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$$\begin{aligned}
 &= \delta_{ij} \Psi^{(i)} \Psi^{(j)} \Psi^{(m)} - \tilde{\Psi}^{(i)} \Psi^{(j)} \Psi^{(k)} \Psi^{(m)} \\
 &+ \tilde{\Psi}^{(i)} \Psi^{(k)} \delta_{il} \Psi^{(m)} + \Psi^{(i)} \Psi^{(k)} \tilde{\Psi}^{(l)} \Psi^{(m)} \Psi^{(j)} \\
 &+ \tilde{\Psi}^{(i)} \Psi^{(j)} A_{jk} \Psi^{(k)} \tilde{\Psi}^{(l)} B_{lm} \Psi^{(m)} \\
 &= \tilde{\Psi}^{(i)} \Psi^{(j)} A_{jk} \Psi^{(k)} \tilde{\Psi}^{(l)} B_{lm} \Psi^{(m)} + A_{ik} \tilde{\Psi}^{(l)} \Psi^{(m)} \Psi^{(k)} \\
 &+ \tilde{\Psi}^{(i)} \Psi^{(j)} A_{jk} B_{lm} \Psi^{(m)}
 \end{aligned}$$

$$M + \frac{1+\sqrt{3}}{2} M' = \frac{1-\sqrt{3}}{2} M + \frac{1+\sqrt{3}}{2} (M+M')$$

$$\frac{4\pi q_1^2}{2r} = M_N - M_P \quad \rho_3 \vec{\sigma}$$

$$\frac{4\pi q_1^2}{M_N - M_P} = \cancel{4\pi} (1+3) = \frac{16\pi q_1^2}{M_N - M_P} = (M_N - M_P) c^2$$

$$\frac{e^2}{m c^2} \frac{16\pi q_1^2 \cdot (\frac{e^2}{m c^2})^2}{(\frac{e^2}{m c^2})^2} = (M_N - M_P) c^2$$

$$\delta \sim \left(\frac{g_1^2}{m c^2} \right)^3 \delta$$

(2)

§2. Linear Equations for the Field of Neutral Heavy

~~Equations~~

$$\left. \begin{aligned} \frac{1}{c} \frac{\partial \vec{B}}{\partial t} - \text{curl } \vec{D} - \kappa \vec{V} &= 0 & \text{div } \vec{B} + \kappa V_0 &= 0 \\ \frac{1}{c} \frac{\partial \vec{V}}{\partial t} + \text{grad } V_0 + \kappa \vec{B} &= 0 & \text{curl } \vec{V} - \kappa \vec{D} &= 0 \end{aligned} \right\}$$

$$\bar{L} = \iiint L dv$$

$$L = \frac{1}{8\pi} (\vec{B}^2 - \vec{D}^2 + V_0^2 - \vec{V}^2)$$

$$V_0^+ = 0 \quad \vec{V}^+ = -\frac{1}{4\pi\kappa c} \vec{B}$$

$$H_V = 2\pi\kappa^2 c^2 V^{+2} - c V^+ \text{grad } V_0 + \frac{1}{8\pi\kappa^2} (\text{curl } V)^2 + \frac{1}{8\pi} (V^2 - V_0^2)$$

$$V_0 = -\frac{1}{\kappa} \text{div } \vec{B} = 4\pi c \text{div } V_0^+$$

$$H_V = 2\pi\kappa^2 c^2 V^{+2} - \cancel{c V^+ \text{grad } V_0} + \frac{1}{8\pi\kappa^2} (\text{curl } V)^2 + 2\pi c^2 (\text{div } V^+)^2 + \frac{1}{8\pi} \dot{V}^2$$

$$\left. \begin{aligned} \frac{\partial \vec{V}}{\partial t} &= 4\pi\kappa^2 c^2 \vec{V}^+ - 4\pi c^2 \text{grad } \text{div } V^+ \\ \frac{\partial \vec{V}^+}{\partial t} &= -\frac{1}{4\pi\kappa^2} \text{curl}(\text{curl } \vec{V}) - \frac{1}{4\pi} \dot{V} \end{aligned} \right\}$$

$$\left. \begin{aligned} \frac{1}{c} \frac{\partial \vec{B}}{\partial t} - \text{curl } \vec{D} - \kappa \vec{V} &= -4\pi g_1 \vec{M}' & \text{div } \vec{B} + \kappa V_0 &= 4\pi g_1 M'_0 \\ \frac{1}{c} \frac{\partial \vec{V}}{\partial t} + \text{grad } V_0 + \kappa \vec{B} &= 4\pi g_2 \vec{T}' & \text{curl } \vec{V} - \kappa \vec{D} &= -4\pi g_2 \vec{S}' \end{aligned} \right\}$$

$$\left. \begin{aligned} \vec{M}' &= \tilde{\Psi}(\vec{a}, \vec{b}) \Psi & M'_0 &= \tilde{\Psi}(\vec{a}, \vec{c}) \Psi \\ \vec{T}' &= -\tilde{\Psi}(\rho_2, \vec{c}) \Psi & \vec{S}' &= \tilde{\Psi}(\rho_3, \vec{c}) \Psi \end{aligned} \right\}$$

(3)

$$L = \frac{1}{8\pi} (B^2 - D^2 + V_0 - V) + \frac{g_1}{\kappa} (VM' - V_0 M_0)$$

$$V_0^+ = 0 + \vec{V}^+ = - \frac{\vec{B}}{4\pi\kappa c}$$

$$\frac{\delta \vec{V}}{\delta \vec{x}} = 4\pi\kappa^2 c^2 \vec{V}^+ - c \text{grad } V_0 + 4\pi g_2 c \vec{T}'$$

$$H = \vec{V}^+ (4\pi\kappa^2 c^2 \vec{V}^+ - c \text{grad } V_0 + 4\pi g_2 c \vec{T}') - 2\pi\kappa^2 c^2 \vec{V}^{+2} + \frac{1}{8\pi\kappa^2} (\text{curl } \vec{V} + 4\pi g_2 \vec{S}')^2 - \frac{1}{8\pi} V_0^2 + \frac{1}{8\pi} \vec{V}^2 - \frac{g_1}{\kappa} (VM' - V_0 M_0)$$

$$V_0 = 4\pi c \text{div } \vec{V}^+ + \frac{4\pi g_1}{\kappa} M_0'$$

$$H = H_0 + H'$$

$$H_0 = 2\pi\kappa^2 c^2 V^{+2} + 2\pi c^2 (\text{div } \vec{V}^+)^2 + \frac{1}{8\pi\kappa^2} (\text{curl } \vec{V})^2 + \frac{1}{8\pi} V^2$$

$$H' = \frac{4\pi g_1 c}{\kappa} \text{div } \vec{V}^+ M_0' - \frac{g_1}{\kappa} \nabla M' + 4\pi g_2 c \vec{V}^+ \vec{T}' + \frac{g_2}{\kappa^2} (\text{curl } \vec{V}, \vec{S}') + \frac{2}{\kappa^2} (g_1^2 M_0'^2 + g_2^2 \vec{S}'^2)$$

$$H = H_V + H' + H_M$$

$$H_M = \int \{ c \vec{\alpha} \vec{p} + \beta (\frac{1+\beta_3}{2} M_N c^2 + \frac{1-\beta_3}{2} M_P c^2) \} \Psi$$

$$\begin{aligned} \dot{\Psi} \frac{\partial \Psi}{\partial t} = & [c \vec{\alpha} \vec{p} + \beta (\frac{1+\beta_3}{2} M_N c^2 + \frac{1-\beta_3}{2} M_P c^2) + \frac{4\pi g_1 c}{\kappa} \text{div } \vec{V}^+ \cdot \vec{\beta}_3 \\ & - \frac{g_1}{\kappa} \vec{V}^+ \vec{\alpha} \cdot \vec{\beta}_3 + 4\pi g_2 c \vec{V}^+ \cdot \vec{\beta}_2 \vec{\beta}_3 + \frac{g_2}{\kappa^2} \text{curl } \vec{V} \cdot \vec{\beta}_3 \vec{\beta}_3 \\ & + \frac{4\pi g_1^2}{\kappa^2} M_0' \vec{\beta}_3] \Psi \\ & + \frac{4\pi g_2^2}{\kappa^2} \vec{S}' \cdot \vec{\beta}_3 \vec{\beta}_3 \end{aligned}$$

④

$$\begin{aligned} \ddot{V} &= 4\pi g_1 c \text{grad div } V + 4\pi g_2 c \vec{T}' \\ -\dot{V}^T &= \frac{1}{4\pi\kappa} \text{curl curl } V + \frac{1}{4\pi} V - \frac{g_1}{\kappa} M' + \frac{g_2}{\kappa} \text{curl } S' \\ \frac{1}{c} \ddot{V} &= -\text{curl curl } V - \kappa^2 V + \text{grad div } V \\ &\quad - \frac{4\pi g_1}{\kappa c} \frac{\partial}{\partial t} \text{div } M_0' + \frac{4\pi g_2}{c} \frac{\partial \vec{T}'}{\partial t} - \frac{4\pi g_1}{\kappa^2} \text{grad div } M' \\ &\quad + 4\pi \kappa^2 g_1 M' - 4\pi g_2 \text{curl } S' \\ \frac{1}{c} \ddot{V}^T &= -\text{curl curl } V^T - \frac{g_2}{\kappa c} \text{curl curl } T' \\ &\quad - \kappa^2 V^T + \text{grad div } V^T + \frac{g_1}{\kappa c} \text{grad } M_0' \\ &\quad - \frac{4\pi g_2}{c} \frac{\partial \vec{T}'}{\partial t} + \frac{g_1}{\kappa c} \frac{\partial M'}{\partial t} - \frac{g_2}{\kappa c^2} \frac{\partial}{\partial t} \text{curl } S' \end{aligned}$$

$$\left\{ \frac{1}{c^2} \frac{\partial^2 V}{\partial t^2} - \Delta V + \kappa^2 V \right\} = -\frac{4\pi g_1}{\kappa c} \frac{\partial}{\partial t} \text{div } M_0' + \frac{4\pi g_2}{c} \frac{\partial \vec{T}'}{\partial t} + 4\pi \kappa g_1 M' + 4\pi g_2 \text{curl } S' - \frac{4\pi g_1}{\kappa^2} \text{grad div } M'$$

$$\left\{ \frac{1}{c} \frac{\partial^2 V^T}{\partial t^2} - \Delta V^T + \kappa^2 V^T \right\} = -\frac{g_2}{\kappa c} \text{curl curl } T' + \frac{g_1}{\kappa c} \text{grad } M_0' - \frac{g_2}{c} T'$$

Non-relativistic Approximation.

$$\left. \begin{aligned} -\Delta V + \kappa^2 V &= 4\pi g_2 \text{curl } S' \\ -\Delta V^T + \kappa^2 V^T &= \frac{g_1}{\kappa c} \text{grad } M_0' \end{aligned} \right\}$$

Interaction Potential,

$$\begin{aligned} &\frac{4\pi g_1 c}{\kappa} \text{div } V^T \cdot \vec{\sigma} \tau_3 + \frac{g_2}{\kappa^2} \text{curl } V \cdot \vec{\sigma} \tau_3 + \frac{4\pi g_1}{\kappa^2} (\vec{\Psi} \cdot \vec{\sigma} \Psi) \tau_3 \\ &+ \frac{4\pi g_2}{\kappa^2} (\vec{\Psi} \cdot \vec{\sigma} \Psi) \vec{\sigma} \tau_3 \\ &\approx \frac{g_1^2 \tau_3}{\kappa^2} \left(\frac{e^{-\kappa r}}{r} \text{div grad } M_0' \right) + \frac{g_2^2}{\kappa^2} \left(\vec{\sigma} \frac{e^{-\kappa r}}{r} \text{curl curl } S' \right) \\ &\quad + \frac{4\pi g_1}{\kappa^2} M_0' + \frac{4\pi g_2}{\kappa} S' \cdot \vec{\sigma} \tau_3 \end{aligned}$$

