

Interaction and drag in non-equilibrium environments: from the study of granular materials

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collaboration with Takahiro Tanabe (Meiji Univ.)

Rheology of disordered particles-suspensions, glassy and granular particles-
Talk on June 21st, 2018

Outline

- Introduction: What do we know about drag in granular media?
- Previous study for pure 2D drag in granular media
- Previous studies on the interaction between intruders
- Simulations of two intruders in 2D granular media
 - Two intruders in a steady motion
 - Two intruders under an oscillation
- Phenomenological theory for the drag and the interactions for intruders
- Discussion & conclusions

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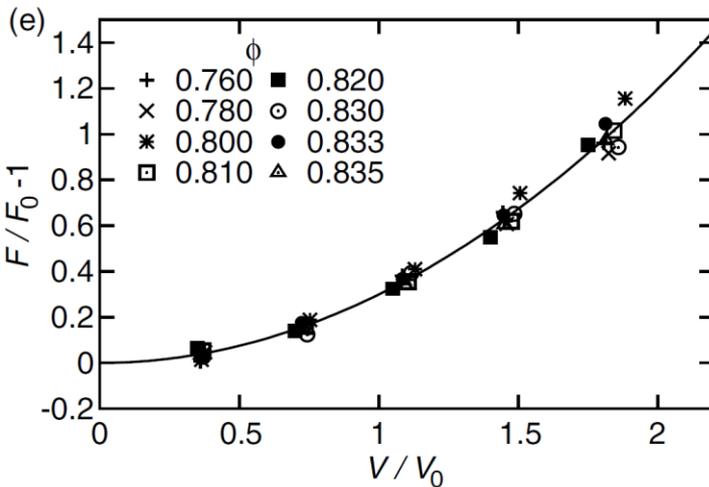
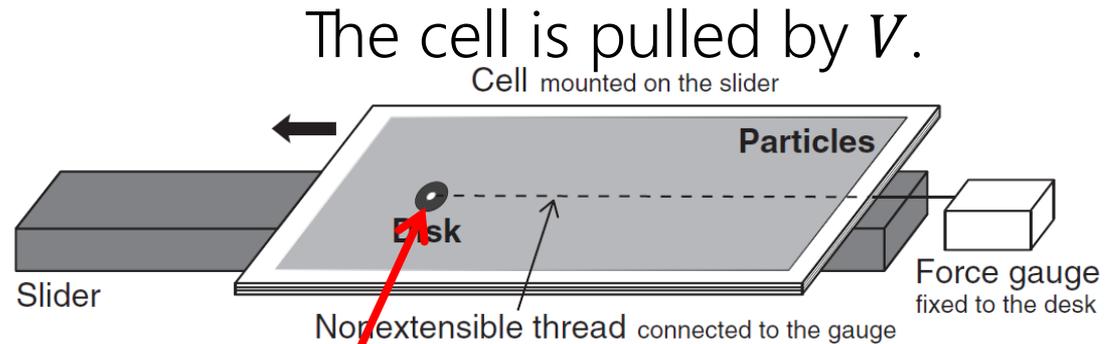
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Introduction

Drag law in a granular media

Y. Takehara & K. Okumura,
PRL, 112, 148001 (2014).

Experimental setup



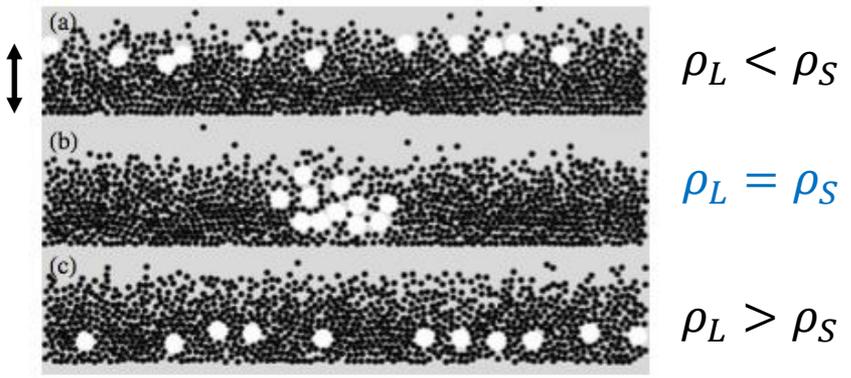
The disk is fixed by a wire.

See S. Takada's talk yesterday.

Interactions of intruders in granular assemblies

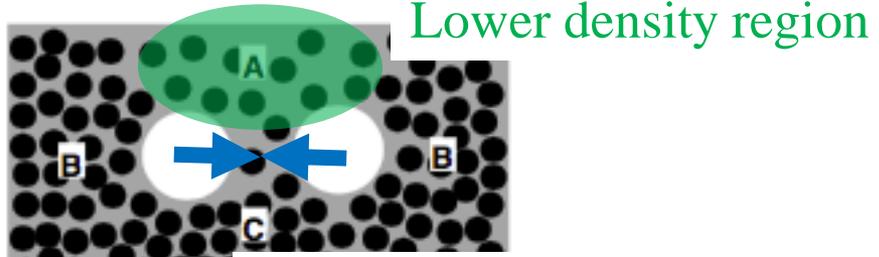
Brazil Nuts Effect (ED)

D. A. Sanders, et al, PRL, **93**, 20, (2004)



$\rho_L / \rho_S \approx 1.0 \Rightarrow$ **Attraction**
 ρ_L, ρ_S : Large/Small granular density

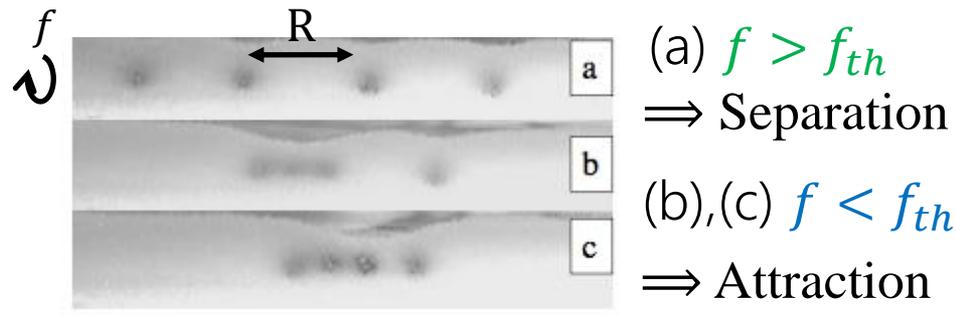
Mechanism



More collisions at region B than region A cause **attraction** (going to lower density)

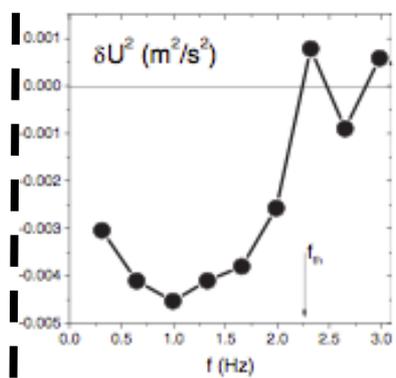
Rolling Cylinder (Exp.)

I. Zuriguel, et al, PRL, **95**, 258002, (2005)



$f < f_{th} \Rightarrow$ **Attraction**
 $f > f_{th} \Rightarrow$ **Separation**

Mechanism



$f < f_{th} \Rightarrow \delta U^2 < 0$
 (large fluctuation outside)
 $\Rightarrow \delta P = \rho \delta U^2 / 2 < 0$
 Pressure difference makes **attraction**.

$$\delta U^2 = -[U_{rms}(out)^2 + V_{rms}(out)^2 - (U_{rms}(in)^2 + V_{rms}(in)^2)]$$

Purpose of this talk

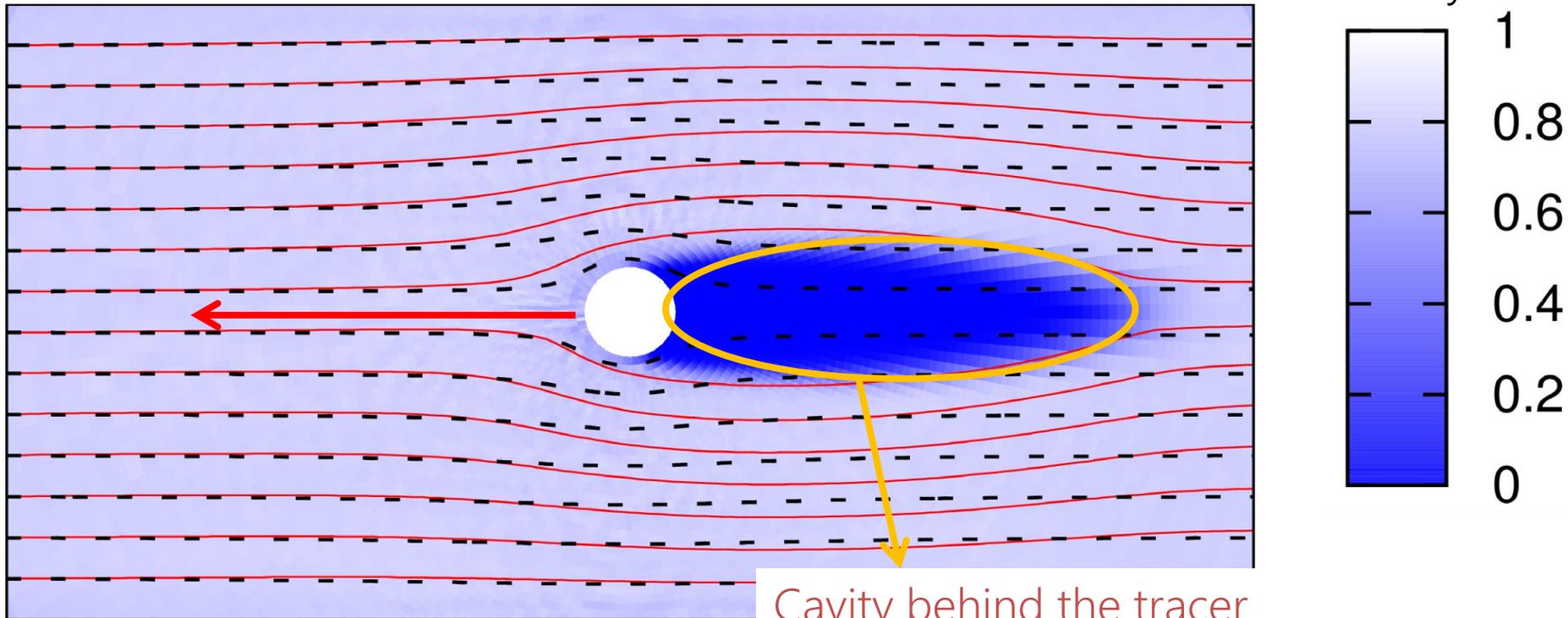
- This talk is dedicated to the **theory** for the drag force and the interaction of intruders mainly in granular media
- For this purpose, we review previous works.
- Then, we introduce recent numerical simulations by Tanabe.
- Finally, I will explain some **phenomenological theories** to understand the results of simulations and experiments.

