Maximal volumes and Euclidean variations

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Introduction

In the recent years, we have advanced a lot in our understanding of codim-2 surfaces and their quantum information interpretation: entanglement entropy and subregion - subregion duality.

However, not much has been proven about codimension 1 surfaces : what is their use in QI QG?

Focus on codim 1 surfaces dual to the boundary t = 0 slice.



Overlaps!

As discussed by Gabor, a natural way to obtain quantities localized in codimension 1 bulk surfaces is through wave functions overlaps .

In particular the bulk symplectic form is dual to an antisymmetrized boundary overlap:

$$\Omega_{\Sigma_{bulk}}(\delta_1\phi,\delta_2\phi)\sim \langle \delta_1J|\delta_2J
angle-(1\leftrightarrow2)$$

where ϕ, J could be the metric and the stress-tensor and the states are naturally defined using the euclidean path integral.

$$^{*}\Omega = \int_{\Sigma_{bulk}} \delta_{1}\phi\delta_{2}\Pi - (1\leftrightarrow2)$$

Volume and EE analogies

For entanglement entropy, we were able to make progress through the replica trick: a boundary deformation creates a conical singularity.

$\delta\partial_n \log Z = \delta S_{EE}$

Can we find a similar deformation for the maximal volume slice that ends at t=0?

$$\delta V =_? \delta \partial_\alpha \log Z$$

Volume and EE analogies

Following the analogy with entanglement entropy, it seems natural that the deformation δ_{lpha} is smooth in the bulk but becomes singular in the boundary.

Close to the boundary of the entangling region ∂_n creates a conical singularity. We expect that close to the t = 0 surface, the metric deformation is discontinuous. As we will see, in the case of the vacuum, the simplest deformation with this property generates the volume:

$$\delta_lpha \gamma_{ab} = \mathrm{sign}(t) \gamma_{ab}$$

While in principle a similar local description should apply to more complicated cases, that seems hard to make precise.

Use symplectic form to understand volume!

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 $\delta V = \Omega_{\Sigma_{bulk}}(\delta_lpha h, \delta h)$

Approach

Obtain δV from the symplectic form: $\delta V = \Omega_{\Sigma_{bulk}}(\delta_{\alpha}h, \delta h)$ Volume generating $\delta_{\alpha}h$, only around extremal surfaces: constraint equations. δ_{α} deforms extremal surface infinitesimally, same canonical fields:

$$\delta_lpha \phi_{grav} = \delta_lpha \pi_{grav} = 0, ``\delta_lpha t "= 1$$

Not a diffeo: fields don't change (equiv change the fields keep surface fixed). It half a York time translation, so we called it the New York deformation.

Similar to $T\bar{T}$: bulk cutoff surface moves while keeping Dirichlet boundary conditions. In this case the bulk vector field acts trivially on the boundary.

$${}^*\delta_lpha h_{ab}=0, \delta_lpha K_{ab}=h_{ab}$$

Vacuum

Obtain boundary deformation explicitly for simple geometries.

Consider the vacuum in WdW coordinates (Euclidean bdy is at $\tau = \pm i\infty$):



Vacuum



It is easy to show that $\delta_lpha \sim \partial_ au$. When mapped to Poincare coordinates, we have that $\delta_lpha\gamma_{ab}=2i~{
m sign}t~\delta_{ab}$

The deformation is a diffeo only in the case when there is a time reflection symmetry and thus $K_{ij} = 0$. Equivalent of Casini-Huerta-Myers for volumes.

All these cases have $\delta V = 0$ for normalizable deformations.

Vacuum + matter fields





In the presence of matter fields, $\ \delta V = \int_{\Sigma} T_{ au au}$

Can recover this from the boundary point of view. One needs to look for the deformation of the scalar fields that satisfies $\delta_lpha\phi=\delta_lpha\pi=0$

This is a combination of the previous diffeomorphism plus a transformation of the sources, can be solved explicitly at large mass.

Thermofield double

Need a $K_{ij}
eq 0$ extremal surface, simplest case $|TFD(T o\infty)
angle$ $ds^2=-d\kappa^2+f(\kappa)dt^2+g(\kappa)dx_{d-1}^2$

Very symmetric case, extremal surface

at $\kappa = \frac{\pi}{4}$.

t is spacelike in this WdW patch.



Thermofield double

$$V = rac{MT}{(d-1)} + \dots$$



Can solve for the lpha deformation in this background.

We can plug the deformation into the boundary overlaps to obtain

 $\partial_T V, \partial_eta V$ from a purely boundary calculation.

The linear in T behaviour arises from the fact that in the path integral preparation of the state, one has to integrate over long times .

 $^{*}16\pi G_{N}=1$

Conclusion

I have presented some motivation to approach the maximal volume in a similar way to entanglement.

Then have pursued this using the dual of the symplectic form.

Main limitation: general picture of the boundary deformation? Should be related with boundary states / singular deformations at t = 0. Local picture should be good to understand the divergences, but they are subtle.

Alternatively, use $T\bar{T}$ in hyperbolic coordinates to generate these New York transformations [WIP]. Bulk arguments allow us to write the volume in terms of the trace of the stress tensor at large deformations.



THANKS **HEP-TH!**

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