

When does a system affect another? Causal influence vs signalling

Extreme Universe - Colloquium

Yukawa Institute for Theoretical Physics, Kyoto University

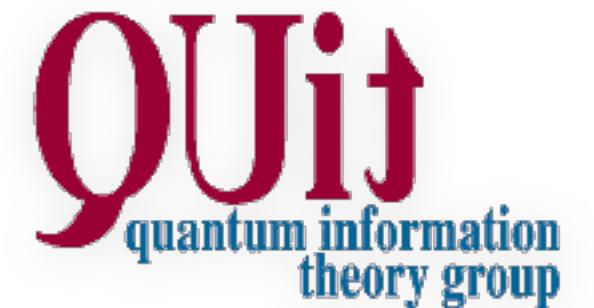
Paolo Perinotti - July 14th 2022



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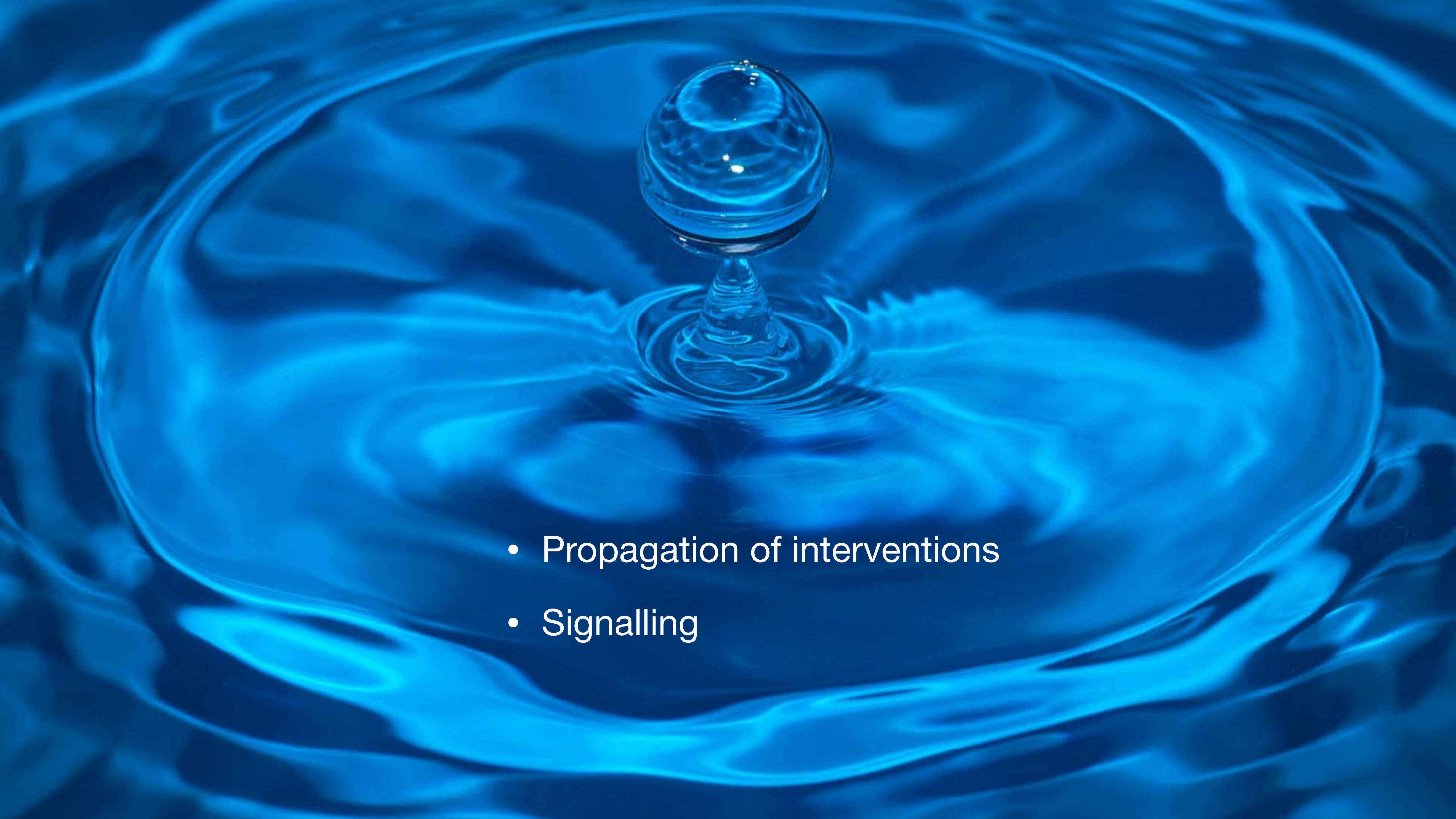
Summary

- OPTs
- Networks and causal cones
- Signalling
- Propagation of interventions
- Classical and Quantum theory
- No interaction without disturbance





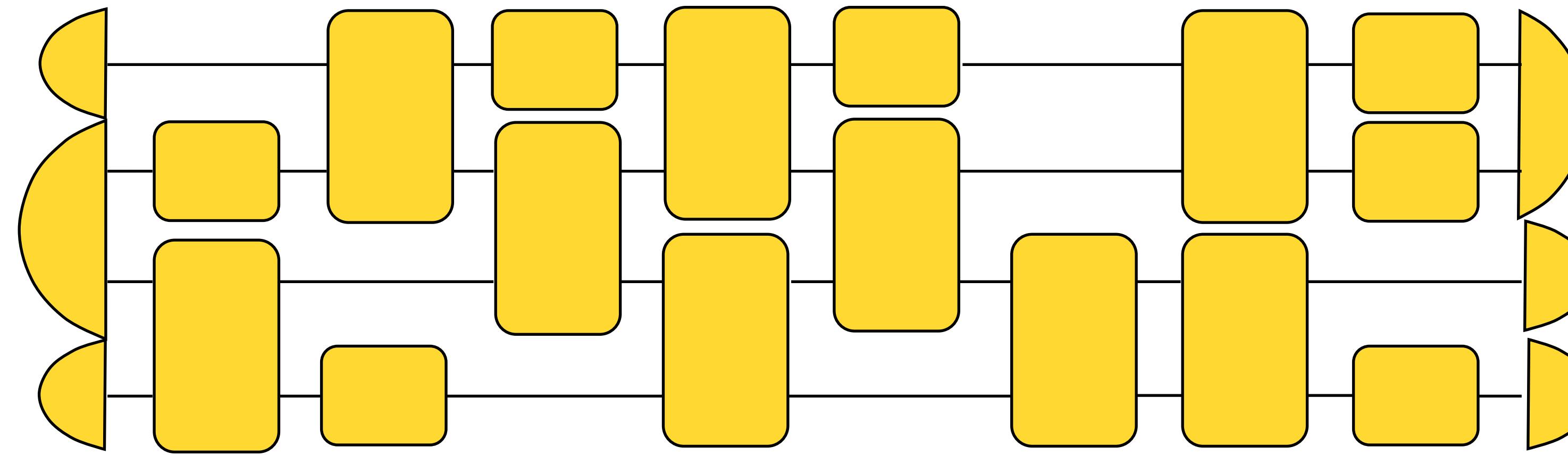
- Propagation of interventions

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- Propagation of interventions
 - Signalling

Chapter I: Prologue

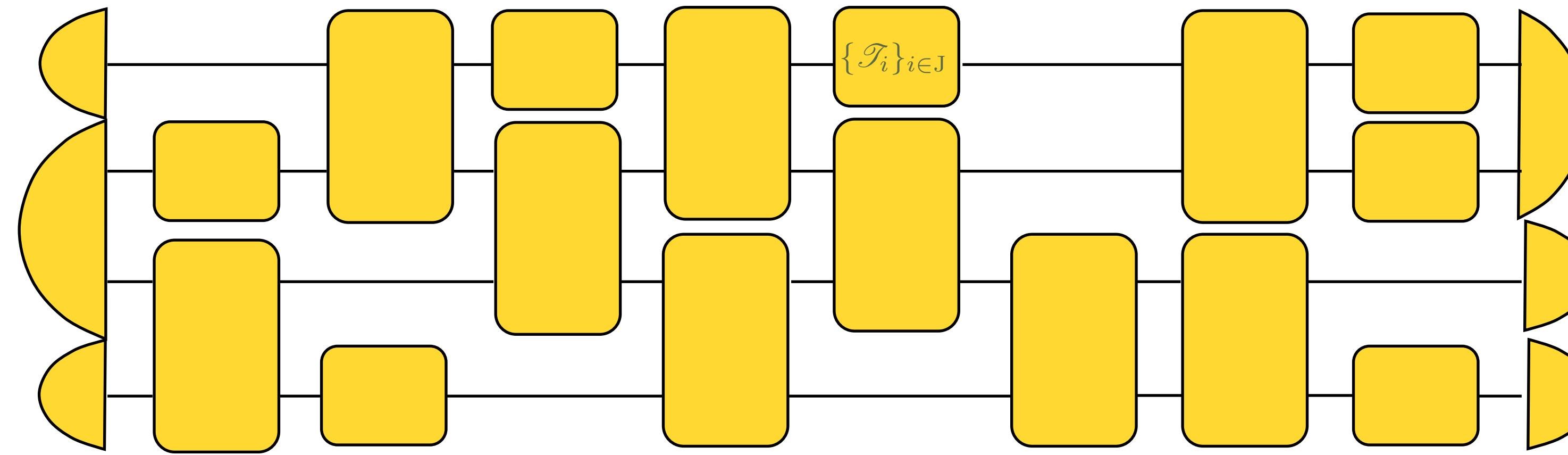
The framework: Operational Probabilistic Theories

Operational Language



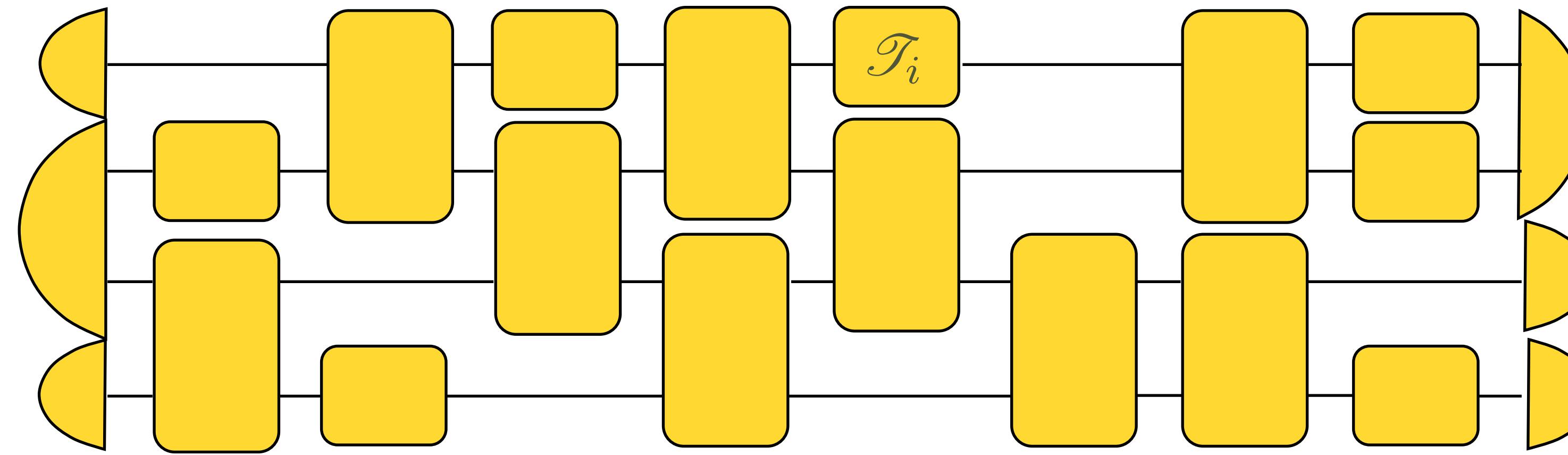
- Operational theory: tests with composition rules

Operational Language



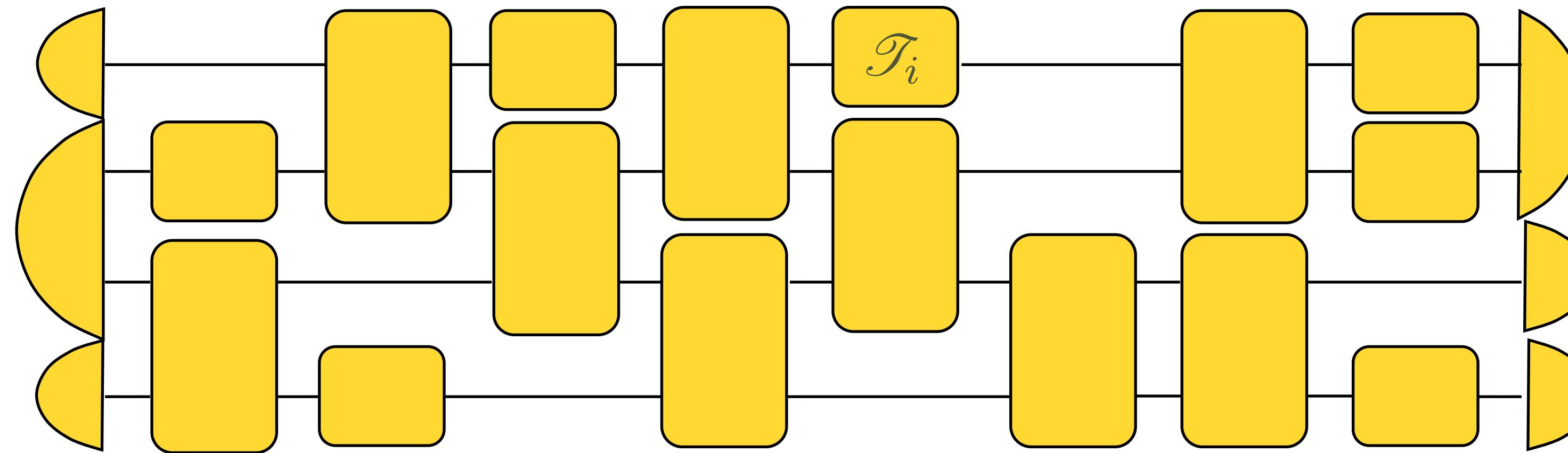
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Operational Language



- Operational theory: tests with composition rules

Operational Language

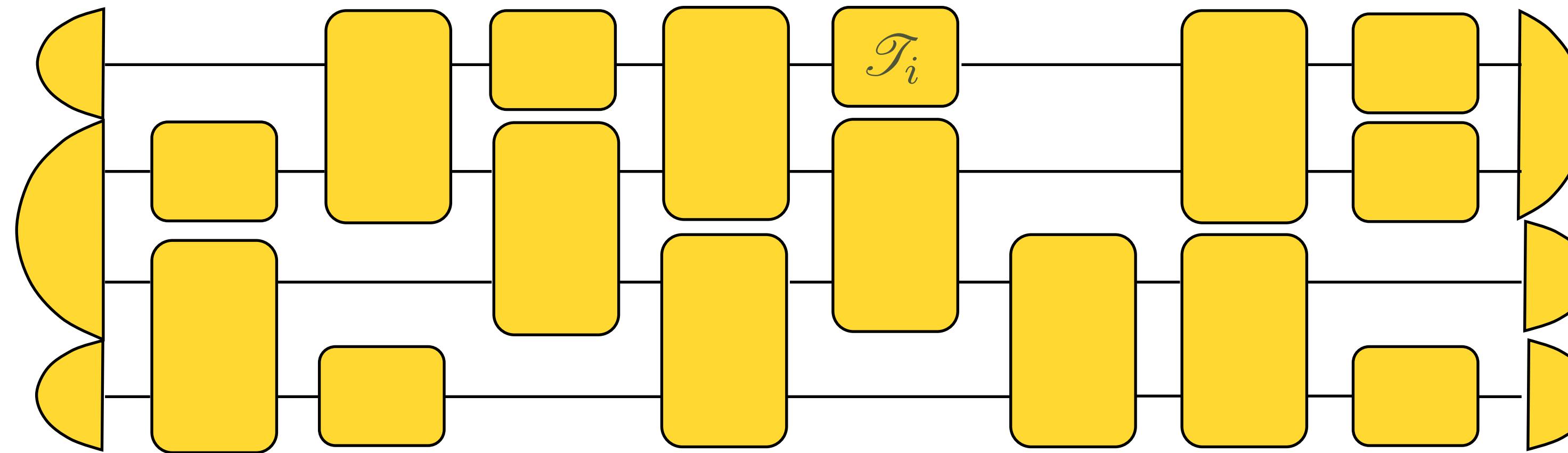


- Operational theory: tests with composition rules

Sequential

$$A - \boxed{B} - C = A - \boxed{C}$$

Operational Language



- Operational theory: tests with composition rules



Operational Language

- Properties of composition rules:

- Associativity

- Unit

$$\begin{array}{c} A \\ \text{---} \end{array} \boxed{B} \begin{array}{c} \mathcal{J}_B \\ \text{---} \end{array} \boxed{B} = \begin{array}{c} A \\ \text{---} \end{array} \boxed{\mathcal{J}_A} \begin{array}{c} A \\ \text{---} \end{array} \boxed{B} = \begin{array}{c} A \\ \text{---} \end{array} \boxed{B}$$

$$\frac{A}{I} = \frac{I}{A} = \underline{A}$$

- $\begin{array}{c} A \\ \text{---} \end{array} \boxed{\mathcal{J}_A} \begin{array}{c} A \\ \text{---} \end{array} = \underline{A}$
- $I \boxed{B} \begin{array}{c} B \\ \text{---} \end{array} = \boxed{B}$
- $A \boxed{I} \begin{array}{c} I \\ \text{---} \end{array} = \boxed{A}$

Reversible events and swap

Reversible event:

$$\begin{array}{c} A \xrightarrow{\mathcal{U}} B \xleftarrow{\mathcal{U}^{-1}} A = \\ \hline \end{array} \quad \begin{array}{c} B \xrightarrow{\mathcal{U}^{-1}} A \xleftarrow{\mathcal{U}} B = \\ \hline \end{array}$$

Reversible events and swap

Reversible event:

$$A \xrightarrow{\mathcal{U}} B \xrightarrow{\mathcal{U}^{-1}} A = A \quad B \xrightarrow{\mathcal{U}^{-1}} A \xrightarrow{\mathcal{U}} B = B$$

Swap (symmetric theories):

$$\begin{array}{c} A \\ \hline B \end{array} \xrightarrow{\mathcal{S}} \begin{array}{c} B \\ \hline A \end{array} = \begin{array}{c} A \\ \hline B \end{array} \xrightarrow{\mathcal{S}^*} \begin{array}{c} B \\ \hline A \end{array} = \begin{array}{c} A & B \\ \diagup & \diagdown \\ B & A \end{array}$$

Reversible events and swap

Reversible event:

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Swap (symmetric theories):

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$$\begin{array}{c} A & B \\ \diagup & \diagdown \\ B & A \end{array} = \begin{array}{c} \text{red box} & \text{blue box} \\ \diagup & \diagdown \\ \text{blue box} & \text{red box} \end{array}$$

Monoidal structure

- Most important rule:

$$(\mathcal{A} \otimes \mathcal{B})(\mathcal{C} \otimes \mathcal{D}) = (\mathcal{A}\mathcal{C}) \otimes (\mathcal{B}\mathcal{D})$$

Monoidal structure

- Most important rule:

$$(\mathcal{A} \otimes \mathcal{B})(\mathcal{C} \otimes \mathcal{D}) = (\mathcal{A}\mathcal{C}) \otimes (\mathcal{B}\mathcal{D})$$

- Consequence:

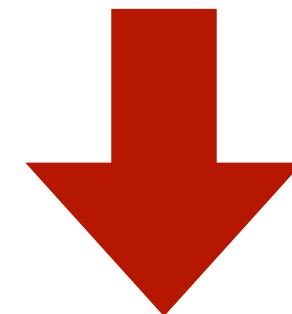
$$\text{Red box} \otimes \text{Yellow box} = \text{Yellow box} \otimes \text{Red box}$$

Probabilistic theories

Every test of type $I \rightarrow I$ is a probability distribution

$$\rho_i \xrightarrow{\hspace{1cm}} a_j = \Pr(a_j, \rho_i)$$

States are functionals on effects and vice-versa



Real vector spaces $\text{St}_{\mathbb{R}}(A), \text{Eff}_{\mathbb{R}}(A)$

Transformations

A transformation $\mathcal{T} \in \text{Transf}(A \rightarrow B)$ induces a **family** of linear maps:

$\{M_C(\mathcal{T})\}_C$ representing $\mathcal{T} \otimes \mathcal{I}_C$ on $\text{St}(AC)_{\mathbb{R}}$

$$\begin{array}{ccc} \Psi_i & \xrightarrow{\quad A \quad} & \mathcal{T} \\ \downarrow & & \downarrow \\ \Phi_j & & \xrightarrow{\quad B \quad} \end{array} = \sum_{j=1}^{D_{BC}} [M_C(\mathcal{T})]_{ij}$$

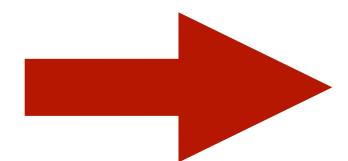
Transformations

Indeed, it is not sufficient to know the linear map induced by \mathcal{T} on $\text{St}(A)_{\mathbb{R}}$

E.g.: transpose map in real quantum theory



$$\rho^T = \rho$$



$$\mathcal{T}(\rho) = \mathcal{I}(\rho) \quad \forall \rho$$

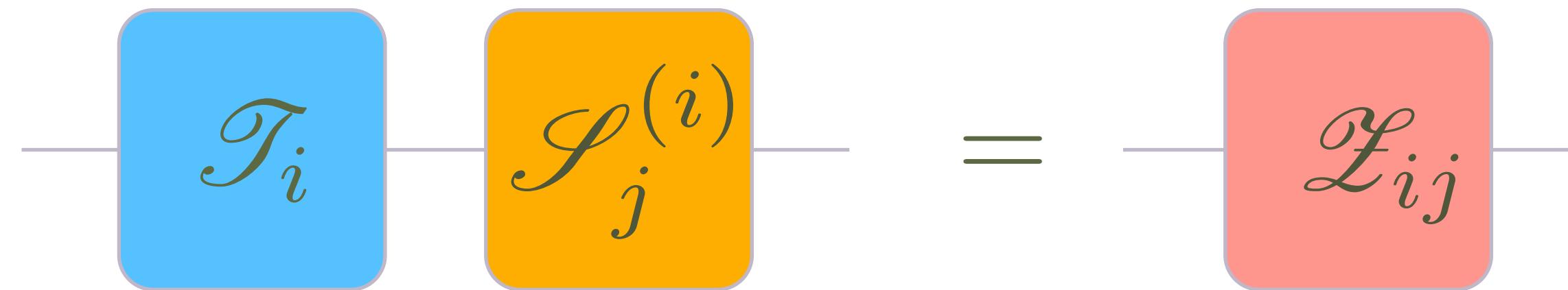


$$\sigma_y \otimes \sigma_y \in \text{St}(AC)_{\mathbb{R}}$$

$$(\mathcal{T} \otimes \mathcal{I}_C)(\sigma_y \otimes \sigma_y) = -\sigma_y \otimes \sigma_y$$

