

Dynamical screening of scalar waves in Cubic Galileon model

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Many attempts to extend General Relativity in the context of scalar(vector)-tensor theories

Required : GR should recover around the Sun
= scalar d.o.f. must be screened around a massive object

Screening mechanisms

- Potential : Chameleon/Symmetron
- 1st-derivative : k-mouflage
- 2nd-derivative : Vainshtein

e.g. Babichev, Deffayet, CQG30 (2013) 184001 [arXiv:1304.7240]

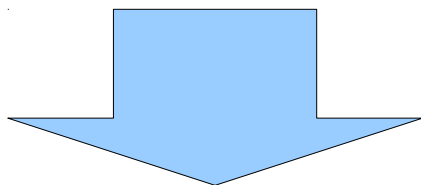
We use the Cubic Galileon model (with $g_{\mu\nu} = \eta_{\mu\nu}$)

Nikolis, Rattazzi, Trincherini, PRD79 (2009) 064036 [arXiv:0811.2197]

Deffayet, Esposito-Farese, Vikman, PRD79 (2009) 084003 [arXiv:0901.1314]

Deffayet, Deser, Esposito-Farese, PRD80 (2009) 064015 [arXiv:0906.1967]

$$S = \int d^4x \left[\frac{c_2}{2} (\partial\varphi)^2 + \frac{c_3}{2M^3} \square\varphi (\partial\varphi)^2 + \frac{\beta}{2m_{\text{pl}}} \rho\varphi \right]$$



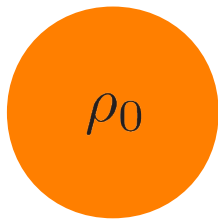
$$c_2 \square\varphi + \frac{c_3}{M^3} [(\square\varphi)^2 - \partial_\mu \partial_\nu \varphi \partial^\mu \partial^\nu \varphi] = \frac{\beta}{2m_{\text{pl}}} \rho$$

Static case

$$c_2 \nabla^2 \varphi + \frac{c_3}{M^3} [(\nabla^2 \varphi)^2 - \partial_i \partial_j \varphi \partial^i \partial^j \varphi] = -\frac{\beta}{2m_{\text{pl}}} \rho$$

Spherical star

$$\varphi'(r) = \frac{r}{4c_3} \left(-1 + \sqrt{1 + \frac{r_*^3}{r^3}} \right)$$



$$\varphi'(r) \propto \frac{1}{r^{1/2}}$$

$$\varphi'(r) \propto \frac{1}{r^2}$$

Vainshtein radius : $r_* = \left(\frac{4c_3 \beta \rho_0}{3c_2^2 M^3 m_{\text{pl}}} r_s^3 \right)^{1/3}$

Spherical star

→ scalar dof is suppressed near the star

Non-spherical cases

→ the suppression becomes weak

Bloomfield, Burrage, Davis, PRD91 (2015) 083510 [arXiv:1408.4759]

Binary star

→ deviating from superposition of Galileon fields sourced by them

TH, Hu, Koyama, Schmidt, PRD, arXiv:1101.5210

Disk system

→ anti-screening near the centre of disk

Ogawa, TH, Kobayashi, CQG, arXiv:1802.04969

Yet another effect on Vainshtein mechanism

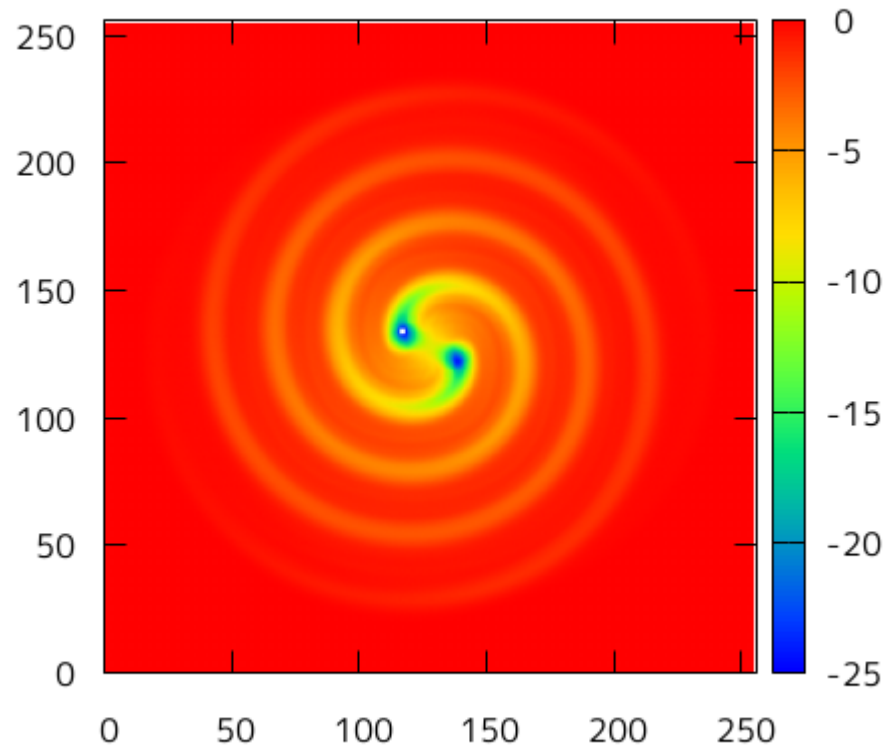
$$\partial_{\mu}\partial_{\nu}\varphi\partial^{\mu}\partial^{\nu}\varphi \ni (\partial_i\dot{\varphi})^2$$