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Density profile & Streamline

Streamline
—: MD result
---: perfect fluid

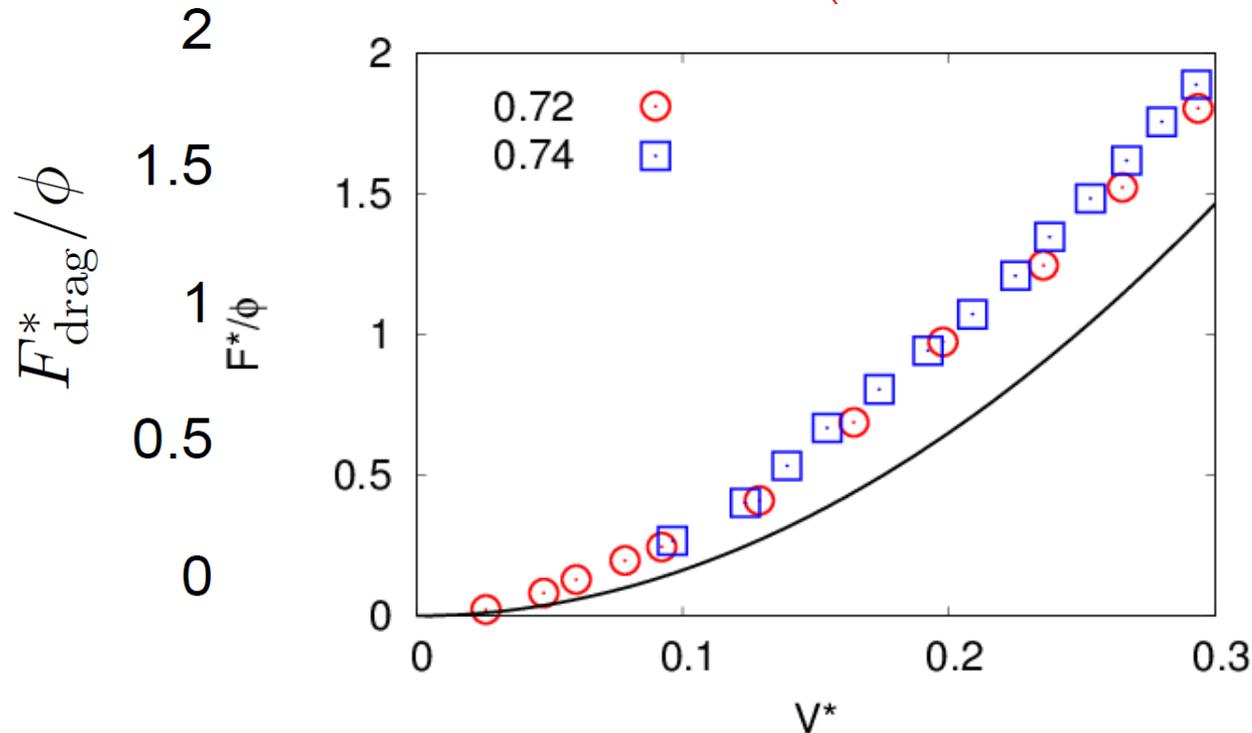


Cavity behind the tracer
(Dead water model can be used.)

The streamline obtained from MD
is well fitted by that of the **perfect fluid**.

Comparison with simulation result

$$F_{\text{drag}} = \left(\frac{3 + 2e}{2} - \frac{2}{3} \sin^2 \theta_0 \right) \sin \theta_0 D \rho V^2$$



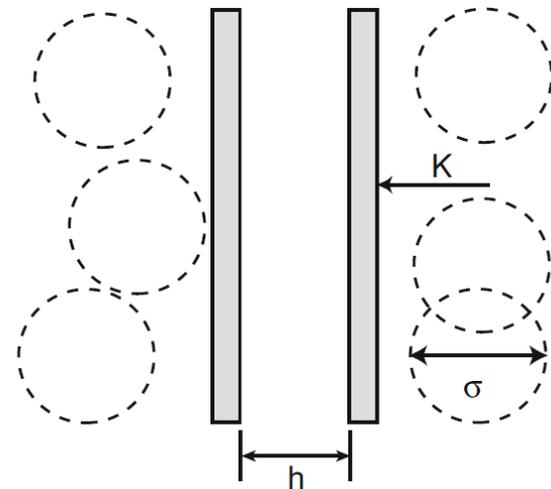
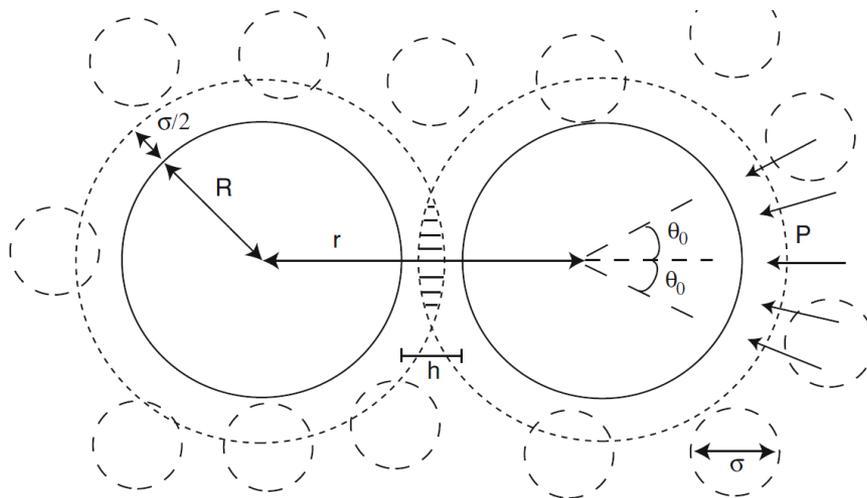
Simulation results are well fitted **without any fitting parameters** !
This is consistent with Chicago group for granular jet.

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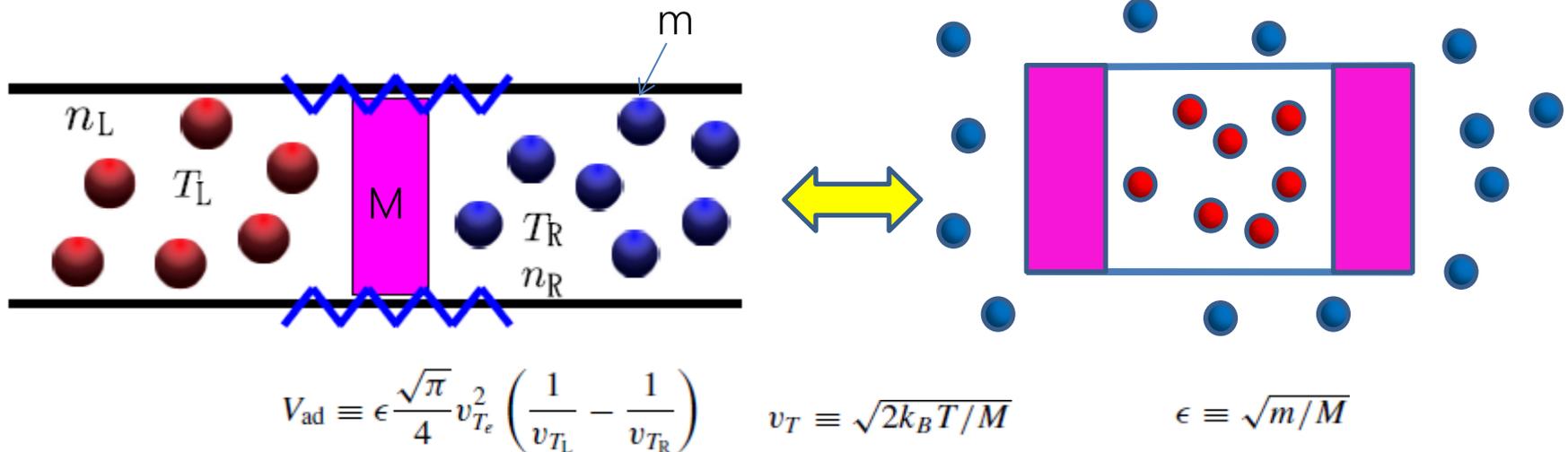
Depletion force & adiabatic piston

- * The problem is related to the depletion force (in a constriction region).
- * Note that the conventional depletion force is the result of the violation of the pressure balance => **acceleration**.
- * However, we are interested in the adiabatic motion **under the pressure balance**. => Casimir effect or adiabatic piston



The adiabatic piston

- * The adiabatic piston problem is equivalent to **fluctuating 1d depletion force** problem.
- * If the density is lower in the depletion region, the attractive interaction between pistons exist **under the pressure balance** as a result of non-Gaussian correction.



Interaction of non-Gaussian systems

We begin with the generalized Fokker-Planck equation:

$$\partial_t P = \sum_k^N \{ \gamma^{-1} \nabla_k (P \nabla_k U) + \mathcal{L}_k P \}$$

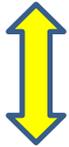
$$\mathcal{L}_k = \lambda \int \sum_{n=1}^{\infty} \frac{(-\mathbf{x} \cdot \nabla_k)^n}{n!} \mathcal{W}(\mathbf{x}) d\mathbf{x} = \lambda \int (e^{-\mathbf{x} \cdot \nabla_k} - 1) \mathcal{W}(\mathbf{x}) d\mathbf{x}.$$

$$\mathcal{L}_k = \lambda [\tilde{\mathcal{W}}(i \nabla_k) - 1]. \quad \tilde{\mathcal{W}}(\mathbf{q}) := \int d\mathbf{x} e^{-i\mathbf{q} \cdot \mathbf{x}} \mathcal{W}(\mathbf{x})$$

If the hopping is nonlocal, we need higher order derivative in Fokker-Planck equation.

Effective interaction in steady state

$$0 = \gamma^{-1} P_{\text{ss}} \nabla_k U + D b_{d\nu} \nabla_k (1 - a^2 c_{d\nu} \nabla_k^2) P_{\text{ss}}$$



$$P_{\text{ss}} = \frac{e^{-\beta U}}{Z} [1 - a^2 \beta W + O(a^4)]$$

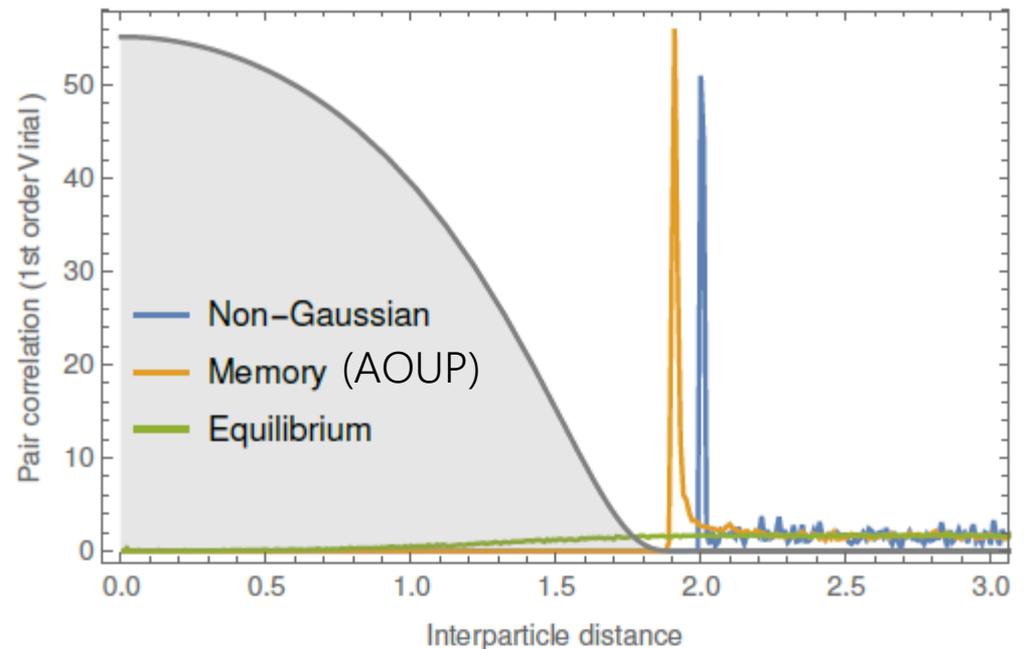
$$\beta = 1/(\gamma D b_{d\nu})$$

$$W = c_{d\nu} \left\{ \beta \sum_{k=1}^N \nabla_k^2 U - \frac{3\beta^2}{2} \sum_{\{k,\ell\}=1}^N \nabla_k U \cdot \nabla_\ell U + \beta^3 \int (\nabla_k U)^3 d\mathbf{r} \right\}$$

Non-Gaussian noise and AOUP

- Both models have effective attractive interactions.
- Nevertheless, the AOUP exhibits strong phase separation but the non-Gaussian model does not.