Causal theories

- Possibility of arbitrary conditional tests

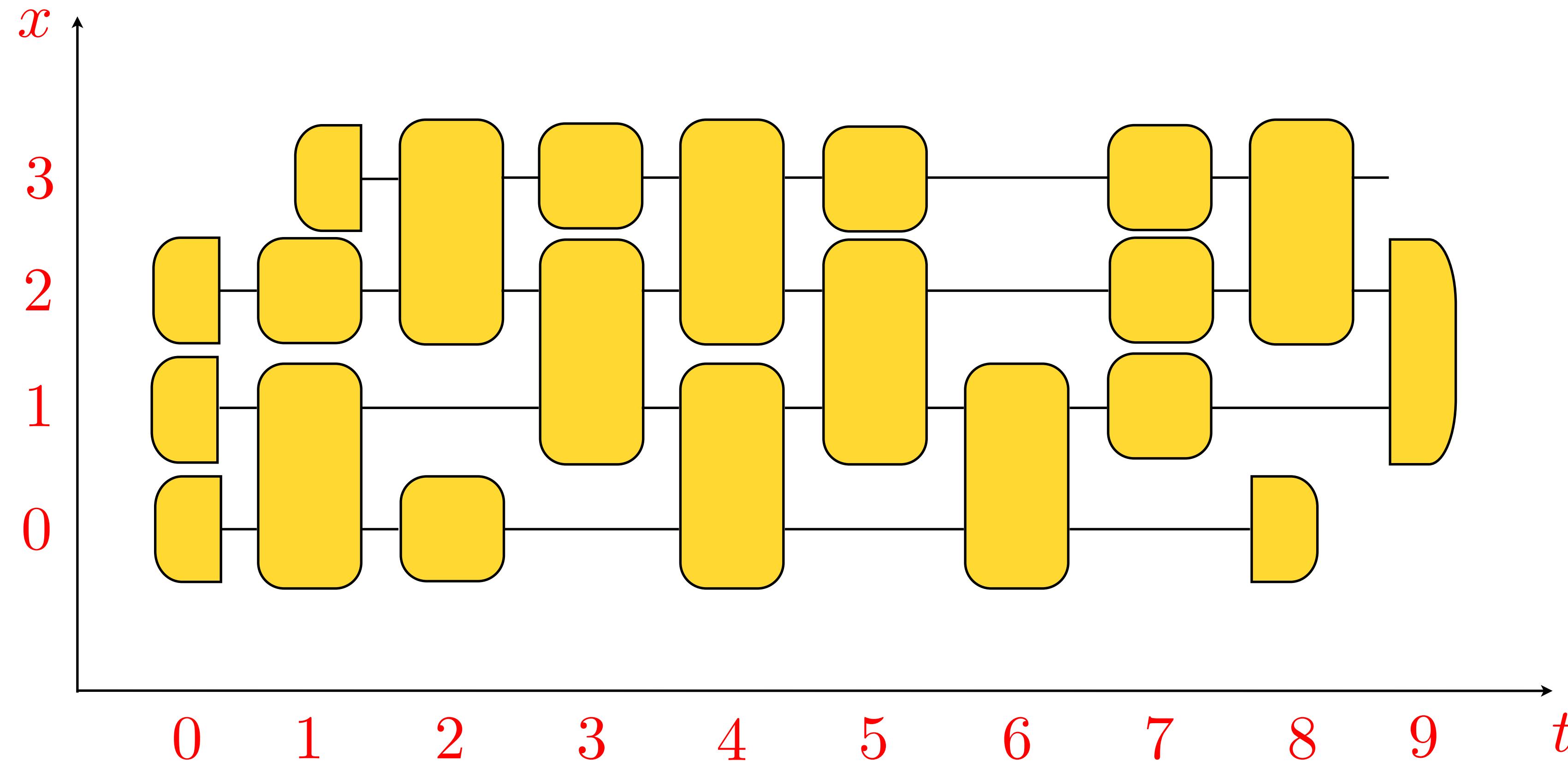


- Causality implies no “backward” signalling

$$p_a(\rho_i) := \sum_j \textcircled{\rho_i} \xrightarrow{A} \textcircled{a_j} = p(\rho_i) \quad \leftrightarrow \quad \sum_j \xrightarrow{A} \textcircled{a_j} = \xrightarrow{A} \textcircled{e}$$

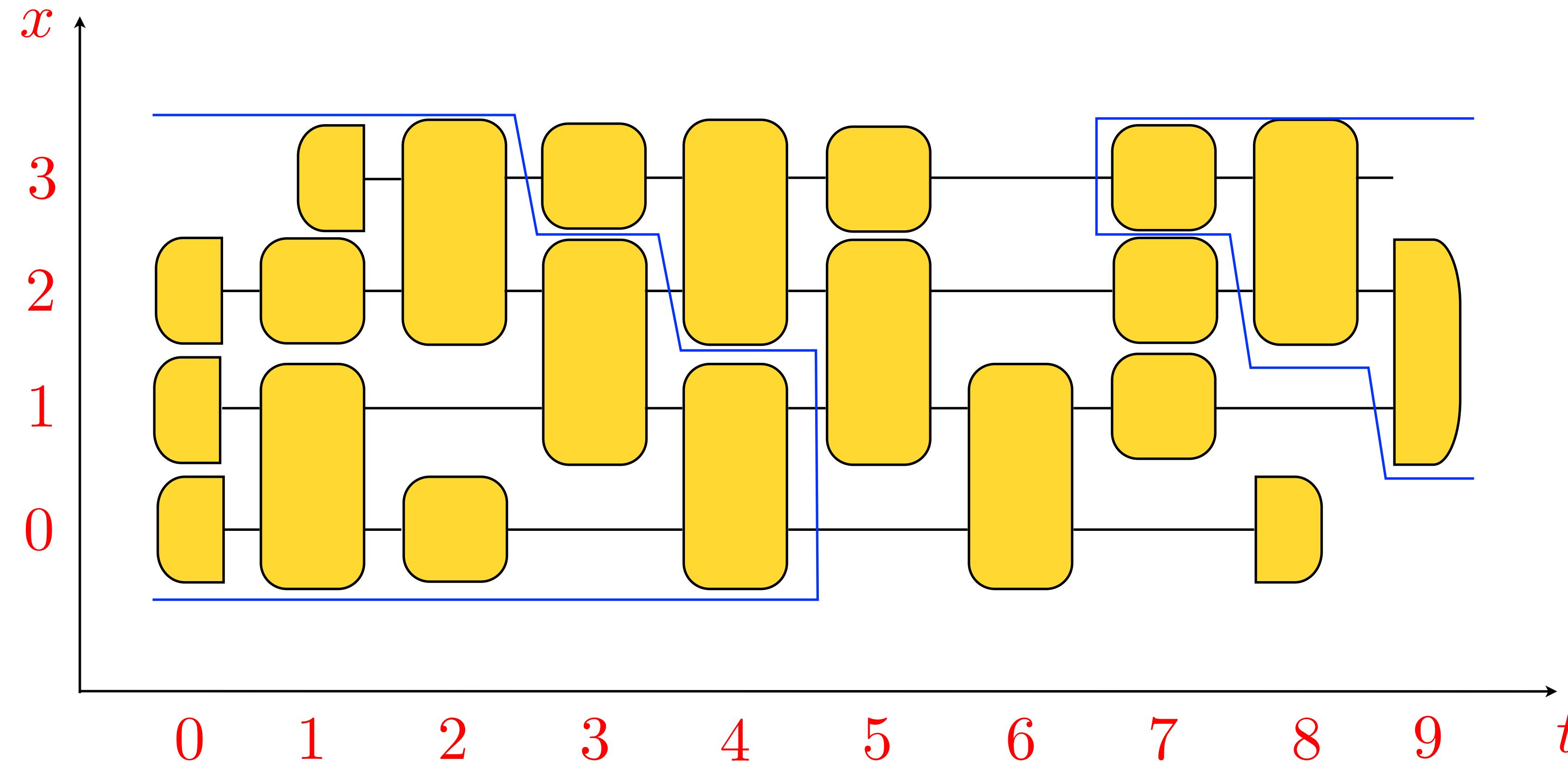
Circuits and causal chains

Logical space-time



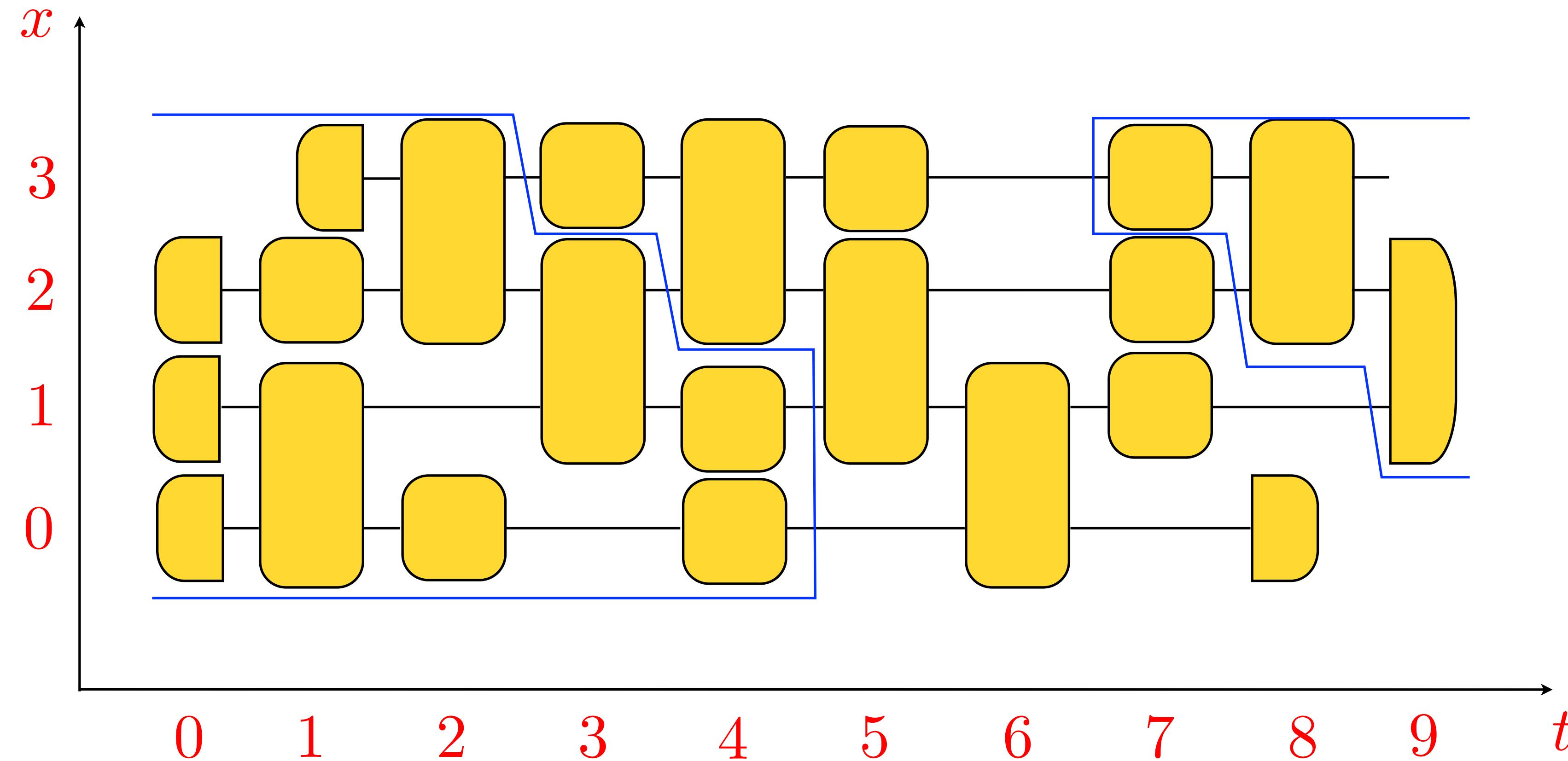
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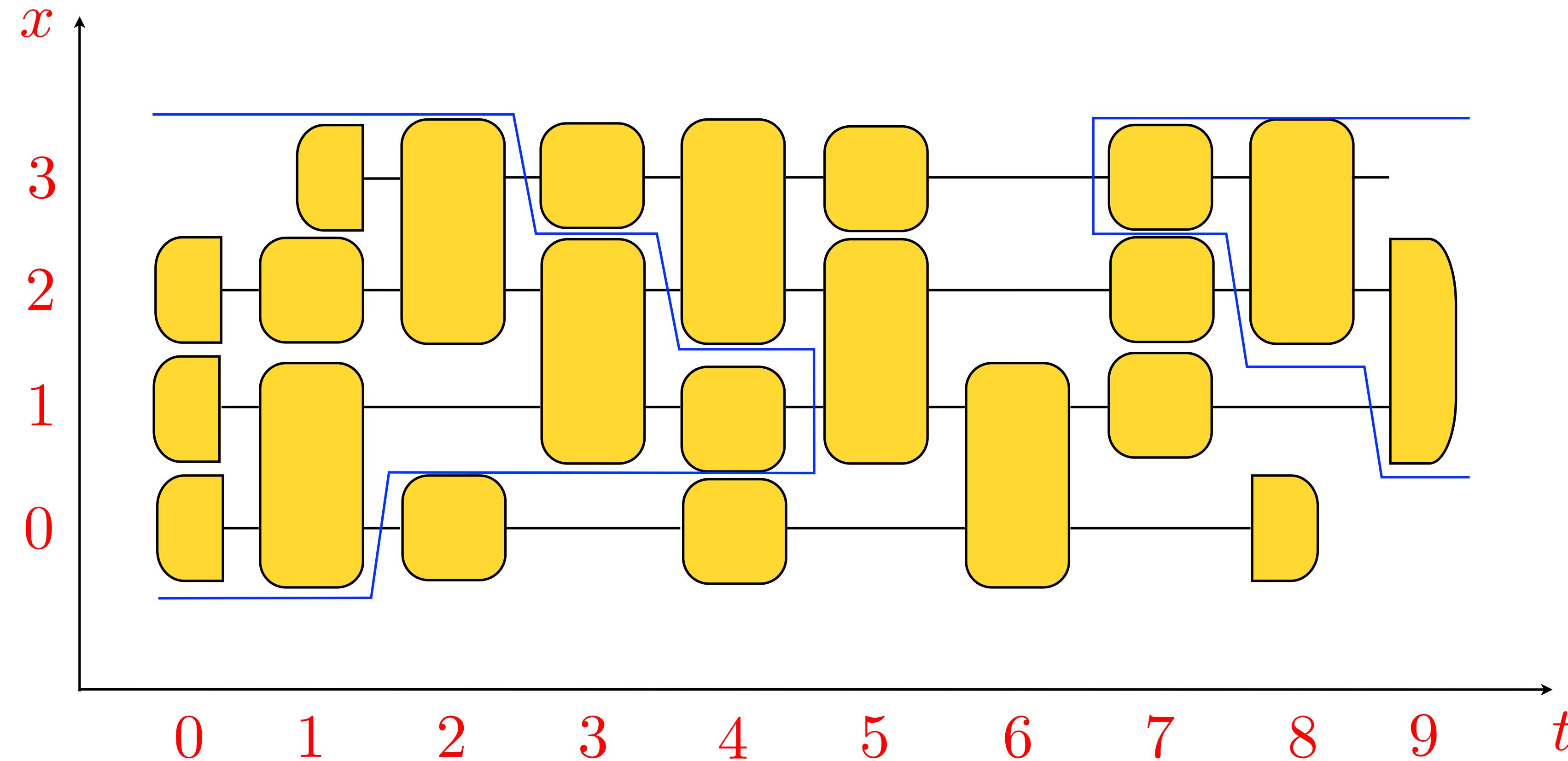
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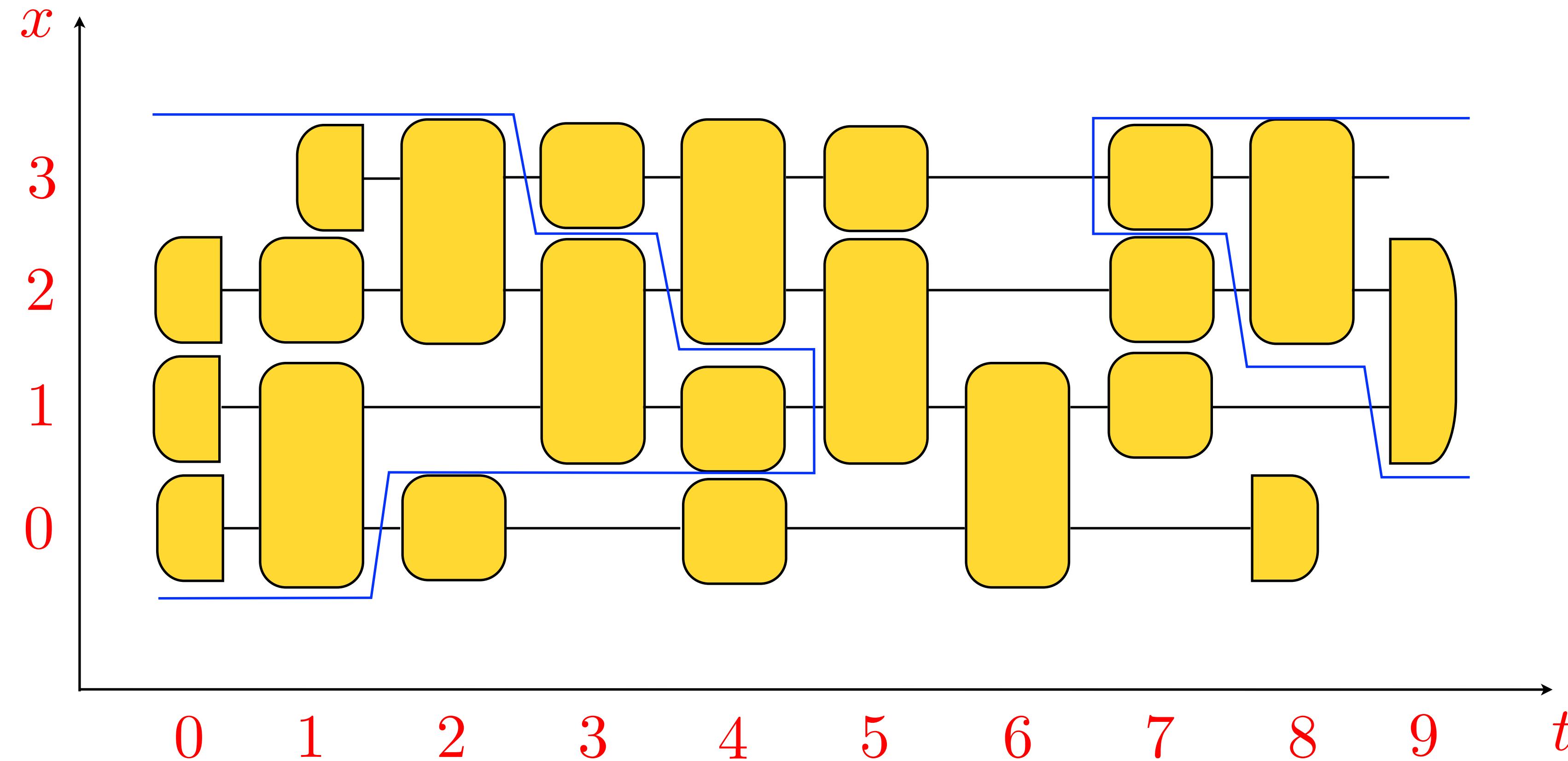
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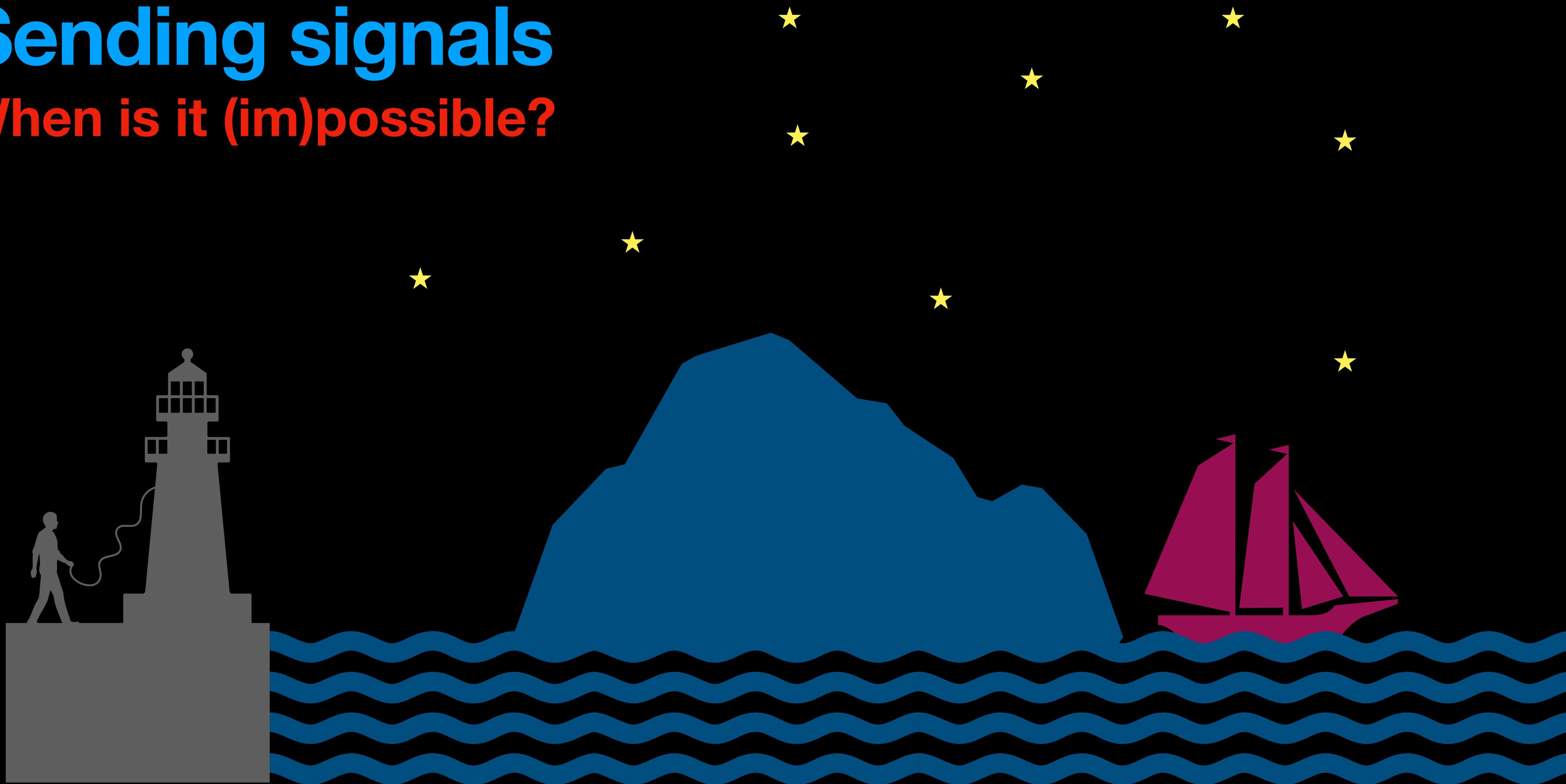
Can we make the causal order relation sharper?