This term emerges when the system is dynamical, e.g., scalar wave radiation.

Can this term suppress the scalar wave radiation ?

3D simulations are too heavy to survey the parameter space

(→ Claudia de Rham's talk last week)



So, let us switch to 1D spherical system

Field redefinition

$$c_2 \square \varphi + \frac{c_3}{M^3} [(\square \varphi)^2 - \partial_\mu \partial_\nu \varphi \partial^\mu \partial^\nu \varphi] = \frac{\beta}{2m_{\text{pl}}} \rho$$

$$\rho(t, x) = \rho_0 [1 + \Xi(t)] \Theta(x)$$
$$x = \frac{r}{r_0} \quad \frac{t}{r_0} \rightarrow t \quad \frac{\varphi}{c_2 M^3 r_0^2} \rightarrow \varphi \quad \mu = \frac{\beta \rho_0}{c_2^2 M^3 m_{\text{pl}}}$$

$$\square \varphi + c_3 [(\square \varphi)^2 - \partial_\mu \partial_\nu \varphi \partial^\mu \partial^\nu \varphi] = \frac{\mu}{2} [1 + \Xi(t)] \Theta(x)$$

Static part + time-dependent part

$$\varphi(t, x) = \varphi_0(x) + \pi(t, x)$$

Evolution equation of $\pi(t, x)$

$$\ddot{\pi} = \frac{2x^2 K^2 \pi'' + 4xL\pi' + 4c_3 K (x^2 \dot{\pi}'^2 + 2x\pi'\pi'' + \pi'^2) - \mu x^2 K \Xi(t) \Theta(x)}{2x [2c_3 K (2\pi' + x\pi'') + xJ]}$$

Linearised equation

$$\ddot{\pi} = \frac{K^2}{J} \pi'' + \frac{2L\pi'}{xJ} - \frac{\mu K}{2J} \Xi(t) \Theta(x) \quad \left\{ \begin{array}{l} y(x) = \frac{1}{4} \left[-1 + \sqrt{1 + 4c_3 \mu \frac{U(x)}{x^3}} \right] \\ K(x) = 4y(x) + 1 \\ L(x) = 4y(x)^2 + 2y(x) + 1 + c_3 \mu \Theta(x) \\ J(x) = 12y(x)^2 + 4y(x) + 1 + c_3 \mu \Theta(x) \end{array} \right.$$