⑤ §3, Deduction of Fermi-Dirac Particles
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$$\frac{g_1^2 \tau_3^{(1)} \tau_3^{(2)}}{x^2} \Delta \frac{e^{-x\gamma}}{\gamma} + \frac{g_2^2 \tau_3^{(1)} \tau_3^{(2)}}{x^2} \left\{ \sigma^{(1)} \text{ and } (\text{curl } \sigma^{(2)} \frac{e^{-x\gamma}}{\gamma}) \right\} \\
+ \frac{4\pi g_1^2}{x^2} \delta(\vec{r}) + \frac{4\pi g_2^2}{x^2} \delta(\vec{r}) \left\{ \sigma^{(1)} \sigma^{(2)} \frac{e^{-x\gamma}}{\gamma} \right\} \\
\left\{ \sigma^{(1)} \text{ grad } \times \left(\text{grad } \times \frac{\sigma^{(2)} e^{-x\gamma}}{\gamma} \right) \right\} \\
= \left\{ \sigma^{(1)} \text{ grad} \right\} \left\{ \sigma^{(2)} \text{ grad} \right\} - \Delta \sigma^{(1)} \sigma^{(2)} \frac{e^{-x\gamma}}{\gamma}$$

$$A \times [B \times C] = (A \cdot B) C - (A \cdot C) B$$

$$= (\text{grad } \text{grad } \sigma^{(1)}) \frac{e^{-x\gamma}}{\gamma} - \Delta \sigma^{(1)} \frac{e^{-x\gamma}}{\gamma}$$

$$= g_1^2 \tau_3^{(1)} \tau_3^{(2)} \frac{e^{-x\gamma}}{\gamma} + g_2^2 \tau_3^{(1)} \tau_3^{(2)} \left\{ \sigma^{(1)} \sigma^{(2)} - \frac{(\sigma^{(1)} \text{ grad})(\sigma^{(2)} \text{ grad})}{x^2} \right\}$$

$$= \frac{1 + \tau_3^{(1)} \tau_3^{(2)}}{2} \left(\dots \right)$$

$$- \frac{1 - \tau_3^{(1)} \tau_3^{(2)}}{2} \left(\dots \right)$$

Exchange interaction の Resultant を求めよ。

$$\left\{ \frac{1 + \tau_3^{(1)} \tau_3^{(2)}}{2} - \frac{1 - \tau_3^{(1)} \tau_3^{(2)}}{2} + \frac{\tau_1^{(1)} \tau_1^{(2)} + \tau_2^{(1)} \tau_2^{(2)}}{2} \right\} \left(\dots \right)$$

for τ_3 の作用 $a + b\tau_3$ と $\lambda \tau_3$

$$\tau_3^{(1)} \tau_3^{(2)} \rightarrow (\tilde{a} + b\tau_3^{(1)}) (a + b\tau_3^{(2)}) + (\tilde{a} + b\tau_3^{(2)}) (a + b\tau_3^{(1)})$$

$$= 2(|a|^2 + |b|^2) \tau_3^{(1)} \tau_3^{(2)} + (\tilde{a}b + a\tilde{b})(\tau_3^{(1)} + \tau_3^{(2)})$$

neutron 1) & proton 1) の free spin τ_3 の resultant

$$\tilde{a}b + a\tilde{b} = 0$$

$$a = |a| e^{i\theta}$$

$$b = |b| e^{i\phi}$$

$$|a||b| \cdot \{ e^{i(\phi-\theta)} + e^{i(\theta-\phi)} \} = 0$$

①
 又、 $|a|=0$ or $|b|=0$ or $\phi-\theta=\pm\pi$.

$\therefore T_3 \rightarrow a + b i T_3$ a, b : real no. \Rightarrow $\frac{1}{2}$

~~or~~ $a=b=\frac{1}{2}$ or ± 1

$T_3^{(1)} T_3^{(2)} \rightarrow \frac{1 + T_3^{(1)} T_3^{(2)}}{2}$: like Particle product, \Rightarrow

$a=1$ $b=0$ or ± 1 ,

$T_3^{(1)} T_3^{(2)} \rightarrow 1 = \frac{1 + T_3^{(1)} T_3^{(2)}}{2} + \frac{1 - T_3^{(1)} T_3^{(2)}}{2} + \dots$

又、最良角子の場 \Rightarrow (7)

$\left\{ \frac{1 + T_3^{(1)} T_3^{(2)}}{2} - \epsilon \frac{1 - T_3^{(1)} T_3^{(2)}}{2} + \frac{T_1^{(1)} T_1^{(2)} + T_2^{(1)} T_2^{(2)}}{2} \right\}$

$\times \left(g_1^2 + g_2^2 (\sigma^{(1)} \sigma^{(2)}) - g_2^2 \frac{(\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad})}{x^2} \right) \frac{e^{-x r}}{r}$

or, $\epsilon = 0, \pm 1$.

\Rightarrow $\frac{1}{2} g_1 g_2 \sigma^{(1)} \sigma^{(2)}$

N-P: $^3S : -(1+\epsilon) \cdot \left(g_1^2 + \frac{2}{3} g_2^2 \right) \frac{e^{-x r}}{r}$

$^1S : (1-\epsilon) \left(g_1^2 - \frac{2}{3} g_2^2 \right) \frac{e^{-x r}}{r}$

N-N } $^1S : (g_1^2 - 2g_2^2) \frac{e^{-x r}}{r}$
 P-P }

$\epsilon=0, (a=b=1 \frac{1+iT_3}{2} \text{ or } \frac{\tau_3+i}{2})$

$g_1=g_2$: $\left. \begin{array}{l} \text{N-P } ^3S : -\frac{5}{3} g^2 \frac{e^{-x r}}{r} \\ \text{N-P } ^1S : -g^2 \frac{e^{-x r}}{r} \\ \text{N-N } ^1S : -g^2 \frac{e^{-x r}}{r} \end{array} \right\}$

Kemmer, The charge-dependence of Nuclear Forces.

(Proc. Camb. Phil. Soc. , 1958)

$$\begin{aligned}
 V &= \frac{1}{2} \left\{ (g' \frac{1+\tau_3^{(1)}}{2} + g'' \frac{1-\tau_3^{(1)}}{2}) \times (g'^* \frac{1+\tau_3^{(2)}}{2} + g''^* \frac{1-\tau_3^{(2)}}{2}) \right. \\
 &\quad \left. + (g' \frac{1+\tau_3^{(2)}}{2} + g'' \frac{1-\tau_3^{(2)}}{2}) \times (g'^* \frac{1+\tau_3^{(1)}}{2} + g''^* \frac{1-\tau_3^{(1)}}{2}) \right\} \\
 &= \frac{1}{2} (|g' + g''|^2 + |g' - g''|^2 (\tau_3^{(1)} \tau_3^{(2)})) \\
 &\quad + (|g'|^2 - |g''|^2) (g' + g'') (g'^* - g''^*) \\
 &\quad + (g' - g'') (g'^* + g''^*) \tau_3^{(1)} \tau_3^{(2)} \} \\
 &\quad |g'|^2 - |g''|^2
 \end{aligned}$$

$$|g' - g''|^2 = |g|^2$$

$$(1+i\tau_3)(1-i\tau_3)$$

$$\rightarrow 1 + \tau_3^{(1)} \tau_3^{(2)}$$

$$\tau_1^{(1)} \tau_1^{(2)} + \tau_2^{(1)} \tau_2^{(2)} + \tau_3^{(1)} \tau_3^{(2)}$$

P-N	symm.	-2 - 1 = -3
	anti.	2 - 1 = 1
N-N	symm	
P-N	anti.	1

$$1 + \tau_2^{(1)} \tau_2^{(2)}$$

P-N	symm	1 - 2 - 1 = -2
	anti	1 + 2 - 1 = 2
N-N	symm	
P-N	anti	1 + 1 = 2

$$\left\{ \frac{\hbar^2}{M} \Delta + E - V \right\} \Psi = 0$$

$$V = \left\{ \frac{\tau_1^{(1)} \tau_1^{(2)} + \tau_2^{(1)} \tau_2^{(2)}}{2} \right\} \left\{ g_1^2 + g_2^2 (\sigma^{(1)} \sigma^{(2)}) - g_2^2 \frac{(\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad})}{\kappa^2} \right\}$$

Symmetric States $\times \frac{e^{-\kappa r}}{r}$

(a) ${}^3S, {}^1P, {}^3D, \dots$

$$V = - \left\{ g_1^2 + g_2^2 (\sigma^{(1)} \sigma^{(2)}) - g_2^2 \frac{(\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad})}{\kappa^2} \right\} \frac{e^{-\kappa r}}{r}$$

i) Even, ${}^3S, {}^3D, \dots$
 (Triplet)

$$V = - \left\{ g_1^2 + g_2^2 - g_2^2 \frac{(\sigma^{(1)} \sigma^{(2)})}{\kappa^2} \right\}$$

$$(\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad}) = \begin{pmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial y} & -\frac{\partial}{\partial x} \end{pmatrix}_1 \begin{pmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial y} & -\frac{\partial}{\partial x} \end{pmatrix}_2 + \begin{pmatrix} \frac{\partial}{\partial x} & -i\frac{\partial}{\partial y} \\ i\frac{\partial}{\partial y} & \frac{\partial}{\partial x} \end{pmatrix}_1 \begin{pmatrix} \frac{\partial}{\partial x} & -i\frac{\partial}{\partial y} \\ i\frac{\partial}{\partial y} & \frac{\partial}{\partial x} \end{pmatrix}_2$$

$$+ \begin{pmatrix} \frac{\partial}{\partial x} & 0 \\ 0 & -\frac{\partial}{\partial x} \end{pmatrix}_1 \begin{pmatrix} \frac{\partial}{\partial x} & 0 \\ 0 & -\frac{\partial}{\partial x} \end{pmatrix}_2$$

Triplet, $\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2$: $\begin{pmatrix} 0 \\ \frac{\partial}{\partial x} \end{pmatrix}_1 \begin{pmatrix} 0 \\ \frac{\partial}{\partial x} \end{pmatrix}_2 + \begin{pmatrix} 0 \\ i\frac{\partial}{\partial y} \end{pmatrix}_1 \begin{pmatrix} 0 \\ i\frac{\partial}{\partial y} \end{pmatrix}_2 + \begin{pmatrix} \frac{\partial}{\partial x} \\ 0 \end{pmatrix}_1 \begin{pmatrix} \frac{\partial}{\partial x} \\ 0 \end{pmatrix}_2$

$\begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2$

$\begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2$

$$(\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad}) = \begin{pmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial x} - i\frac{\partial}{\partial y} \\ \frac{\partial}{\partial x} + i\frac{\partial}{\partial y} & -\frac{\partial}{\partial x} \end{pmatrix}_1 \begin{pmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial x} - i\frac{\partial}{\partial y} \\ \frac{\partial}{\partial x} + i\frac{\partial}{\partial y} & -\frac{\partial}{\partial x} \end{pmatrix}_2$$