AOUP=Active Ornstein Uhrenbeck process
Fodor et al., PRL 117, 038103 (2016).

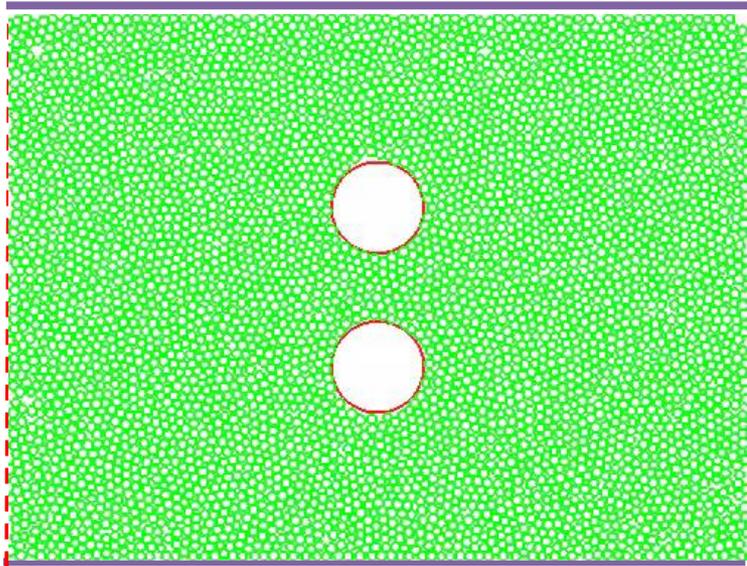


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Simulation for two intruders

$$v_{ex}^x = V^* (D \sqrt{k_n / M_S})$$



- Fixed flat wall $L_y = 60D_S$
- Periodic boundary $L_x = 80D_S$
- Two intruders are pinned in system

$$m_i \ddot{\mathbf{r}}_i = \sum_j F_c^{i,j} + F_{ex}$$

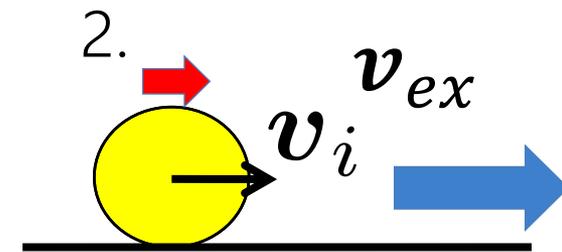
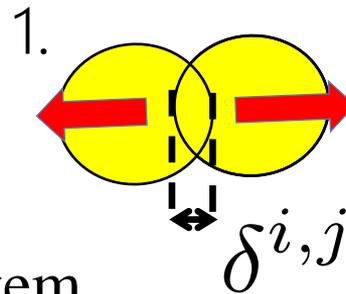
i : Disk index
 \mathbf{r}_i : Position m_i : Mass

1. Repulsive force (only normal force)

$$F_c^{i,j} = k_n \delta^{i,j} \mathbf{n}^{i,j} - \gamma_n \mathbf{v}_n^{i,j}$$

2. Driving force (follow tray oscillation)

$$F_{ex} = -\mu(\mathbf{v}_i - \mathbf{v}_{ex})$$



Explanation for simulations

$$v_{ex}^x = V^* (D \sqrt{k_n / M_S})$$

- Diameter of disks (density: const.)

$$D_S = D(1 \pm 0.1r) : \text{Small disks}$$

$$D_L = 10D : \text{Intruder}$$

(poly-dispersity: Uniform distr.)

- Intruders are fixed on system with distance L_0 for y-direction

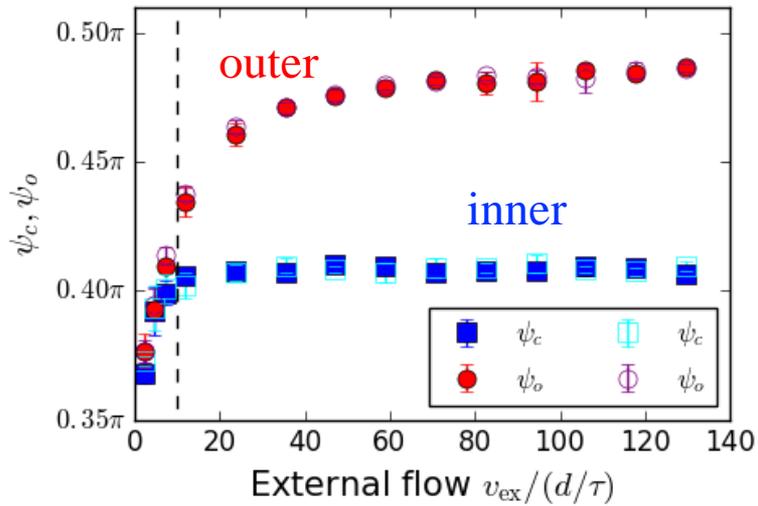
i : Disk index \mathbf{r}_i : Position m_i : Mass
--

- Control parameter: non-dimensional speed V^*

$$m_i \ddot{\mathbf{r}}_i = \sum_j F_c^{i,j} + F_{ex}$$

- Fixed flat wall $L_y = 60D_S$
- Periodic boundary $L_x = 80D_S$
- Two intruders are pinned or mobile in system

Separation angle: Low V differs from high V .

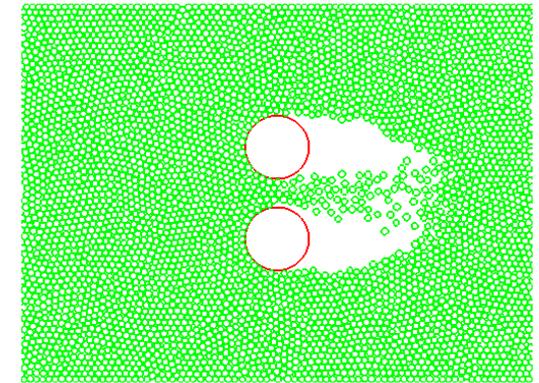
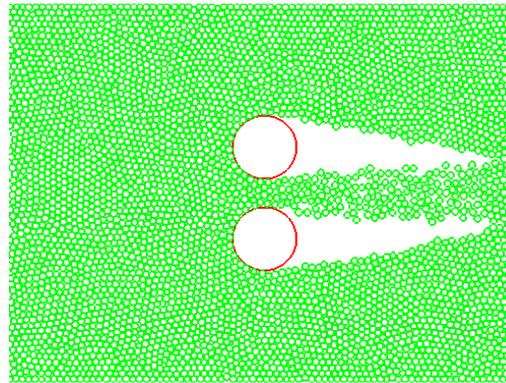


Flow time > relaxation time

$D/v_{ex} > \tau \Rightarrow v_{ex}\tau/d < 10$: Flow is different.

$$v_{ex}\tau/d = 4.71$$

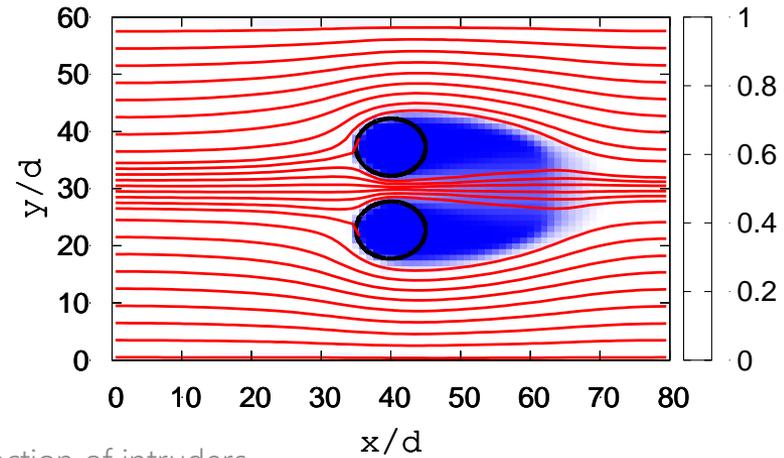
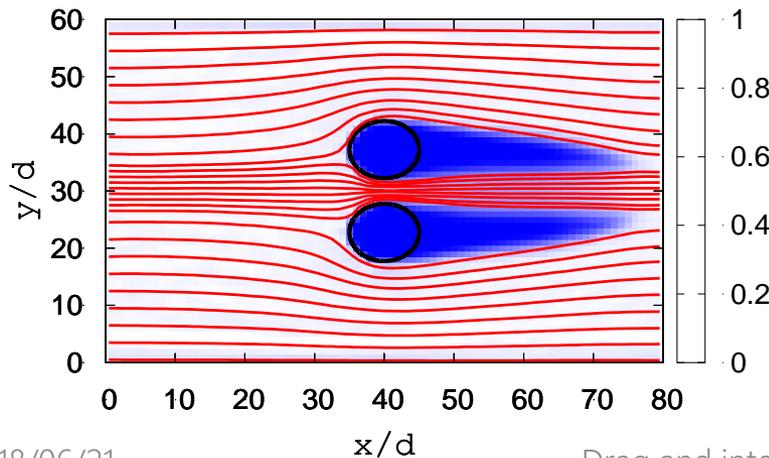
$$v_{ex}\tau/d = 23.57$$