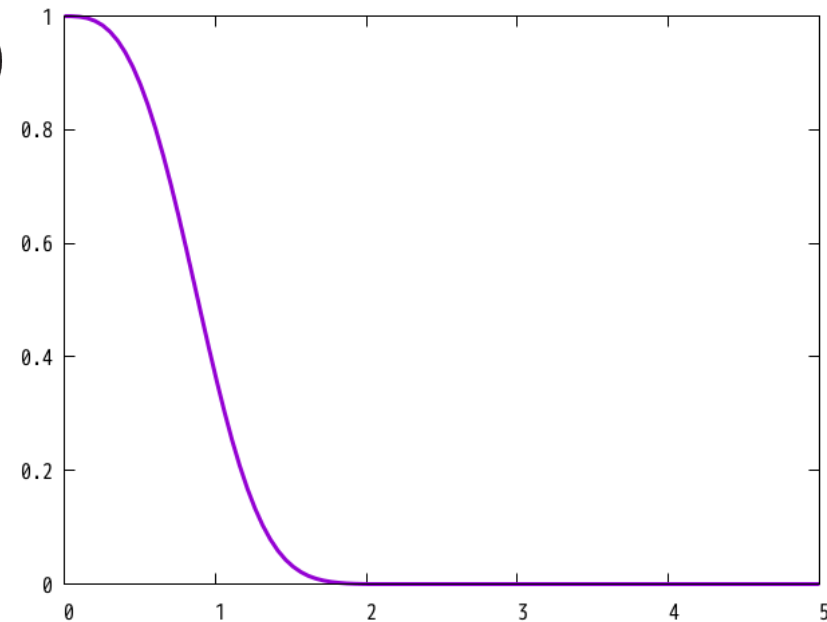
Time-dependent density field (sinusoidal + Gaussian-like)

$$\rho(t, x) = \rho_0 [1 + \Xi(t)] \Theta(x)$$

Density profile $\Theta(x) = e^{-x^3}$

Enclosed mass $U(x) = \int \Theta(x) x^2 dx = \frac{1}{3} (1 - e^{-x^3})$

Time-dependence $\Xi(t) = A \sin(\omega t)$
($A < 1$)



$$\Xi(t) = A \sin(\omega t)$$

$$\square\varphi + c_3 [(\square\varphi)^2 - \partial_\mu\partial_\nu\varphi\partial^\mu\partial^\nu\varphi] = \frac{\mu}{2} [1 + \Xi(t)]\Theta(x)$$

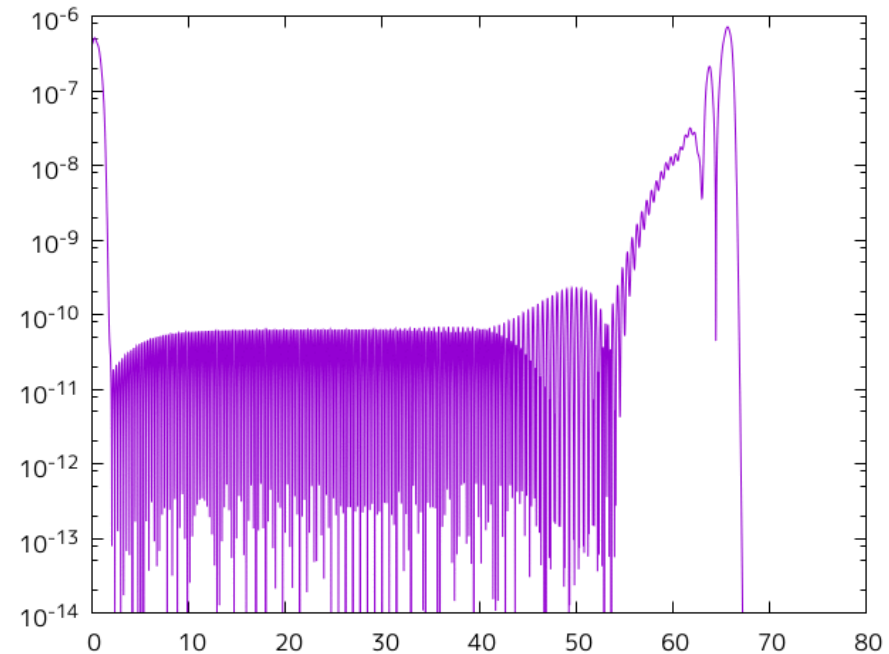
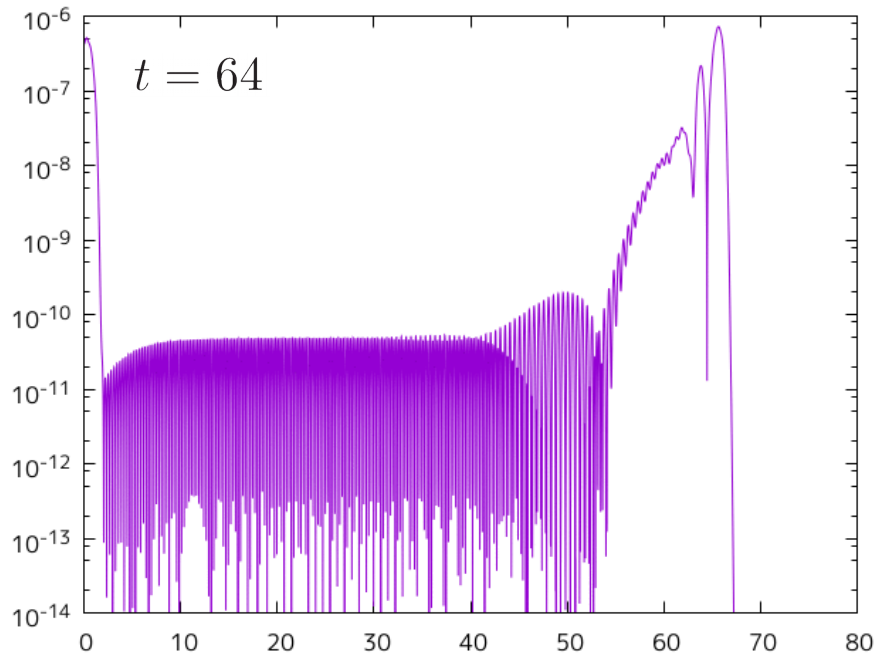
Fiducial parameters

