

Two a positive energy state

$$U(\theta, \varphi) U^{-1} U \psi = E U \psi$$

$$(1 - 1) U \psi_{\pm} = \pm U \psi_{\pm}$$

$$H = (\sigma p)$$

$$(\sigma p) \psi = E \psi$$

$$\sigma p = p(\sigma_x \sin \theta \cos \varphi + \sigma_y \sin \theta \sin \varphi + \sigma_z \cos \theta)$$

$$= p \begin{pmatrix} \cos \theta & e^{i\varphi} \sin \theta \\ e^{i\varphi} \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\begin{pmatrix} \cos \theta & e^{i\varphi} \sin \theta \\ e^{i\varphi} \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$

$$= \begin{pmatrix} a_{11} & -a_{12} \\ a_{21} & -a_{22} \end{pmatrix}$$

$$\cos \theta = 2 \cos^2 \frac{\theta}{2}$$

$$= \begin{pmatrix} e^{-\frac{i\varphi}{2}} \cos \frac{\theta}{2} & + e^{-\frac{i\varphi}{2}} \sin \frac{\theta}{2} \\ e^{\frac{i\varphi}{2}} \sin \frac{\theta}{2} & e^{\frac{i\varphi}{2}} \cos \frac{\theta}{2} \end{pmatrix} \sqrt{\frac{1 + \cos \theta}{2}} = \cos \frac{\theta}{2}$$

$$\left( \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right) e^{-\frac{i\varphi}{2}} \cos \frac{\theta}{2} + 2 e^{-\frac{i\varphi}{2}} \sin \frac{\theta}{2} \cos \frac{\theta}{2}$$

$$= e^{-\frac{i\varphi}{2}} \cos \frac{\theta}{2} = a_{11}$$

$$2 e^{\frac{i\varphi}{2}} \sin \frac{\theta}{2} \cos \frac{\theta}{2} - \left( \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right) e^{\frac{i\varphi}{2}} \sin \frac{\theta}{2}$$

$$= e^{\frac{i\varphi}{2}} \sin \frac{\theta}{2} = a_{21}$$

$$\left( \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right) e^{-\frac{i\varphi}{2}} \sin \frac{\theta}{2} + 2 e^{-\frac{i\varphi}{2}} \sin \frac{\theta}{2} \cos \frac{\theta}{2}$$

$$= e^{-\frac{i\varphi}{2}} \sin \frac{\theta}{2}$$

$$2 e^{\frac{i\varphi}{2}} \sin \frac{\theta}{2} \cos \frac{\theta}{2} - e^{\frac{i\varphi}{2}} \left( \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right) \cos \frac{\theta}{2}$$

$$J_1 = L_1 + \frac{x_1}{x_2 + x_3} S$$

$$J_2 = L_2 + \frac{x_2}{x_2 + x_3} S$$

$$J_3 = L_3 + S$$

$$S = \frac{1}{2} \left( \alpha - \frac{1}{2} \right)$$

$$L_1 = x_2 p_3 - x_3 p_2$$

$$L_2 = x_3 p_1 - x_1 p_3$$

$$L_3 = x_1 p_2 - x_2 p_1$$

$$x_2 \left( -i\hbar \frac{\partial}{\partial x_3} + \right) - x_3 \left( -i\hbar \frac{\partial}{\partial x_2} + \right)$$