$$v_{ex}\tau/d = 4.71$$

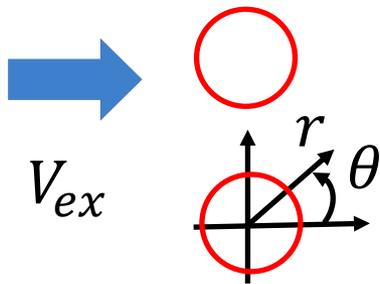
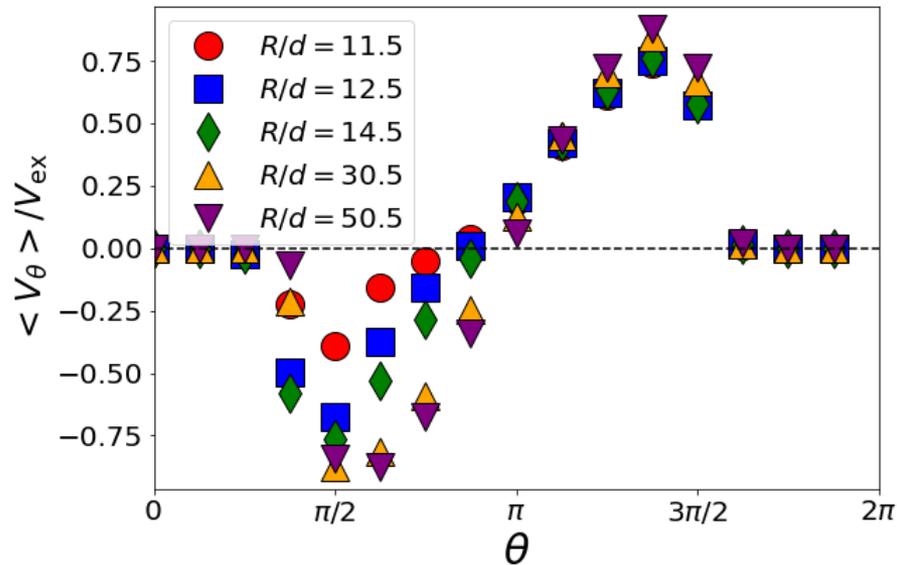
No coalescence of wakes

$$v_{ex}\tau/d = 23.57$$

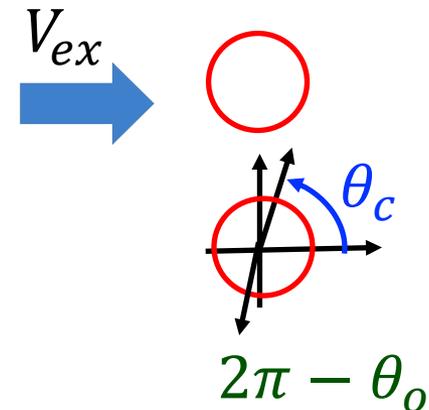
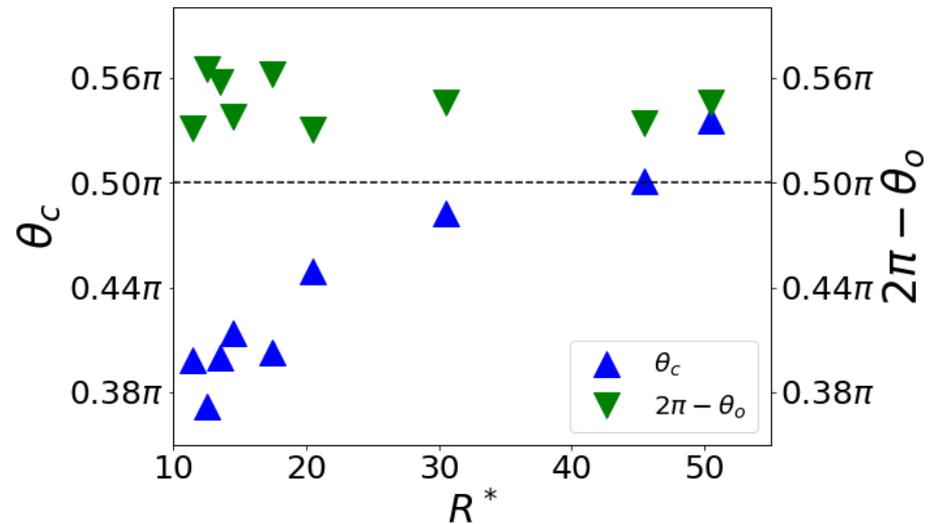


Granular flow : Velocity & Separation angle

Velocity field



Separation angle



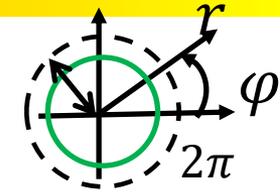
Granular temperature (steady flow)



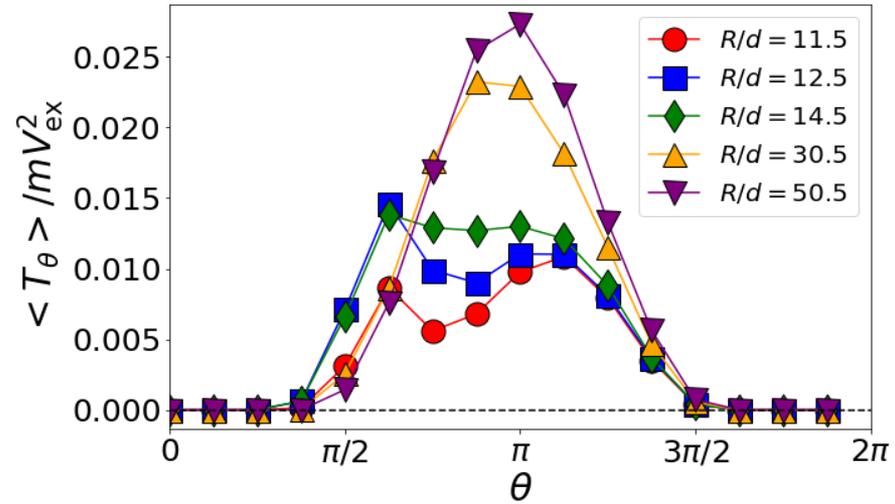
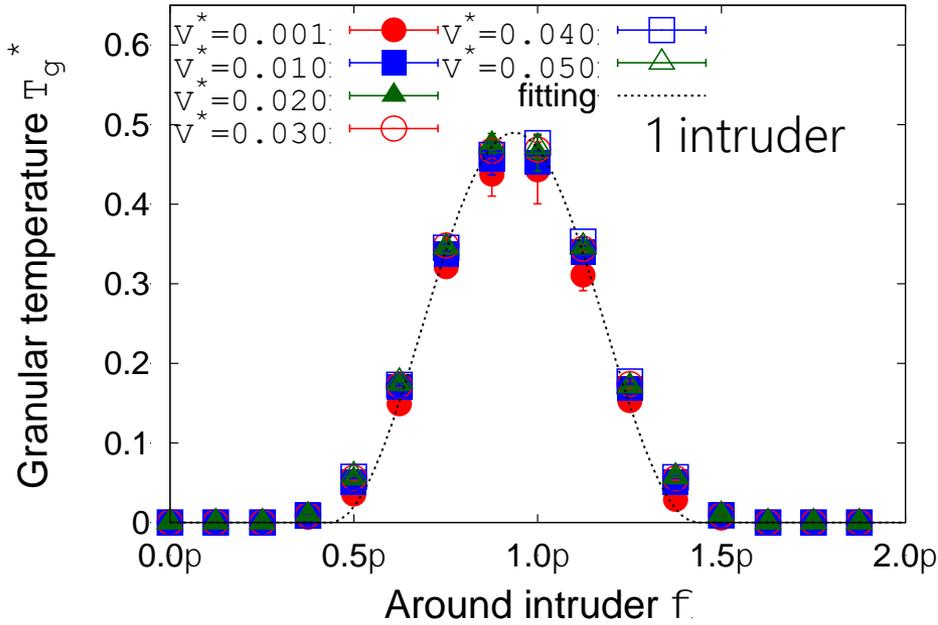
Fitting with $\cos^2 \theta$

2 intruders

$$(D_L + 2D)/2$$



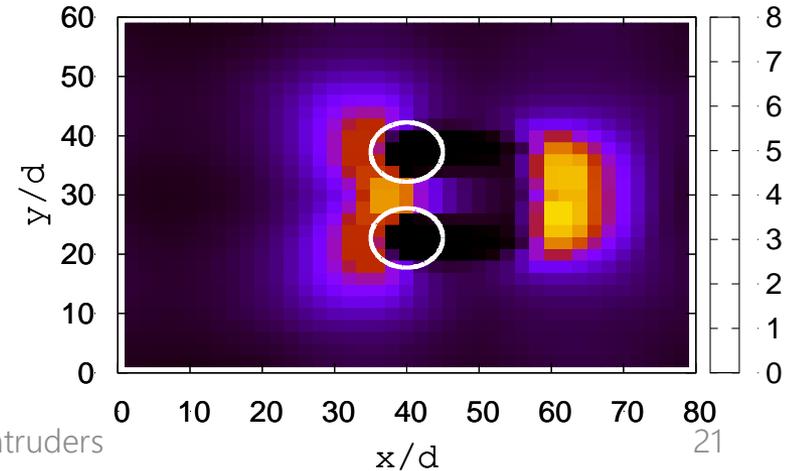
One intruder



$$T_G(\varphi) = \begin{cases} 0, & |\varphi + \Delta| < \varphi_S \\ \gamma(\cos((\varphi + \Delta) - \pi))^2, & \text{otherwise} \end{cases}$$

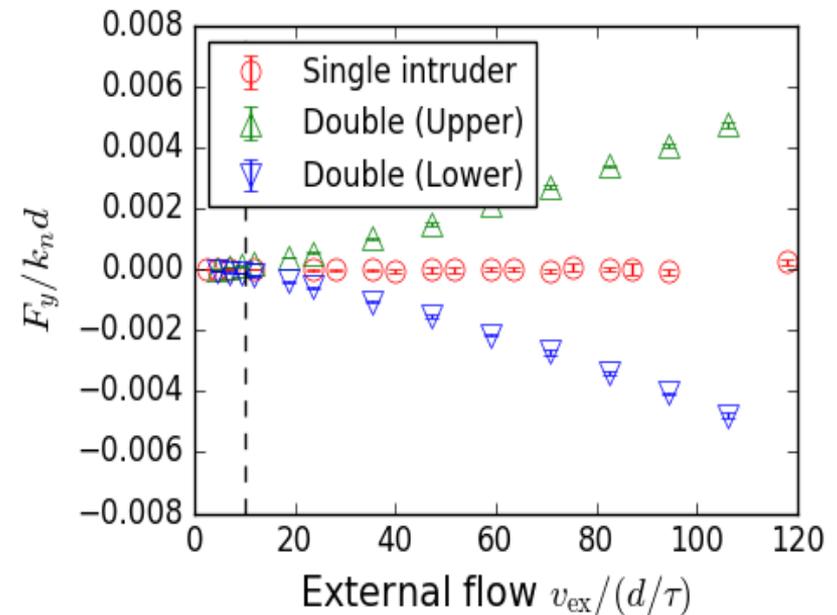
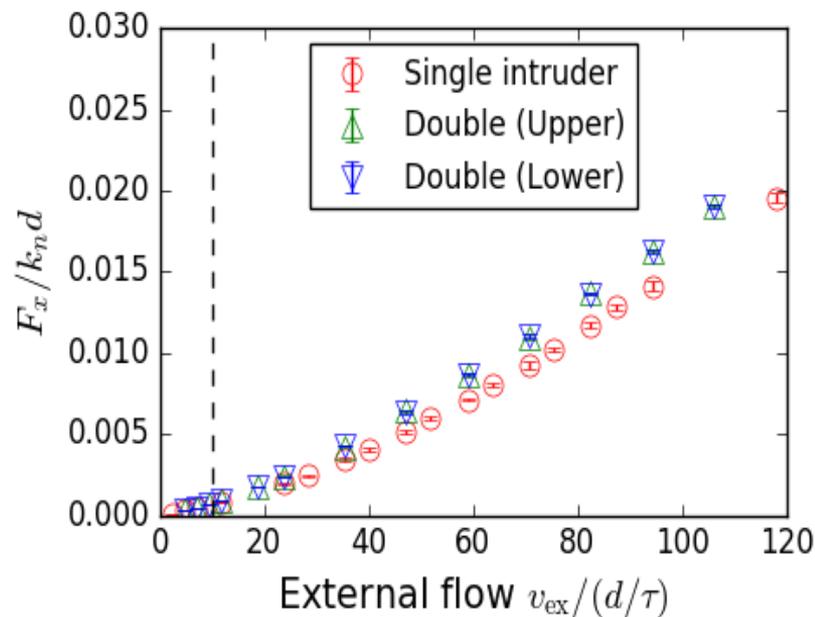
$$(\gamma = 0.47, \Delta = 0.203, \varphi_S = 1.5691)$$