A	Amplitude of pulsation	$A = 0.3$
ω	Frequency of pulsation	$\omega = 4\pi$
μ	Matter coupling constant	$\mu = 1$
c_3	Non-linear coupling constant	$c_3 = 100$

$$\text{Energy density of } \pi(t, x) : \rho_\pi = \dot{\pi}^2 + \pi'^2$$

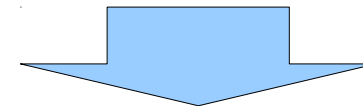
Non-linear

Linearised



Star

Artifacts caused by
initial conditions

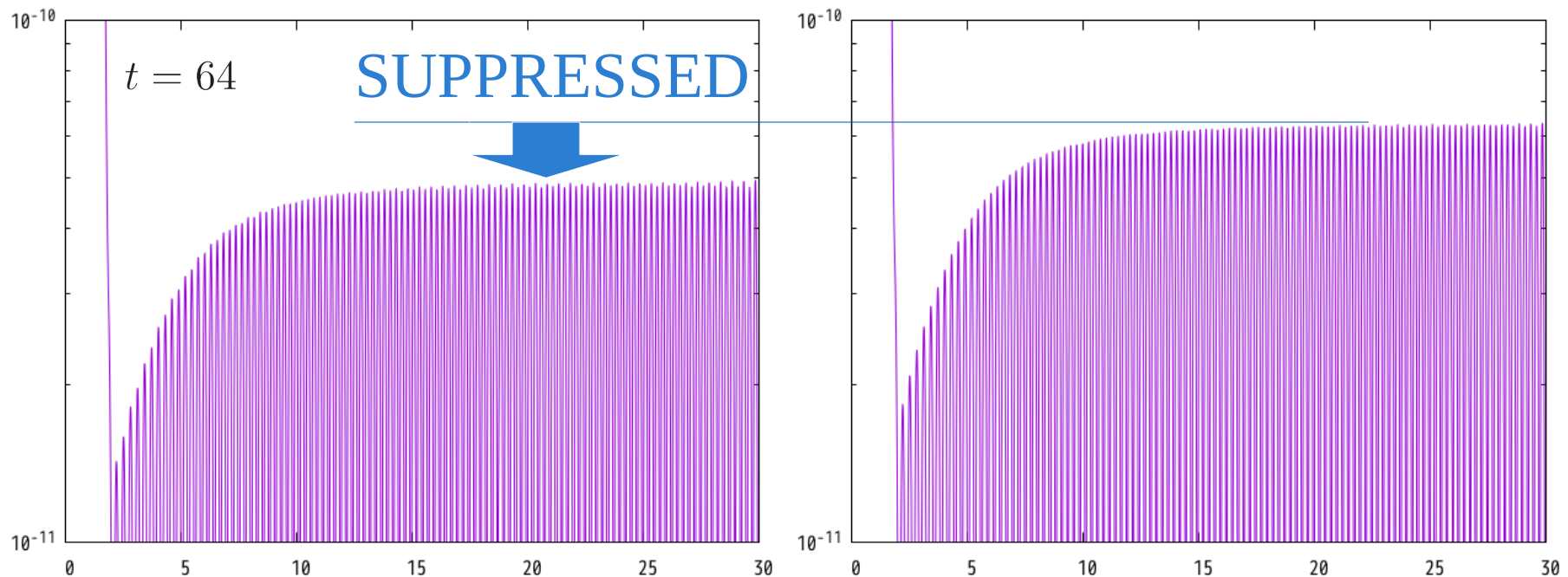


zoom..