Chapter II: The main characters

Signalling vs causal influence

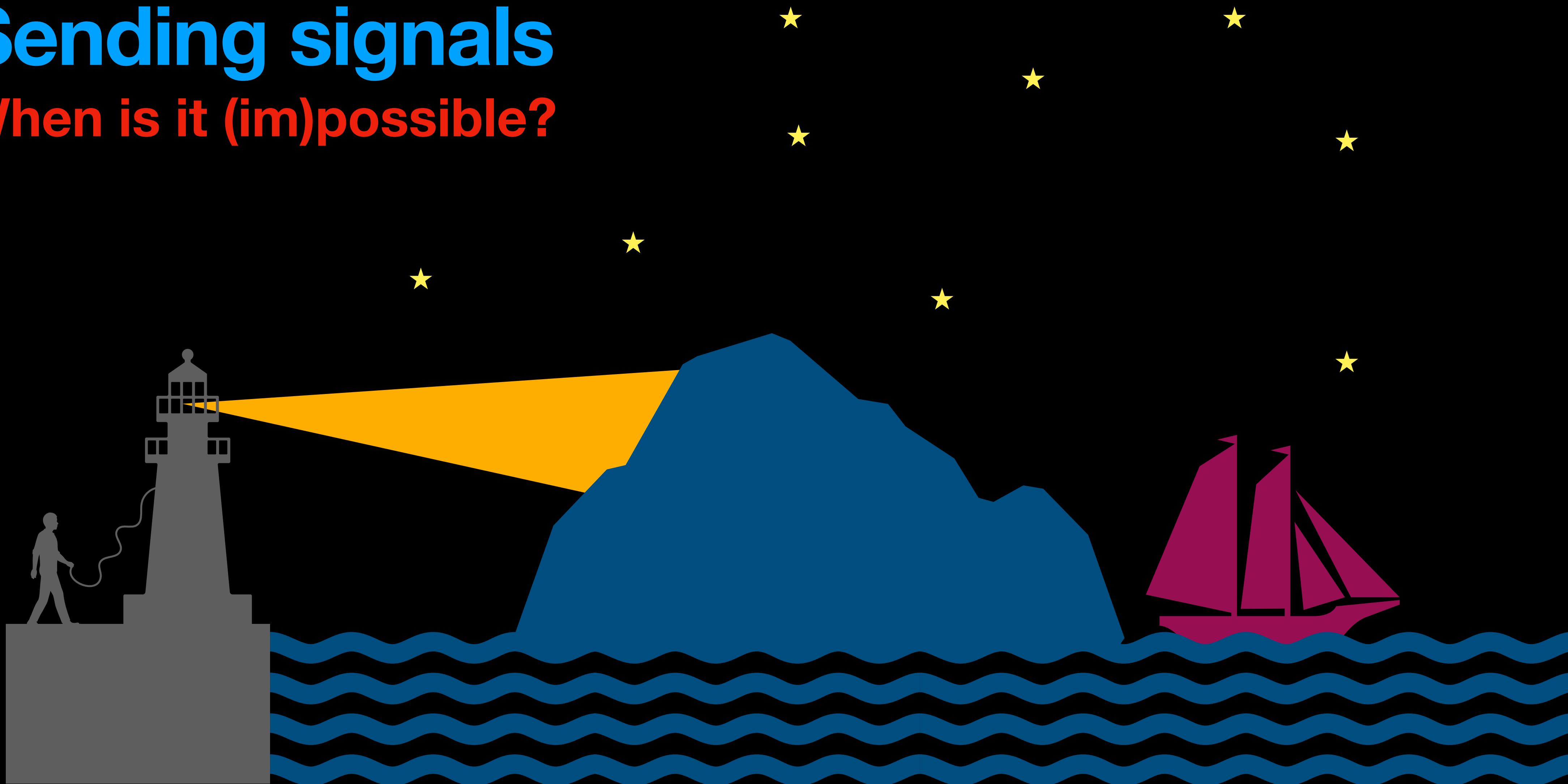
Sending signals

When is it (im)possible?



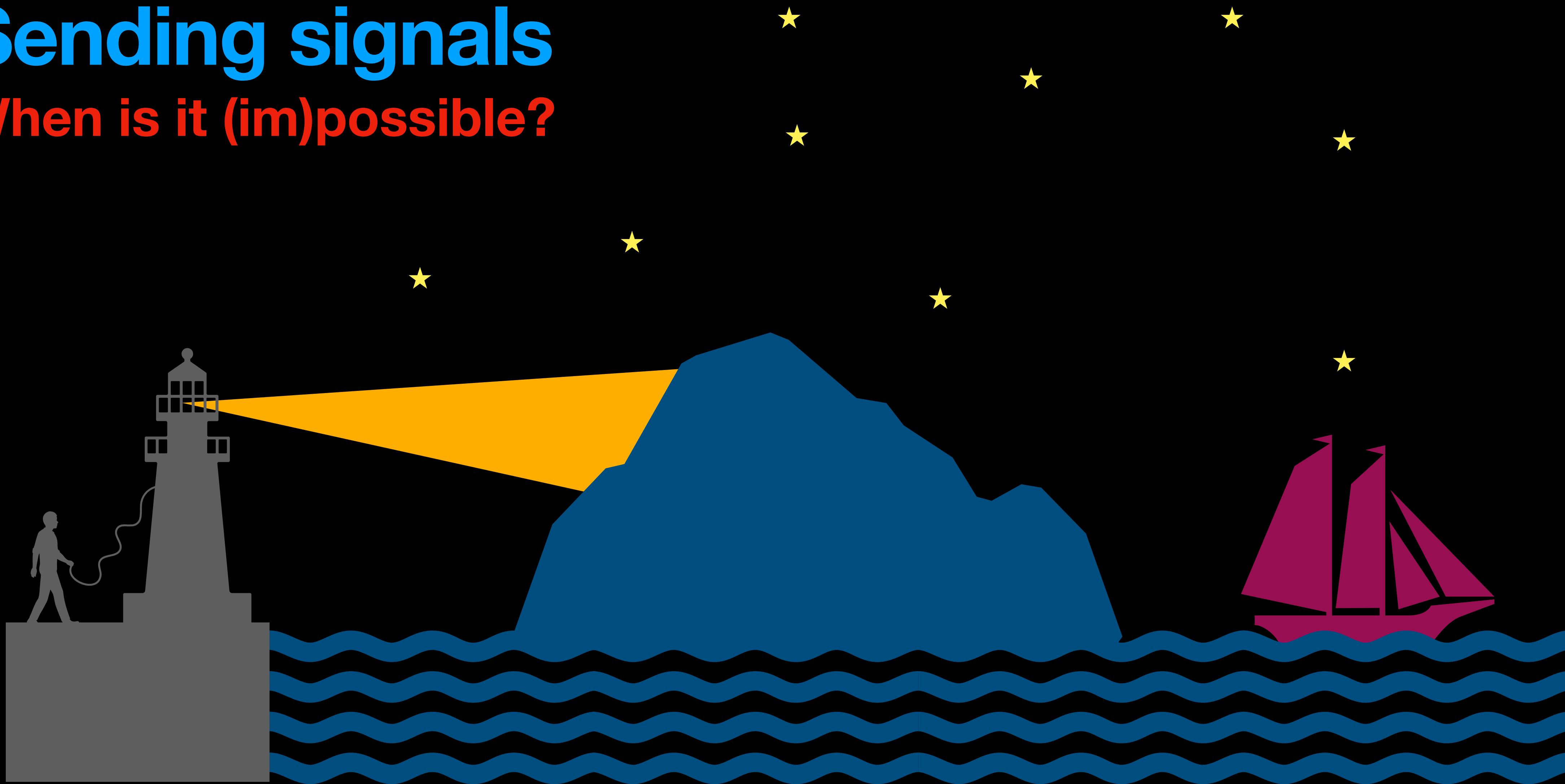
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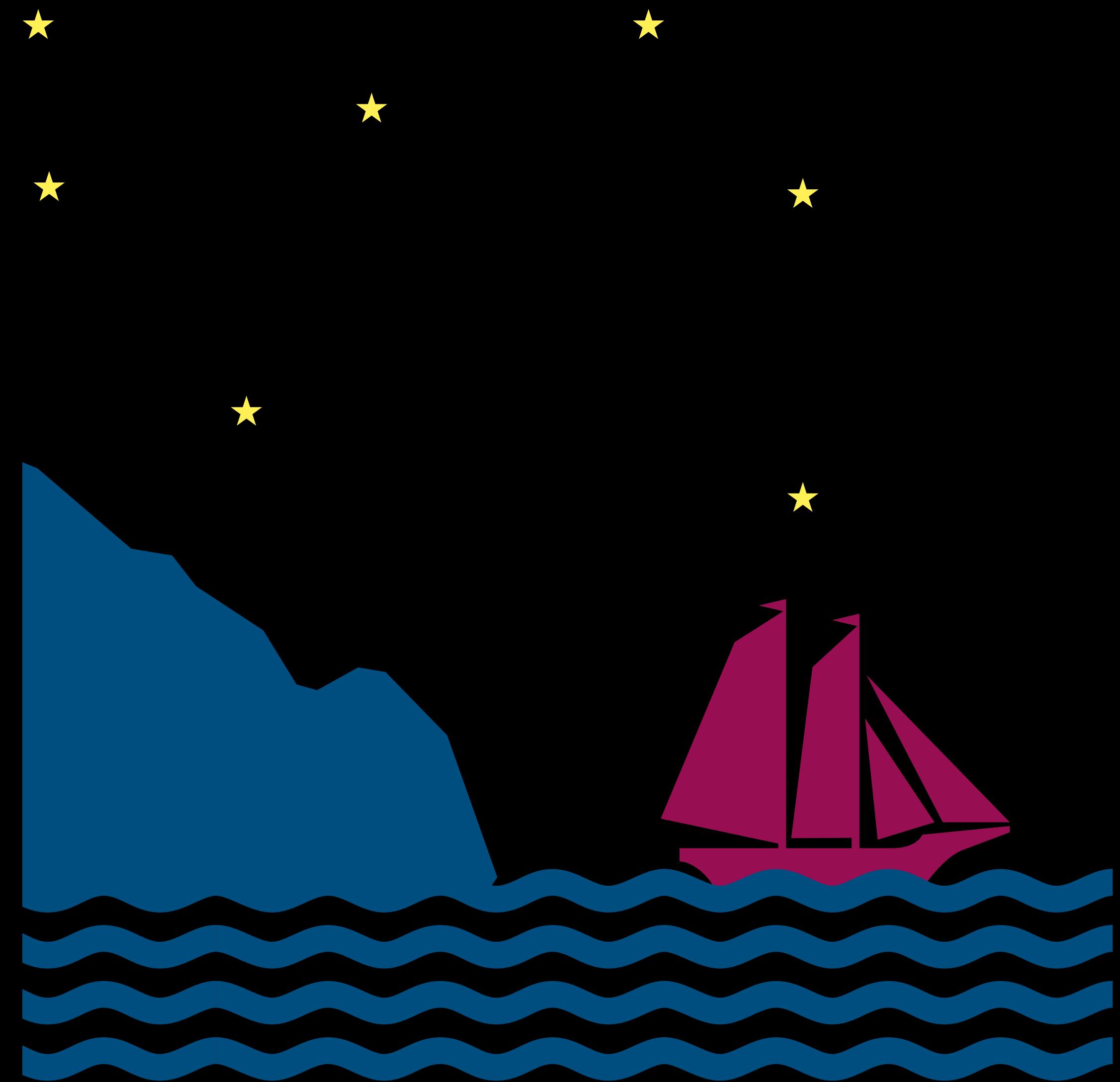
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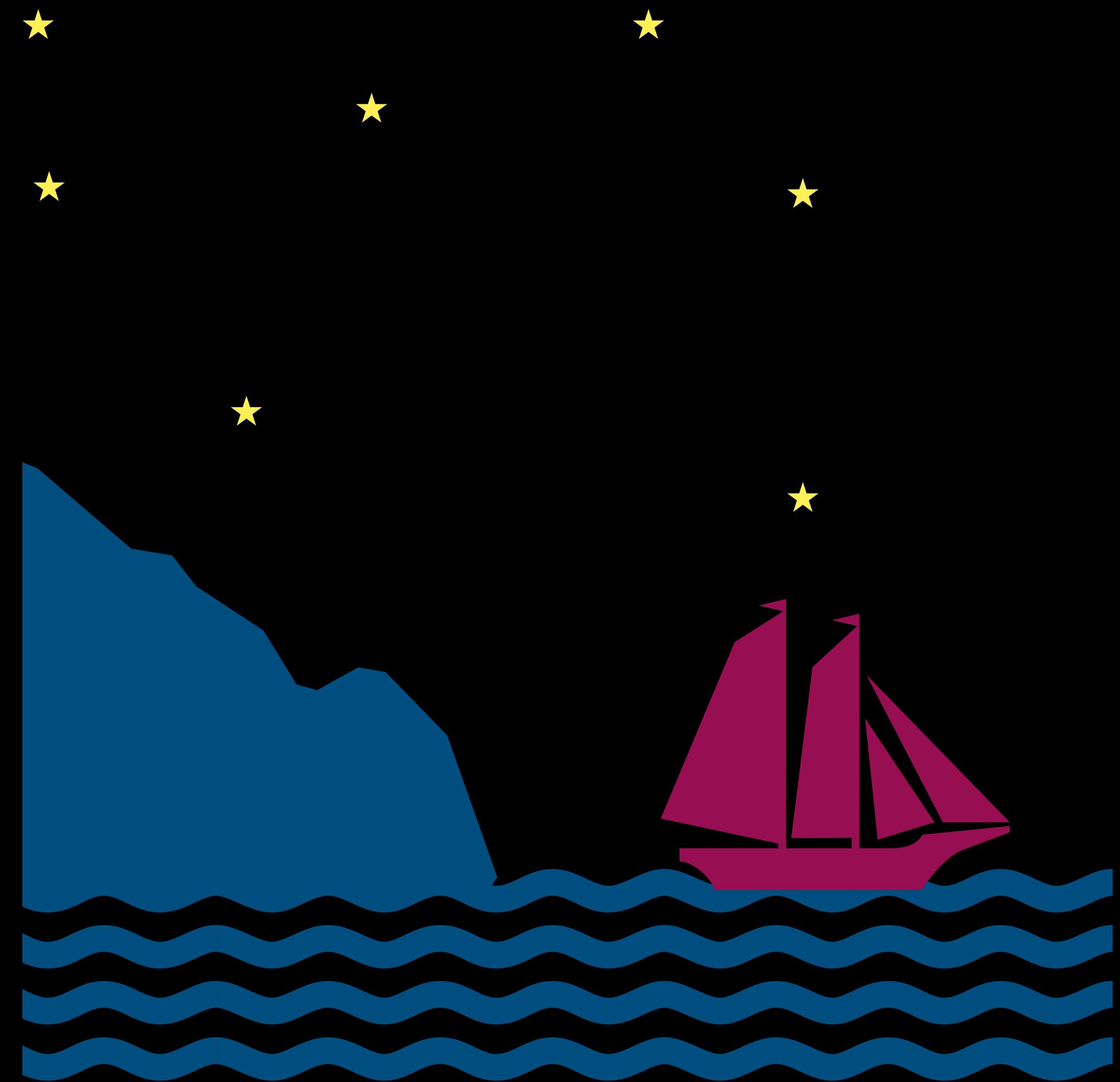
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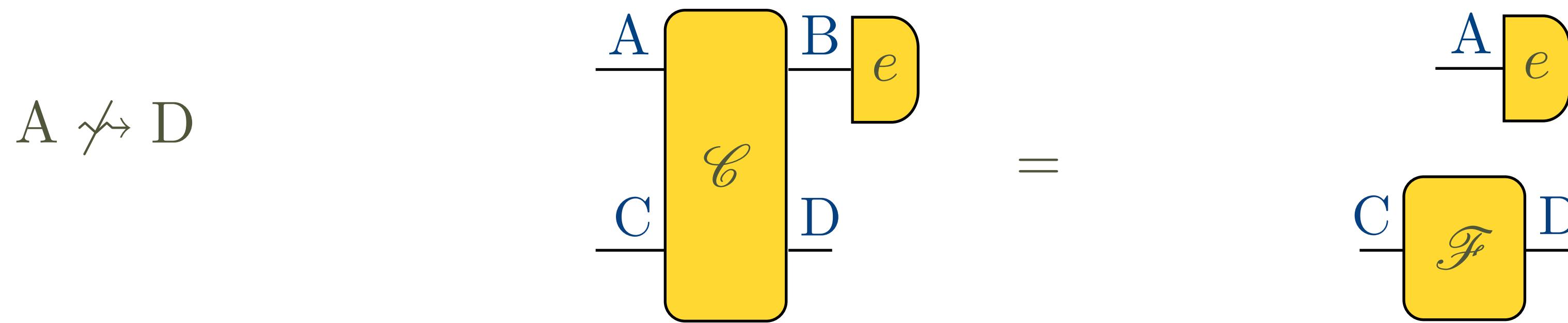
Sending signals

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Non-signalling channels

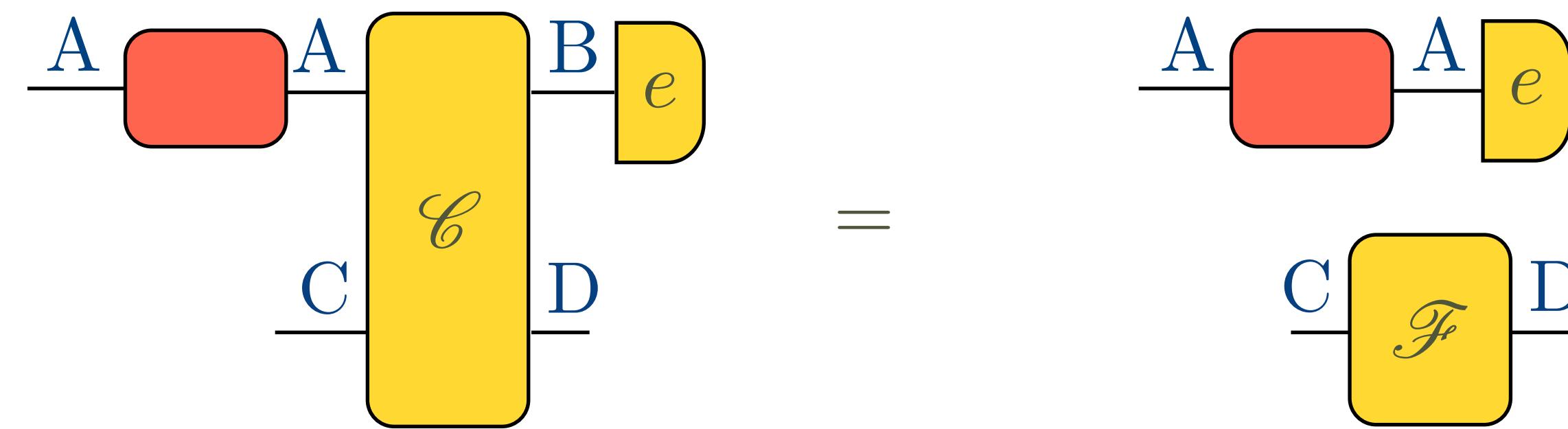
The usual approach



No intervention on the state of A can influence the state of C

Non-signalling channels

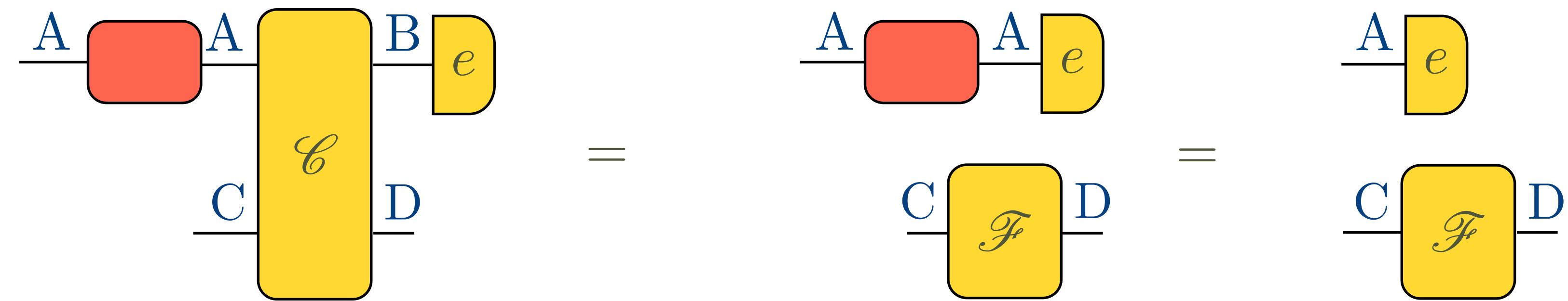
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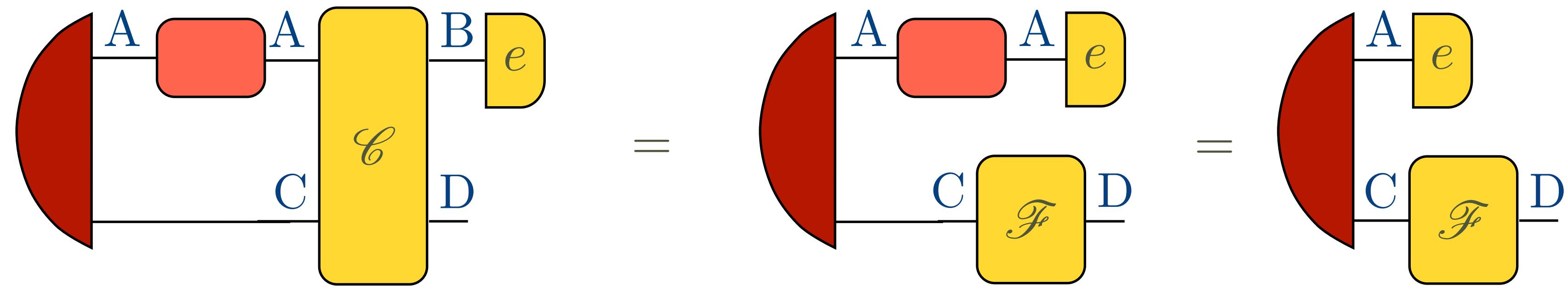
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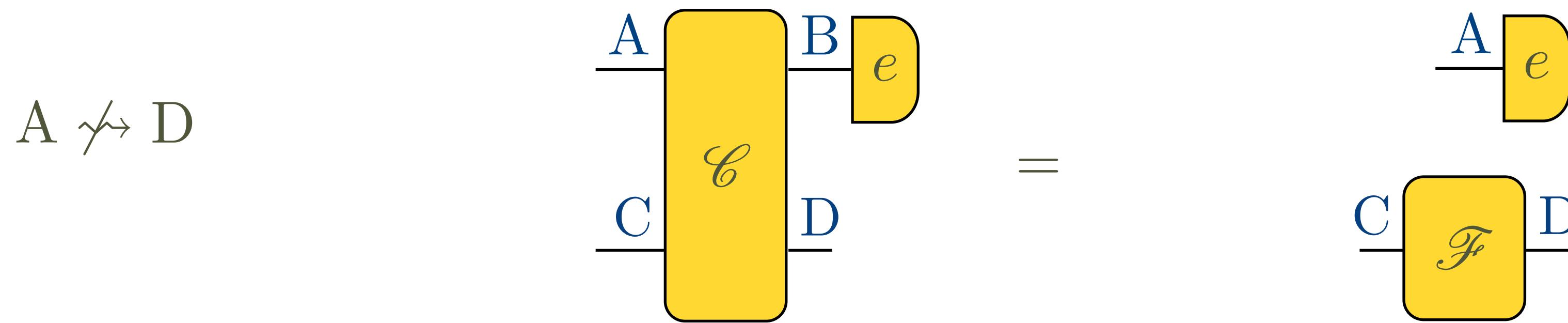
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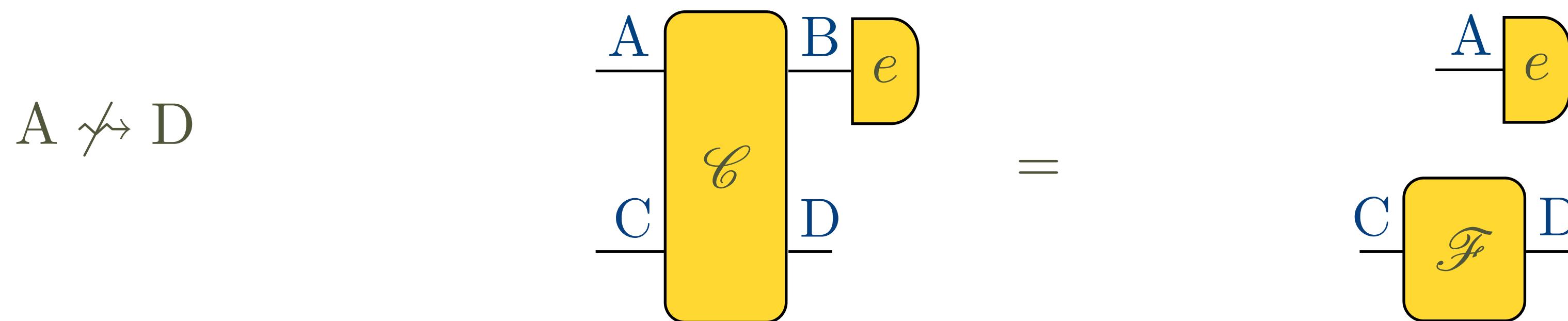
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In quantum theory

$$\text{Tr}_B[R_{\mathcal{E}}] = I_A \otimes R_{\mathcal{F}}$$

$R_{\mathcal{E}}$ denoting the Choi operator corresponding to \mathcal{E}

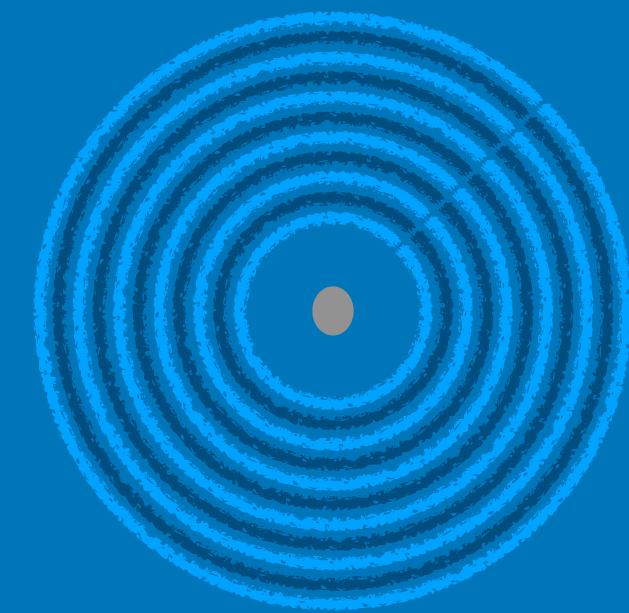
Propagation of an intervention

When does(n't) it happen?