(φ_S : separation angle)

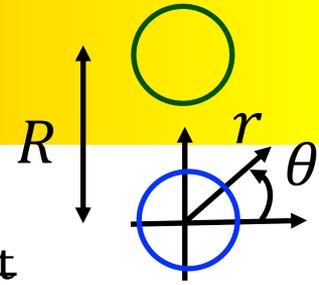


Repulsive force between two intruders

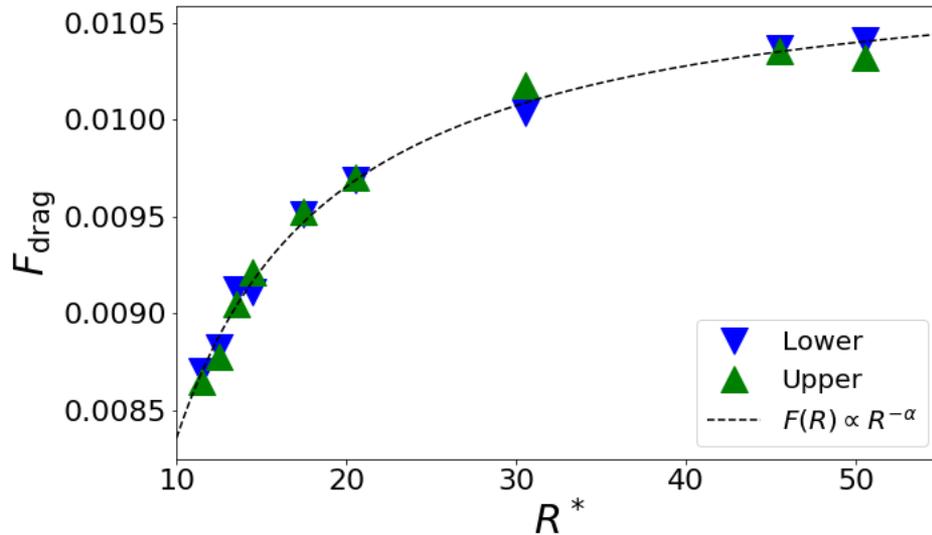
- The effective repulsive interaction exists between two.
- => This is contrast to perfect fluidity (Bernoulli).



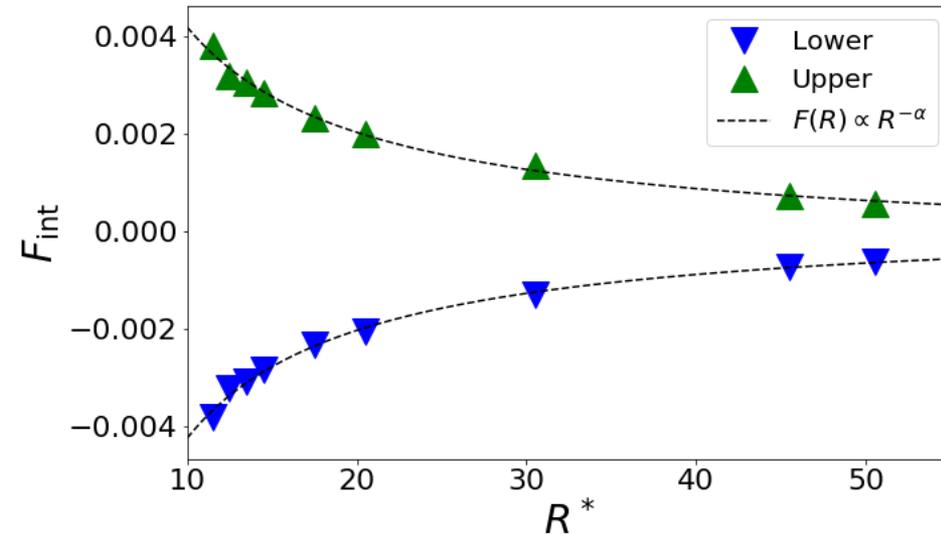
Drag & interaction force for R



Drag force F_{drag}



Interaction force F_{int}



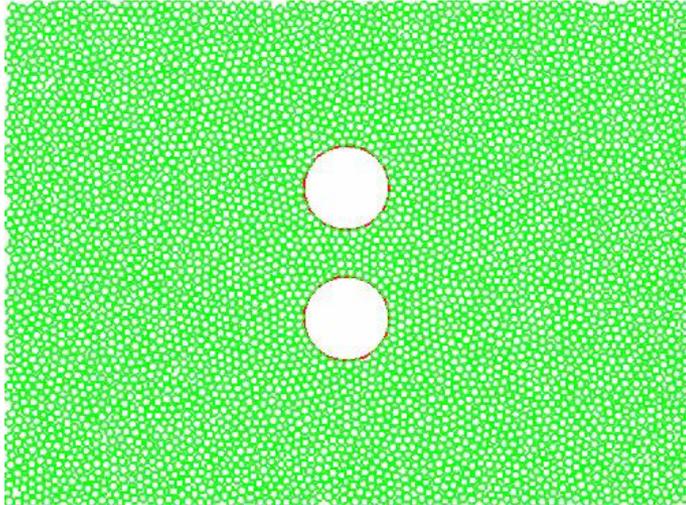
Both $F_{\text{drag}}(R)$ & $F_{\text{int}}(R)$ can be fit as $F(R) = a + bR^{-\alpha}$ ($\alpha \approx 1$).

F_{drag} is suppressed when R is small because the flow speed decreases.

F_{int} approaches 0 as increasing R .

Oscillatory flow

$$\underline{v_{ex}^x(t) = 2\pi A v \sin(2\pi v t)}$$



$$m_i \ddot{r}_i = \sum_j F_c^{i,j} + F_{ex}$$

i : Disk index
 r_i : Position m_i : Mass

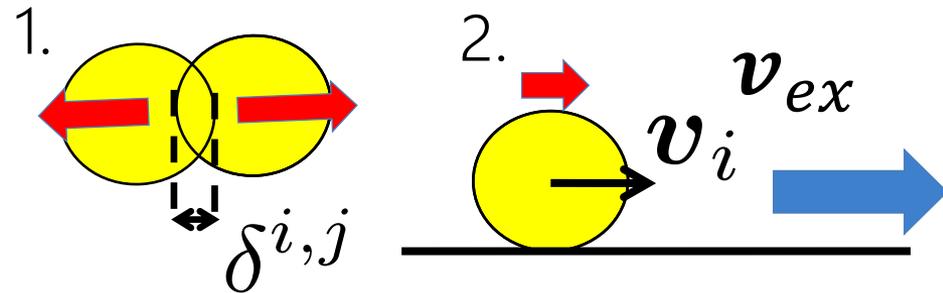
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2. Driving force (follow tray oscillation)

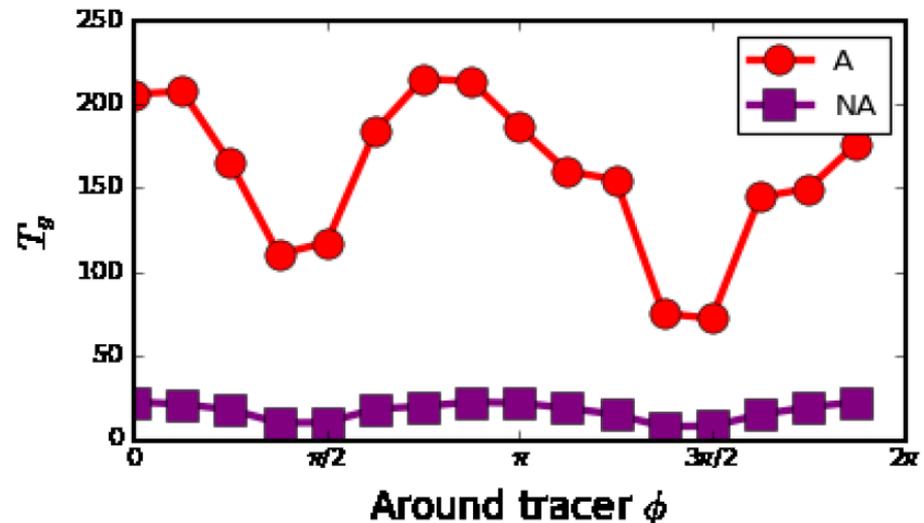
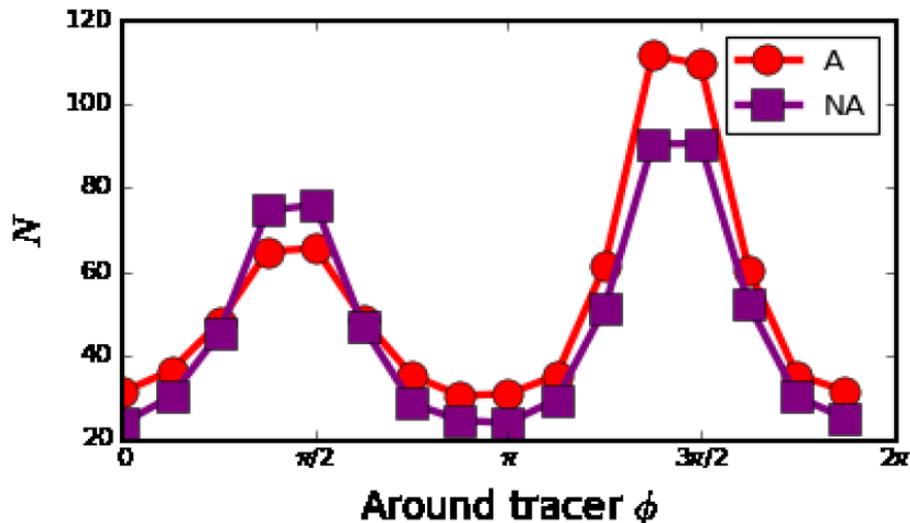
$$F_{ex} = -\mu(v_i - v_{ex})$$

- Fixed flat wall $L_y = 60D_S$
- Periodic boundary $L_x = 80D_S$



Origin of attractive force

- There are wakes in front and back of intruders.
- Grains in the channel are squeezed out.
- Density in the channel is much lower than that outside.
- Pressure difference exists.



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Outline of the theory

- We assume that **Enskog theory** for binary systems can be used.
- Then, the environment is assumed to be **Maxwellian**.
- Then, we adopt **Kramers-Moyal** expansion.
- We can determine the drag force if we know the temperature.
- The temperature is determined by a phenomenological simple model.
- The interaction is also guessed from a simple crude theory.