$$\text{Energy density of } \pi(t, x) : \rho_{\pi} = \dot{\pi}^2 + \pi'^2$$

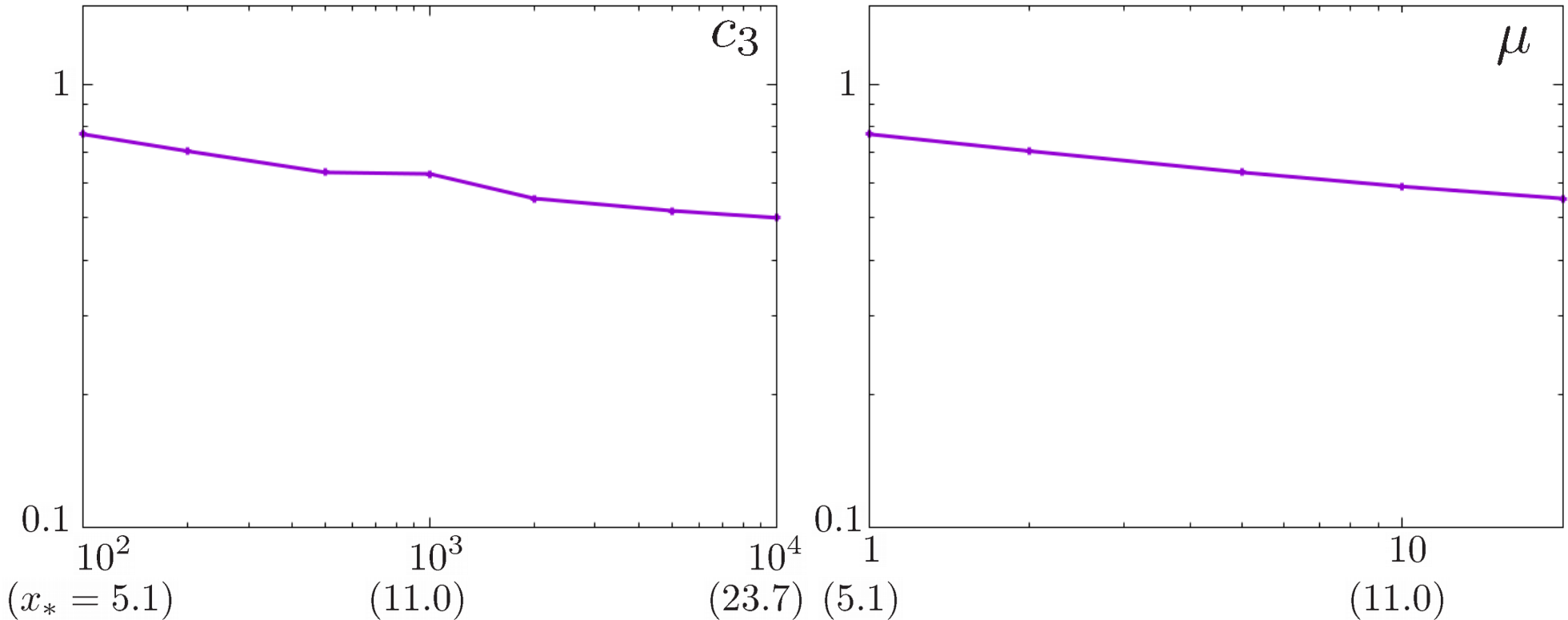
Non-linear

Linearised



Amplitude of radiated scalar wave is suppressed by $\sim 20\%$.