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$$V = \frac{\tau_1^{(12)} + \tau_2^{(12)}}{2} \left[g_1 + g_2 \left(\frac{1}{r} \right) + g_2^2 \left\{ (\sigma_1^{(1)} \sigma_2^{(2)}) - \frac{3(\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(2)} \cdot \mathbf{r})}{r^2} \right\} \left(\frac{1}{x^2} - \frac{1}{x^2 y} \right) \right] \frac{e^{-\kappa r}}{r}$$

a) Symmetric State (${}^3S, {}^1P, {}^3D, \dots$)

$$V = - \left\{ g_1^2 + g_2^2 \left\{ (\sigma_1^{(1)} \sigma_2^{(2)}) - \frac{3(\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(2)} \cdot \mathbf{r})}{r^2} \right\} + g_2^2 \left\{ (\sigma_1^{(1)} \sigma_2^{(1)}) - \frac{3(\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(1)} \cdot \mathbf{r})}{r^2} \right\} \right\} \frac{e^{-\kappa r}}{r}$$

1) Triplet state

$$\sigma_1^{(1)} \sigma_2^{(2)} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_2 + \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}_1 \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}_2 + \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}_1 \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}_2$$

$$\sigma_1^{(1)} \sigma_2^{(2)} \begin{cases} \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \\ \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 = 2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 - \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 \\ \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = 2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 \\ \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 \end{cases}$$

$\sigma_1^{(1)} \sigma_2^{(2)}$ (triplet) = 1. (triplet)

$$(\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(2)} \cdot \mathbf{r}) = \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_1 \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_2$$

$$(\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(2)} \cdot \mathbf{r}) \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = \begin{pmatrix} z \\ x+iy \end{pmatrix}_1 \begin{pmatrix} z \\ x+iy \end{pmatrix}_2$$

$$\begin{aligned} (\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(2)} \cdot \mathbf{r}) \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 &= \begin{pmatrix} z \\ x+iy \end{pmatrix}_1 \begin{pmatrix} x-iy \\ -z \end{pmatrix}_2 \\ (\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(2)} \cdot \mathbf{r}) \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 &= \begin{pmatrix} x-iy \\ -z \end{pmatrix}_1 \begin{pmatrix} z \\ x+iy \end{pmatrix}_2 \\ (\sigma_1^{(1)} \cdot \mathbf{r})(\sigma_2^{(2)} \cdot \mathbf{r}) \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 &= \begin{pmatrix} x-iy \\ -z \end{pmatrix}_1 \begin{pmatrix} x-iy \\ -z \end{pmatrix}_2 \end{aligned}$$

Triplet, Diagonal

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2$$

(9)

$$\frac{1}{2} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = -z^2 + (x^2 + y^2) = v^2 \sin^2 \theta$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 + \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = z^2 = v^2 \cos^2 \theta \quad (3)$$

Singlet

$$\frac{1}{2} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 = -(z^2 + y^2 + x^2) \quad (1)$$

Triplet, Non-Diagonal

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = (x + iy)^2 = x^2 - y^2 + 2ixy \quad (8)$$

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 = x^2 - y^2 - 2ixy$$

$$\frac{1}{\sqrt{2}} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = \sqrt{2} z x + \sqrt{2} i y z$$

$$\frac{1}{\sqrt{2}} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = -\sqrt{2} z x + \sqrt{2} i y z$$

Singlet - Singlet

(6)

$$\frac{1}{\sqrt{2}} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = 0$$

$$\frac{1}{2\sqrt{2}} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 = 0$$

$$\left[(\vec{\sigma}_1 \cdot \vec{\sigma}_2) (\vec{\sigma}_1 \cdot \vec{r}) \right] = \left[(\sigma_x^{(1)} \sigma_x^{(2)} + \sigma_y^{(1)} \sigma_y^{(2)} + \sigma_z^{(1)} \sigma_z^{(2)}) (\sigma_x^{(1)} x + \sigma_y^{(1)} y + \sigma_z^{(1)} z) \right]$$

$$= 2i (\sigma_z^{(1)} \sigma_x^{(2)} y - \sigma_y^{(1)} \sigma_x^{(2)} z + \dots)$$

$$\left[(\vec{\sigma}_1 \cdot \vec{\sigma}_2) (\vec{\sigma}_2 \cdot \vec{r}) (\vec{\sigma}_1 \cdot \vec{r}) \right] = 0$$

Total Angular Momentum

$$(\vec{r} \times \vec{p}) (\vec{\sigma}^{(1)} \cdot \vec{r}) - (\vec{\sigma}^{(1)} \cdot \vec{r}) (\vec{r} \times \vec{p}) = -i\hbar (\vec{r} \times \vec{\sigma}^{(1)})$$

$$(\because (x p_y - y p_x) \{ \sigma_x^{(1)} x + \sigma_y^{(1)} y + \sigma_z^{(1)} z \} - \{ \sigma_x^{(1)} x + \sigma_y^{(1)} y + \sigma_z^{(1)} z \} (x p_y - y p_x))$$

$$= -i\hbar (x \sigma_y^{(1)} - y \sigma_x^{(1)}) = -i\hbar (\vec{r} \times \vec{\sigma}^{(1)})_z$$

$$[(\vec{r} \times \vec{p}), (\vec{\sigma}^{(1)} \cdot \vec{r}) (\vec{\sigma}^{(2)} \cdot \vec{r})] = -i\hbar (\vec{r} \times \vec{\sigma}^{(1)}) (\sigma^{(2)} \cdot \vec{r}) - i\hbar (\sigma^{(1)} \cdot \vec{r}) (\vec{r} \times \sigma^{(2)})$$

$$\vec{\sigma}^{(1)} (\vec{\sigma}^{(1)} \cdot \vec{r}) - (\vec{\sigma}^{(1)} \cdot \vec{r}) \vec{\sigma}^{(1)} = i(\vec{r} \times \vec{\sigma}^{(1)})$$

$$(\because \sigma_x (\sigma_x x + \sigma_y y + \sigma_z z) - (\sigma_x x + \sigma_y y + \sigma_z z) \sigma_x = 2i(\sigma_z y - \sigma_y z))$$

$$\{ (\vec{r} \times \vec{p}) + \frac{\hbar}{2} (\sigma^{(1)} + \sigma^{(2)}) \} (\sigma^{(1)} \cdot \vec{r}) (\sigma^{(2)} \cdot \vec{r}) - (\sigma^{(1)} \cdot \vec{r}) (\sigma^{(2)} \cdot \vec{r}) \{ \dots \} = 0$$

$j = l + s$	$l = s$ (Sym)	anti (sp)	Sym (D)	anti (F)
triplet, $s=1$	$l=0$	1	2	3
$J = \begin{cases} 1 \\ 0 \\ 0 \end{cases}$	$\begin{cases} 3S_1 \\ 3S_0 \\ 3S_{-1} \end{cases}$	$\begin{cases} 3P_2 \\ 3P_1 \\ 3P_0 \end{cases}$	$\begin{cases} 3D_3 \\ 3D_2 \\ 3D_1 \end{cases}$	$\begin{cases} 3F_4 \\ 3F_3 \\ 3F_2 \end{cases}$

3S combine to 3D_1 etc.

3S - 3D₁ - states

$$V = - \left[g_1^2 + g_2^2 \left(1 - \frac{(z, x-iy)(z, x-iy)}{r^2} \right) \right. \\ \left. + g_3^2 \left(1 - \frac{3(z, x-iy)(z, x-iy)}{r^2} \right) \left(\frac{1}{kr} + \frac{1}{k^2 r^2} \right) \right] \frac{e^{-kr}}{r}$$

$$\frac{1}{r} (\vec{\sigma}^{(1)} \cdot \vec{r}) = \sigma_r^{(1)} \quad \sigma_r^{(1)2} = 1 \\ \frac{1}{r} (\vec{\sigma}^{(2)} \cdot \vec{r}) = \sigma_r^{(2)} \quad \sigma_r^{(2)2} = 1$$

$$V = - \left[g_1^2 + g_2^2 \left(1 - \sigma_r^{(1)} \sigma_r^{(2)} \right) + g_3^2 \left(1 - 3 \sigma_r^{(1)} \sigma_r^{(2)} \right) \left(\frac{1}{kr} + \frac{1}{k^2 r^2} \right) \right] \frac{e^{-kr}}{r}$$

$$\left\{ \frac{\hbar^2}{M} \Delta + E + \left[\frac{e^{-kr}}{r} \right] \right\} \Psi = 0$$

- S-state $u_S(r)$
- D-state $m=0$ $u_0 \sqrt{\frac{5}{4\pi}} \left(\frac{3}{2} \cos^2 \theta - \frac{1}{2} \right)$
- $m=1$ $u_{1,1} \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{i\varphi}$ $m=2$ $u_2 \cdot \frac{1}{4} \sqrt{\frac{15}{2\pi}} \sin^2 \theta e^{2i\varphi}$
- $m=-1$ $u_{-1} \dots e^{-i\varphi}$ $m=-2$ $u_{-2} \dots e^{-2i\varphi}$

3D₁ $\left. \begin{matrix} m_s = 1 \\ m_s = 0 \\ m_s = -1 \end{matrix} \right\} = \frac{9}{4} x^4 - \frac{3}{2} x^2 + \frac{1}{4} \frac{2\sqrt{2}}{9-1+5} = \frac{4}{5} = \frac{2}{15}$

$j=1$

$\sqrt{\frac{3}{4\pi}} \sin \theta e^{i\varphi}$	$\frac{1}{2}(x+iy)$	} $\frac{1}{2}(x+iy)^2 = \frac{1}{2}(x^2 - y^2 + 2ixy)$
$\sqrt{\frac{3}{4\pi}} \cos \theta$	z	
$\sqrt{\frac{3}{4\pi}} \sin \theta e^{-i\varphi}$	$\frac{1}{2}(x-iy)$	

$l=2, s=1$ $j = \begin{matrix} 3 \\ 2 \\ 1 \end{matrix}$ $5X = 15$

Marginal

S=1

$$\left. \begin{aligned}
 \chi_1 &= \frac{1}{\sqrt{2}}(x+iy) \\
 \chi_0 &= z \\
 \chi_{-1} &= \frac{1}{\sqrt{2}}(x-iy)
 \end{aligned} \right\} \begin{aligned}
 v_2 &= \frac{1}{2}\sqrt{\frac{3}{2}}(x+iy)^2 \\
 v_1 &= \sqrt{\frac{3}{2}}(x+iy)z \\
 v_0 &= 2z^2 - x^2 - y^2 \\
 v_{-1} &= \sqrt{\frac{3}{2}}(x-iy)z \\
 v_{-2} &= \frac{1}{2}\sqrt{\frac{3}{2}}(x-iy)^2
 \end{aligned}$$

$$\left. \begin{aligned}
 (x+iy)^2 \\
 (x+iy)^2 z \\
 (x+iy)(4z^2 - x^2 - y^2) \\
 (4z^2 - 3x^2 - 3y^2)z \\
 (x-iy)(4z^2 - x^2 - y^2) \\
 (x-iy)^2 z \\
 (x-iy)^2
 \end{aligned} \right\} \begin{aligned}
 &= \chi_1 v_2 \\
 &= \chi_1 v_1, \chi_0 v_2 \\
 &= \frac{2}{\sqrt{3}}\chi_0 v_1 + \chi_1 v_0 \\
 &= \\
 &=
 \end{aligned}$$

$$\sqrt{3} z^{-2} z^2 +$$

$$\hat{j}=1 \left\{ \begin{aligned}
 a_{11}\chi_1 v_0 + a_{12}\chi_0 v_1 + a_{13}\chi_{-1} v_2 &\propto \frac{1}{\sqrt{2}}(x+iy) f(r) \\
 a_{21}\chi_1 v_{-1} + a_{22}\chi_0 v_0 + a_{23}\chi_{-1} v_{-1} &\propto z f(r) \\
 a_{31}\chi_1 v_{-2} + a_{32}\chi_0 v_{-1} + a_{33}\chi_{-1} v_0 &\propto \frac{1}{\sqrt{2}}(x-iy) f(r)
 \end{aligned} \right.$$

