemble of directed polymer

is equivalent to

the path ensemble of a Brownian particle by the KPZ

The independence of the boundary condition (in the time axis)

Equilibrium ensemble of directed polymer exhibits 1-RSB, while its discretized version exhibits weakly RSB

## PART IV Concluding Remarks

#### Summary of my talk

We have studied a simple model : a Brownian particle driven by a KPZ field

We have provided evidence of RSB in trajectories of the single particle

See Ueda-Sasa, arXiv:1411.1816 to appear in Phys. Rev. Lett. soon Next obvious questions

## Other examples?

### **Experiments?**

#### Diffusion

#### in active environments



Cell 158 822-832 (2014) Probing the Stochastic, Motor-Driven Properties of the Cytoplasm Using Force Spectrum Microscopy, M Guo et al

### Statistical mechanics of trajectories

#### **Dynamical free energy**

= cumulant generating function for a quantity X

X : activity, current, Lyapunov exponent, or overlap

**Non-analytic (singular) behavior of the dynamical free energy** = one class of non-equilibrium phase transitions

Classification? The concept of **universality class** ?



#### The concept of RSB:

born in spin glass problems

Application to molecular glasses, jamming..

Application to information science

Application to time-series analysis of fluctuation!