## Discontinuous shear thickening on dense non-Brownian suspensions via lattice Boltzmann method

#### Pradipto and Hisao Hayakawa

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Rheology of disordered particle part 1, YITP, June 22nd 2018



Outline Introduction

> Outline of our model Hydrodynamics: lattice Boltzmann method Particle contacts Electrostatic repulsive forces Sheared suspensions simulations Results Discussions Future prospect



2/38

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## Solid particles suspended in solvent fluid







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Fluids are described by Stokes equation ( $Re \rightarrow 0$ ):

 $\nabla \cdot \mathbf{u} = \mathbf{0}$  $\nabla p = \eta \nabla^2 \mathbf{u}$ 

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Suspensions rheology have unique behavior!

### Discontinuous shear thickening (experimental observations)



 H. A. Barnes, J. Rheol. 33, 329 (1989).

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 R. G. Egres and N. J.
Wagner J. Rheol. 49 3 , 719-746(2015)

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5/38

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 $\phi = 0.5f$ 

 $\dot{\gamma}/\dot{\gamma}_0$ 

= 0.54

 $10^{0}$ 

 $10^{1}$ 

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Recover DST using LBM

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Motivations:

- Recover DST using LBM
- Decompose all contributions to the shear stress
  - Helpful for the theoretical construction

#### Lattice Boltzmann vs Stokesian Dynamics Lattice Boltzmann

#### Stokesian Dynamics



- Particle motion obey the Newton equations.
- Hydrodynamic fields are calculated by solving the resistance matrix
- Separate lubrication calculation.

#### Lattice Boltzmann vs Stokesian Dynamics Lattice Boltzmann (susp3d)

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- Hydrodynamic fields are calculated *locally* at each lattice point.
- mesoscopic, possible to have simple local rules between fluid and solid
- Particle motion obey the Newton equations
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Equation of motions:

$$m \cdot \frac{d}{dt} \begin{pmatrix} \mathbf{U} \\ \mathbf{\Omega} \end{pmatrix} = \sum_{\alpha} \begin{pmatrix} \mathbf{F}_{\alpha} \\ \mathbf{T}_{\alpha} \end{pmatrix}$$
$$\sum_{\alpha} \mathbf{F}_{\alpha} = \mathbf{F}^{h} + \mathbf{F}^{c} + \mathbf{F}^{R}$$

$$\sum_{\alpha} \mathbf{T}_{\alpha} = \mathbf{T}^{h} + \mathbf{T}^{c} + \mathbf{T}^{R}$$
$$\mathbf{U}(t + \Delta t) = \mathbf{U}(t) + \frac{\Delta t}{m} \mathbf{F}(t)$$
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Hydrodynamics (lattice Boltzmann)



Contact between

particles



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By using LBM, we need to discretize the unit length *a* (particle radius) to lattice unit  $\Delta x$ ! Our simulation used  $\Delta x = 0.1a$ All quantities below are written in lattice units!

## History of LBM

 Initially devised as an extension of the Lattice Gas Automata by McNamara and Zanetti (McNamara, Zanetti, 1988)



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► Now, LBM is widely used for various computational fluid dynamics simulation.

## The discrete distribution function (He and Luo, 1997)

 $n \rightarrow$  particle velocity (**v**) distribution function on space time point (**r**, t)

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$$\partial_t n + \mathbf{v} \cdot \nabla n = \left(\frac{dn}{dt}\right)_{\text{coll}}$$
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we can project to the Hermite bases:

$$n(\mathbf{r},\mathbf{v},t) = \omega(\mathbf{v}) \sum_{l=0}^{\infty} \frac{1}{l!} \mathbf{A}^{(l)} \mathcal{H}^{(l)}(\mathbf{v})$$

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which is linear combination of the moments of n

The first few of the Hermite polynomials  $(\mathcal{H}^{(l)}(\mathbf{v}))$ :

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**Truncate:** (to several orders of *K*)

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discrete distribution function  $\rightarrow n_i(\mathbf{r}, \mathbf{c}_i, t) = w_i n(\mathbf{r}, \mathbf{v}, t) / \omega(\mathbf{v})$  and  $m_i(\mathbf{r}, \mathbf{v}, t) / \omega(\mathbf{v})$ 