$$a_{11} \frac{1}{2}(2z^2 - x^2 - y^2) + a_{12} \sqrt{\frac{3}{2}} z^2 + a_{13} \frac{1}{2}\sqrt{\frac{3}{2}}(x^2 + y^2) = f(r)$$

$$= \underbrace{(a_{13} \frac{1}{2}\sqrt{\frac{3}{2}} - 2a_{11})}_{=0} r^2 + (2a_{11} + \sqrt{3}a_{12} - a_{13} \frac{1}{2}\sqrt{\frac{3}{2}}) z^2$$

$$a_{11} \frac{1}{\sqrt{2}}(x+iy)(2z^2 - x^2 - y^2) + a_{12} \sqrt{\frac{3}{2}} z (x+iy)z + a_{13} \frac{\sqrt{3}}{4} (x-iy)(x+iy)^2$$

$$\Psi_m^L = \sum_{\mu\nu} S_{Lm;\mu\nu}^* \Psi_\mu \Psi_\nu \quad \text{Wigner, Gruppentheorie XVII}$$

$$S_{L,\mu+\nu;\mu,\nu} = S_{L,\mu\nu}$$

$$\Psi_m^L = \sum_{\mu} S_{L\mu m;\mu} \Psi_\mu \Psi_{m-\mu}$$

$$S_{L\mu\nu} = \frac{\sqrt{(L+l-\bar{l})(L-l+\bar{l})(l+\bar{l}-L)!(L+\mu+\nu)!(L-\mu-\nu)!}}{\sqrt{(L+l+\bar{l}+1)!(l-\mu)!(l+\mu)!(\bar{l}-\mu)!(\bar{l}+\nu)!}}$$

$$\times \sum_{\kappa} \frac{(-1)^{\kappa+\bar{l}+\nu} \sqrt{2L+1} (L+\bar{l}+\mu-\kappa)!(l-\mu+\kappa)!}{(L-l+\bar{l}-\kappa)!(L+\mu+\nu-\kappa)! \kappa! (\kappa+l-\bar{l}-\mu-\nu)!}$$

$l=1, l=2$ ©2023 YHA, YITP, Kyoto University
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 $(0, m+v-1) \leftarrow \kappa < \frac{1}{2} m+v$ (13)

$$S_{\kappa \mu \nu} = \frac{2 \sqrt{2} \cdot (1+\mu+\nu)! (1-\mu-\nu)!}{\sqrt{5! (2-\mu)! (2+\mu)! (1-\nu)! (1+\nu)!}}$$

$$\times \sum_{\kappa} \frac{(-1)^{\kappa+1+\nu} \sqrt{3} (2+\mu-\kappa)! (2-\mu+\kappa)!}{(\kappa)! (1+\mu+\nu-\kappa)! \kappa! (\kappa-\mu-\nu+1)!}$$

$\begin{matrix} 1+2-1 & & 0 & & -2+1+1 \\ & & & & 0 \end{matrix}$

$m=1:$

$$\Psi_1 = \sum_{\mu} S_{\mu, 1-\mu} \Psi_{\mu} \bar{\Psi}_{1-\mu} = S_{2,-1} \Psi_2 \bar{\Psi}_{-1} + S_{1,0} \Psi_1 \bar{\Psi}_0 + S_{0,1} \Psi_0 \bar{\Psi}_1$$

$$\Psi_0 = \sum_{\mu} S_{\mu, 0-\mu} \Psi_{\mu} \bar{\Psi}_{0-\mu} = S_{1,-1} \Psi_1 \bar{\Psi}_{-1} + S_{0,0} \Psi_0 \bar{\Psi}_0 + S_{-1,1} \Psi_{-1} \bar{\Psi}_1$$

$$\Psi_{-1} = \sum_{\mu} S_{\mu, -1-\mu} \Psi_{\mu} \bar{\Psi}_{-1-\mu} = S_{0,-1} \Psi_0 \bar{\Psi}_{-1} + S_{1,0} \Psi_1 \bar{\Psi}_0 + S_{-2,1} \Psi_{-2} \bar{\Psi}_1$$

$$S_{2,-1} = \frac{2 \sqrt{2} \cdot \sqrt{3} 4!}{\sqrt{5! 4! 2!}} = \sqrt{\frac{12}{5}}$$

$$S_{1,0} = \frac{2 \sqrt{2} (-1) \sqrt{3} 3!}{\sqrt{5! 3! 2!}} = -\sqrt{\frac{3}{10}}$$

$$S_{0,1} = \frac{2 \sqrt{2} \sqrt{3} 2!}{\sqrt{5! 2! 3!}} = \sqrt{\frac{24}{5}}$$

$\bar{l} = s = 1, L = l$

L	$v = -1$	$v = 0$	$v = 1$
$l-1$	$\frac{\sqrt{l+\mu} \sqrt{l+\mu-1}}{\sqrt{2l} \sqrt{2l+1}}$	$\frac{\sqrt{l-\mu} \sqrt{l+\mu}}{\sqrt{l} \sqrt{2l+1}}$	$\frac{\sqrt{l-\mu-1} \sqrt{l-\mu}}{\sqrt{2l} \sqrt{2l+1}}$

$l=2$ $L=1$	$\frac{\sqrt{2+\mu} \sqrt{1+\mu}}{2 \cdot \sqrt{5}}$	$-\frac{\sqrt{2-\mu} \sqrt{2+\mu}}{\sqrt{2} \sqrt{5}}$	$\frac{\sqrt{1-\mu} \sqrt{2-\mu}}{2 \sqrt{5}}$
----------------	--	--	--

$S_{0,-1} = \frac{\sqrt{2}}{2\sqrt{5}} = \frac{1}{\sqrt{10}}$	$S_{-1,0} = \frac{\sqrt{3}}{\sqrt{10}} = \sqrt{\frac{3}{10}}$	$S_{-2,1} = \frac{\sqrt{3} \cdot 2}{2\sqrt{5}} = \sqrt{\frac{3}{5}}$
$S_{1,-1} = \frac{\sqrt{3} \cdot \sqrt{2}}{2\sqrt{5}} = \sqrt{\frac{3}{10}}$	$S_{0,0} = \sqrt{\frac{2}{5}}$	$S_{-1,1} = \frac{\sqrt{2} \cdot \sqrt{3}}{2\sqrt{5}} = \sqrt{\frac{3}{10}}$
$S_{2,-1} = \frac{2 \cdot \sqrt{3}}{2\sqrt{5}} = \sqrt{\frac{3}{5}}$	$S_{1,0} = \sqrt{\frac{3}{10}}$	$S_{0,1} = \sqrt{\frac{1}{10}}$

$\Psi_{-1} = \frac{1}{\sqrt{10}} (\sqrt{5} \chi_{-1} - \sqrt{3} \sqrt{2} \chi_0 + \sqrt{6} \sqrt{2} \chi_1)$

$\Psi_0 = \frac{1}{\sqrt{10}} (\sqrt{3} \sqrt{2} \chi_{-1} - 2 \sqrt{5} \chi_0 + \sqrt{3} \sqrt{2} \chi_1)$

$\Psi_{+1} = \frac{1}{\sqrt{10}} (\sqrt{6} \sqrt{2} \chi_{-1} - \sqrt{3} \sqrt{2} \chi_0 + \sqrt{5} \chi_1)$

$\chi_{-1} = \beta(1)\beta(2)$	} $\left. \begin{aligned} v_0 &= \sqrt{\frac{5}{4\pi}} \left(\frac{3}{2} \cos^2 \theta - \frac{1}{2} \right) \\ v_{\pm 1} &= \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{\pm i\varphi} \\ v_{\pm 2} &= \frac{1}{4} \sqrt{\frac{15}{2\pi}} \sin^2 \theta e^{\pm 2i\varphi} \end{aligned} \right\}$
$\chi_0 = \frac{1}{\sqrt{2}} (\alpha(1)\beta(2) + \alpha(2)\beta(1))$	
$\chi_1 = \alpha(1)\alpha(2)$	

$\Psi_1 = \frac{1}{\sqrt{10}} \left\{ \sqrt{\frac{5}{4\pi}} (\) \chi_{-1} - \sqrt{\frac{5}{8\pi}} 3 \sin \theta \cos \theta \right\}$

$\frac{1}{4} \sqrt{\frac{3}{4\pi}}$

(15)

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$$(\vec{\sigma}_1 \cdot \vec{n}) (\vec{\sigma}_2 \cdot \vec{n}) = \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_1 \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_2$$

$$\begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_1 \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_2 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2 = \begin{pmatrix} x-iy \\ -z \end{pmatrix}_1 \begin{pmatrix} x-iy \\ -z \end{pmatrix}_2$$

$$= z^2 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2 - \sqrt{2} z (x-iy) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2 + \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_2$$

$$+ (x-iy)^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_2$$

$$|(\vec{\sigma}_1 \cdot \vec{n})(\vec{\sigma}_2 \cdot \vec{n}) \chi_{-1} = z^2 \chi_{-1} - \sqrt{2} z (x-iy) \chi_0 + (x-iy)^2 \chi_1|$$

$$\begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_1 \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_2 \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2$$

$$= \frac{1}{\sqrt{2}} \left\{ \begin{pmatrix} z & \\ x+iy & \end{pmatrix}_1 \begin{pmatrix} x-iy \\ -z \end{pmatrix}_2 + \begin{pmatrix} x-iy \\ -z \end{pmatrix}_1 \begin{pmatrix} z & \\ & x+iy \end{pmatrix}_2 \right\}$$

$$= \sqrt{2} z (x-iy) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_2 + \frac{1}{\sqrt{2}} (x^2 + y^2 - z^2) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2$$

$$- \sqrt{2} z (x+iy) \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2$$

$$|(\vec{\sigma}_1 \cdot \vec{n})(\vec{\sigma}_2 \cdot \vec{n}) \chi_0 = -\sqrt{2} z (x+iy) \chi_{-1} + (x^2 + y^2 - z^2) \chi_0 + \sqrt{2} z (x-iy) \chi_1|$$

$$\begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_1 \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_2 \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}_1 \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}_2 = \begin{pmatrix} z & \\ x+iy & \end{pmatrix}_1 \begin{pmatrix} z \\ x+iy \end{pmatrix}_2$$

$$= z^2 \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}_1 \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}_2 + \sqrt{2} z (x+iy) \left\{ \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2 + \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_2 \right\} + (x-iy)^2 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_1 \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}_2$$

$$|(\vec{\sigma}_1 \cdot \vec{n})(\vec{\sigma}_2 \cdot \vec{n}) \chi_1 = (x-iy)^2 \chi_{-1} + \sqrt{2} z (x+iy) \chi_0 + z^2 \chi_1|$$

$$\begin{pmatrix} z^2 & -\sqrt{2} z (x+iy) & (x+iy)^2 \\ \sqrt{2} z (x+iy) & z^2 + (x+iy)^2 & \sqrt{2} z (x-iy) \\ (x+iy)^2 & \sqrt{2} z (x-iy) & z^2 \end{pmatrix} = r^2 \begin{pmatrix} \cos^2 \theta & -\sqrt{2} \cos \theta \sin \theta e^{i\varphi} & \sin^2 \theta e^{2i\varphi} \\ -\sqrt{2} \cos \theta \sin \theta e^{-i\varphi} & \cos^2 \theta + \sin^2 \theta & \sqrt{2} \cos \theta \sin \theta e^{i\varphi} \\ \sin^2 \theta e^{-2i\varphi} & \sqrt{2} \cos \theta \sin \theta e^{-i\varphi} & \cos^2 \theta \end{pmatrix}$$

$$\left\{ \frac{(\sigma_1 r)(\sigma_2 r)}{r^2} \right\}_{ij} = \sum_{\substack{k \\ \neq i}} \sum_{\substack{l \\ \neq j}} \left\{ \frac{(\sigma_1 r)(\sigma_2 r)}{r^2} \right\}_{kl}$$

$$\sum_{\substack{k \\ \neq i}} \left\{ \frac{(\sigma_1 r)(\sigma_2 r)}{r^2} \right\}_{ij} = \sum_{\substack{k \\ \neq i}} \Psi_{-1} = \Psi_{-1} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \sqrt{\frac{1}{10}} \begin{pmatrix} v_0 \cos^2 \theta \\ \sqrt{6} v_{-1} \cos \theta \sin \theta e^{+i\varphi} \\ \sqrt{6} v_2 \sin^2 \theta e^{2i\varphi} \end{pmatrix}$$

$$\Psi_{-1+} = \sqrt{\frac{1}{10}} \left\{ v_0 \cos^2 \theta + \sqrt{6} v_{-1} \cos \theta \sin \theta e^{+i\varphi} + \sqrt{6} v_2 \sin^2 \theta e^{2i\varphi} \right\}$$

$$\Psi_{-10} = \sqrt{\frac{1}{10}} \left\{ -\sqrt{6} v_{-1} \cos \theta \sin \theta e^{-i\varphi} - 2v_0 (\cos^2 \theta - \sin^2 \theta) + \sqrt{6} v_2 \cos \theta \sin \theta e^{+i\varphi} \right\}$$

$$\Psi_{-1-1} = 0$$

$$\left\{ \frac{(\sigma_1 r)(\sigma_2 r)}{r^2} \right\}_{ij} = 0 \text{ for } i \neq j$$

