研究会「原子核物理でつむぐrプロセス」 YTTP, Kyoto U., May 22-24, 2019

Towards systematic and consistent nuclear data inputs for astrophysical *r*-process with Bayesian approaches

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May 23, 2019



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Contents

Introduction

Nuclear inputs with Bayesian approaches

- > A toy model
- Nuclear Masses
- > Nuclear β -decay half-lives
- **Summary and Perspectives**

Nucl eosynthesis



Slow neutron-capture process (s-process)



Abundance



Rapid neutron-capture process (r-process)



r-process nucleosynthesis and nuclear inputs

The 11 greatest unanswered questions of physics



Question 3 How were the heavy elements from iron to uranium made?



★ Nuclear data inputs for *r*-process

| Quantity | | Effects |
|----------------------------------|--|--|
| S _n | neutron separation energy | path |
| $T_{1/2}$ | β -decay half-lives | abundance pattern, time scale |
| P_n | β -delayed <i>n</i> -emission branchings | final abundance pattern |
| Y_i | fission (products and branchings) | endpoint, degree of fission cycling |
| | | abundance pattern (?) |
| G | partition functions | path (very weakly) |
| $N_A \langle \sigma \nu \rangle$ | neutron capture rates | conditions for waiting point approximation |
| | | final abundance pattern during freezeout (?) |

Nuclear inputs for r-process

Key exp. @ RIKEN masses β-decay half-lives β-delayed n-emssions





To provide and organize all these inputs in a systematic and consistent way

 \blacktriangleright e.g., changes in mass \rightarrow changes in half-lives, capture rates ...

(not hybrid databases !)

➢ more exp. data → more reliable extrapolation / smaller uncertainties (higher accuracy ?)

Nuclear mass models

- Theoretically, the development of nuclear mass model can be traced back to the early age of nuclear physics, known as Bethe-Weizsacker liquid drop model in 1935.
- To take into account the nuclear shell effects: the microscopic models and the microscopic-macroscopic (mic-mac) models.



Theories + Bayesian approaches (I)

Nuclear mass predictions based on Bayesian neural network approach with pairing and shell effects

Z.M. Niu (牛中明)^{a,b}, H.Z. Liang (梁豪兆)^{b,c,d,*}

Physics Letters B 778 (2018) 48-53

arXiv:1810.03156

Predictions of nuclear $\beta\text{-decay}$ half-lives with machine learning and their impacts on r

process





Another (ultimate) goal: to structure energy density functionals for DFT

Theories + Bayesian approaches (II)

PHYSICAL REVIEW LETTERS 122, 062502 (2019)

Neutron Drip Line in the Ca Region from Bayesian Model Averaging

Léo Neufcourt,1,2 Yuchen Cao (曹字晨),3 Witold Nazarewicz,4 Erik Olsen,2 and Frederi Viens1



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Bayesian and frequentist views

Differences between Bayesians and frequentists Bishop2006Springer

Frequentists:

- Data are a repeatable random sample
 --- there is a frequency
- Underlying parameters remain
 constant during this repeatable process
- Parameters are unknown but fixed

Bayesians:

- ✓ Data are observed from the realized sample
- Parameters are unknown and described probabilistically
- \checkmark Data are fixed

Example: tossing a coin of unknown properties; probability ω of the coin landing heads

- ✓ Choose some criterion, such as maximum likelihood
- ✓ Find the optimal estimator according to this criterion, such as the frequency of heads in past tosses



- Express this unknown properties using a probability distribution over possible values based on our intuitive believes
- ✓ Update this distribution using the Bayes' theorem as the outcome of each toss becomes known

$$p(\omega \mid D) = \frac{p(D \mid \omega)p(\omega)}{p(D)}$$



Bayesian approach in regression problem

Posterior distributions of parameters are Neal1996Springer

$$p(\omega \mid D) = \frac{p(D \mid \omega) p(\omega)}{p(D)} \propto p(D \mid \omega) p(\omega), \quad D = \{(x_1, t_1), (x_2, t_2), \dots, (x_N, t_N)\}$$

prior distribution $p(\omega)$:





Bayesian approach in regression problem

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sampling with Markov chain Monte Carlo (MCMC) method

Make predictions

$$\left\langle y_n \right\rangle = \int y(x_n, \omega) p(\omega \mid x, t) d\omega = \frac{1}{K} \sum_{k=1}^{K} y(x_n, \omega_k)$$

$$\Delta y_n = \sqrt{\left\langle y_n^2 \right\rangle - \left\langle y_n \right\rangle^2}$$

□ The BNN approach can give the joint probability distribution of all parameters, from which we can get the correlations among parameters, so the number of independent parameters may be much less the number of BNN parameters.