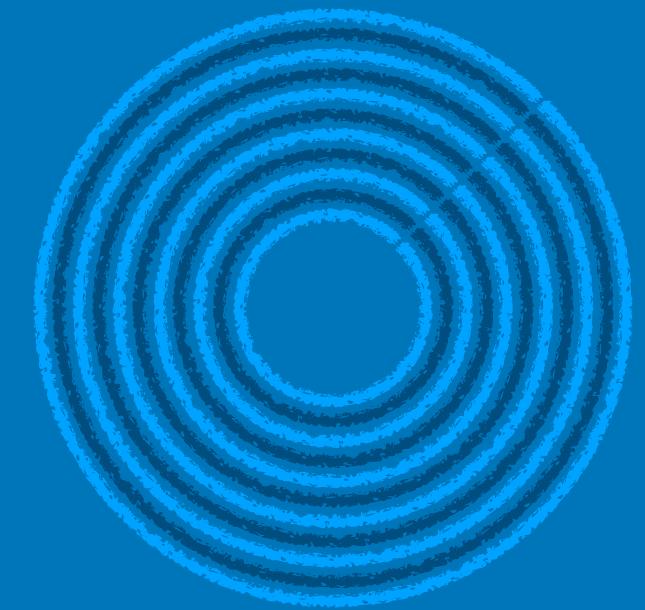
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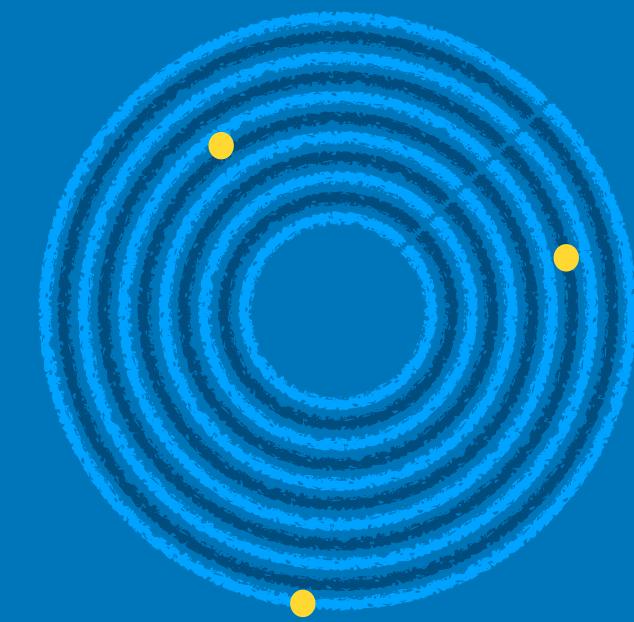
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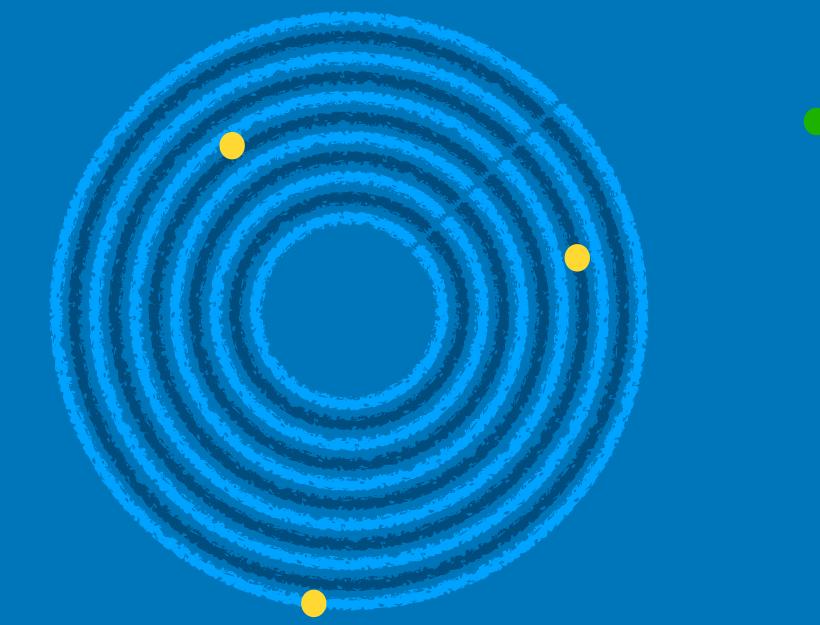
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Propagation of interventions

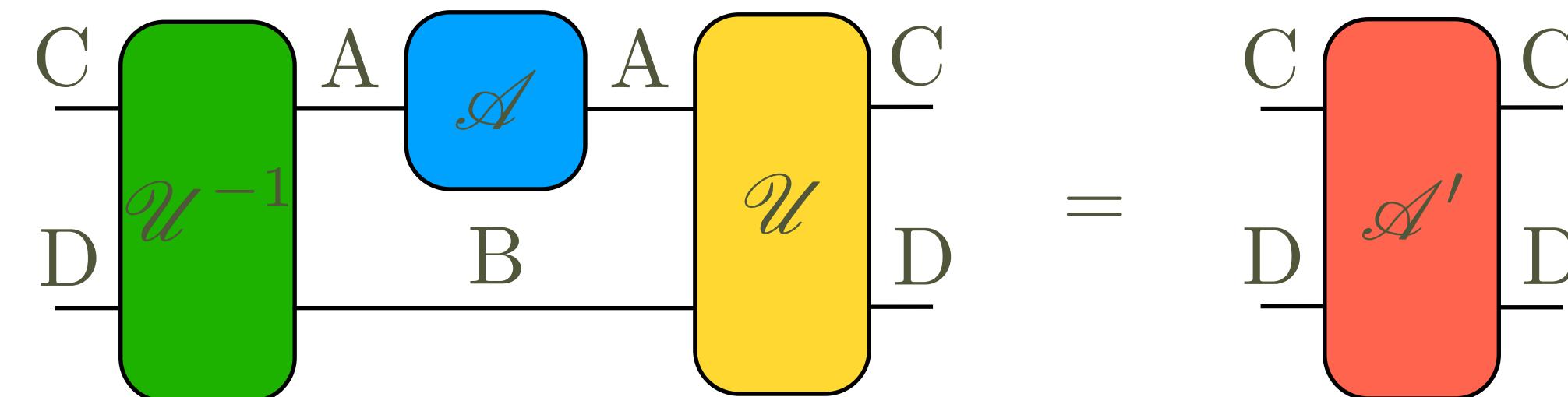
The raw idea

- The definition is inspired by the notion of neighbourhood in QCAs
- It holds for **reversible** transformations

Propagation of interventions

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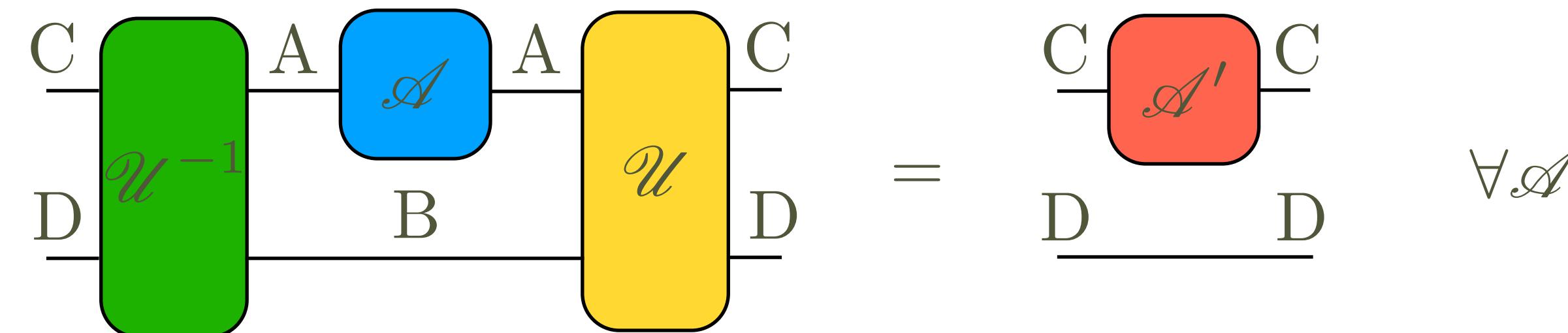
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Propagation of interventions

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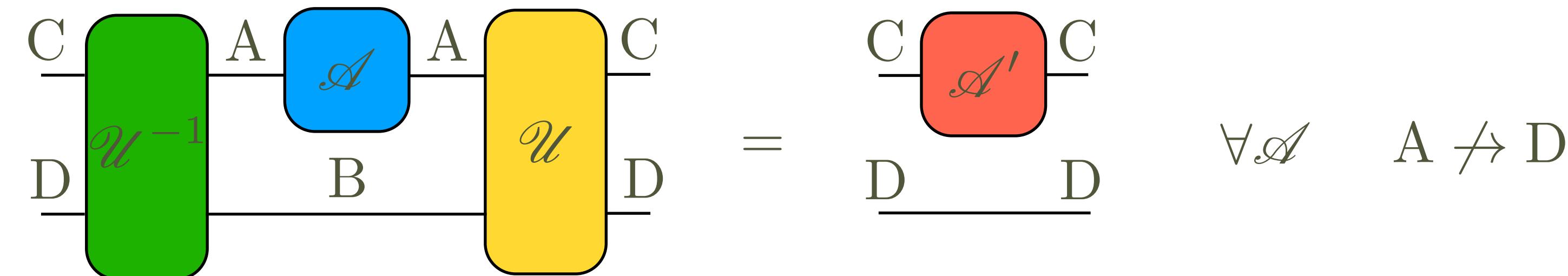
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Propagation of interventions

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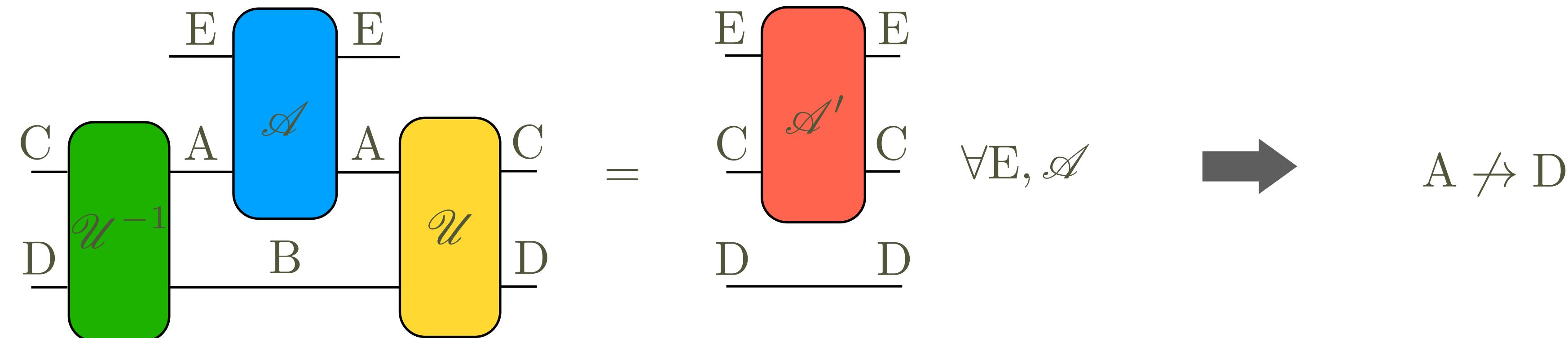
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Defining (no) causal influence in OPTs

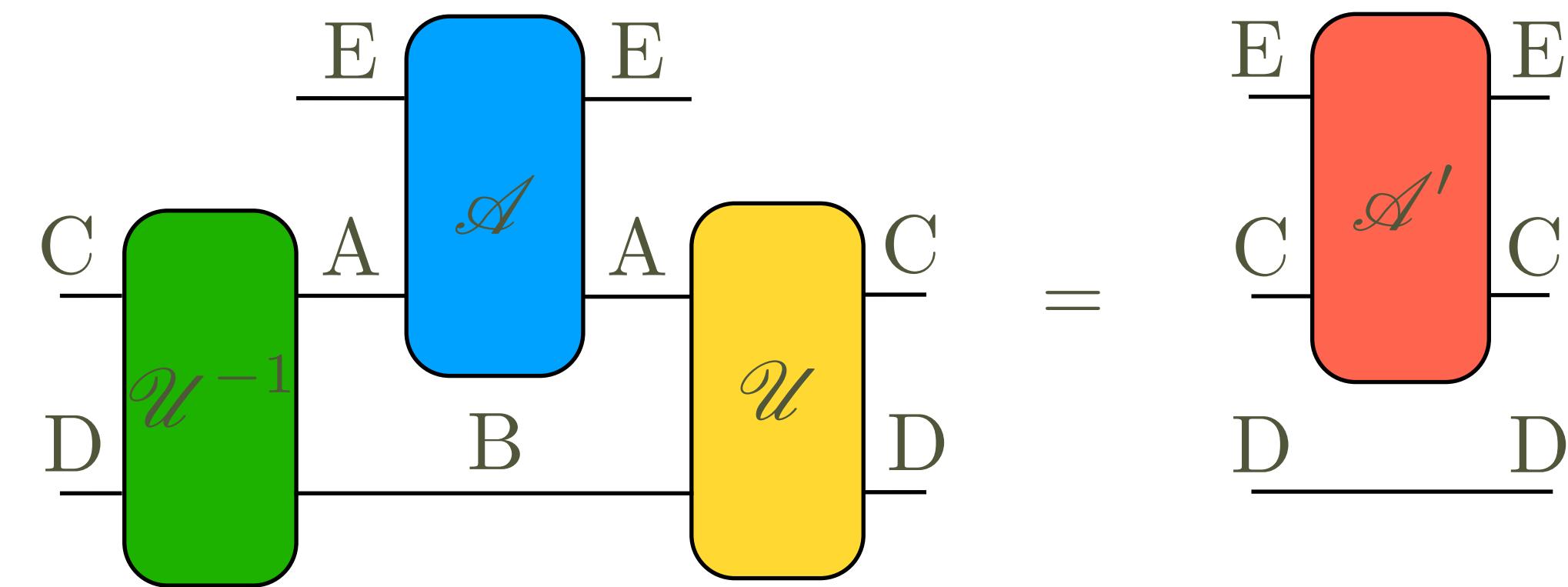
The precise notion

- Without local discriminability (local tomography/tomographic locality) we need to take into account interventions involving ancillary systems



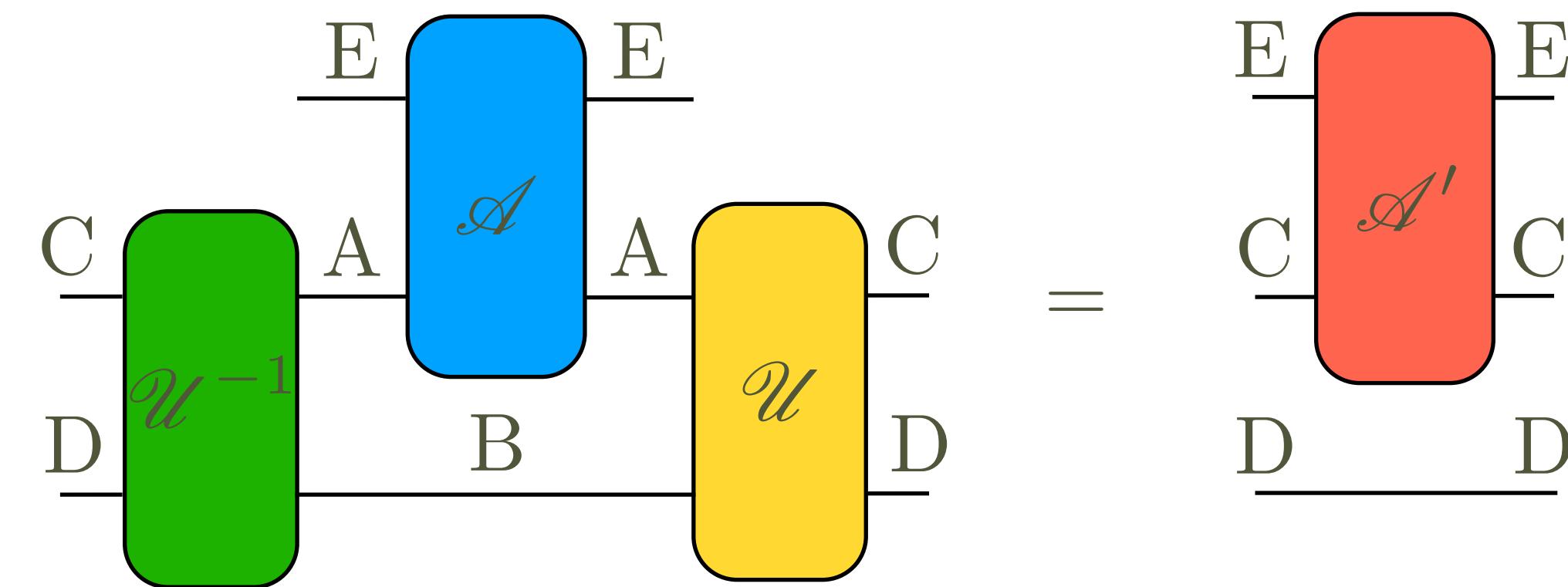
Explanation of the definition

Suppose that under \mathcal{U} one has $A \not\rightarrow D$

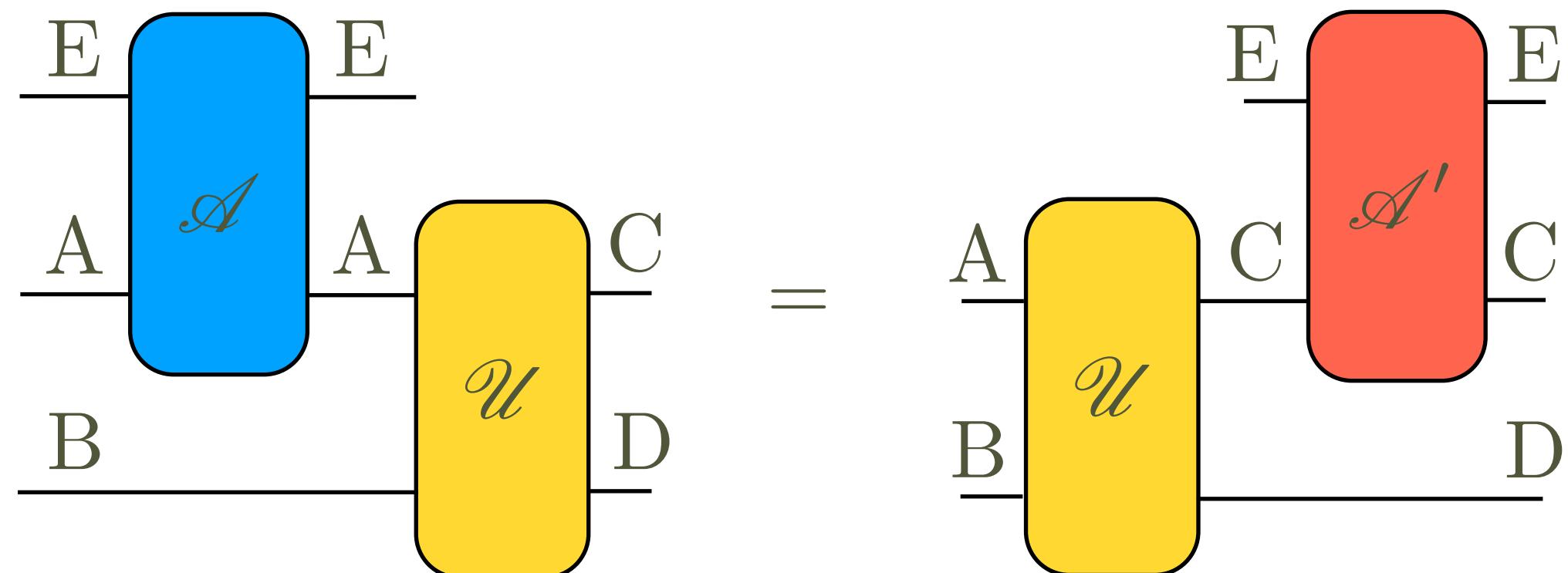


Explanation of the definition

Suppose that under \mathcal{U} one has $A \not\rightarrow D$



Equivalently:



Chapter III: The story

Results

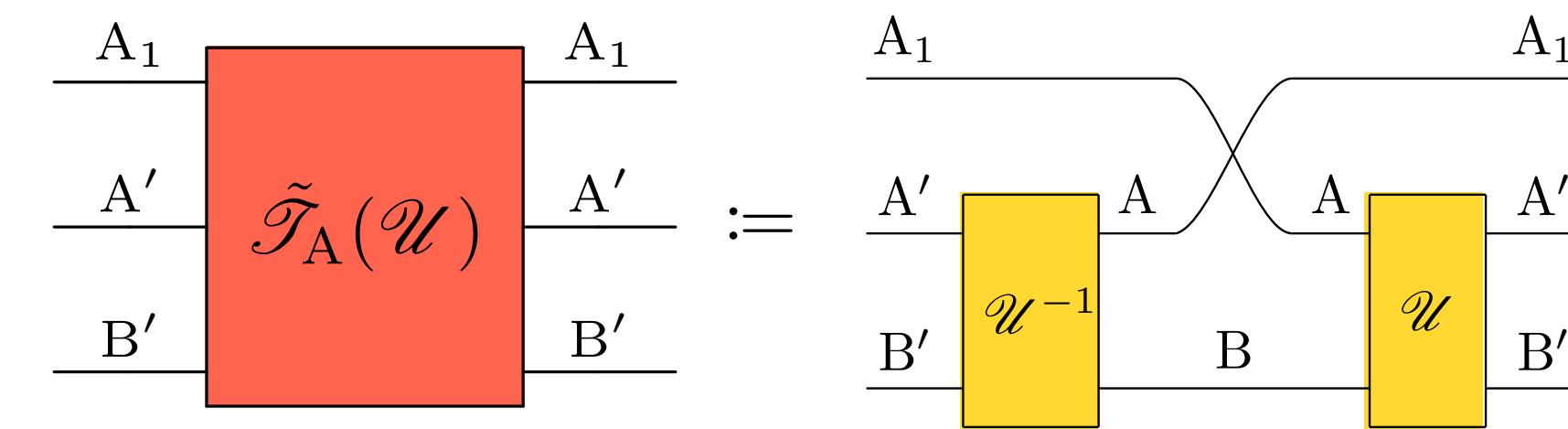
Signalling: sufficient for causal influence

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But not necessary!