(∵ Total angular momentum is 2-comp & $\left\{ \frac{(\sigma_1 r)(\sigma_2 r)}{r^2} \right\}$ is commutative.)

$$\left\{ \frac{(\sigma_1 r)(\sigma_2 r)}{r^2} \right\}_{-1-1} = \sqrt{\frac{1}{10}} \left\{ v_0 \cos^2 \theta - \sqrt{6} v_{-1} \cos \theta \sin \theta e^{i\varphi} + \sqrt{6} v_2 \sin^2 \theta e^{2i\varphi} \right\}$$

$$= \sqrt{\frac{1}{10}} \left\{ \sqrt{\frac{5}{4\pi}} \left(\frac{3}{2} \cos^2 \theta - \frac{1}{2} \right) \cos^2 \theta \right.$$

$$\left. - \sqrt{6} \sqrt{\frac{15}{8\pi}} \sin^2 \theta \cos^2 \theta + \frac{\sqrt{6}}{4} \sqrt{\frac{15}{2\pi}} \sin^4 \theta \right\}$$

$$= \sqrt{\frac{1}{10}} \sqrt{\frac{5}{4\pi}} \frac{1}{\sqrt{4}} \left\{ \frac{3}{2} \frac{z^4}{r^4} - \frac{1}{2} \frac{z^2}{r^2} + 3 \frac{z^2 (x^2 + y^2)}{r^4} + \frac{3\sqrt{2}}{24} \frac{(x^2 + y^2)^2}{r^4} \right\}$$

$$= \sqrt{\frac{1}{10}} \sqrt{\frac{5}{4\pi}} \left\{ \frac{3}{2} - \frac{1}{2} + \frac{\sqrt{6}}{\sqrt{6}} \frac{1}{6} \right\} = \sqrt{\frac{1}{10}} \sqrt{\frac{5}{4\pi}} \frac{84}{84} = \frac{1}{3} \sqrt{\frac{18}{8\pi}}$$

$$= \frac{1}{3} \sqrt{\frac{2}{\pi}} \cdot \frac{1}{r} \left\{ \frac{z^2 + (x^2 + y^2)}{r^2} \right\}^2$$

$$= \left\{ \begin{matrix} 1_{00} \\ \neq 1_{-1} \end{matrix} \right\} \frac{1}{r^4}$$

3S-3D₁

$$\Psi = \frac{u(r)}{r} \chi_{-1} + \frac{v(r)}{r} \sqrt{\frac{2}{10}} (Y_0 \chi_{-1} - \sqrt{3} Y_{-1} \chi_0 + \sqrt{6} Y_{-2} \chi_1)$$

$$\left. \begin{aligned} Y_0 &= \sqrt{\frac{5}{4\pi}} \left(\frac{3}{2} \cos^2 \theta - \frac{1}{2} \right) \\ Y_{-1} &= \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{-i\varphi} \\ Y_{-2} &= \frac{1}{4} \sqrt{\frac{15}{2\pi}} \sin^2 \theta e^{-2i\varphi} \end{aligned} \right\} \begin{aligned} &\sqrt{\frac{1}{10}} Y_0 \\ &-\sqrt{\frac{3}{10}} Y_{-1} \\ &\sqrt{\frac{6}{10}} Y_{-2} \end{aligned} \left\} = \begin{aligned} &\frac{3}{4} \sqrt{\frac{1}{8\pi}} \left(\frac{3}{2} \cos^2 \theta - \frac{1}{2} \right) \\ &-\frac{1}{4} \sqrt{\frac{3}{8\pi}} \frac{3\sqrt{3}}{2} \sin \theta \cos \theta e^{-i\varphi} \\ &\frac{1}{4} \sqrt{\frac{3}{8\pi}} \frac{3}{2} \sin^2 \theta e^{-2i\varphi} \end{aligned}$$

$$\left\{ \frac{\hbar^2}{m} \Delta + E + \left(g_1^2 + g_2^2 \left(1 - \frac{\sigma^{(1)} r \sigma^{(2)} r}{r^2} \right) + g_2^2 \left(1 - \frac{3\sigma^{(1)} r \sigma^{(2)} r}{r^2} \right) \left(\frac{1}{x r} + \frac{1}{x r v} \right) \right\} \frac{e^{-x r}}{r} \Psi = 0$$

$$\Psi = \begin{pmatrix} \frac{u(r)}{r} + \sqrt{\frac{1}{10}} \frac{v(r)}{r} Y_0 \\ -\sqrt{\frac{3}{10}} \frac{v(r)}{r} Y_{-1} \\ \sqrt{\frac{6}{10}} \frac{v(r)}{r} Y_{-2} \end{pmatrix}$$

$$\frac{\sigma^{(1)} r \sigma^{(2)} r}{r^2} = \begin{pmatrix} \cos^2 \theta & -\sqrt{2} \cos \theta \sin \theta e^{i\varphi} & \sin^2 \theta e^{2i\varphi} \\ -\sqrt{2} \cos \theta \sin \theta e^{-i\varphi} & -\cos^2 \theta + \sin^2 \theta & \sqrt{2} \cos \theta \sin \theta e^{i\varphi} \\ \sin^2 \theta e^{-2i\varphi} & \sqrt{2} \cos \theta \sin \theta e^{-i\varphi} & \cos^2 \theta \end{pmatrix}$$

$$\left\{ \frac{\hbar^2}{m} \Delta + E + \left(g_1^2 + g_2^2 \left(1 + \frac{1}{x r} + \frac{1}{x r v} \right) \right) \frac{e^{-x r}}{r} \right\} \begin{pmatrix} \frac{u(r)}{r} + \sqrt{\frac{1}{10}} \frac{v(r)}{r} Y_0 \\ -\sqrt{\frac{3}{10}} \frac{v(r)}{r} Y_{-1} \\ \sqrt{\frac{6}{10}} \frac{v(r)}{r} Y_{-2} \end{pmatrix}$$

$$\left(1 + \frac{3}{x r} + \frac{3}{x r v} \right) \left(\begin{aligned} & \left(u + \frac{1}{\sqrt{10}} v Y_0 \right) \cos^2 \theta + \frac{\sqrt{6}}{\sqrt{10}} v Y_{-1} \cos \theta \sin \theta e^{i\varphi} + \frac{\sqrt{6}}{\sqrt{10}} v Y_{-2} \sin^2 \theta e^{2i\varphi} \\ & - \left(u + \frac{1}{\sqrt{10}} v Y_0 \right) \sqrt{2} \cos \theta \sin \theta e^{-i\varphi} + \frac{\sqrt{3}}{\sqrt{10}} v Y_{-1} (\cos^2 \theta - \sin^2 \theta) + \frac{2\sqrt{3}}{\sqrt{10}} v Y_{-2} \cos \theta \sin \theta e^{i\varphi} \\ & \left(u + \frac{1}{\sqrt{10}} v Y_0 \right) \sin^2 \theta e^{-2i\varphi} - \frac{\sqrt{6}}{\sqrt{10}} v Y_{-1} \cos \theta \sin \theta e^{-i\varphi} + \frac{\sqrt{6}}{\sqrt{10}} v Y_{-2} \cos^2 \theta \end{aligned} \right)$$

$$\left\{ \frac{\hbar^2}{M} \frac{d^2 u}{dr^2} + E u + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 v}{dr^2} - \frac{l(l+1)}{r^2} v + E v + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 w}{dr^2} - \frac{l(l+1)}{r^2} w + E w + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 x}{dr^2} - \frac{l(l+1)}{r^2} x + E x + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 y}{dr^2} - \frac{l(l+1)}{r^2} y + E y + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 z}{dr^2} - \frac{l(l+1)}{r^2} z + E z + \dots \right] \right] \right] \right] \right] \right] \right] \right]$$

$$+ \left\{ \frac{\hbar^2}{M} \frac{d^2 v}{dr^2} - \frac{l(l+1)}{r^2} v + E v + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 w}{dr^2} - \frac{l(l+1)}{r^2} w + E w + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 x}{dr^2} - \frac{l(l+1)}{r^2} x + E x + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 y}{dr^2} - \frac{l(l+1)}{r^2} y + E y + \left[\frac{3}{4} \frac{\hbar^2}{M} \frac{d^2 z}{dr^2} - \frac{l(l+1)}{r^2} z + E z + \dots \right] \right] \right] \right] \right] \right]$$

$$- \left(1 + \frac{3}{kr} + \frac{3}{2kr^2} \right) u \begin{pmatrix} \cos^2 \theta - \frac{1}{3} \\ -\sqrt{2} \cos \theta \sin \theta e^{-i\varphi} \\ \sin^2 \theta e^{-2i\varphi} \end{pmatrix}$$

$$\frac{3}{4} \frac{1}{2\pi} \begin{pmatrix} \cos^2 \theta - \frac{1}{3} \\ -\sqrt{2} \cos \theta \sin \theta e^{i\varphi} \\ \sin^2 \theta e^{-2i\varphi} \end{pmatrix}$$

$$- \left(1 + \frac{3}{kr} + \frac{3}{2kr^2} \right) \left(\cos^2 \theta - \frac{1}{3} \right) \cos^2 \theta + 2 \cos^2 \theta \sin^2 \theta + \sin^4 \theta \quad \Rightarrow 0$$

$$\left(\cos^2 \theta - \frac{1}{3} \right) \cos^2 \theta + 2 \cos^2 \theta \sin^2 \theta + \sin^4 \theta = (\cos^2 \theta + \sin^2 \theta)^2 = 1$$

$$\frac{3}{4} \frac{1}{2\pi}$$

$$\left(\sqrt{2} \left(\cos^2 \theta - \frac{1}{3} \right) \cos \theta \sin \theta e^{-i\varphi} + \sqrt{2} \cos \theta \sin \theta \left(\cos^2 \theta - \frac{1}{3} \right) e^{-i\varphi} + \sqrt{2} \sin^2 \theta \cos \theta \sin \theta e^{i\varphi} \right)$$