A toy model

True : $y = 0.3 + 0.4x + 0.5\sin(2x)$

Data : $y = 0.3 + 0.4x + 0.5\sin(2x) + 0.2 \times randn$

> Number of training data: N=61, $x \in [-3, 3]$

 $1 \operatorname{input} : y = f(x)$

2 inputs :
$$y = f[x_1 = x, x_2 = \sin(2x)]$$

- Number of hidden unit: $H=20 \text{ for } f(x); H=15 \text{ for } f(x_1, x_2)$
- Number of parameters: 61

Likelihood function :
$$p(x, y | \omega) = \exp(-\chi^2/2), \chi^2 = \sum_{i=1}^{N} \left(\frac{y_i - f(x_i, \omega)}{\sigma}\right)^2$$



- BNN can avoid overfitting if a Gamma distribution is taken as the noise prior.
- Direct BNN fitting with x as the only input variable can only extrapolate around a few steps from known region.

A toy model



Including reasonable variable is very effective for the extrapolation of neural network.

Uncertainties of predictions are also reasonable.

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Numerical details

Likelihood function $p(D|\omega)$

$$p(D \mid \omega) = \exp(-\chi^2 \mid 2), \ \chi^2 = \sum_{n=1}^{N} \left[\frac{t_n - y_n(x, \omega)}{\sigma_n} \right]^2$$
$$t_n = M_n^{\exp} - M_n^{\operatorname{th}}, \ y(x, \omega) = a + \sum_{j=1}^{H} b_j \tanh\left(c_j + \sum_{i=1}^{I} d_{ji} x_i\right) \Longrightarrow M_n^{\prime \operatorname{th}} = M_n^{\operatorname{th}} + y(x, \omega)$$

 \star Inputs:

✓ 2 inputs (I=2): Z, A

✓ 4 inputs (I=4): Z, A,
$$\delta$$
, P; $\delta = [(-1)^{Z} + (-1)^{N}]/2$, $P = v_{n}v_{p}/(v_{p} + v_{n})$
 $v_{p} = \min(|Z - Z_{0}|), v_{n} = \min(|N - N_{0}|)$

 \star Hidden units:

- ✓ 2 inputs (I=2): H=42
- ✓ 4 inputs (I=4): H=28
- \star Number of parameters: 169
- ★ Data: Huang et al., CPC 41 030002; Wang et al., CPC 41 030003.
 - ✓ Entire set: 2272 nuclei in AME2016 (Z, N>=8 and σ^{exp} <=100 keV)
 - ✓ Learning set: 1800 data randomly selected from entire set
 - ✓ **Validation set**: the remaining 472 data in entire set

Rms deviations of mass and S_n



- The predictions of nuclear mass and neutron-separation energy are significantly improved with the BNN approach.
- After the improvement using the BNN approach with four inputs, the rms deviations are generally around 200 keV.
- The BNN with four inputs is more powerful than the BNN with two inputs, especially for the neutron separation energy.

Mass extrapolation



The smooth deviations can be improved significantly, while the odd-even staggering can only remarkably reduced with BNN-I4 approach.
 The BNN corrections are still reasonable if the extrapolation is *not far away from the training region*.