Enskog theory for mixtures

The distribution function for i -species $f_i(\mathbf{V}, t)$ for the velocity

$$\left(\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \right) f_i(\mathbf{V}, t) = \sum_{j=1}^2 J_{ij}^E(\mathbf{V} | f_i, f_j),$$

$$J_{ij}^E(\mathbf{V}_1 | f_i, f_j) = d_{ij} g_{ij} \int d\mathbf{V}_2 \int d\hat{\boldsymbol{\sigma}} \Theta(\hat{\boldsymbol{\sigma}} \cdot \mathbf{V}_{12}) (\hat{\boldsymbol{\sigma}} \cdot \mathbf{V}_{12}) \\ \times \left[\frac{1}{e_{ij}^2} f_i(\mathbf{r}, \mathbf{V}_i''; t) f_j(\mathbf{r} + \boldsymbol{\sigma}, \mathbf{V}_2''; t) - f_i(\mathbf{r}, \mathbf{V}_i; t) f_j(\mathbf{r} - \boldsymbol{\sigma}, \mathbf{V}_2; t) \right]$$

with the radial distribution at contact g_{ij} between i and j ,
the precollisional velocities \mathbf{V}_i'' , $\mathbf{V}_{12} = \mathbf{V}_1 - \mathbf{V}_2$
restitution coefficient e_{ij} between i and j

Model

intruder (mass M and the diameter D)
in another species (consisting of N identical disks of the mass m

a small parameter $\epsilon \equiv \sqrt{m/M}$

the geometric factor

$$\chi = \frac{1}{2}n(d + D)g_{dD}(\varphi)$$

$$g_{dD}(\varphi) = \frac{1}{1 - \varphi} + \frac{9\varphi}{16(1 - \varphi)^2}z \quad z = 2dD\langle\sigma\rangle/((d + D)\langle\sigma^2\rangle)$$

Boltzmann-Enskog equation

- Boltzmann-Enskog equations for the intruder and grains are given by

$$\frac{\partial P(\mathbf{V}, t)}{\partial t} = \int d\mathbf{V}' [W_{\text{tr}}(\mathbf{V}|\mathbf{V}')P(\mathbf{V}', t) - W_{\text{tr}}(\mathbf{V}'|\mathbf{V})P(\mathbf{V}, t)] + \mathcal{B}_{\text{tr}}P(\mathbf{V}, t)$$

$$\frac{\partial p(\mathbf{v}, t)}{\partial t} = \int d\mathbf{v}' [W_{\text{g}}(\mathbf{v}|\mathbf{v}')p(\mathbf{V}', t) - W_{\text{g}}(\mathbf{v}'|\mathbf{v})p(\mathbf{v}, t)] + \mathcal{B}_{\text{g}}p(\mathbf{v}, t) + \chi J_E[\mathbf{v}|p, p],$$

Transition rate

- Transition rate is given by

$$W_{\text{tr}}(\mathbf{V}|\mathbf{V}') = \chi \int d\mathbf{v}' \int d\hat{\boldsymbol{\sigma}} p(\mathbf{v}', t) \Theta(-(\mathbf{V}' - \mathbf{v}') \cdot \hat{\boldsymbol{\sigma}}) (\mathbf{V}' - \mathbf{v}') \cdot \hat{\boldsymbol{\sigma}} \delta \left(\mathbf{V} - \mathbf{V}' + \frac{\epsilon^2}{1 + \epsilon^2} (1 + e) [(\mathbf{V}' - \mathbf{v}') \cdot \hat{\boldsymbol{\sigma}}] \hat{\boldsymbol{\sigma}} \right)$$

and

$$W_{\text{g}}(\mathbf{v}|\mathbf{v}') = \frac{\chi}{N} \int d\mathbf{v}' \int d\hat{\boldsymbol{\sigma}} P(\mathbf{V}', t) \Theta(-(\mathbf{V}' - \mathbf{v}') \cdot \hat{\boldsymbol{\sigma}}) (\mathbf{V}' - \mathbf{v}') \cdot \hat{\boldsymbol{\sigma}} \delta \left(\mathbf{v} - \mathbf{v}' + \frac{1}{1 + \epsilon^2} (1 + e) [(\mathbf{v}' - \mathbf{V}') \cdot \hat{\boldsymbol{\sigma}}] \hat{\boldsymbol{\sigma}} \right),$$

$$\mathbf{V}' = \mathbf{V} - \frac{(1 + e)}{e} \frac{M}{M + m} \hat{\boldsymbol{\sigma}} \hat{\boldsymbol{\sigma}} \cdot (\mathbf{V} - \mathbf{v}) = \mathbf{V} + (1 + e) \frac{1}{1 + \epsilon^2} \hat{\boldsymbol{\sigma}} (\hat{\boldsymbol{\sigma}} \cdot (\mathbf{V}' - \mathbf{v})).$$

$\hat{\boldsymbol{\sigma}}$ is the unit normal at contact and $\Theta(x)$ is Heaviside's step function

If we assume $p(\mathbf{v}) = (m/2\pi T)^{d/2} \exp[-mv^2/(2T)]$, one can rewrite

$$W_{\text{tr}}(\mathbf{v}'_1|\mathbf{v}_1) = \frac{\chi |\Delta v|^{2-d}}{k(\epsilon, e)^2} \sqrt{\frac{m}{2\pi T}} \exp[-mv_{2\sigma}^2/2T].$$

If we are interested in the case of $d = 2$,

$$W_{\text{tr}}(\mathbf{V}'|\mathbf{V}) = \frac{\chi}{k(\epsilon, e)^2} \sqrt{\frac{m}{2\pi T}} \exp \left[-\frac{m[V'_\sigma - V_\sigma + k(\epsilon, e)V_\sigma]^2}{2Tk(\epsilon, e)^2} \right], \quad 31$$

Kramers-Moyal expansion

$$\frac{\partial P(\mathbf{V}, t)}{\partial t} = \mathcal{L}_{\text{gas}} P(\mathbf{V}, t) + \mathcal{B}_{\text{tr}} P(\mathbf{V}, t),$$

Introducing $W(\mathbf{V}; \mathbf{v}) \equiv W_{\text{tr}}(\mathbf{V}' | \mathbf{V})$

$$\begin{aligned} \mathcal{L}_{\text{gas}} P(\mathbf{V}, t) &= - \int d\mathbf{v} W(\mathbf{V}; \mathbf{v}) P(\mathbf{V}, t) + \int d\mathbf{v} W(\mathbf{V} - \mathbf{v}; \mathbf{v}) P(\mathbf{V} - \mathbf{v}, t) \\ &= - \int d\mathbf{v} W(\mathbf{V}; \mathbf{v}) P(\mathbf{V}, t) + \sum_{n=0}^{\infty} \frac{(-)^n}{n!} \left(\frac{\partial}{\partial \mathbf{V}} \right)^n \cdot \int d\mathbf{v} \mathbf{v}^n W(\mathbf{V}; \mathbf{v}) P(\mathbf{V}, t) \\ &= \sum_{n=1}^{\infty} \frac{(-)^n}{n!} \left(\frac{\partial}{\partial \mathbf{V}} \right)^n \cdot \int d\mathbf{v} \mathbf{v}^n W(\mathbf{V}; \mathbf{v}) P(\mathbf{V}, t), \end{aligned}$$

where we have used the formal relation

$$f(\mathbf{V} - \mathbf{v}) = \sum_{n=0}^{\infty} \frac{(-\mathbf{v})^n}{n!} \cdot \left(\frac{\partial}{\partial \mathbf{V}} \right)^n f(\mathbf{V}) = \exp[-\mathbf{v} \cdot \frac{\partial}{\partial \mathbf{V}}] f(\mathbf{V})$$

Summary of Kramers-Moyal expansion

$$\mathcal{L}_{\text{gas}}P(\mathbf{V}, t) = \sum_{n=1}^{\infty} \frac{(-1)^n \partial^n}{\partial V_{\alpha_1} \cdots \partial V_{\alpha_n}} D_{\alpha_1 \cdots \alpha_n}^{(n)}(\mathbf{V}) P(\mathbf{V}, t)$$

$$D_{\alpha_1 \cdots \alpha_n}^{(n)}(\mathbf{V}) = \frac{1}{n!} \int d\mathbf{V}' (V'_{\alpha_1} - V_{\alpha_1}) \cdots (V'_{\alpha_n} - V_{\alpha_n}) W_{\text{tr}}(\mathbf{V}' | \mathbf{V}).$$

Thermal system

- Drag law

$$F_{\text{ex}} = -MD_x^{(1)}(\mathbf{V}).$$

- If we assume that the thermal speed is larger than pulling speed, we obtain

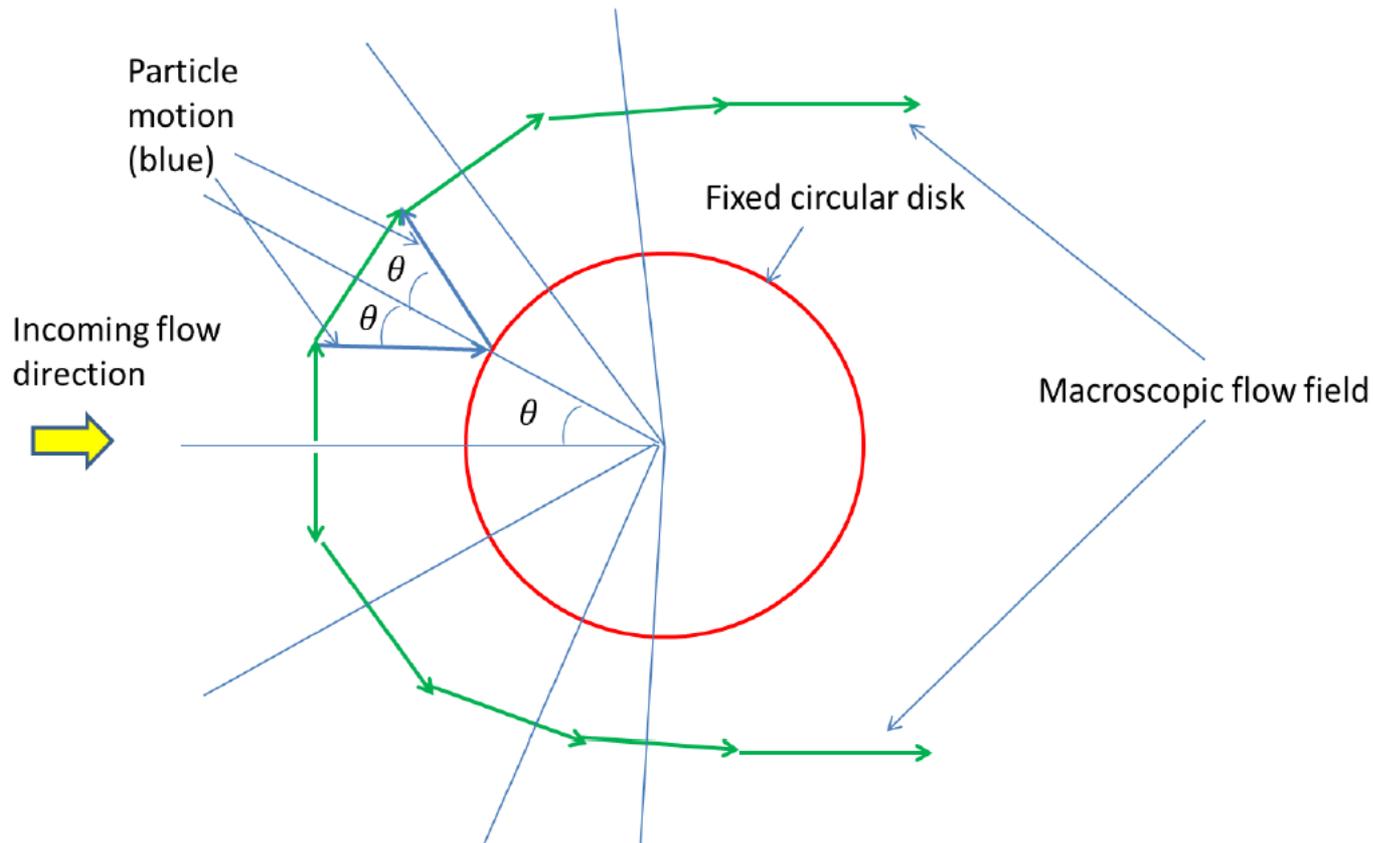
$$D_x^{(1)} \approx -2(1+e)\epsilon^2/(3(1+\epsilon^2))\chi\sqrt{2\pi T/m}V_x \text{ for } V_x \ll \sqrt{T/m},$$