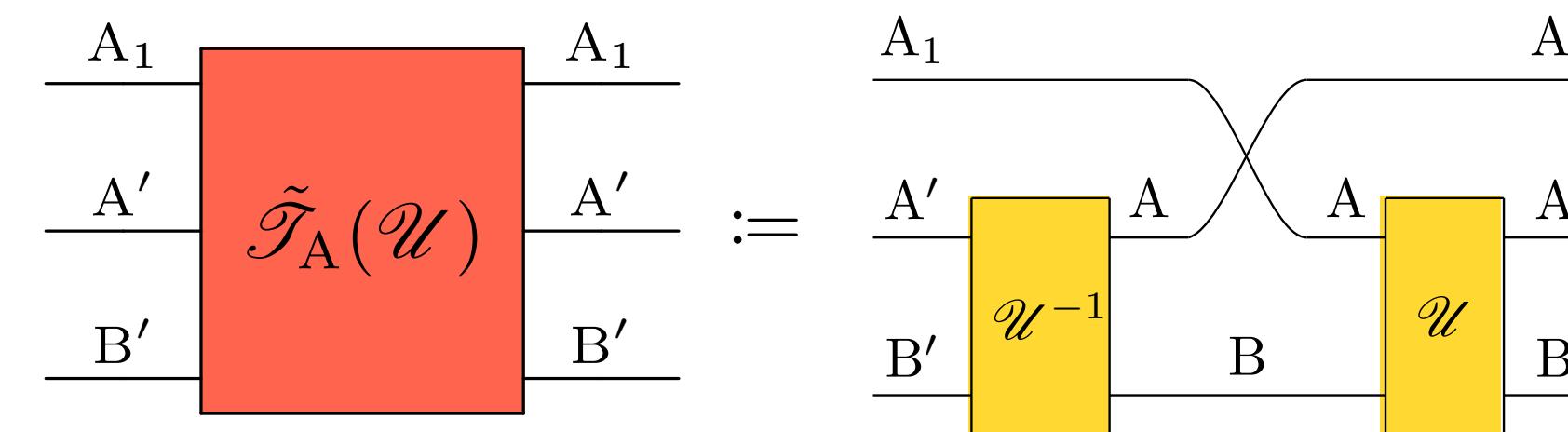
Necessary and sufficient condition

- Definition:



Necessary and sufficient condition

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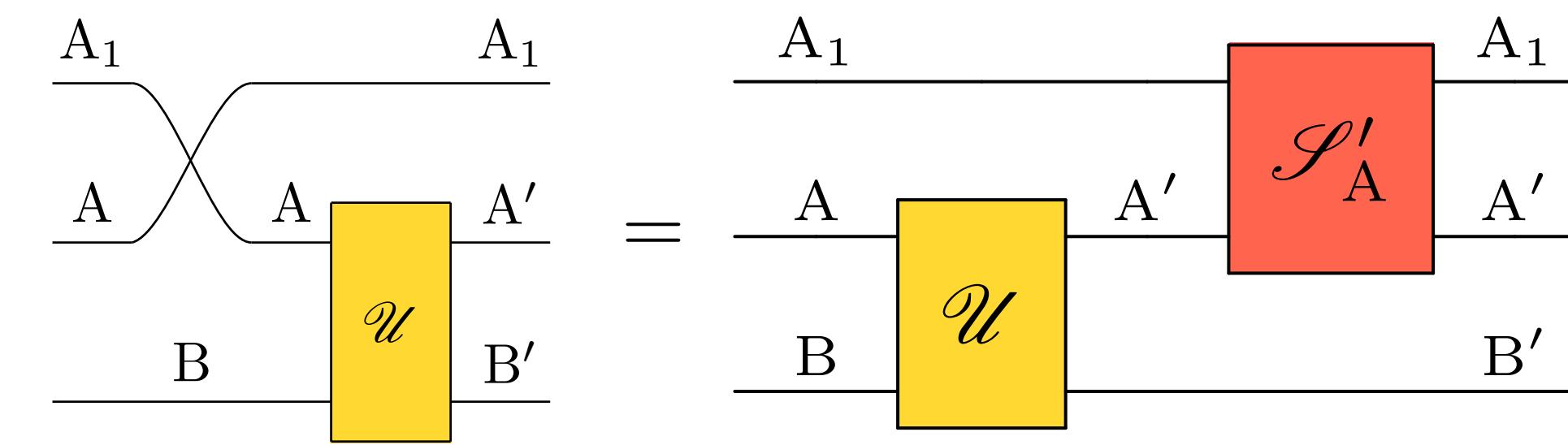
- Condition:

$A \not\rightarrow B'$ iff

$$\begin{array}{ccc} \begin{array}{c} A_1 \\ \hline A' \\ \hline B' \end{array} & \boxed{\tilde{\mathcal{T}}_A(\mathcal{U})} & \begin{array}{c} A_1 \\ \hline A' \\ \hline B' \end{array} \\ \hline & = & \hline \end{array}$$

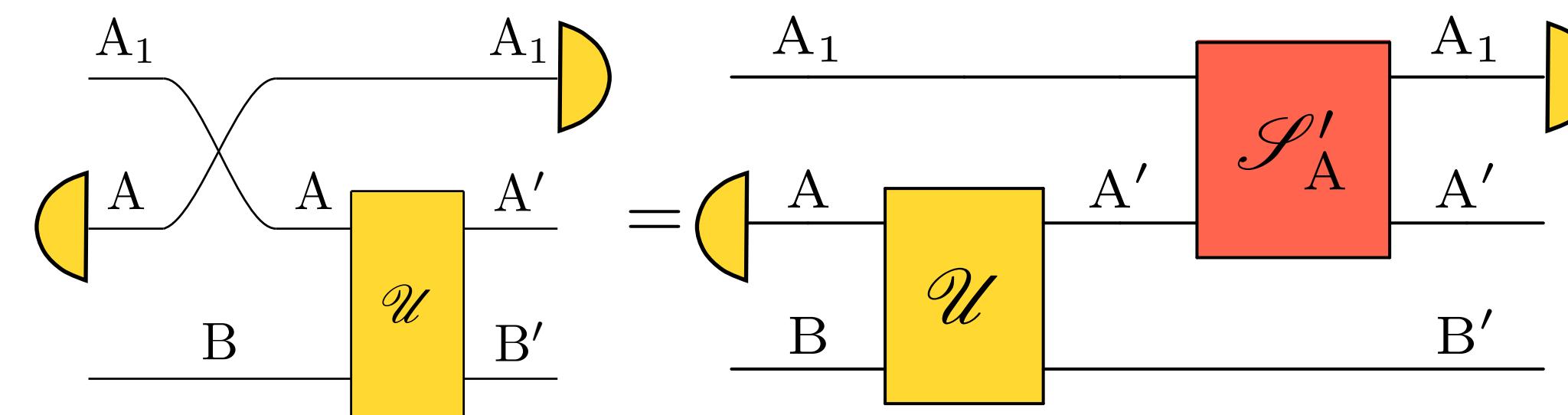
Necessary condition: comb structure

- Suppose that $A \not\rightarrow B'$. Then it must be



Necessary condition: comb structure

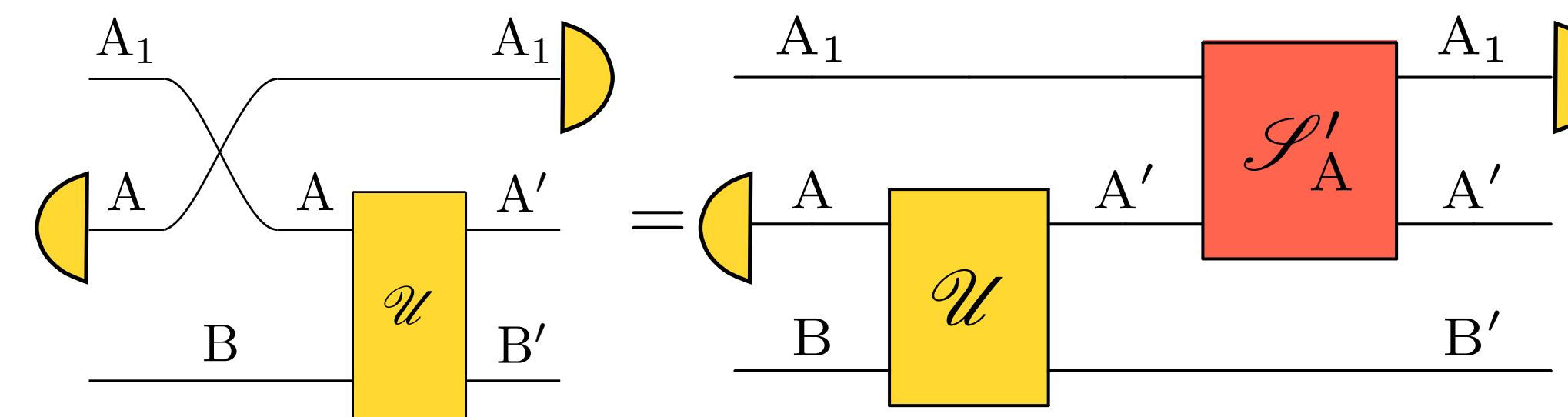
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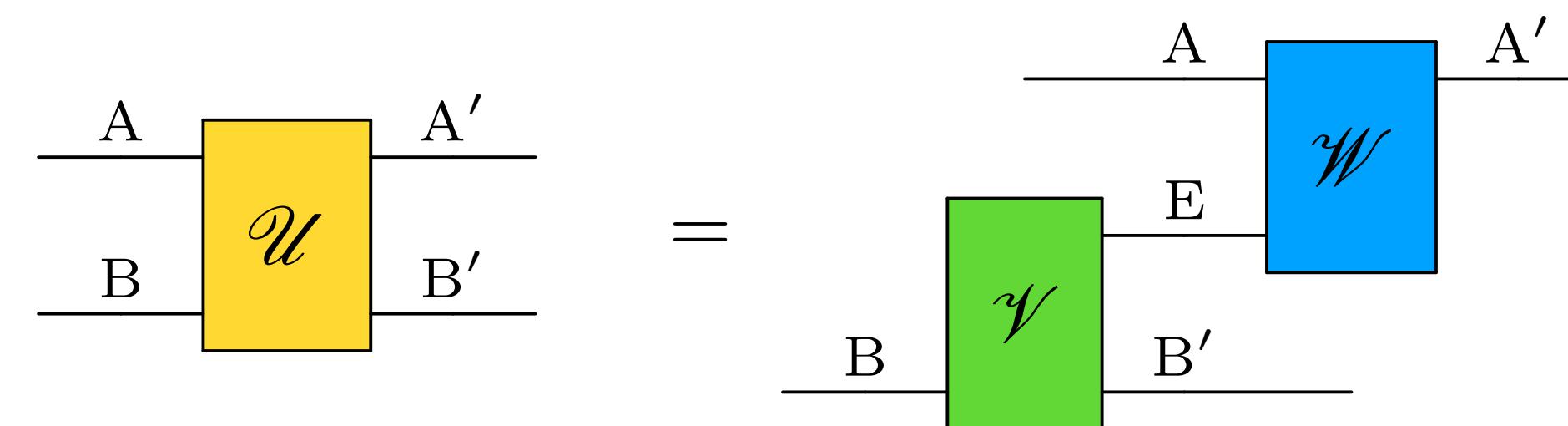
- Preparing a state of A and discarding A_1

Necessary condition: comb structure

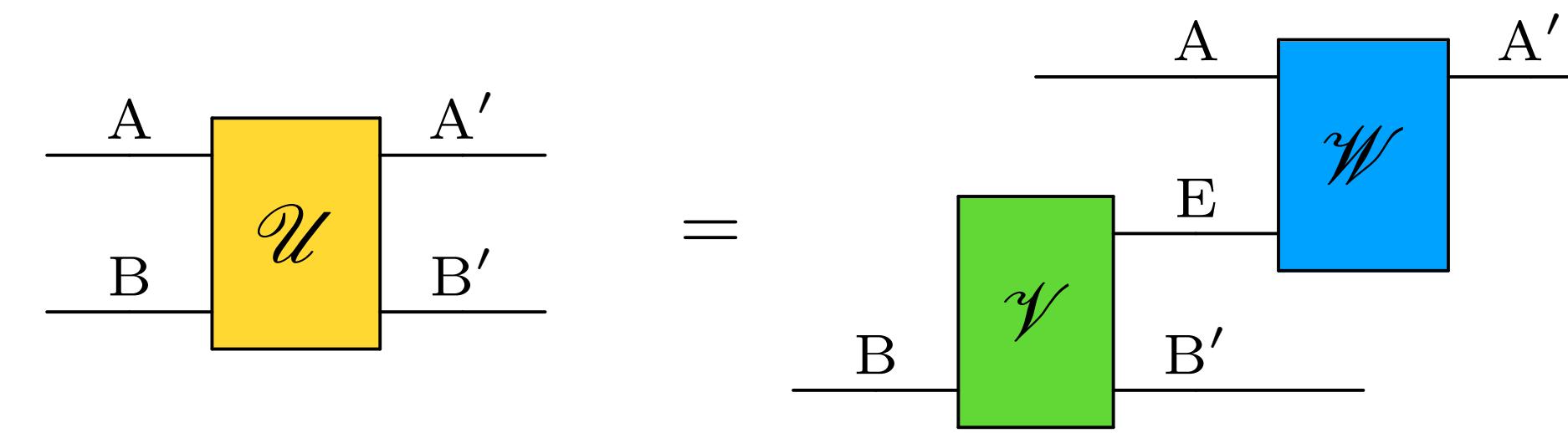
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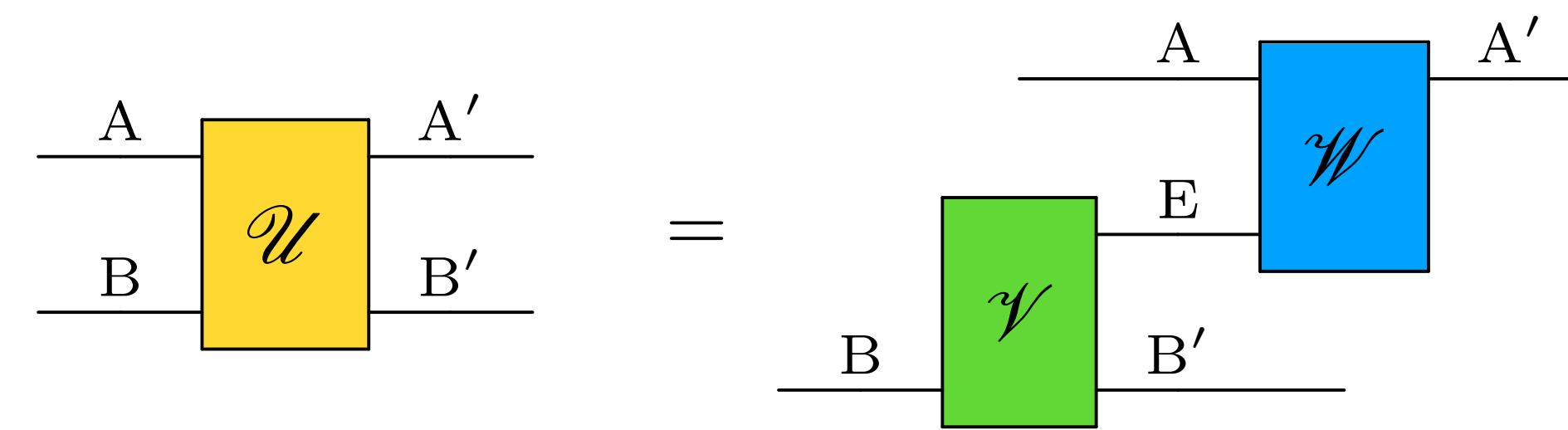


Necessary condition: no-signalling



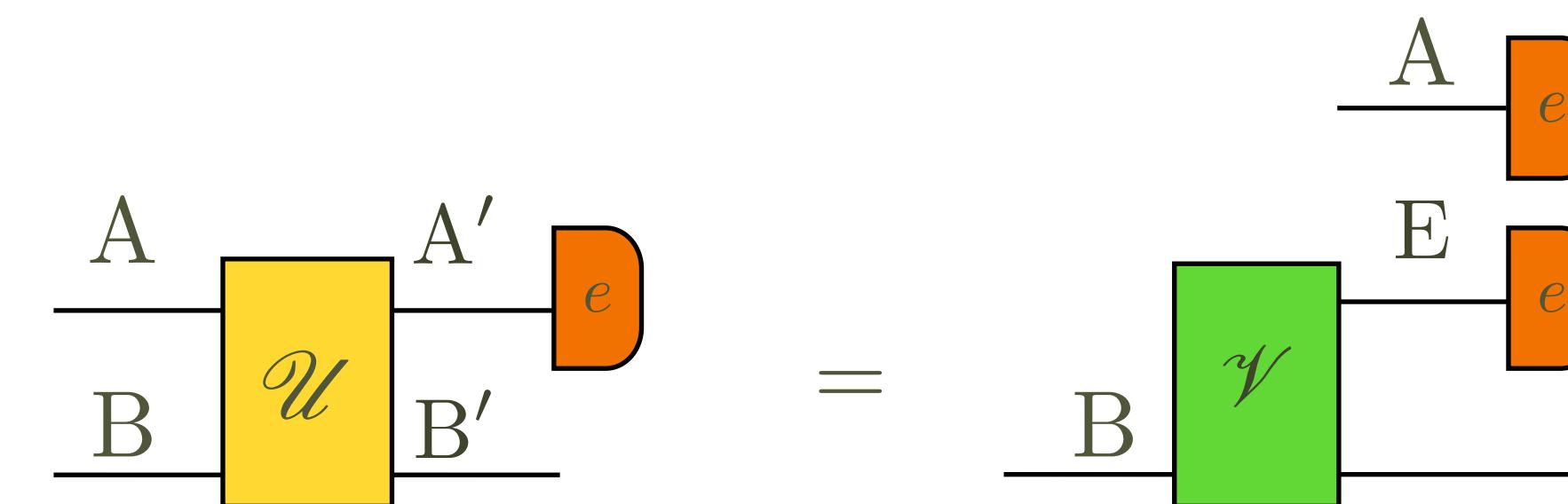
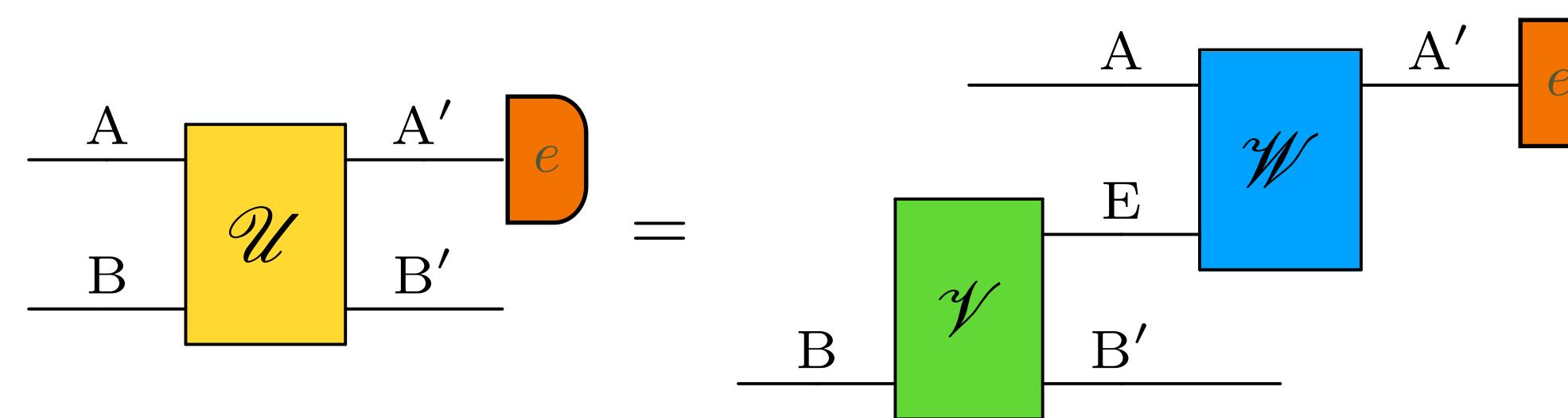
Necessary condition: no-signalling

- Discarding A'

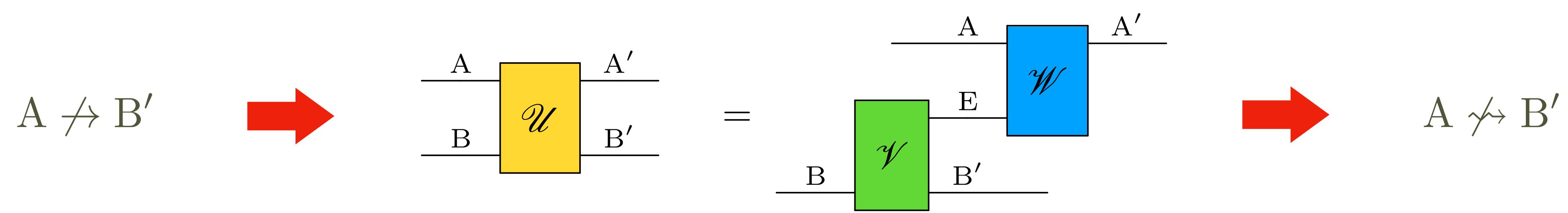


Necessary condition: no-signalling

- Discarding A'