Evolving equation:

$$n_i(\mathbf{r}+\mathbf{c}_i,t+1)=n_i(\mathbf{r},t)+\Delta_i(\mathbf{r},t)$$

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streaming



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streaming

collision

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Evolving equation:

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streaming collision Hydrodynamic fields:

mass density  $\rho = \sum_{i} n_{i}$ momentum density  $\mathbf{j} = \sum_{i} n_{i} \mathbf{c}_{i}$ momentum flux  $\mathbf{\Pi} = \sum_{i} n_{i} \mathbf{c}_{i} \mathbf{c}_{i}$ 

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Linearized collision operator

$$\Delta_i(n) = \Delta_i(n_i^{eq}) + \sum_j \mathcal{L}_{ij} n_j^{neq}$$

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$$n^{eq} = \rho\left(\frac{m}{2\pi k_b T}\right)^{\frac{3}{2}} \exp\left(\frac{-m(\mathbf{v}-\mathbf{u})\cdot(\mathbf{v}-\mathbf{u})}{2k_b T}\right)$$

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Expanding with Hermite polynomials up to 2nd order, with coefficients:

$$\begin{aligned} A^0_{eq} &= \rho \\ A^1_{eq} &= \rho \mathbf{u} \\ A^2_{eq} &= \rho (\mathbf{u} - c_s^2) \end{aligned}$$

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discrete equilibrium distribution function:

$$n_i^{eq} = a^{c_i} \left( \rho + \frac{\mathbf{j} \cdot \mathbf{c}_i}{c_s^2} + \frac{(\rho \mathbf{u} \mathbf{u}) : (\mathbf{c}_i \mathbf{c}_i - c_s^2 \mathbf{1})}{2c_s^4} \right)$$

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Weight coefficients:

$$a^0 = 12$$
  $a^1 = 2$   
 $a^{\sqrt{2}} = 1$ 

 $c_s = \sqrt{k_b T} \rightarrow \text{lattice sound speed}$  $\mathbf{A} : \mathbf{B} = Tr(\mathbf{AB})$ 

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$$\sum_{i} \mathcal{L}_{ij} = 0 \qquad \sum_{i} \mathbf{c}_{i} \mathcal{L}_{ij} = 0 \qquad \sum_{i} \overline{\mathbf{c}_{i} \mathbf{c}_{i}} \mathcal{L}_{ij} = \lambda \overline{\mathbf{c}_{j} \mathbf{c}_{j}} \qquad \sum_{i} c_{i}^{2} \mathcal{L}_{ij} = \lambda_{\nu} c_{j}^{2}$$

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$$n_i^{eq} = \mathbf{a}^{c_i} \left( \rho + \frac{\mathbf{j} \cdot \mathbf{c}_i}{c_s^2} + \frac{(\rho \mathbf{u} \mathbf{u}) : (\mathbf{c}_i \mathbf{c}_i - c_s^2 \mathbf{1})}{2c_s^4} \right)$$

Only the second moment of  $n_i^{eq}$  that is affected by collision

Linearized collision operator

$$\Delta_i(n) = \Delta_i(n^{eq}) + \sum_j \mathcal{L}_{ij} n_j^{neq}$$

not necessary to construct and calculate  $\mathcal{L}_{ij}$ , use its eigen equation instead!

$$\sum_{i} \mathcal{L}_{ij} = 0 \qquad \sum_{i} \mathbf{c}_{i} \mathcal{L}_{ij} = 0 \qquad \sum_{i} \overline{\mathbf{c}_{i} \mathbf{c}_{i}} \mathcal{L}_{ij} = \lambda \overline{\mathbf{c}_{j} \mathbf{c}_{j}} \qquad \sum_{i} c_{i}^{2} \mathcal{L}_{ij} = \lambda_{\nu} c_{j}^{2}$$

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$$\longrightarrow \text{Calculate } \mathbf{\Pi}^{neq_{a}*, a} \in \mathbb{R} \times \mathbb{R} \times$$

$$\mathbf{\Pi}^{neq} = \mathbf{\Pi} - \mathbf{\Pi}^{eq} \qquad \mathbf{\Pi} = \sum_{i} n_i \mathbf{c}_i \mathbf{c}_i$$