- Then, we reach

$$F_{\text{ex}} \approx \frac{\chi(1+e)}{3(1+\epsilon^2)}\sqrt{2\pi mT}V_x$$

Granular or athermal system

- We need to determine the temperature for athermal systems.
- For this, we adopt the simple picture:

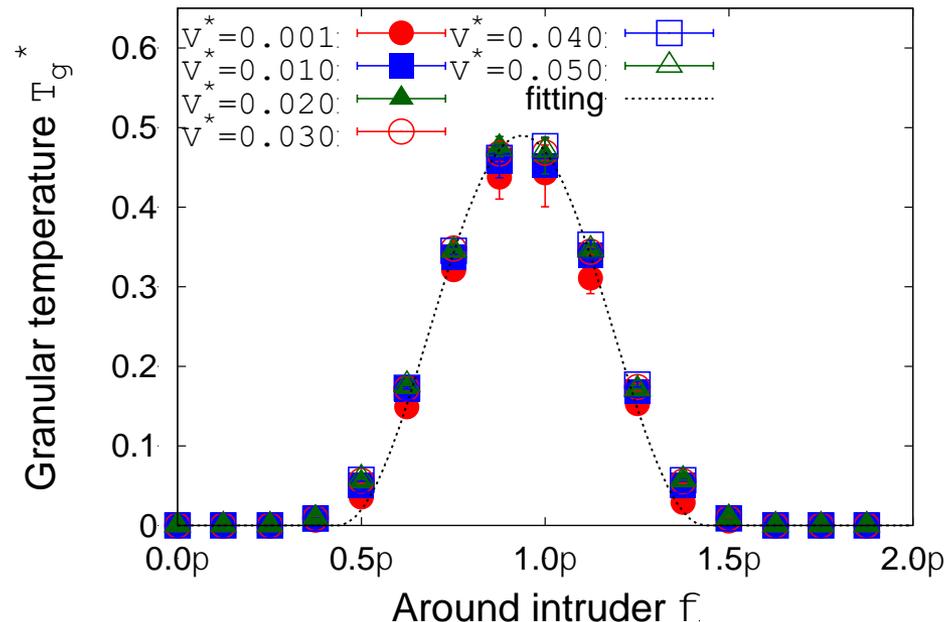


Mean flow and the temperature

- The mean flow is the tangential projection of particle velocity.
- The fluctuation is the normal velocity:

$$\delta v_n = \pm v \cos \theta$$

$$T(\theta) \approx m \langle (\Delta v)_n^2 \rangle = m v^2 \cos^2 \theta.$$



Drag law for granular systems

Using the average temperature

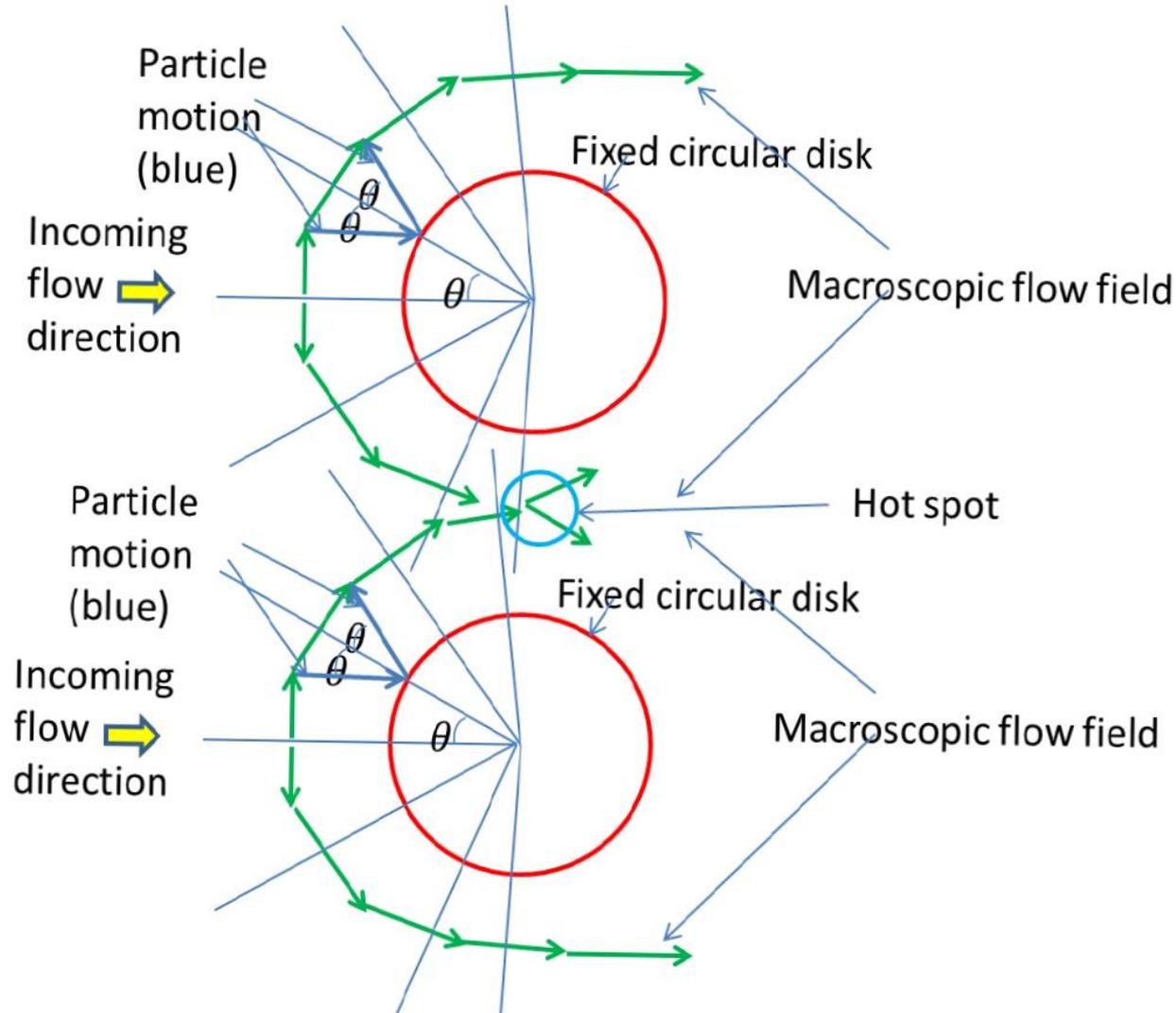
$$T \approx \overline{T(\theta)} \equiv \frac{1}{\pi} \int_{-\pi/2}^{\pi/2} d\theta T(\theta) = m \frac{V^2}{\pi n_0} \int_{-\pi/2}^{\pi/2} d\theta \cos^2 \theta = mV^2/2$$

We obtain

$$F_{\text{drag}} = \frac{\sqrt{\pi(1+e)\epsilon^2}}{6(1+\epsilon^2)} n(d+D) g_{dD}(\varphi) e^{-1/2} (5I_0(1/2) + 3I_1(1/2)) V^2,$$

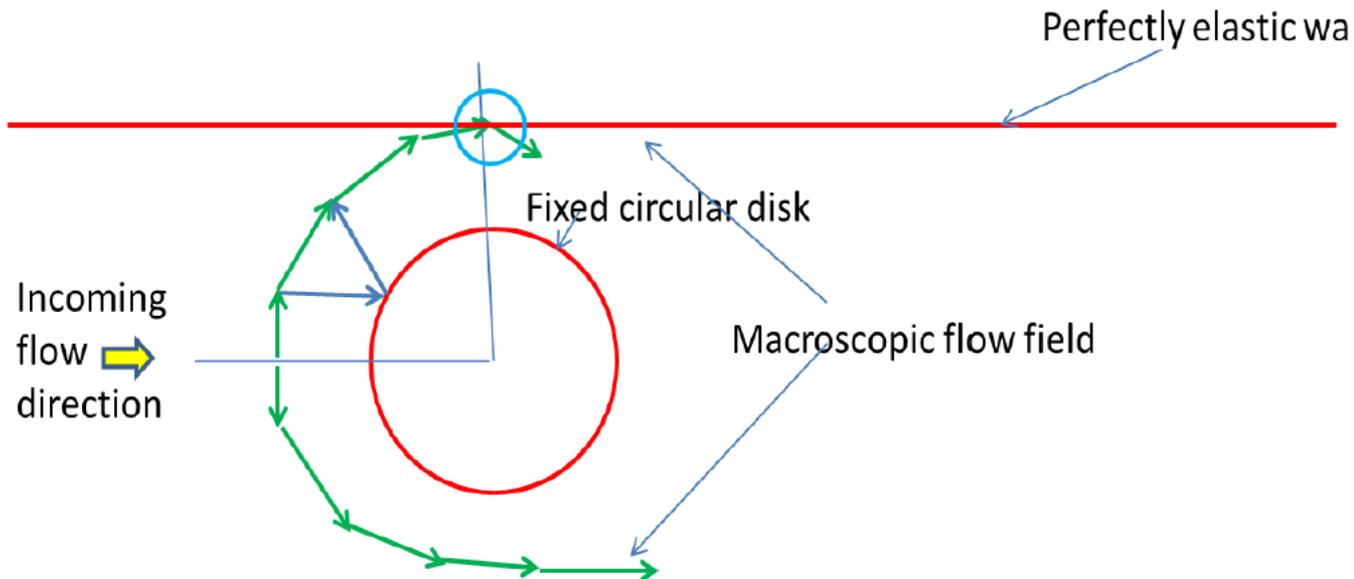
Interaction between two intruders

- Let us consider a steady flow:



A simplified model

- Two-body problem can be reduced to one-body problem:



The perpendicular component to the wall is $u \sin(\pi/2 - \theta_0) = u \cos \theta_0 = (V_0/2) \sin 2\theta_0$.

$$\Delta T \approx \bar{m} (V^2/4) \sin^2(2\theta_0),$$

$$\Delta \dot{T}(\theta) \approx (1/4) \bar{m} V^2 \sin^2(2\theta_0) \exp[-2(\theta' - \theta_0)^2]$$