$$\left(\cos^2 \theta - \frac{1}{3} \right) \sin^2 \theta e^{-2i\varphi} + 2 \cos^2 \theta \sin \theta e^{-2i\varphi} + \sin^2 \theta \cos^2 \theta e^{-2i\varphi}$$

$$2 \cos^4 \theta - 2 \sin^2 \theta$$

$$\begin{pmatrix} 1 - \frac{1}{3} \cos^2 \theta \\ \sqrt{2} + \frac{\sqrt{2}}{3} \cos^2 \theta \sin \theta e^{-i\varphi} - \left(\cos^2 \theta - \frac{1}{3} \right) \\ - \frac{1}{3} \sin^2 \theta e^{-2i\varphi} \end{pmatrix}$$

$$\left\{ \frac{\hbar^2}{M} \frac{d^2 u}{dr^2} + E u + \left[\frac{3\sqrt{I}}{4\sqrt{2\pi}} \right] \frac{e^{-kr}}{r} u \right\}$$

$$+ \left\{ \frac{\hbar^2}{M} \frac{d^2 v}{dr^2} - \frac{l(l+1)}{r^2} v + E v + \left[\frac{3\sqrt{I}}{4\sqrt{2\pi}} \right] \frac{e^{-kr}}{r} v \right\} \frac{3\sqrt{I}}{4\sqrt{2\pi}} \begin{pmatrix} \cos\theta - \frac{1}{3} \\ -\sqrt{2} \cos\theta \sin\theta e^{i\varphi} \\ \sin^2\theta e^{-2i\varphi} \end{pmatrix}$$

$$- \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) u \begin{pmatrix} \cos^2\theta \\ -\sqrt{2} \cos\theta \sin\theta e^{i\varphi} \\ \sin^2\theta e^{-2i\varphi} \end{pmatrix}$$

$$\left\{ \begin{pmatrix} -\frac{1}{3} \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} \cos^2\theta \\ -\sqrt{2} \cos\theta \sin\theta \\ \sin^2\theta \end{pmatrix} \right\}$$

$$- \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) v \frac{3\sqrt{I}}{4\sqrt{2\pi}} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\frac{12 \frac{3\sqrt{I}}{4\sqrt{2\pi}}}{3 \frac{3\sqrt{I}}{4\sqrt{2\pi}}} = \frac{12}{3} = 4$$

$$+ \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) v \frac{1}{4\sqrt{2\pi}} \begin{pmatrix} \cos^2\theta \\ \dots \\ \dots \end{pmatrix} \geq 0$$

$$(x^2 + y^2)^2$$

$$\textcircled{3} \left\{ \frac{\hbar^2}{M} \frac{d^2 u}{dr^2} + E u + \left[\frac{3\sqrt{I}}{4\sqrt{2\pi}} \right] \frac{e^{-kr}}{r} u \right\} - \frac{1}{4\sqrt{2\pi}} \left\{ \frac{\hbar^2}{M} \frac{d^2 v}{dr^2} - \frac{l(l+1)}{r^2} v + E v + \left[\frac{3\sqrt{I}}{4\sqrt{2\pi}} \right] \frac{e^{-kr}}{r} v \right\} - 3 \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) \frac{v}{r} = 0$$

$$\frac{3\sqrt{I}}{4\sqrt{2\pi}} \left\{ \frac{\hbar^2}{M} \frac{d^2 v}{dr^2} - \frac{l(l+1)}{r^2} v + E v + \left[\frac{3\sqrt{I}}{4\sqrt{2\pi}} \right] \frac{e^{-kr}}{r} v \right\} - \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) u = 0$$

$$+ \frac{1}{3} \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) \frac{e^{-kr}}{r} v$$

$$\left\{ \frac{\hbar^2}{M} \frac{d^2 u}{dr^2} + E u + \left[\frac{3\sqrt{I}}{4\sqrt{2\pi}} \right] \frac{e^{-kr}}{r} u \right\} - \frac{1}{3} \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) \frac{e^{-kr}}{r} u$$

$$+ \frac{1}{4\sqrt{2\pi}} \left(3 - \frac{1}{3} \right) \left(1 + \frac{3}{kr} + \frac{3}{k^2 r^2} \right) \frac{e^{-kr}}{r} v = 0$$

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$$\frac{\hbar^2}{m} \frac{d^2 u}{dr^2} + E u - \left(\frac{6}{r^2} u \right) = \left(g_1^2 + g_2^2 \left(\frac{4}{3} + \frac{2}{kr} + \frac{2}{k^2 r^2} \right) \right) \frac{e^{-kr}}{r} u$$

$$\left\{ \frac{\hbar^2}{m} \frac{d^2 u}{dr^2} - \left(\frac{6}{r^2} u \right) + E u + \left(g_1^2 + g_2^2 \left(\frac{4}{3} + \frac{2}{kr} + \frac{2}{k^2 r^2} \right) \right) \frac{e^{-kr}}{r} u \right\} = 0$$

$$\frac{1}{4} - 4\sqrt{2\pi} g_1^2 \left(\frac{1}{3} + \frac{1}{kr} + \frac{1}{k^2 r^2} \right) \frac{e^{-kr}}{r} u = 0$$

$$g_1^2 + g_2^2 \left(\frac{4}{3} + \frac{2}{kr} + \frac{2}{k^2 r^2} \right)$$

$$v = r^3 w, \quad \frac{dv}{dr} = r^3 \frac{dw}{dr} + 3r^2 dw, \quad \frac{d^2 v}{dr^2} = r^3 \frac{d^2 w}{dr^2} + 6r^2 \frac{dw}{dr} + 6r w$$

$$\left\{ \frac{\hbar^2}{m} \left(r^3 \frac{d^2 w}{dr^2} + 6r^2 \frac{dw}{dr} \right) + E r^3 w + \left[\left(g_1^2 + \frac{4}{3} g_2^2 \right) r^2 + g_2^2 \frac{2r}{k} + g_2^2 \frac{2r^2}{k^2} \right] e^{-kr} w \right\} + 4\sqrt{2\pi}$$

$$r^k \quad k(k-1) = 6$$

$$k=3$$

$$k=-2$$

$$v = \frac{1}{r^2} (\dots)$$

$$1 - \frac{3(\sigma^{11}r)(\sigma^{44}r)}{r^2}$$

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$$\frac{(\sigma^{11}r)(\sigma^{44}r)}{r^2} - \frac{1}{3} = \begin{pmatrix} \cos^2\theta & -\sqrt{2}\cos\theta\sin\theta e^{i\varphi} & \sin^2\theta e^{2i\varphi} \\ -\sqrt{2}\cos\theta\sin\theta e^{-i\varphi} & -\cos^2\theta + \sin^2\theta - \frac{1}{3} & \sqrt{2}\cos\theta\sin\theta e^{i\varphi} \\ \sin^2\theta e^{-2i\varphi} & \sqrt{2}\cos\theta\sin\theta e^{-i\varphi} & \cos^2\theta \end{pmatrix}$$

$$\left[\frac{\hbar^2}{m} \frac{d^2 u}{dr^2} + E u + \left(g_1^2 + \frac{2}{3} g_2^2 \right) \frac{e^{-\kappa r}}{r} u \right] = 0$$

$$\frac{\hbar^2}{m} \frac{d^2 u}{dr^2} - \frac{6}{r^2} u + E u + \left[\frac{4}{3} \frac{e^{-\kappa r}}{r} \right] u$$

$$+ \frac{4}{3} \left(\frac{1}{3} + \frac{1}{\kappa r} + \frac{1}{\kappa^2 r^2} \right) u$$

$$- \frac{4}{3} \frac{\sqrt{2\kappa}}{\sqrt{2\kappa}}$$

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$$\left\{ \frac{\hbar^2}{M} \Delta + E + (g_1^2 + \frac{2}{3}g_2^2) \frac{e^{-\kappa r}}{r} \right\} \psi$$

$$- 3g_2^2 \left(\frac{(\sigma^{11}r)(\sigma^{22}r)}{r^2} - \frac{1}{3} \right) \left(\frac{1}{3} + \frac{1}{\kappa r} + \frac{1}{\kappa^2 r^2} \right) \frac{e^{-\kappa r}}{r} \psi = 0$$

$$\frac{(\sigma^{11}r)(\sigma^{22}r)}{r^2} - \frac{1}{3} = \begin{pmatrix} \cos^2\theta - \frac{1}{3}, & -\sqrt{2} \cos\theta \sin\theta e^{i\varphi}, & \sin^2\theta e^{2i\varphi} \\ -\sqrt{2} \cos\theta \sin\theta e^{-i\varphi}, & -\cos^2\theta + \sin^2\theta - \frac{1}{3}, & \sqrt{2} \cos\theta \sin\theta e^{i\varphi} \\ \sin^2\theta e^{-2i\varphi}, & \sqrt{2} \cos\theta \sin\theta e^{-i\varphi}, & \cos^2\theta - \frac{1}{3} \end{pmatrix}$$

$$\psi = \frac{u(r)}{r} \chi_{-1} + \frac{v(r)}{r} \left(\sqrt{\frac{1}{10}} Y_0 \chi_{-1} - \sqrt{\frac{3}{10}} Y_{-1} \chi_0 + \sqrt{\frac{6}{10}} Y_{-2} \chi_1 \right)$$

$$\sqrt{\frac{1}{10}} Y_0 = \sqrt{\frac{1}{10} \cdot \frac{5}{4\pi}} \left(\frac{3}{2} \cos^2\theta - \frac{1}{2} \right) = \sqrt{\frac{1}{8\pi}} \cdot \frac{3}{2} \left(\cos^2\theta - \frac{1}{3} \right)$$

$$\sqrt{\frac{3}{10}} Y_{-1} = \sqrt{\frac{3}{10} \cdot \frac{15}{8\pi}} \sin\theta \cos\theta e^{-i\varphi} = \sqrt{\frac{1}{8\pi}} \cdot \frac{3}{2} \left(\sqrt{2} \sin\theta \cos\theta e^{-i\varphi} \right)$$

$$\sqrt{\frac{6}{10}} Y_{-2} = \frac{1}{4} \sqrt{\frac{63}{10} \cdot \frac{15}{2\pi}} \sin^2\theta e^{-2i\varphi} = \sqrt{\frac{1}{8\pi}} \cdot \frac{3}{2} \sin^2\theta e^{-2i\varphi}$$

$$\left(\frac{(\sigma^{11}r)(\sigma^{22}r)}{r^2} - \frac{1}{3} \right) \chi_{-1} = \begin{pmatrix} \cos^2\theta - \frac{1}{3} \\ -\sqrt{2} \sin\theta \cos\theta e^{-i\varphi} \\ \sin^2\theta e^{-2i\varphi} \end{pmatrix} \frac{1}{4} \left(\cos^2\theta - \frac{2}{3} \cos^2\theta \right)$$

$$\left(\frac{(\sigma^{11}r)(\sigma^{22}r)}{r^2} - \frac{1}{3} \right) \begin{pmatrix} \cos^2\theta - \frac{1}{3} \\ \sqrt{2} \sin\theta \cos\theta e^{-i\varphi} \\ \frac{2}{3} \sin^2\theta e^{-2i\varphi} \end{pmatrix} = \begin{pmatrix} (\cos^2\theta - \frac{1}{3})^2 + \frac{2}{3} \sin^2\theta \cos^2\theta + \sin^4\theta \\ \frac{2}{3} \sqrt{2} \sin\theta \cos\theta \left\{ (-\sqrt{2} + 2\sqrt{2})(\cos^2\theta - \frac{1}{3}) + \sqrt{2} \sin^2\theta \right\} e^{-i\varphi} \\ \frac{2}{3} \sqrt{2} \cos^2\theta \sin^2\theta e^{-2i\varphi} \\ \sin^2\theta \left\{ \cos^2\theta - \frac{1}{3} - 2\cos^2\theta + \cos^2\theta - \frac{1}{3} \right\} e^{2i\varphi} \\ - \frac{2}{3} \sin^2\theta e^{-2i\varphi} \end{pmatrix}$$