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nonequilibrium second moments obtained from the eigen equation of  $\mathcal{L}_{ij}$ :

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 $\lambda$  and  $\lambda_{\nu}$  are related to shear  $\eta$  and bulk  $\eta_{\nu}$  viscosities from the multiscale analysis:

$$\eta = -\rho c_s^2 \Delta t \left(\frac{1}{\lambda} + \frac{1}{2}\right) \qquad \eta_\nu = -\rho c_s^2 \Delta t \left(\frac{2}{3\lambda_\nu} + \frac{1}{3}\right)$$

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What will happen on the solid boundary conditions (surface of the particles) ?

Anthony Ladd's bounce-back rule:



Velocity of the boundary nodes:

$$\mathbf{u}_b = \mathbf{U} + \mathbf{\Omega} imes (\mathbf{r}_b - \mathbf{R})$$

R is the center of mass of the particle,  $A \equiv A = O \otimes O = 18/38$ 



Forces exerted at the boundary nodes:

$$\mathbf{f}(\mathbf{r}_b, t + \frac{1}{2}\Delta t) = \frac{\Delta x^3}{\Delta t} \left[ 2n_b^*(\mathbf{r}, t) - \frac{2a^{c_b}\rho_0\mathbf{u}_b \cdot \mathbf{c}_b}{c_s^2} \right] \mathbf{c}_b$$

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Sum over all boundary nodes within a particle:

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Sum over all boundary nodes within a particle:

 $\mathbf{F}^{h} = \sum_{b} \mathbf{f}(\mathbf{r}_{b})$  $\mathbf{T}^{h} = \sum_{b} \mathbf{r}_{b} \times \mathbf{f}(\mathbf{r}_{b})$  $\sigma^{h} = \sum_{b} \mathbf{r}_{b} \mathbf{f}(\mathbf{r}_{b})$ 

### Shared nodes


#### Shared nodes



need separated lubrication forces calculation!

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If gap between particle is less than 1 lattice unit ..

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$$\begin{pmatrix} \textbf{F}_1 \\ \textbf{T}_1 \\ \textbf{T}_2 \\ \textbf{S}_1 \\ \textbf{S}_2 \end{pmatrix} = - \begin{pmatrix} \textbf{A}_{11} & -\textbf{B}_{11} & \textbf{B}_{22} \\ \textbf{B}_{11} & \textbf{C}_{11} & \textbf{C}_{12} \\ -\textbf{B}_{22} & \textbf{C}_{12} & \textbf{C}_{22} \\ \textbf{G}_{11} & \textbf{H}_{11} & \textbf{H}_{12} \\ \textbf{G}_{22} & -\textbf{H}_{21} & \textbf{H}_{22} \end{pmatrix} \begin{pmatrix} \textbf{U}_{12} \\ \textbf{\Omega}_1 \\ \textbf{\Omega}_2 \end{pmatrix}$$

(Kim and Karilla, 1991)

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 $\textbf{U}_{12} = \textbf{U}_1 - \textbf{U}_2$  relative velocity

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$$\mathbf{H}_{12} = Y_{12}^{H}(\epsilon_{lpha\gamma\delta}d_{\delta}d_{eta} + \epsilon_{eta\gamma\delta}d_{\delta}d_{lpha})$$

 $\mathbf{d} \rightarrow$  displacement unit vector along axis.  $\epsilon \rightarrow$  Levi-Civita symbol

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$$\mathbf{H}_{12} = Y_{12}^{H} (\epsilon_{\alpha\gamma\delta} d_{\delta} d_{\beta} + \epsilon_{\beta\gamma\delta} d_{\delta} d_{\alpha})$$

 $\mathbf{d} \rightarrow \mathbf{displacement}$  unit vector along axis.  $\epsilon \rightarrow$  Levi-Civita symbol

Each scalar function is a function of gap h and  $\beta = \frac{a_i}{a_i}$  i.e

$$Y_{12}^{H} = 8 \log\left(\frac{1}{h}\right) \pi \eta a_{i} \frac{2\beta^{2}(1+7\beta)}{5(1+\beta)^{5}}$$