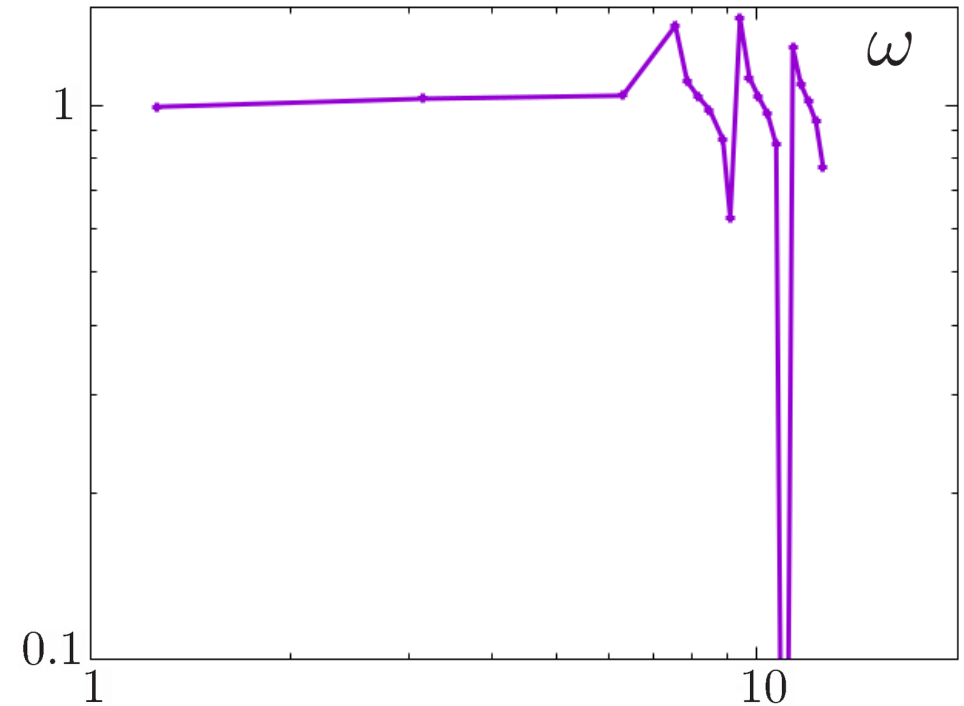
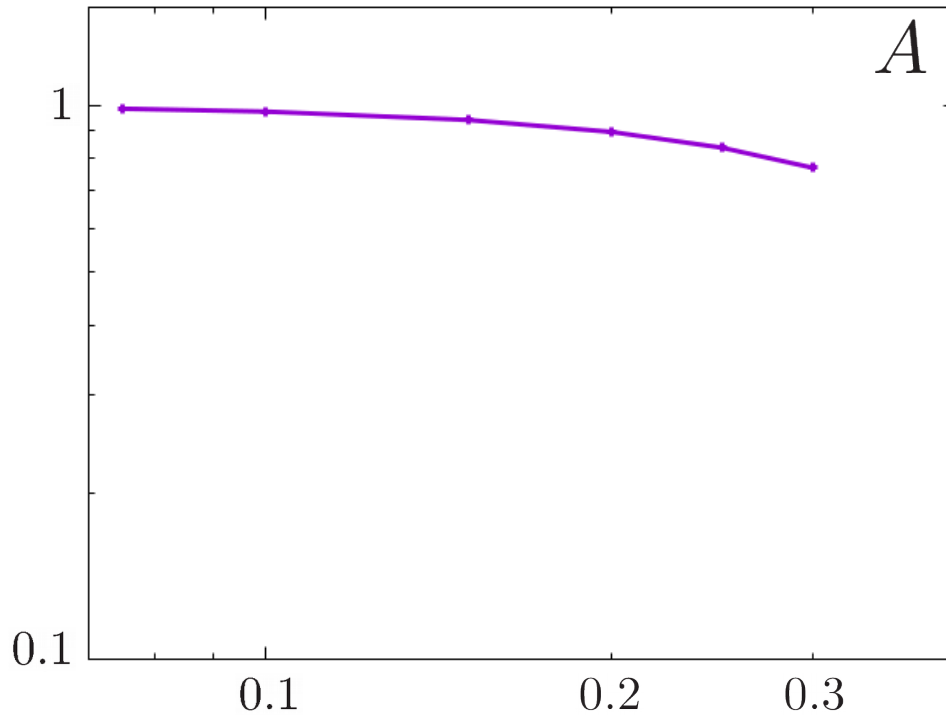
Non-linear/Linearised



$$x_* \equiv \frac{r_*}{r_s} = \left(\frac{4}{3} c_3 \mu \right)^{1/3}$$

As the non-linearity or matter coupling becomes stronger, the wave is more suppressed.

Non-linear/Linearised



For larger pulsation amplitude, the wave is more suppressed.

Linear equation has resonant nature.

→ we should carefully consider

We investigate dynamical effects of Vainshtein mechanism in the cubic Galileon model.

Finding : scalar waves from a pulsating star are suppressed by non-linear effects.

To-do

- resonant nature of the linearised equation (ω dependence)
- should go to 3D again ?