$$= \frac{8}{9} \chi_{-1} - \frac{2}{3} \begin{pmatrix} \cos^2\theta - \frac{1}{3} \\ -\sqrt{2} \sin\theta \cos\theta e^{-i\varphi} \\ \sin^2\theta e^{-2i\varphi} \end{pmatrix}$$

$$\left(\frac{(0^{(1)} r)(0^{(2)} r)}{r^2} - \frac{1}{3} \right) \psi = \frac{1}{r} \begin{pmatrix} \psi \\ \psi \\ \psi \end{pmatrix}$$

$$+ \frac{V(r)}{r} \sqrt{\frac{1}{8\pi}} \cdot \frac{4}{3} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} - \frac{V(r)}{r} \sqrt{\frac{1}{8\pi}} \begin{pmatrix} \cos\theta - \frac{1}{3} \\ 0 \\ 0 \end{pmatrix}$$

$$\left\{ \frac{\hbar^2}{M} \frac{d^2 u}{dr^2} + E u + (g_1^2 + \frac{2}{3} g_2^2) \frac{e^{-kr}}{r} u \right. \\ \left. - \frac{V(r)}{r} \sqrt{\frac{1}{8\pi}} \cdot 4 g_2^2 \left(\frac{1}{3} + \frac{1}{kr} + \frac{1}{k^2 r^2} \right) \frac{e^{-kr}}{r} u = 0 \right.$$

$$\frac{1}{18\pi} \left\{ \frac{\hbar^2}{M} \left(\frac{d^2 v}{dr^2} - \frac{6v}{r^2} \right) + (g_1^2 + \frac{2}{3} g_2^2) \frac{e^{-kr}}{r} v + 2 g_2^2 \left(\frac{1}{3} + \frac{1}{kr} + \frac{1}{k^2 r^2} \right) \frac{e^{-kr}}{r} v \right\} \\ - \frac{1}{2} g_2^2 \left(\frac{1}{3} + \frac{1}{kr} + \frac{1}{k^2 r^2} \right) \frac{e^{-kr}}{r} u = 0$$

$$2 \frac{1}{4\pi} u = u' \sqrt{\frac{1}{4\pi}}$$

$$\left\{ \frac{\hbar^2}{M} \frac{d^2 u'}{dr^2} + E u' + (g_1^2 + \frac{2}{3} g_2^2) \frac{e^{-kr}}{r} u' \right. \\ \left. - 2\sqrt{2} g_2^2 \left(\frac{1}{3} + \frac{1}{kr} + \frac{1}{k^2 r^2} \right) \frac{e^{-kr}}{r} u' = 0 \right. \quad \frac{e^{-kr}}{r} v$$

$$\frac{\hbar^2}{M} \left(\frac{d^2 v}{dr^2} - \frac{6v}{r^2} \right) + E v + (g_1^2 + \frac{2}{3} g_2^2) \frac{e^{-kr}}{r} v + 2 g_2^2 \left(\frac{1}{3} + \frac{1}{kr} + \frac{1}{k^2 r^2} \right) \frac{e^{-kr}}{r} v$$

$$- 2\sqrt{2} g_2^2 \left(\frac{1}{3} + \frac{1}{kr} + \frac{1}{k^2 r^2} \right) \frac{e^{-kr}}{r} u' = 0$$

$$kr = \frac{-3 \pm \sqrt{9+12}}{2}$$

$$\frac{k^2 r^2 + 3kr - 3}{3k^2 r^2}$$

$$\frac{1}{3} + \frac{1}{4} = \frac{17}{12}$$

$$= \frac{-3 \pm \sqrt{21}}{2} \quad |kr| < 1$$

$$\frac{d}{dx} (x^2 - x^3) = 1 - 2x = 0 \quad x = \frac{1}{2}$$

$$kr = 2 \quad \frac{1}{2} - \frac{1}{4} = \frac{1}{4}$$

[S] [P] etc.

$$\begin{aligned} & \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_1 \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix}_2 \\ &= \frac{1}{\sqrt{2}} \left\{ \begin{pmatrix} z \\ x+iy \end{pmatrix}_1 \begin{pmatrix} x-iy \\ -z \end{pmatrix}_2 - \begin{pmatrix} x-iy \\ -z \end{pmatrix}_1 \begin{pmatrix} z \\ x+iy \end{pmatrix}_2 \right\} \\ &= \frac{1}{\sqrt{2}} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right\} \end{aligned}$$

$\frac{(\sigma_1 \sigma_2)}{\lambda^2} = -1$ for singlet state.

$$(\sigma_1 \sigma_2) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_2 + \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}_1 \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}_2 + \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}_1 \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}_2$$

$$\frac{1}{\sqrt{2}} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right\}$$

$$= \frac{1}{\sqrt{2}} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 + \begin{pmatrix} 0 \\ i \end{pmatrix}_1 \begin{pmatrix} i \\ 0 \end{pmatrix}_2 + \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 \right.$$

$$\left. - \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 - \begin{pmatrix} -i \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ i \end{pmatrix}_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 \right\}$$

$$= + \frac{3}{\sqrt{2}} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}_2 - \begin{pmatrix} 1 \\ 0 \end{pmatrix}_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}_2 \right\} \Rightarrow (\sigma_1 \sigma_2) = 3$$

$$V = + \left[g_1^2 + g_2^2 (\sigma_1^x \sigma_2^x) - \frac{(\sigma_1^y \sigma_2^y)}{\lambda^2} \right] + g_2^2 \left[\frac{(\sigma_1^z \sigma_2^z)}{\lambda^2} - \frac{3(\sigma_1^x \sigma_2^x)}{\lambda^2} \right]$$

$$\times \left(\frac{1}{\lambda} - \frac{1}{\lambda^2} \right) \frac{e^{-\lambda r}}{\lambda}$$

$$= + \left[g_1^2 - 2g_2^2 \right] \frac{e^{-\lambda r}}{\lambda} = - (2g_2^2 - g_1^2) \frac{e^{-\lambda r}}{\lambda}$$

$$\frac{g_1 + \frac{2}{3}g_2^2}{g_2} \approx \frac{5}{2}g_2$$

$$\frac{2g_2^2 - g_1^2}{g_2}$$

$$\iint \frac{\partial}{\partial z} \left(f(\vec{r}) \frac{e^{-\kappa r}}{r} \right) d\vec{r}$$

$$= \iint f(\vec{r}) \frac{e^{-\kappa r}}{r} \frac{\partial}{\partial z} \left(\frac{1}{r} \right) d\vec{r} + \iint \left[f(\vec{r}) \frac{e^{-\kappa r}}{r} \right] \frac{\partial}{\partial z} \left(\frac{1}{r} \right) d\vec{r} =$$



$$dxdy = df \cdot \cos\theta$$

$$\int f(\vec{r}) \frac{e^{-\kappa r}}{r} \cos\theta df$$

$$= \int \int \int f(\vec{r}) \frac{e^{-\kappa r}}{r} r^2 \sin\theta d\theta d\phi dr$$

$$= f(0) \left(\frac{e^{-\kappa r}}{r} \right) \int \int \int \frac{\partial}{\partial r} \left(\frac{e^{-\kappa r}}{r} \right) r^2 \sin\theta d\theta d\phi dr$$

$$\frac{\partial}{\partial r} \left(\frac{e^{-\kappa r}}{r} \right) = \frac{\partial}{\partial r} \left(e^{-\kappa r} \cdot r^{-1} \right) = -\kappa e^{-\kappa r} r^{-1} - e^{-\kappa r} r^{-2}$$

$$= -\kappa \int \int \int \frac{e^{-\kappa r}}{r} r^2 \sin\theta d\theta d\phi dr - \int \int \int \frac{e^{-\kappa r}}{r^2} r^2 \sin\theta d\theta d\phi dr$$

$$= -\kappa \int \int \int \frac{e^{-\kappa r}}{r} r^2 \sin\theta d\theta d\phi dr - \int \int \int e^{-\kappa r} r \sin\theta d\theta d\phi dr$$

$$= \frac{\partial}{\partial r} \left(\frac{e^{-\kappa r}}{r} \right) + f \frac{\partial}{\partial r} \left(\frac{e^{-\kappa r}}{r} \right) + \iint \int f \frac{\partial}{\partial r} \left(\frac{e^{-\kappa r}}{r} \right)$$

$$\begin{aligned}
 -\Delta U + \kappa^2 U &= -4\pi g_2 \text{curl } S \\
 -\Delta \tilde{U} + \kappa^2 \tilde{U} &= \frac{g_1}{\kappa^2} \text{grad } M_0 \\
 \text{curl } U &= g_2 \frac{e^{-\kappa r}}{r} \text{curl curl } S(r_2) \\
 -\frac{g_1^2}{\kappa^2} \sigma_1 \frac{e^{-\kappa r}}{r} \sigma_1 \text{curl curl } (\tilde{\sigma}_2 \Psi)
 \end{aligned}$$

∴

3S, 3D の coupling ubs $(\frac{1}{\kappa r} - \frac{1}{\kappa^2 r^2}) \frac{e^{-\kappa r}}{r}$ の π の
 4 singularity 問題. 0 以外 finite 解 solution を 得る
 非-1 非-2 相互作用の κ^2 partial integration による
 2D $\kappa^2 \rightarrow S(r)$.

實際 interaction energy

$$H = \iint H(\mathbf{r}) d\mathbf{r}$$

$$\begin{aligned}
 H(\mathbf{r}) &= \tilde{\Psi}(\mathbf{r}) \left[\frac{g_1}{\kappa^2} (\text{curl } \tilde{U} \cdot \tilde{\sigma} \tilde{\sigma} + \text{curl } U \cdot \tilde{\sigma} \tilde{\sigma}) \right. \\
 &\quad \left. + \frac{4\pi g_2}{\kappa^2} \{ (\tilde{\sigma} \sigma) \tilde{Q} + (\sigma \sigma) Q \} \right] \Psi(\mathbf{r})
 \end{aligned}$$

$$= -\frac{g_1^2}{\kappa^2} \left\{ \tilde{\sigma}(\mathbf{r}_2) \frac{e^{-\kappa r}}{r} \text{curl curl } \tilde{S}(\mathbf{r}_2) \cdot \tilde{\sigma} \sigma + \tilde{S}(\mathbf{r}_2) \frac{e^{-\kappa r}}{r} \text{curl curl } \tilde{S}(\mathbf{r}_2) \right\}$$

$$+ \frac{4\pi g_2}{\kappa^2} \{ \tilde{S}(\mathbf{r}_2) S(\mathbf{r}_1) + S(\mathbf{r}_2) \tilde{S}(\mathbf{r}_1) \}$$

$$= -\frac{g_1^2}{\kappa^2} \tilde{u}_m(\mathbf{r}_1) \frac{e^{-\kappa r}}{r} \text{curl curl } u_p(\mathbf{r}_2) + \frac{4\pi g_2}{\kappa^2}$$

$$\left\{ u_m(\mathbf{r}_1) \tilde{\sigma}_m(\mathbf{r}_1) v_p(\mathbf{r}_2) \tilde{\sigma}_p(\mathbf{r}_2) \right\} +$$

$$= \tilde{u}_m(\mathbf{r}_1) \tilde{\sigma}_m \left(\nabla_2 \times \tilde{\sigma}_2 \right) u_p(\mathbf{r}_2) v_p(\mathbf{r}_2)$$