Cutoff length  $\delta = \frac{a_{\rm contact} - a_{\rm hydro}}{a_{\rm contact}}$  to allow contact

We used  $\delta = 0.01$ 

### Particle contacts



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Linear spring dashpot model (Luding, 2008)



(Fleischmann, 2015)

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Coulomb friction rules:  $|\mathbf{F}_{ij}^{tan}| \geq \mu(|\mathbf{F}_{ij}^{nor}|) \rightarrow$ 

 $\begin{array}{l} \text{Coulomb friction rules:} \\ |\mathbf{F}_{ij}^{tan}| \geq \mu (|\mathbf{F}_{ij}^{nor}|) \rightarrow \text{slip} \end{array}$ 

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$$|\mathbf{F}_{ij}^{tan}| \leq \mu(|\mathbf{F}_{ij}^{nor}|) \rightarrow \mathsf{stick}$$

Stress contribution from contact: Normal:

$$\sigma_{\alpha\beta}^{nor} = -\frac{1}{2V} \sum_{i} \sum_{j \neq i} (\mathbf{r}_{ij,\alpha} \mathbf{F}_{ij,\beta}^{nor} + \mathbf{r}_{ij,\beta} \mathbf{F}_{ij,\alpha}^{nor})$$

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we used  $\lambda = 0.2a$ 

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#### Sheared suspensions





#### Sheared suspensions



- wall moves with velocity  $u_{wall}$  to x and -x directions
- ► All simulation use N=512 particles.

#### Shear stress:

$$\sigma_{\alpha\beta} = \sigma^{h}_{\alpha\beta} + \sigma^{tan}_{\alpha\beta} + \sigma^{nor}_{\alpha\beta} + \sigma^{r}_{\alpha\beta}$$

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#### Apparent viscosity:

$$\eta = \sigma_{\alpha\beta}/\dot{\gamma}$$

Shear stress:

$$\sigma_{\alpha\beta} = \sigma^{h}_{\alpha\beta} + \sigma^{tan}_{\alpha\beta} + \sigma^{nor}_{\alpha\beta} + \sigma^{r}_{\alpha\beta}$$

#### Apparent viscosity:

#### Dimensionless shear rate:

$$\eta = \sigma_{\alpha\beta}/\dot{\gamma}$$

$$\dot{\gamma}^* = \frac{6\pi\eta_0 a^2 \dot{\gamma}}{F^*}$$

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Shear stress:

$$\sigma_{\alpha\beta} = \sigma^{h}_{\alpha\beta} + \sigma^{tan}_{\alpha\beta} + \sigma^{nor}_{\alpha\beta} + \sigma^{r}_{\alpha\beta}$$

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# Sheared Suspensions: $\frac{\eta}{\eta_0}$ vs $\dot{\gamma}^*$ , compared with results from (Mari, et al, 2014)



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## Sheared Suspensions: $\frac{\eta}{\eta_0}$ vs $\sigma/\eta_0\dot{\gamma}$ , compared with results from (Mari, et al, 2014)



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## Sheared Suspensions: $\frac{\eta}{\eta_0}$ vs $\sigma/\eta_0\dot{\gamma}$ , compared with results from (Mari, et al, 2014)



#### Contributions to shear viscosity for $\phi = 0.57$



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#### Contributions to shear viscosity for $\phi = 0.57$



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## Contributions to shear viscosity for $\phi = 0.54$ and 0.48



## Contributions to shear viscosity for $\phi = 0.54$ and 0.48



## Time evolution of shear viscosity $\phi = 0.57$ and $\phi = 0.48$



#### 

## Time evolution of shear viscosity $\phi = 0.57$ and $\phi = 0.48$



# Time evolution of contact number for $\phi = 0.57$



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Evolution of the contact network ( $\phi = 0.57$ )

high shear rate

low shear rate

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Slight deviation from Seto's

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  - Need to allow separate "switching" length between boundary nodes and lubrication calculation for normal, tangential, and rotation modes

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  - To travel a distance of its radius, one particles needs > 6200 time steps

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- Implement contact with rolling friction.
- Use more realistic boundary conditions

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