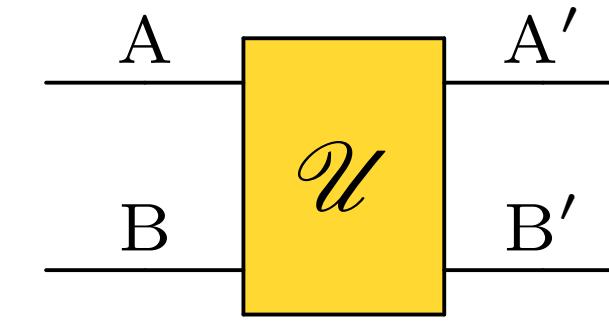
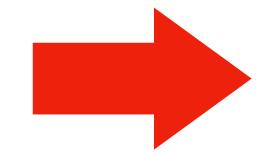
Chain of conditions



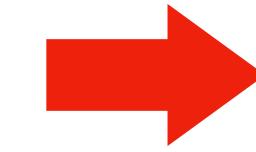
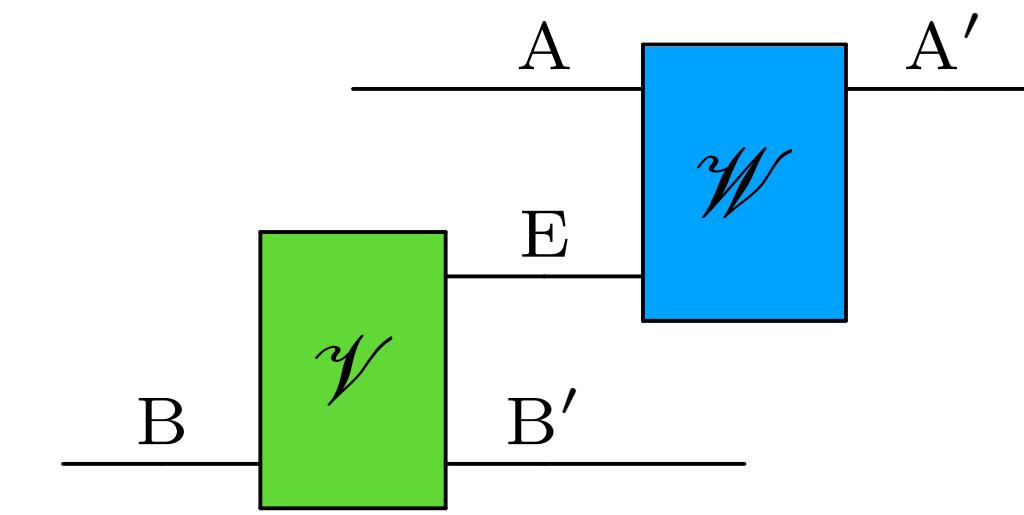
Classical theory

Example 1

$A \not\rightarrow B'$



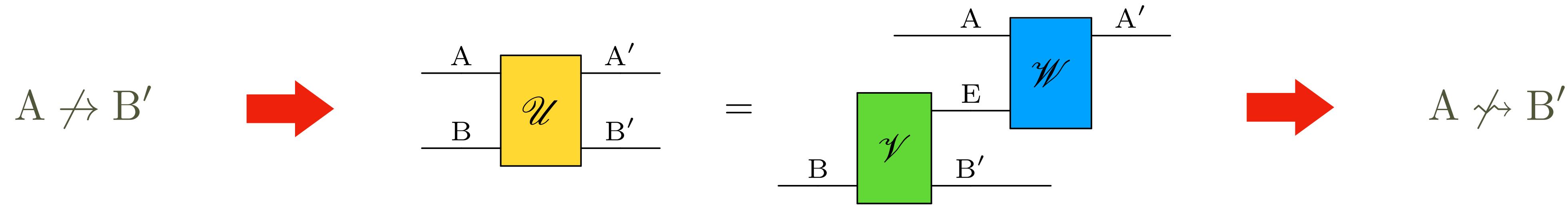
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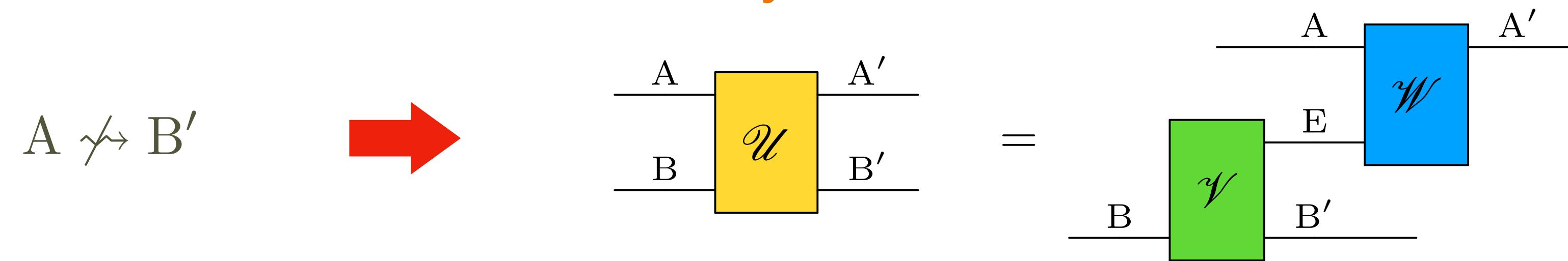
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Classical theory

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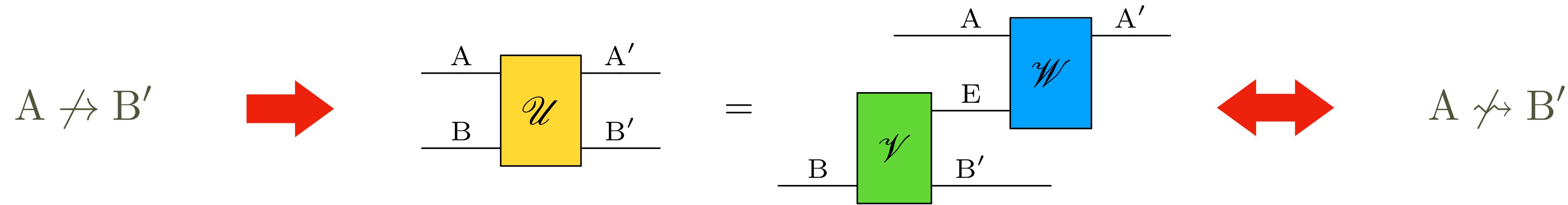


- One can prove that **in classical theory**

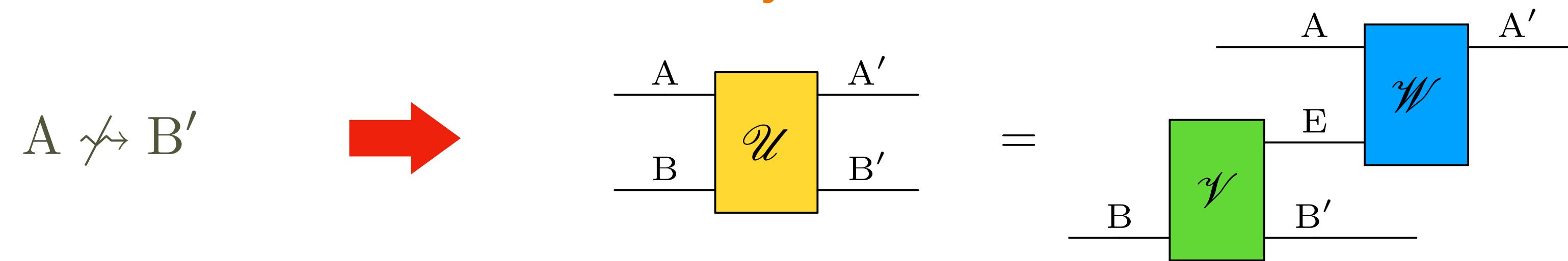


Classical theory

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Classical theory

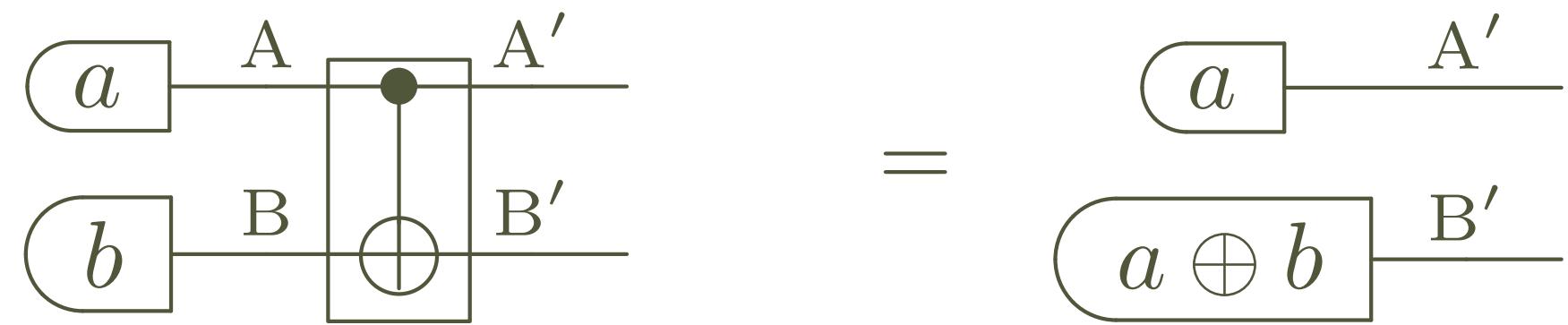
Example 1

- Classical C-not

Classical theory

Example 1

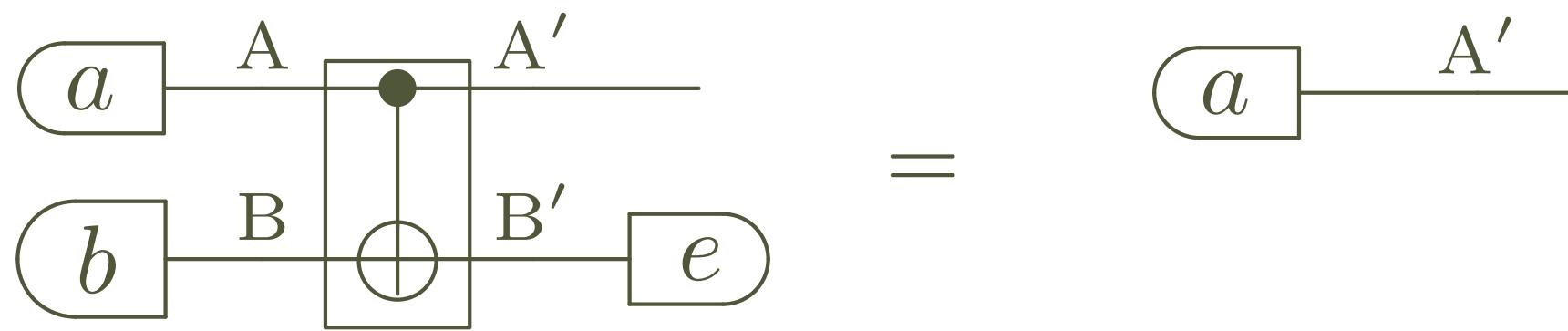
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Classical theory

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Classical theory

Example 1

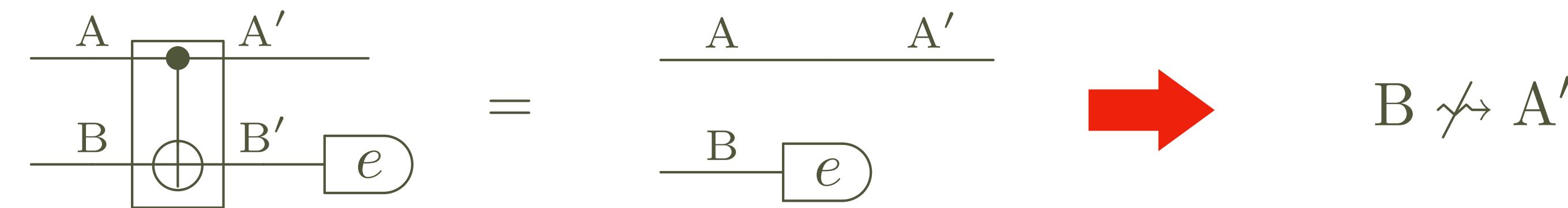
- Classical C-not



Classical theory

Example 1

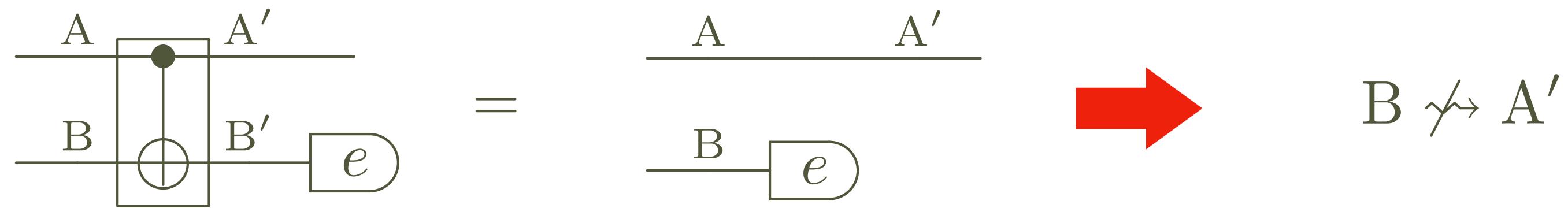
- Classical C-not



Classical theory

Example 1

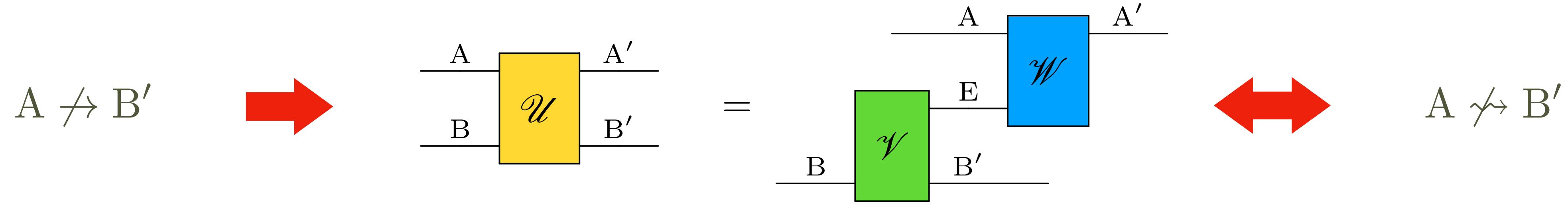
- Classical C-not



- No causal influence: violated, thus $B \rightarrow A'$

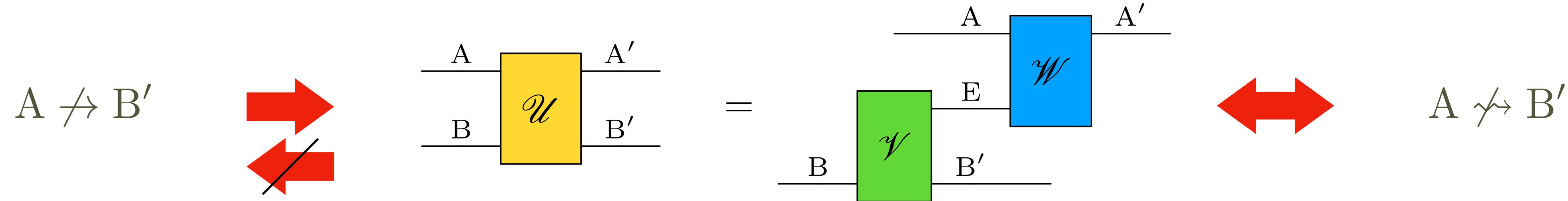
Chain of conditions

In classical theory



Chain of conditions

In classical theory

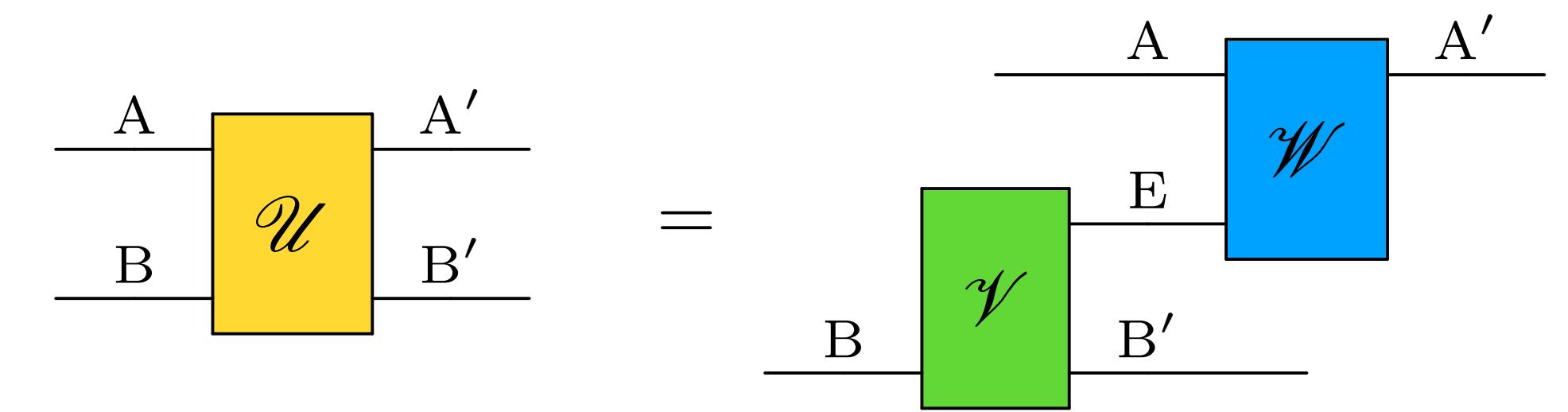
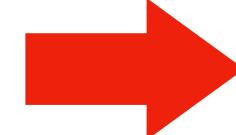


Quantum theory

Example 2

- Also in quantum theory

$A \not\rightsquigarrow B'$

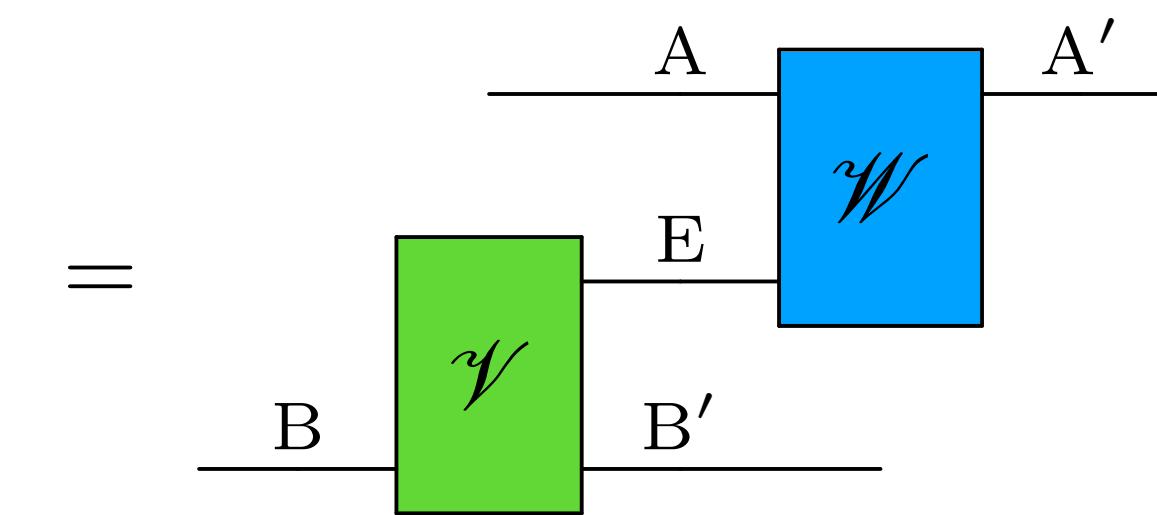
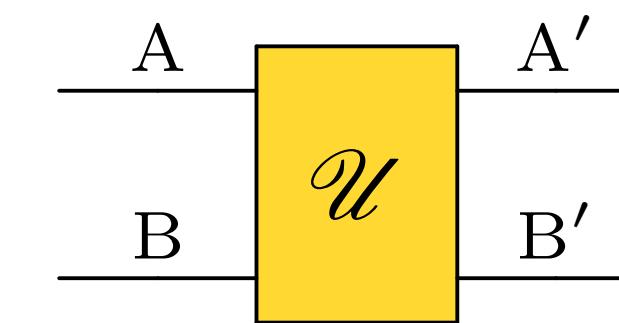
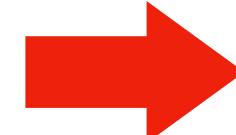


Quantum theory

Example 2

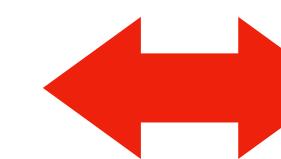
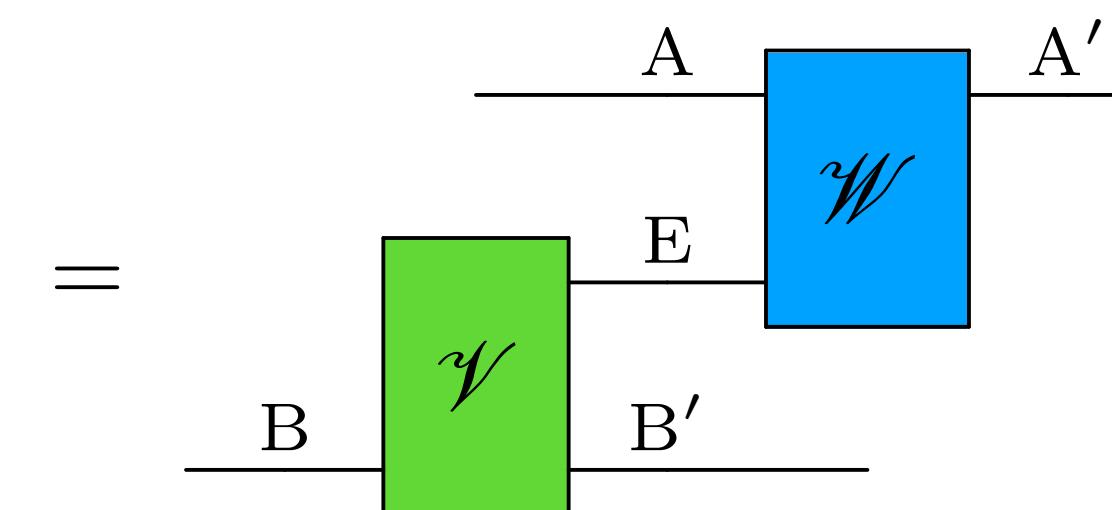
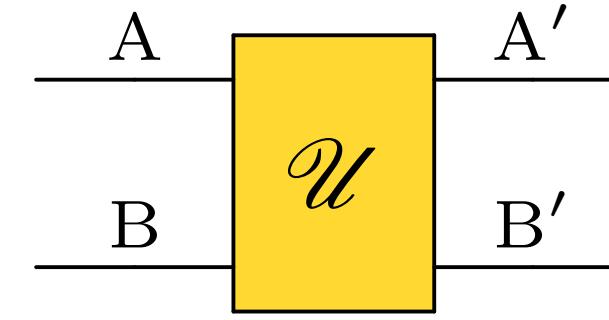
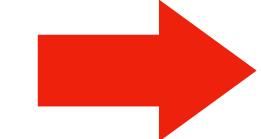
- Also in quantum theory