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Nuclear β -decay half-lives

The nuclear β -decay half-life in the allowed Gamow-Teller approximation reads as follows:

$$T_{1/2} = \frac{\ln 2}{\lambda_{\beta}} = \frac{D}{g_A^2 \sum_m B_{\text{GT}}(E_m) f(Z, A, E_m)} \rightarrow T_{1/2} = a / f(Z, A, E_m = Q_{\beta} - c(\delta - 1) / \sqrt{A})$$

where $D = \frac{\hbar^7 2\pi^3 \ln 2}{g^2 m_e^5 c^4} = 6163.4 \text{ s}, g_A = 1$, $B_{GT}(E_m)$ is the transition probability, and E_m is the maximum value of β -decay energy. The phase volume is

$$f(Z, A, E_m) = \frac{1}{m_e^5} \int_{m_e}^{E_m} p_e E_e (E_m - E_e)^2 F(Z, A, E_m) dE_e,$$



Numerical details

Likelihood function $p(D|\omega)$

$$p(D \mid \omega) = \exp(-\chi^2 / 2), \ \chi^2 = \sum_{n=1}^{N} \left[\frac{t_n - y_n(x, \omega)}{\sigma_n} \right]^2$$

$$t_n = \log(T_n^{\exp}/T_n^{\text{th}}), \ y(x,\omega) = a + \sum_{j=1}^H b_j \tanh\left(c_j + \sum_{i=1}^I d_{ji}x_i\right) \Longrightarrow \log(T_n^{\prime\text{th}}) = \log(T_n^{\text{th}}) + y(x,\omega)$$

 \star Inputs:

- ✓ 2 inputs (BNN-I2): Z, N
- ✓ 4 inputs (BNN-I4): *Z*, *N*, $\delta = [(-1)^{Z} + (-1)^{N}]/2$, *Q*_β

 \star Hidden units:

- ✓ 2 inputs (BNN-I2): *H*=30
- ✓ 4 inputs (BNN-I4): *H*=20
- \star Number of parameters: 121
- ★ Data: Audi et al., CPC 41, 030001 (2017)
 - ✓ Entire set: 1009 nuclei in NUBASE2016 (*Z*, *N*>=8 and β -decay fraction=100%)
 - ✓ Learning set: 900 data randomly selected from entire set
 - ✓ **Validation set**: the remaining 109 data in entire set

Half-lives with BNN approaches



★ Logarithmic rms deviations with respect to the known β decay half-lives from NUBASE2016

Predictions of nuclear half-lives



- > The results of WS4+BNN-I4 approach are in a good agreement with the experimental data, in particular, for those with $T_{1/2} < 1$ s.
- > Extrapolating to unknown region, **uncertainties** of WS+BNN-I4 **increase remarkably**.
- Results of other models generally agree with WS4+BNN-I4 within uncertainties.



Prolific sources of nuclides far away from the stability line will be provided using projectile fragmentation, in-flight fission, multi-nucleon transfer, and fusion reactions. The limits shown are the production rate of one nuclide per day, which enable the "discovery experiments"

Predictions of nuclear half-lives



If we can further measure three more β -decay half-lives for each isotopes towards neutron-drip line

- the uncertainties of BNN predictions are similar in the training region
- they will be decreased about 3 times when extrapolate to the region far from known region.

Predictions of r-process abundances



> The uncertainties from nuclear beta-decay half-lives lead to large uncertainties for the rprocess abundances of elements with $A > \sim 140$, which can be remarkably reduced if we can further measure three more β-decay half-lives.

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Summary and Perspectives

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(not hybrid databases !)

 \blacktriangleright more exp. data \rightarrow more reliable extrapolation / smaller uncertainties

(higher accuracy?)

| Quantity | | Effects |
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| | | abundance pattern (?) |
| G | partition functions | path (very weakly) |
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★ Nuclear data inputs for r-process



Summary and Perspectives

D To construct density functional with BNN approach?

$$E_{\text{tot}} = E_{\text{RMF}} + E_{\text{res}}$$

$$E_{\text{RMF}} = \sum_{k=1}^{A} \varepsilon_{k} - \int \left[\frac{1}{2} \alpha_{s} \rho_{s}^{2} + \frac{1}{2} \delta_{s} \rho_{s} \Delta \rho_{s} + \frac{1}{2} \alpha_{v} \rho_{v}^{2} + \frac{1}{2} \delta_{v} \rho_{v} \Delta \rho_{v} + \dots \right] d\vec{r}$$

$$E_{\text{res}} = a + \sum_{j=1}^{H} b_{j} \int \tanh\left(c_{j} + d_{j1}\rho_{s} + d_{j2}\Delta\rho_{s} + d_{j3}\rho_{v} + d_{j4}\Delta\rho_{v} + \dots\right) d\vec{r}$$