Two-body interaction

- Induced pressure

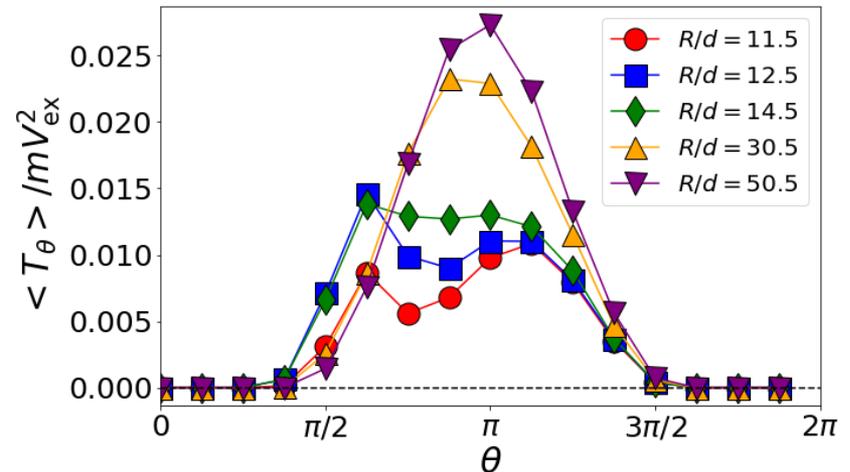
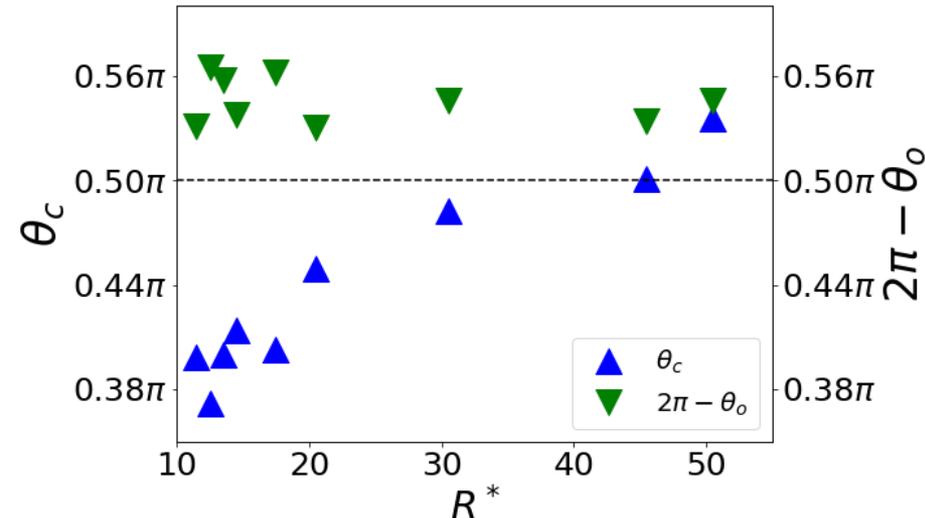
$$\Delta P(\theta) \approx ng_{dd}(\varphi)\Delta T(\theta).$$

- Total induced force is repulsive:

$$F_{\text{tot}} \approx (1/4)ng_{dD}(\varphi)mV^2 \sin^2(2\theta_0) \int_{-\infty}^{\infty} d\psi e^{-2\psi^2} = (1/4)\sqrt{\pi/2}ng_{dD}(\varphi)mV^2 \sin^2(2\theta_0).$$

the separation angle θ_0 $\theta_0 \approx 2\pi/5$ in the simulation.

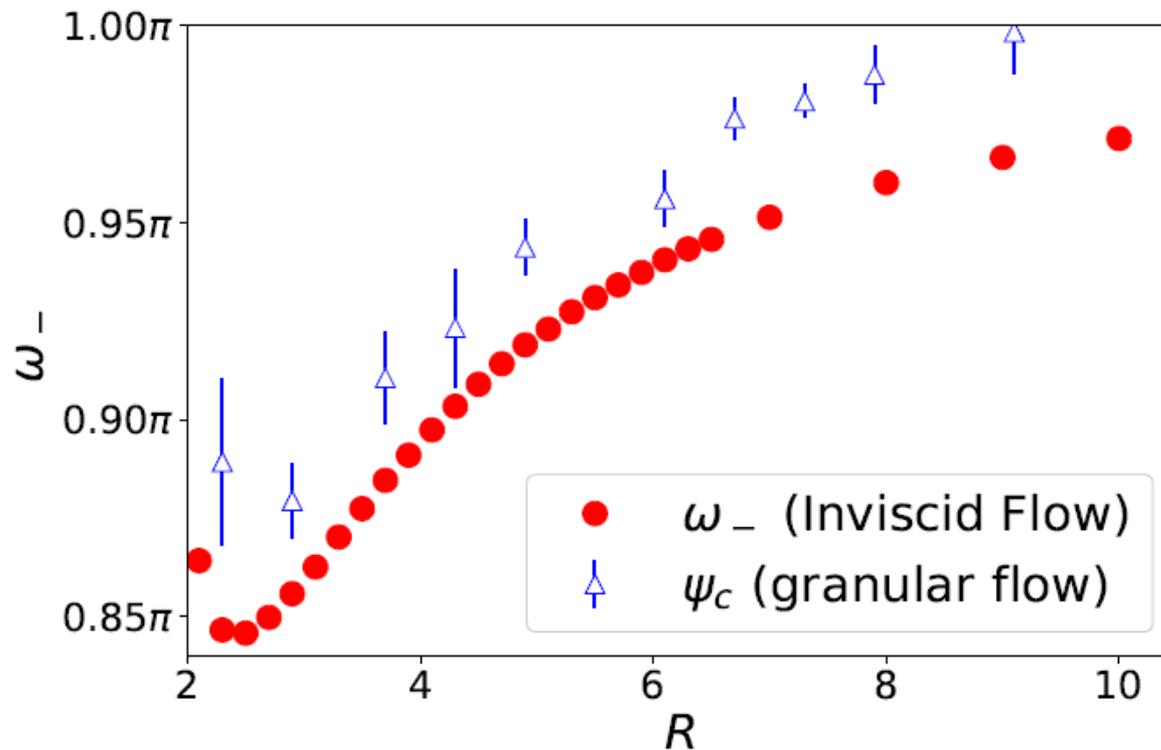
$$F_{\text{tot}} = 0 \text{ if } \theta_0 = \pi/2$$



Separation angle?

- Although the perfect fluid model cannot

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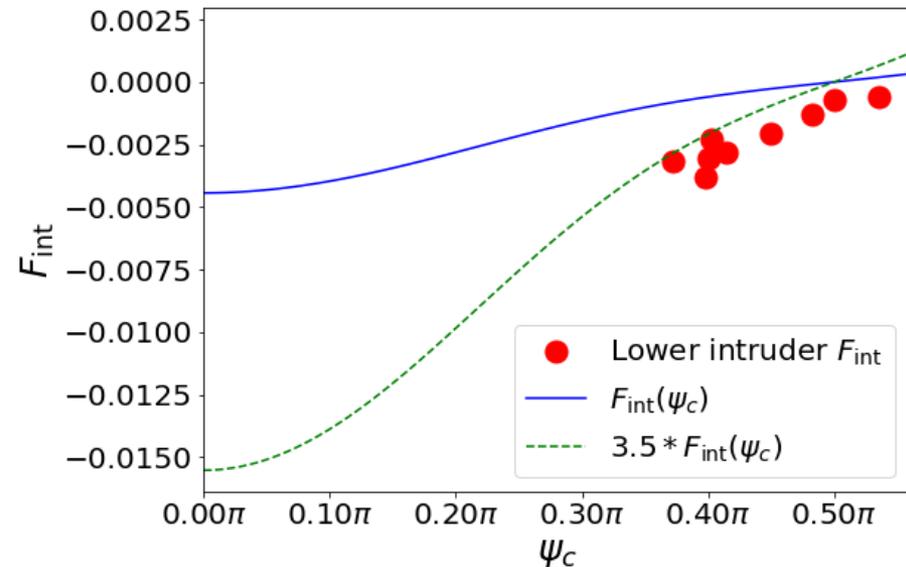
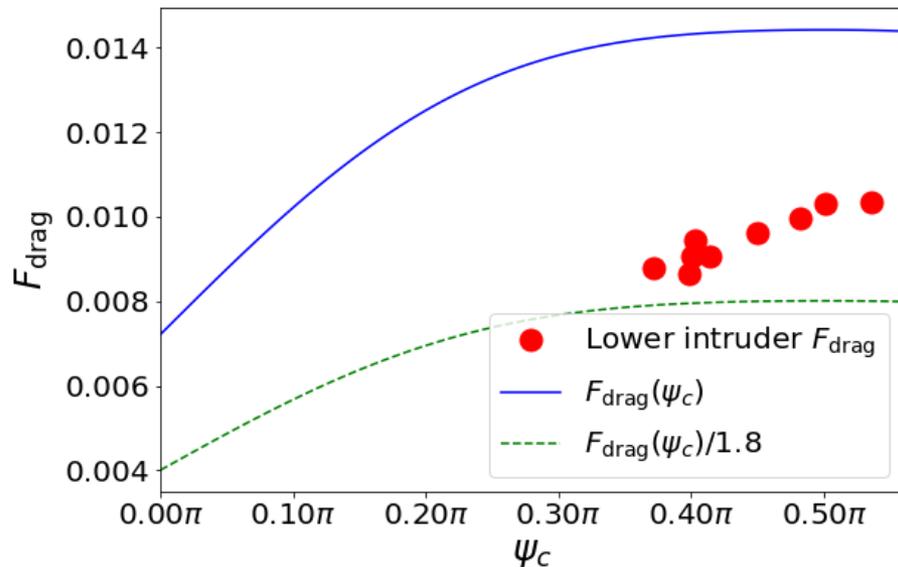
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Application of perfect fluid model to two single bodies

$$F_{drag} = \frac{D}{2} \rho V^2 \left[\left(\left(e + \frac{3}{2} \right) - \frac{2}{3} \sin^2 \psi_c \right) \sin \psi_c + \left(e + \frac{5}{6} \right) \right]$$

$$F_{int} = \frac{D}{2} \rho V^2 \left(- \left(e - \frac{1}{2} \right) - \frac{2}{3} \cos^2 \psi_c \right) \cos \psi_c$$

Drag and resistance against separation angle ψ_c where $\psi_o = 3\pi/2$



Note that pure two body calculation gives attractive interaction even if there exists the separation.

Outline

- Introduction: What do we know about drag in granular media?
- Previous study for pure 2D drag in granular media
- Previous studies on the interaction between intruders
- Simulations of two intruders in 2D granular media
 - Two intruders in a steady motion
 - Two intruders under an oscillation
- Phenomenological theory for the drag and the interactions for intruders
- **Discussion & conclusions**

Attractive interaction in oscillation

- The origin of the attractive interaction in oscillatory systems can be understood **qualitatively**:
- There are **wakes (cavities)** in front and back of the intruders.
- **Grains** in the channel can be **squeezed out** because the wake regions do not have pressure.
- The **density** in the channel is much **lower** than the outside density.
- The pressure also has the same tendency.
- So the intruders approach with each other.

Conclusions

- Perfect fluidity seems to work for the drag force in pure 2D.
- However, **the interaction** between two intruders cannot be expressed by the perfect fluid model.
- Instead, a simple model can be used for the drag force and the interaction in a steady flow.
- The qualitative picture for the interaction in an oscillatory flow exists, but there is no quantitative description.

THANK YOU