$A \not\rightarrow B'$



- Thus

$A \not\rightarrow B'$



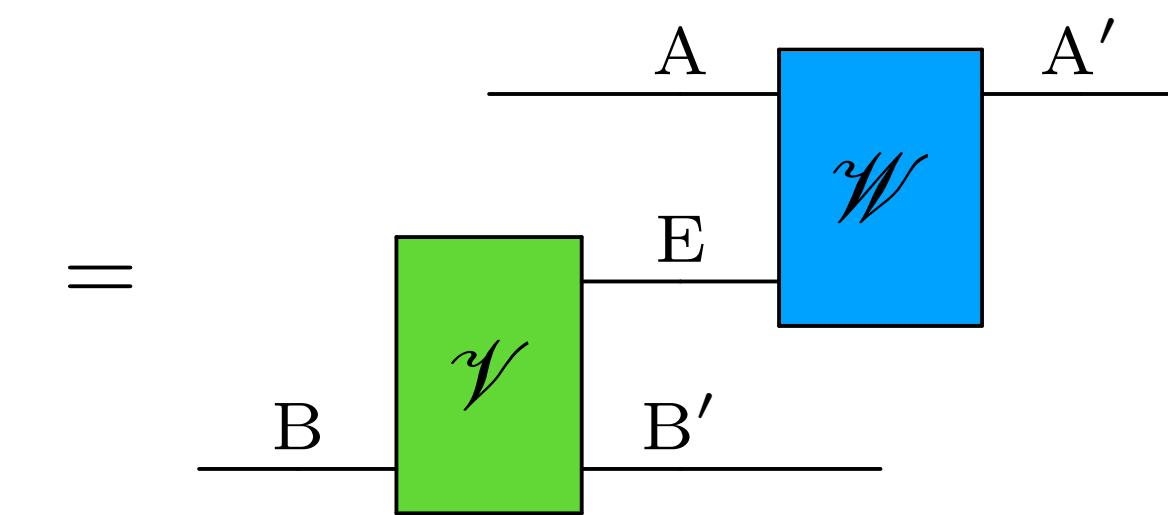
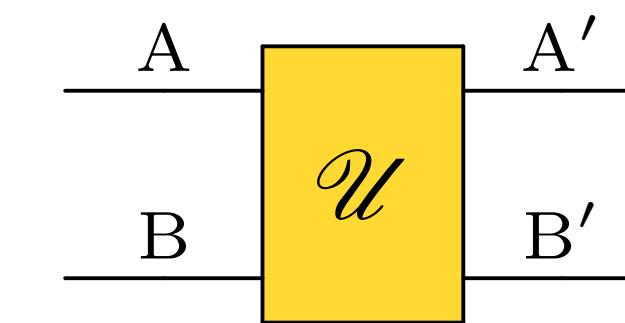
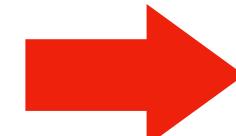
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Quantum theory

Example 2

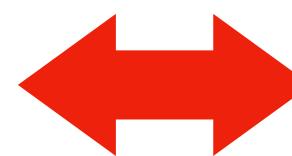
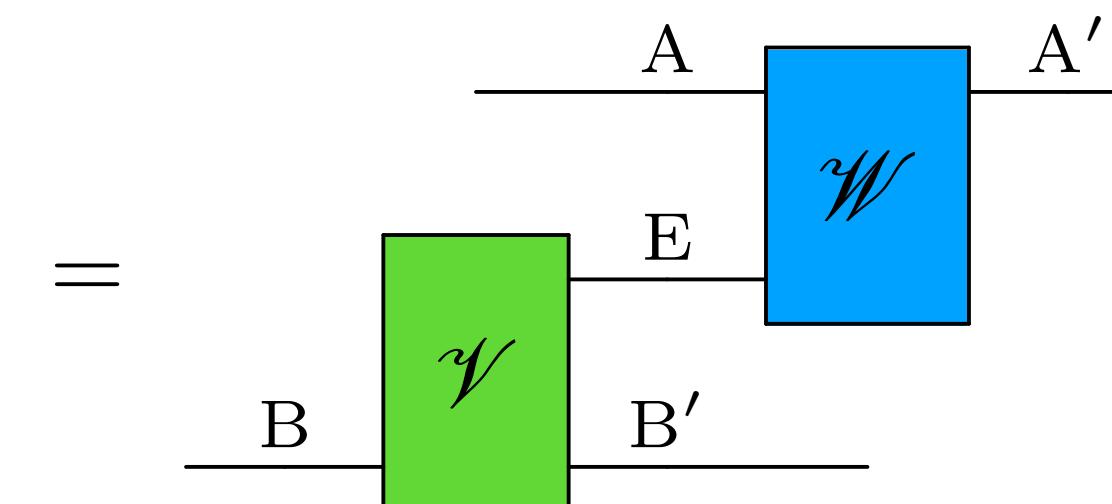
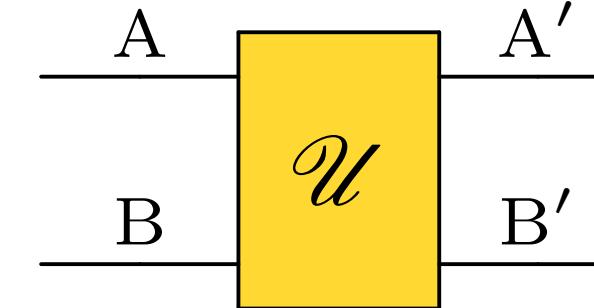
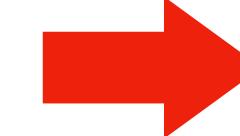
- Also in quantum theory

$A \not\rightarrow B'$



- Thus

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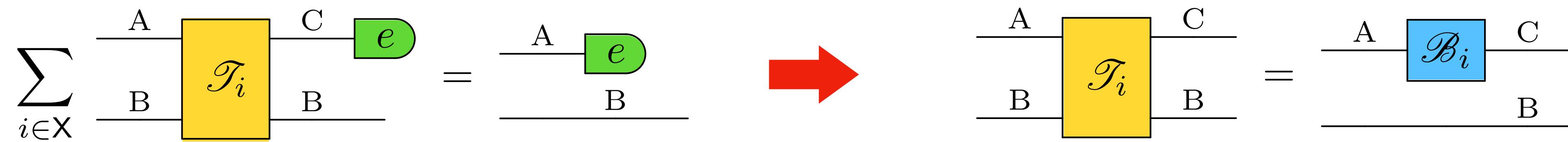


$A \not\rightarrow B'$

- What about the first implication?

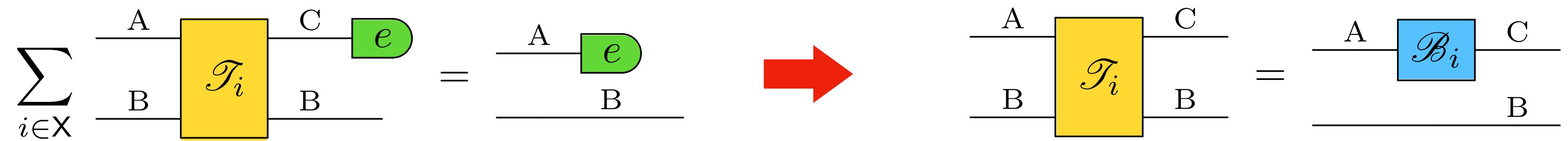
Quantum theory

- From the characterisation of Kraus decompositions of a given channel



Quantum theory

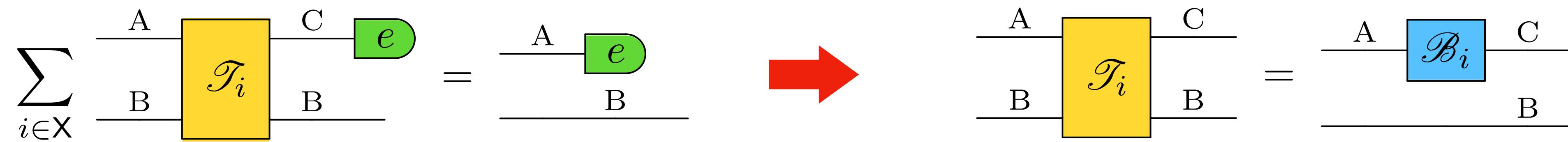
- From the characterisation of Kraus decompositions of a given channel



- Also from **purification**

Quantum theory

- From the characterisation of Kraus decompositions of a given channel

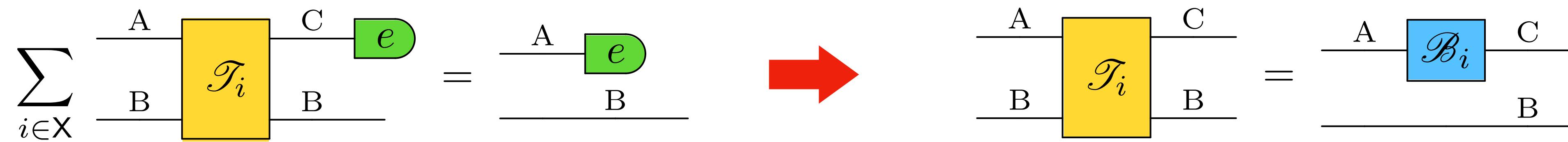


- Also from **purification**

→ The above result holds also in **Fermionic theory** and **Real Quantum theory**

Quantum theory

- From the characterisation of Kraus decompositions of a given channel



- Also from **purification**

→ The above result holds also in **Fermionic theory** and **Real Quantum theory**

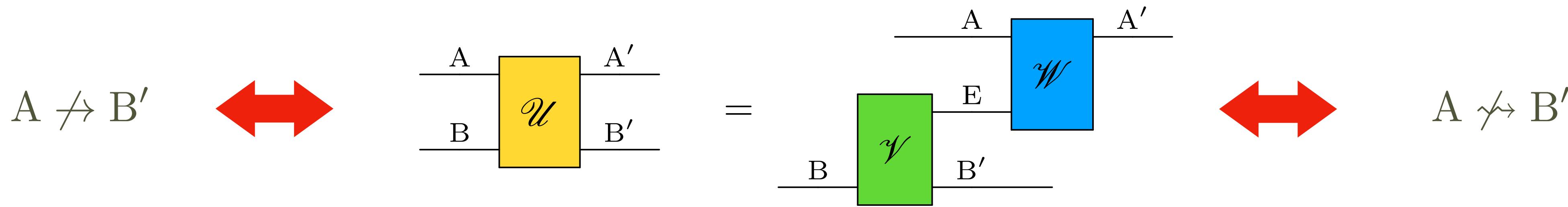
No interaction without disturbance

Quantum theory

- From no interaction without disturbance one has $A \not\rightsquigarrow B \rightarrow A \not\rightleftharpoons B$

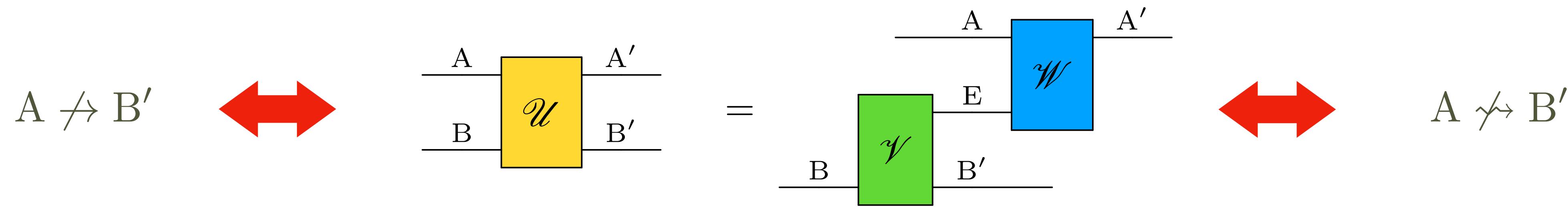
Quantum theory

- From no interaction without disturbance one has $A \not\rightsquigarrow B$  $A \not\rightarrow B$
- Thus



Quantum theory

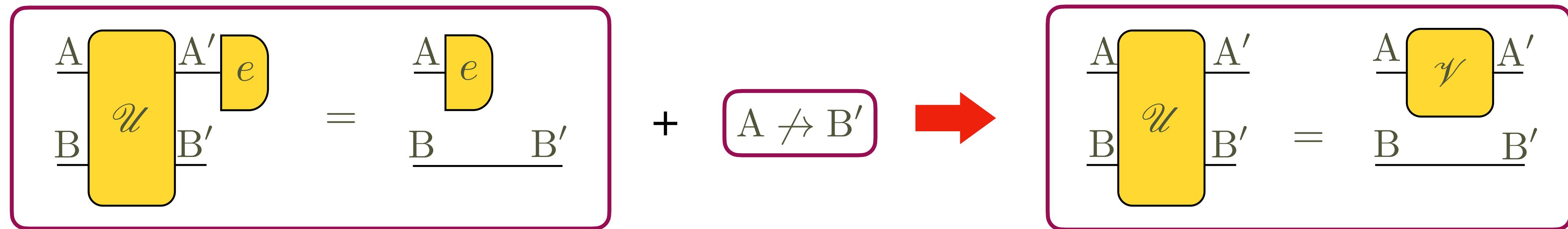
- From no interaction without disturbance one has $A \not\rightsquigarrow B \rightarrow A \not\rightsquigarrow B$
- Thus



- True in every theory with purification or just no interaction without disturbance

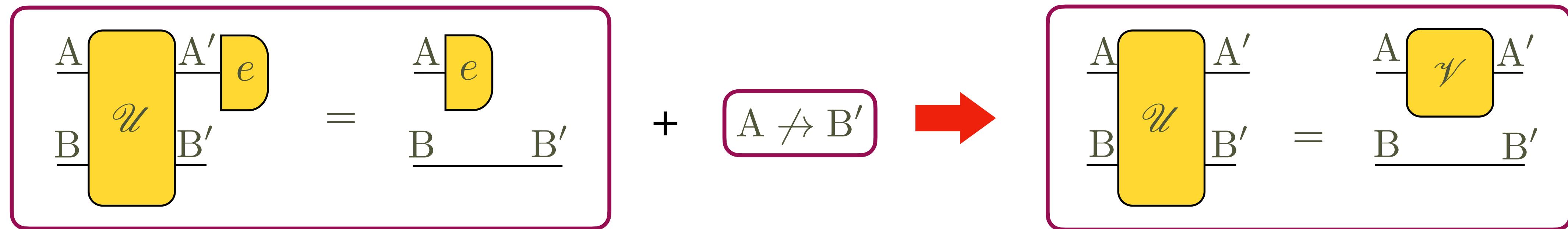
Interaction without disturbance

- What about a theory featuring interactions without disturbance?

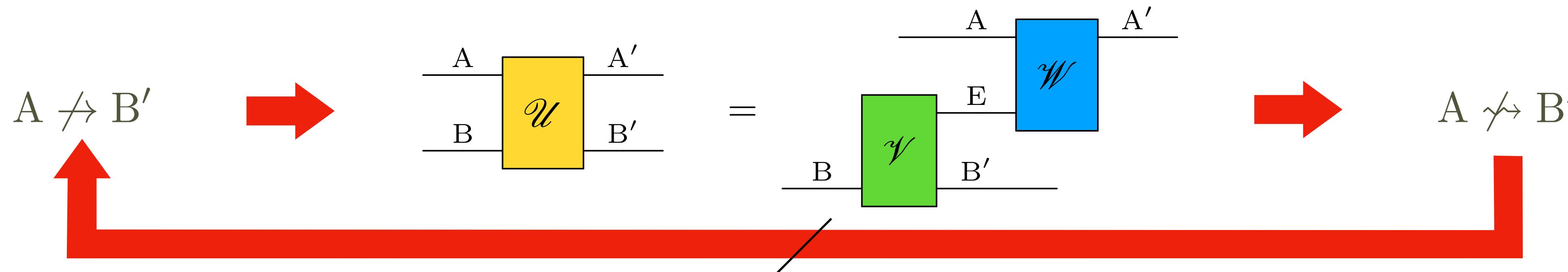


Interaction without disturbance

- What about a theory featuring interactions without disturbance?



- Thus, if the special interaction without disturbance is reversible, one has



Chapter III: Epilogue

Open problems and conclusions

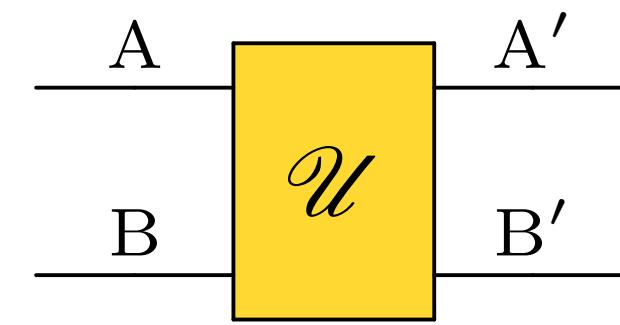
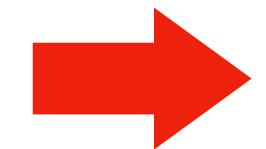
Open question

The quest for counterexamples

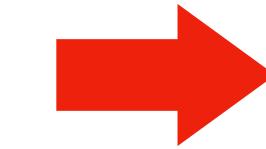
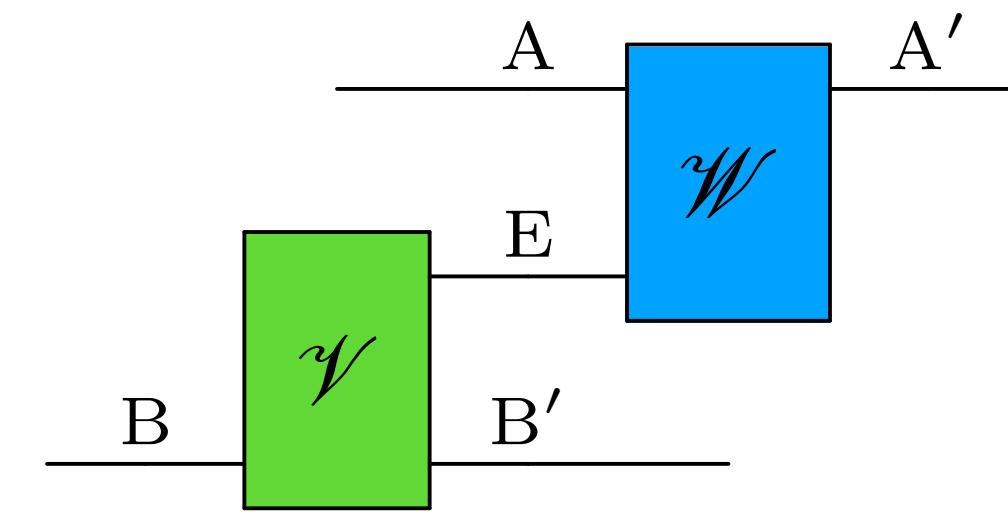
Open question

The quest for counterexamples

$A \not\rightarrow B'$



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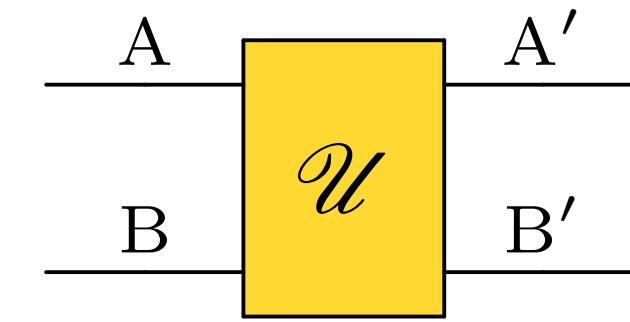
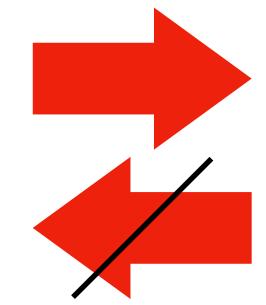


$A \not\rightsquigarrow B'$

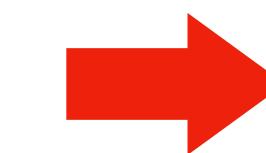
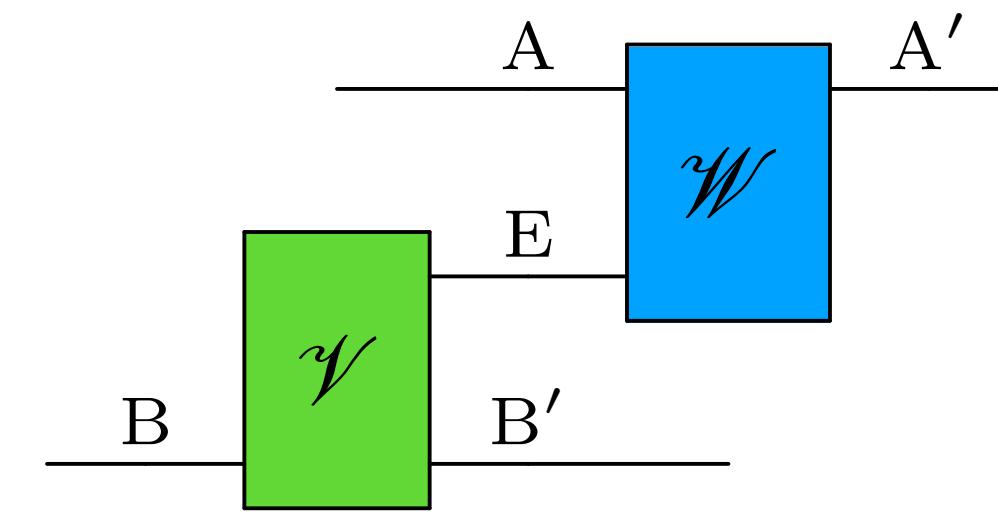
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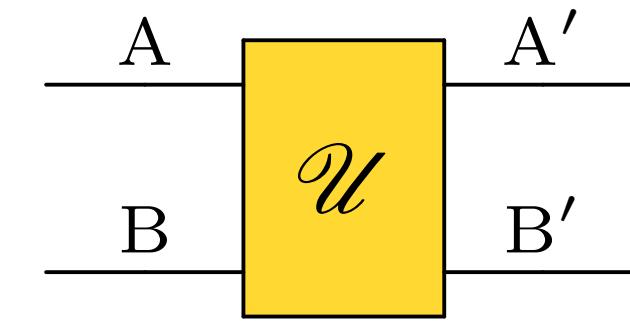
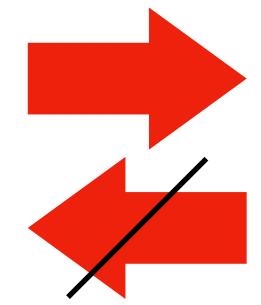


$A \not\rightarrow B'$

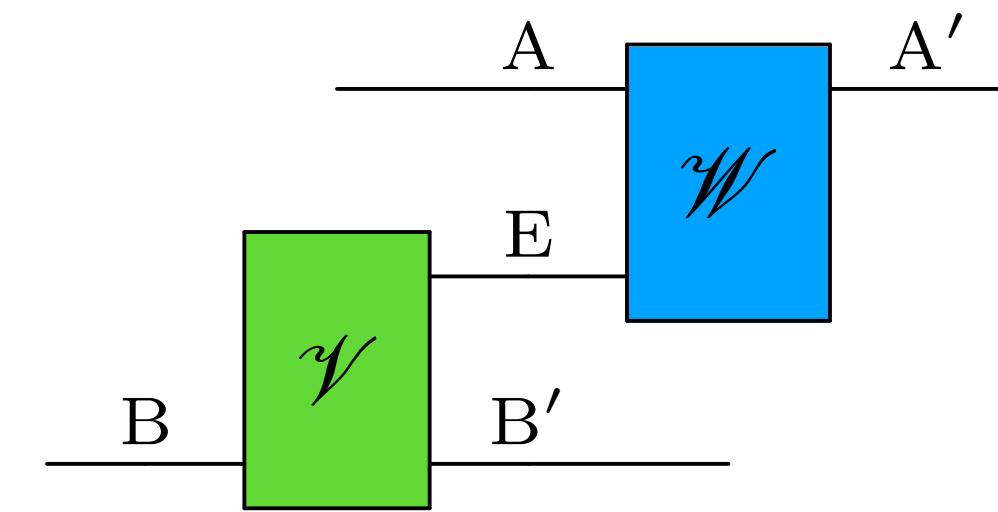
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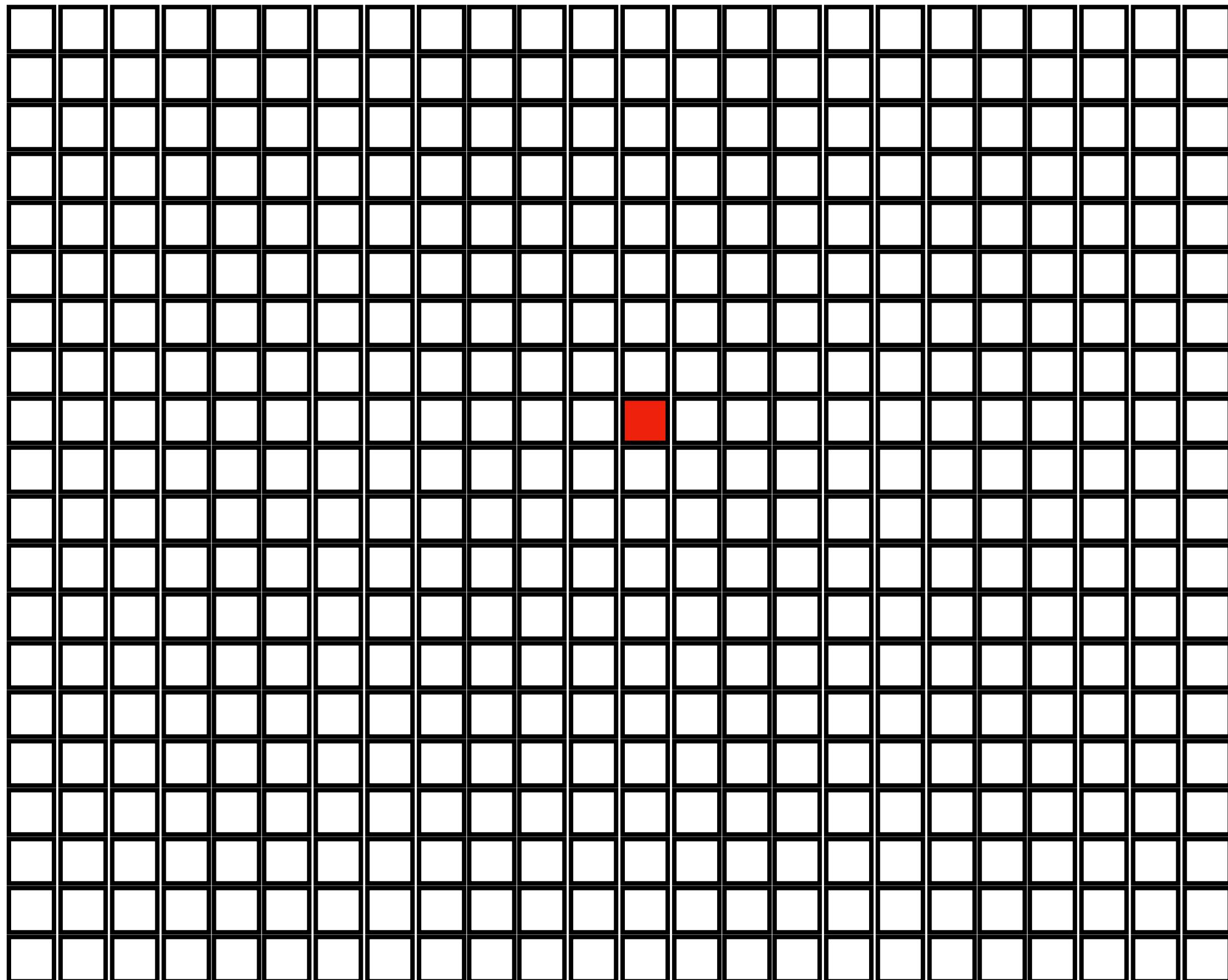
$A \not\rightarrow B'$

Why bother?

Neighbourhood of a cell in a QCA

$$\square = \mathcal{H}_x \leftrightarrow A_x$$

C.A.: $U : \bigotimes_x \mathcal{H}_x \rightarrow \bigotimes_x \mathcal{H}_x$



Why bother?

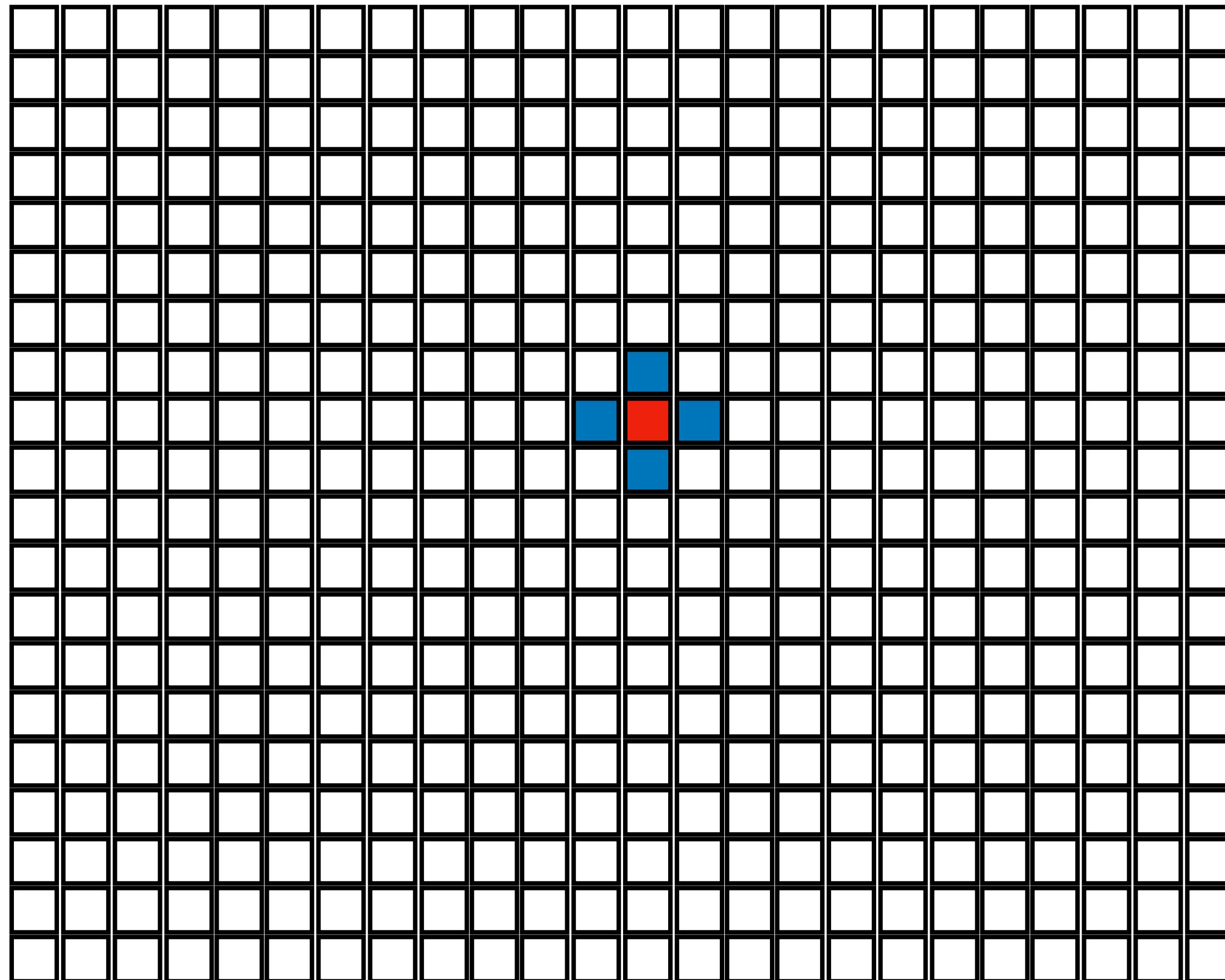
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Neighbourhood of the cell x_0

$$U A_{x_0} U^{-1} \subseteq A_{N(x_0)} \otimes I_{\bar{x}_0}$$



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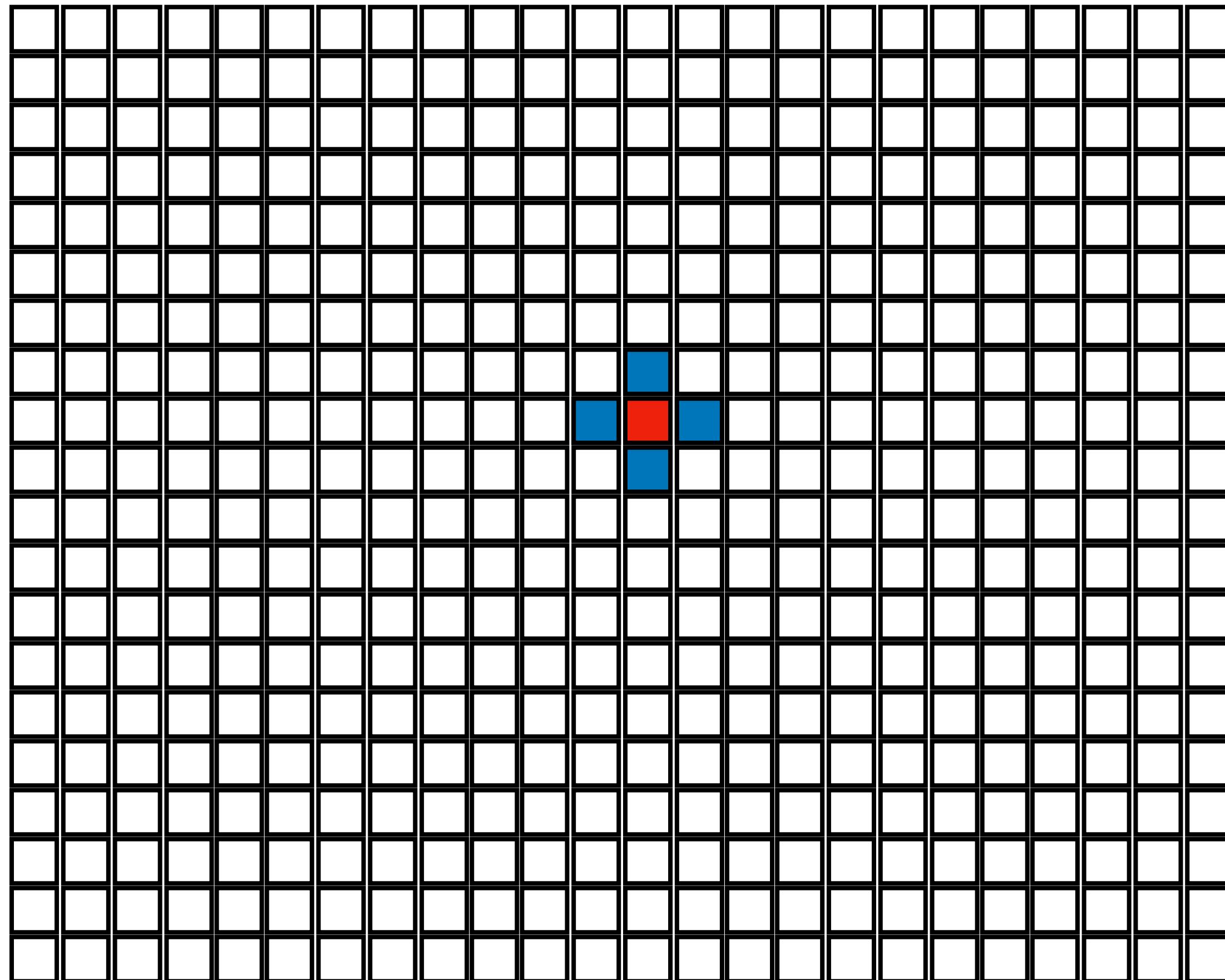
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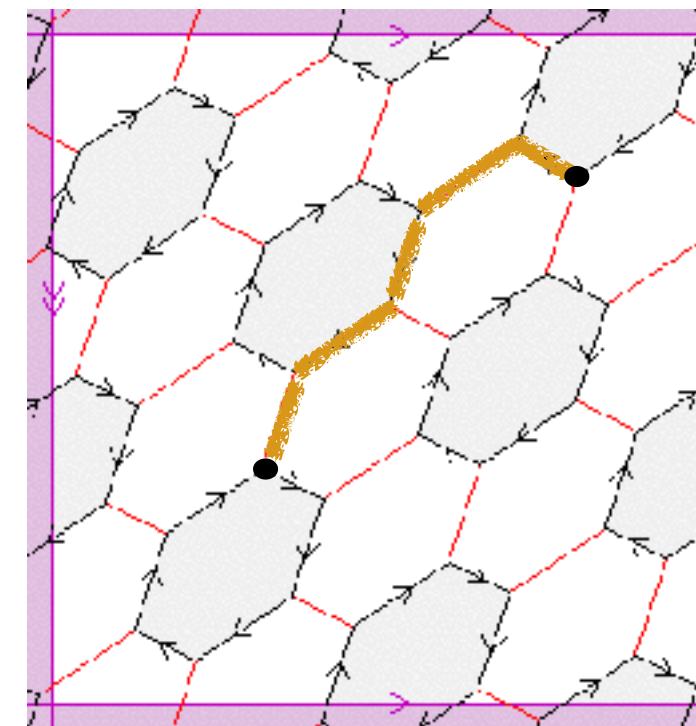
$x_0 \rightarrow y \quad \forall y \in N(x_0)$

Emergent space-time

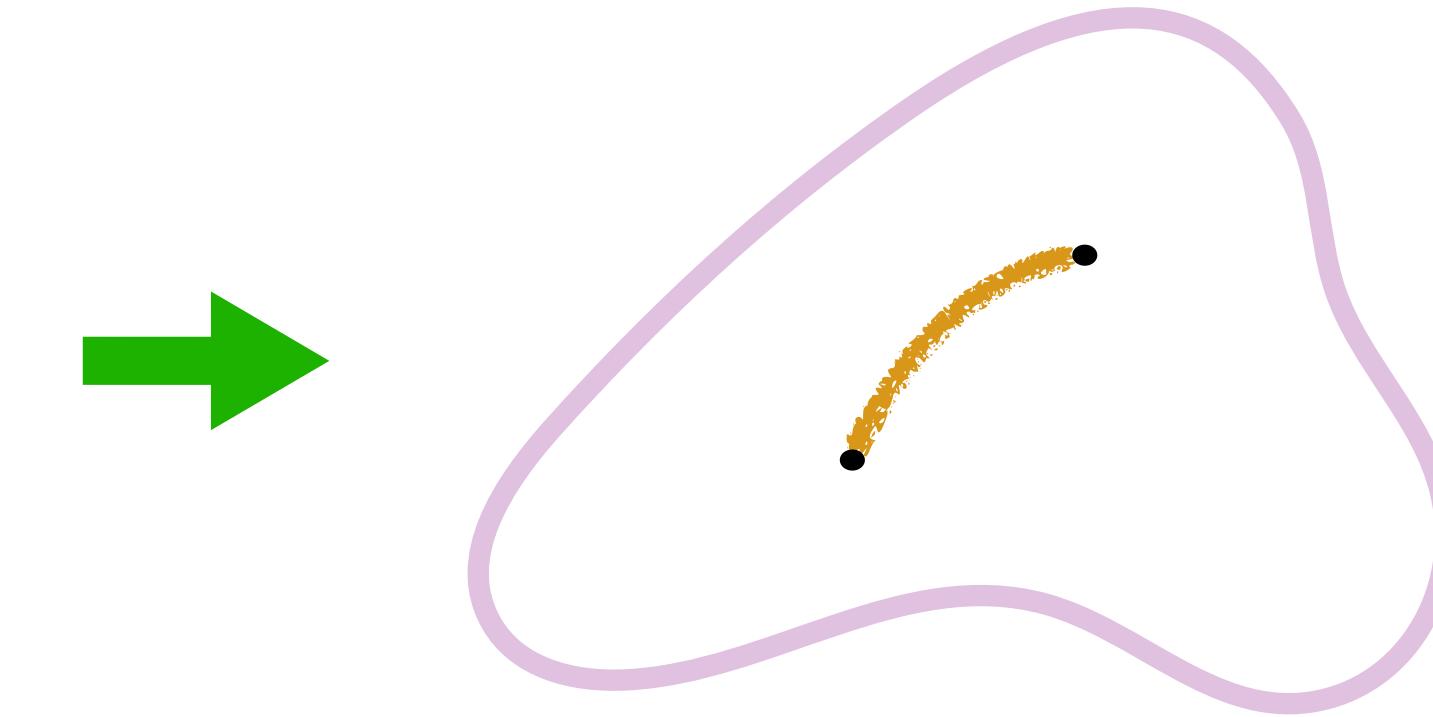
Properties of the evolution $W = \sum_{h \in S} T_h \otimes A_h$

Dynamical laws

$$i\partial_t \psi(\mathbf{k}, t) = \mathbf{k} \cdot \boldsymbol{\sigma}^\pm \psi(\mathbf{k}, t)$$



Essentially unique geometry

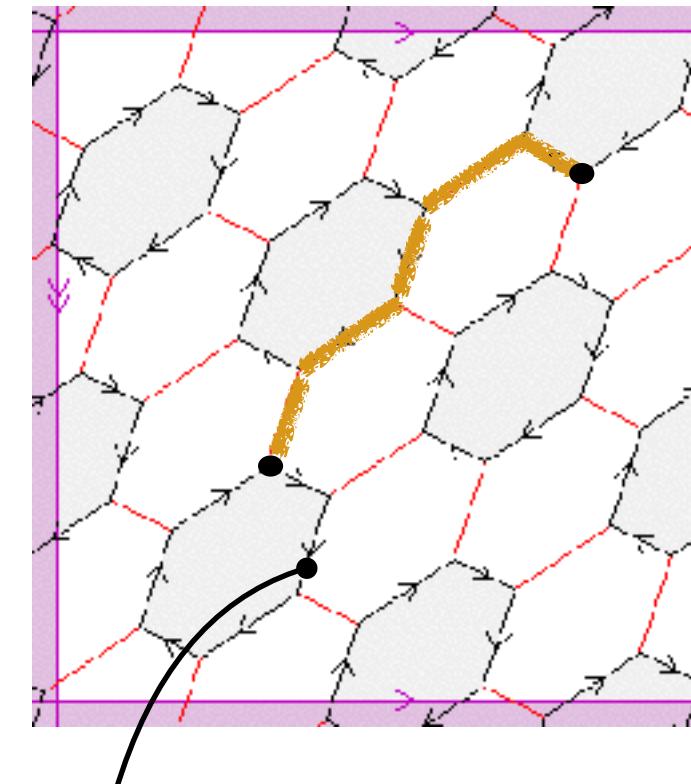


Emergent space-time

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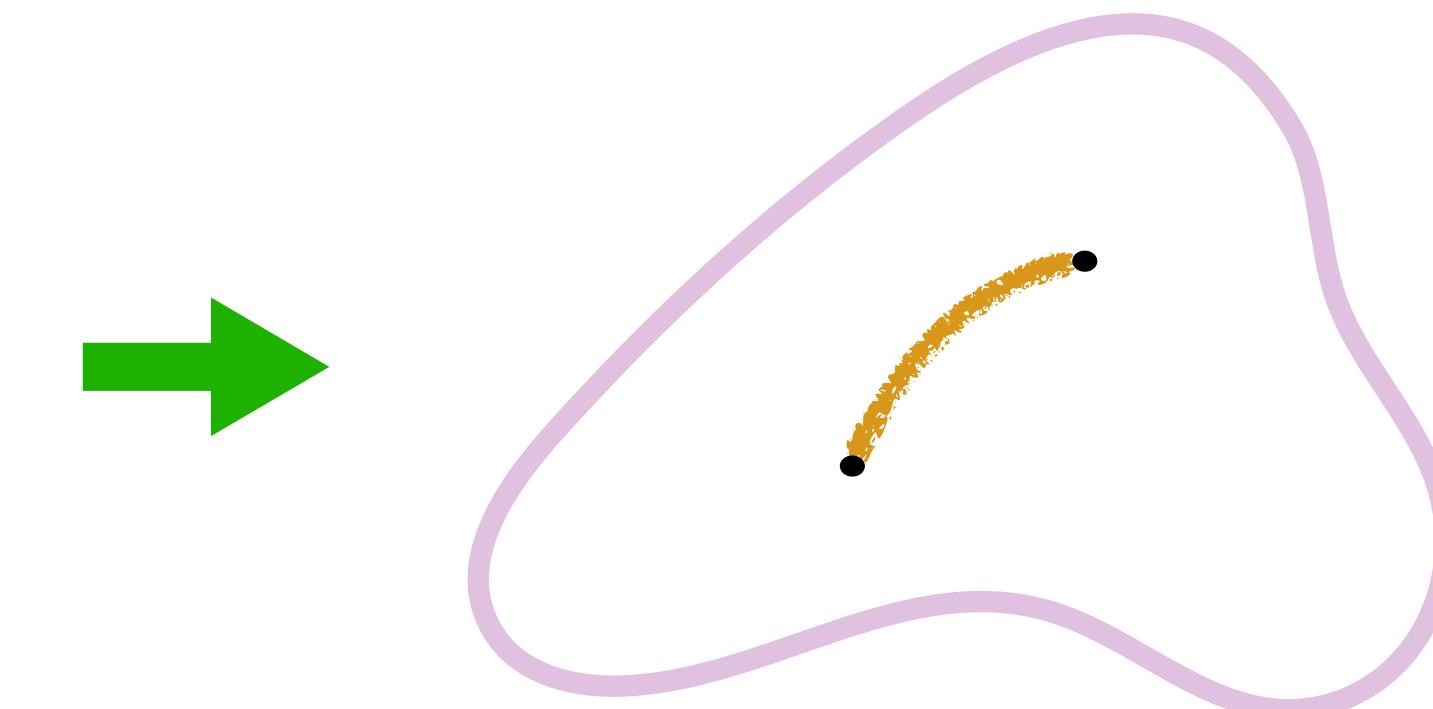
Dynamical laws

$$i\partial_t \psi(\mathbf{k}, t) = \mathbf{k} \cdot \boldsymbol{\sigma}^\pm \psi(\mathbf{k}, t)$$



Causal influence

Essentially unique geometry



Action equals reaction

- In CT: accidental consequence of translation invariance of physical laws
- It is universal in QT or in theories with no interaction without disturbance

Conclusion

- Proposal: (no) causal influence
- Relation with comb structure and (no) signalling
- Classical and Quantum theory
- No interaction without disturbance
- Cellular automata and causal relations