$$\vec{\sigma}^{(1)} \left\{ \nabla_2 \times [\nabla_2 \times \tilde{v}_p(r_2) u_q(r_2)] \right\}$$

$$= -\vec{\sigma}^{(1)} \left\{ \nabla_2 \times \left[\tilde{v}_p(\sigma^{(1)} \times \nabla_2) u_q(r_2) \pm \tilde{v}_p(\sigma^{(2)} \times \nabla_2) \cdot u_q(r_2) \right] \right\}$$

$$= -(\vec{\sigma}^{(1)} \times \nabla_2) \left\{ \tilde{v}_p(\sigma^{(2)} \times \nabla_2) u_q(r_2) \pm \tilde{v}_p(\sigma^{(1)} \times \nabla_2) \cdot u_q(r_2) \right\}$$

$$= -\left\{ \tilde{v}_p(r_2) \cdot (\sigma^{(1)} \times \nabla_2) (\sigma^{(2)} \times \nabla_2) u_q(r_2) \right.$$

$$\left. - \tilde{v}_p(r_2) (\sigma^{(1)} \times \nabla_2) \cdot (\sigma^{(2)} \times \nabla_2) u_q(r_2) \right.$$

$$\left. - \tilde{v}_p(r_2) (\sigma^{(2)} \times \nabla_2) \cdot (\sigma^{(1)} \times \nabla_2) u_q(r_2) \right.$$

$$\left. + \tilde{v}_p(r_2) (\sigma^{(2)} \times \nabla_2) (\sigma^{(1)} \times \nabla_2) \cdot u_q(r_2) \right\}$$

$$\frac{g_1}{x_1} \tilde{u}_m(r_1) v_p(r_2) \left\{ \frac{e^{-x_1 r}}{r} (\sigma^{(1)} \times \nabla_2) (\sigma^{(2)} \times \nabla_2) \right.$$

$$\left. - (\sigma^{(1)} \times \nabla_2) \frac{e^{-x_1 r}}{r} (\sigma^{(2)} \times \nabla_2) - (\sigma^{(2)} \times \nabla_2) \frac{e^{-x_1 r}}{r} (\sigma^{(1)} \times \nabla_2) \right.$$

$$\left. + (\sigma^{(1)} \times \nabla_2) (\sigma^{(2)} \times \nabla_2) \frac{e^{-x_1 r}}{r} \right\} v_n(r_1) u_q(r_2)$$

$$= \frac{g_1}{x_1} \tilde{u}_m(r_1) \tilde{v}_p(r_2) \left\{ (\sigma^{(1)} \times \nabla_2) \frac{e^{-x_1 r}}{r} \frac{e^{-x_2 r}}{r} \sigma^{(2)} \right.$$

$$\left. (\sigma^{(2)} \times \nabla_2) (\sigma^{(1)} \times \nabla_2) \left(\frac{e^{-x_1 r}}{r} \right) - \left(\frac{e^{-x_1 r}}{r} \right) (\sigma^{(1)} \times \nabla_2) \right.$$

$$\left. - \left((\sigma^{(1)} \times \nabla_2) \left(\frac{e^{-x_1 r}}{r} \right) - \frac{e^{-x_1 r}}{r} (\sigma^{(1)} \times \nabla_2) \right) (\sigma^{(2)} \times \nabla_2) \right\} v_n(r_1) u_q(r_2)$$

$$\parallel \sigma^{(2)} \left\{ (\sigma^{(2)} \times \nabla_2) (\sigma^{(1)} \times \nabla_2) \frac{e^{-x_1 r}}{r} \right\}$$

$$\sigma^{(2)} \cdot (\vec{A} \times \vec{B})(\vec{C} \times \vec{D}) = \{(\vec{A} \times \vec{B}) \times \vec{C}\} \cdot \vec{D}$$

$$= \{(\vec{A} \times \vec{B}) \cdot \vec{D}\} \times \vec{C}$$

$$(\sigma^{(1)} \times \nabla_2) (\sigma^{(1)} \times \nabla_2) = \{(\sigma^{(1)} \times \nabla_2) \times \nabla_2\} \cdot \nabla_2 = \{(\sigma^{(2)} \times \nabla_2) \times \nabla_2\} \cdot \nabla_2$$

$$= -(\sigma^{(1)} \cdot \nabla_2) (\sigma^{(2)} \cdot \nabla_2) + \sigma^{(1)} \sigma^{(2)} \Delta_2 + \sigma^{(2)} \sigma^{(1)} \Delta_2 - (\sigma^{(1)} \times \nabla_2) (\sigma^{(2)} \times \nabla_2)$$

$$H' = \frac{4\pi g_1 c}{\kappa} (\text{div } \vec{U} \cdot \vec{Q} + \text{div } \vec{U}^\dagger \cdot \vec{Q}) + \frac{4\pi g_2}{\kappa^2} (\text{curl } \vec{U} \cdot \vec{\sigma} \vec{Q} + \text{curl } \vec{U} \cdot \vec{\sigma} \vec{Q}) + \frac{4\pi g_1^2}{\kappa^2} (\vec{M}_0 \vec{Q} + M_0 Q) + \frac{4\pi g_2^2}{\kappa^2} \{ (\vec{S} \sigma) \vec{Q} + (S \sigma) Q \} \quad (54), III$$

$$\left. \begin{aligned} -\Delta \vec{U} + \kappa^2 \vec{U} &= -4\pi g_2 \text{curl } \vec{S} \\ -\Delta \vec{U}^\dagger + \kappa^2 \vec{U}^\dagger &= \frac{g_1}{\kappa c} \text{grad } M_0 \\ M_0 &= \vec{\Psi} \vec{Q} \Psi, \quad \vec{S} = \vec{\Psi} \vec{\sigma} \vec{Q} \Psi \end{aligned} \right\} \quad (55), IV$$

Interaction energy

$$\Psi = \sum a_i u_i$$

$$H' = \frac{4\pi g_1 c}{\kappa^2} \iint \vec{\Psi} (\text{div } \vec{U}^\dagger \cdot \vec{Q} + \text{div } \vec{U} \cdot \vec{Q}) \Psi \, dv + \frac{4\pi g_2^2}{\kappa^2} \iint \vec{\Psi} (\vec{M}_0 \vec{Q} + M_0 Q) \Psi \, dv + \frac{4\pi g_2^2}{\kappa^2} \iint \vec{\Psi} (\text{curl } \vec{U} \cdot \vec{\sigma} \vec{Q} + \text{curl } \vec{U} \cdot \vec{\sigma} \vec{Q}) \Psi \, dv + \frac{4\pi g_2^2}{\kappa^2} \iint \vec{\Psi} \{ (\vec{S} \sigma) \vec{Q} + (S \sigma) Q \} \Psi \, dv$$

$$= \sum a_i^\dagger a_i$$

$$H_0 =$$

$$U = \text{curl } A$$

$$(\Delta + \kappa^2) A + \kappa^2 A = -4\pi g_2 S + \text{grad } M_0$$

$$A =$$

$$H = \frac{1}{2} p^2 + V(r)$$
$$\frac{\partial^2 \psi}{\partial r^2} + \frac{2}{r} \frac{\partial \psi}{\partial r} + \left(E - V(r) - \frac{l(l+1)}{2r^2} \right) \psi = 0$$

$$\psi(r, \theta, \phi) = R(r) Y_{lm}(\theta, \phi)$$
$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial R}{\partial r} \right) + \left(E - V(r) - \frac{l(l+1)}{2r^2} \right) R = 0$$

$$R(r) = \frac{e^{-\kappa r}}{r}$$

$$(\sigma_x^2 + \sigma_y^2)(\sigma_x^2 + \sigma_y^2) = (\sigma_x^4 + \sigma_y^4 + 2\sigma_x^2\sigma_y^2)$$
$$= \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)^2 = \frac{\partial^4}{\partial x^4} + \frac{\partial^4}{\partial y^4} + 2 \frac{\partial^4}{\partial x^2 \partial y^2}$$

$$= \begin{pmatrix} \frac{\partial^2}{\partial x^2} & -i \frac{\partial^2}{\partial x \partial y} \\ i \frac{\partial^2}{\partial x \partial y} & -\frac{\partial^2}{\partial y^2} \end{pmatrix} \begin{pmatrix} \frac{\partial^2}{\partial x^2} & -i \frac{\partial^2}{\partial x \partial y} \\ i \frac{\partial^2}{\partial x \partial y} & -\frac{\partial^2}{\partial y^2} \end{pmatrix}$$

$$+ \begin{pmatrix} \frac{\partial}{\partial x} & -\frac{\partial}{\partial y} \\ -\frac{\partial}{\partial x} & -\frac{\partial}{\partial y} \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial x} & -\frac{\partial}{\partial y} \\ -\frac{\partial}{\partial x} & -\frac{\partial}{\partial y} \end{pmatrix}$$

$$+ \begin{pmatrix} \frac{\partial}{\partial x} & 0 \\ 0 & \frac{\partial}{\partial y} + i \frac{\partial}{\partial x} \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial x} & 0 \\ 0 & \frac{\partial}{\partial y} - i \frac{\partial}{\partial x} \end{pmatrix}$$

$$=$$

$$= (\sigma_x^{(1)} \sigma_x^{(2)}) \Delta$$

~~$$(\sigma_y^{(1)} \sigma_z^{(2)} + \sigma_z^{(1)} \sigma_y^{(2)}) \frac{\partial}{\partial y} \frac{\partial}{\partial z}$$~~

~~$$- (\sigma_y^{(1)} \sigma_z^{(2)}) \frac{\partial}{\partial y} \frac{\partial}{\partial z}$$~~

$$= (\sigma^{(1)} \sigma^{(2)}) \Delta - (\sigma_x^{(1)} \frac{\partial}{\partial x} + \dots)$$

$$(\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad}) \cdot \frac{e^{-\kappa r}}{r}$$

$$= (\sigma^{(1)} \text{grad}) \left(\sigma_x^{(2)} \frac{x}{r} \cdot \frac{e^{-\kappa r}}{r} \left(-\kappa - \frac{1}{r} \right) + \sigma_y^{(2)} \frac{y}{r} \cdot \frac{e^{-\kappa r}}{r} \left(-\kappa - \frac{1}{r} \right) \right)$$

=

$$\iint \frac{e^{-\kappa r}}{r} (\sigma^{(1)} \text{grad}_2) (\sigma^{(2)} \text{grad}_2) f(\vec{r}_2) dV$$

=

wave equation (54) for Ψ in Dirac Hamiltonian

Φ in (53) is given by

$$\text{curl } U = -\frac{g_1}{4\pi\kappa c} \text{curl curl } S \cdot \frac{e^{-\kappa r}}{r} dV$$

$$d\vec{w} \vec{U}^t = \frac{g_1}{4\pi\kappa c} \Delta M_0 \cdot \frac{e^{-\kappa r}}{r} dV$$

is the form

$$c \vec{\alpha} \vec{p} + \beta \left(\frac{1}{2} M_0 c^2 + \dots \right)$$

$$- \frac{g_1}{4\pi\kappa c}$$

$$\begin{aligned} & \iiint \frac{e^{-\kappa r}}{r} (\sigma^{(1)} \text{grad}_2) (\sigma^{(1)} \text{grad}_2 f(\vec{r}_2)) dv_2 \\ & \quad (\text{grad}_2 \vec{f}(\vec{r}_2)) dv_2 \\ &= \iiint \text{div} \left\{ \sigma^{(1)} \frac{e^{-\kappa r}}{r} \right\} \text{grad}_2 \vec{f}(\vec{r}_2) dv_2 \\ & \Rightarrow \iiint \left(\frac{\sigma^{(1)} \vec{r}}{r^2} \left(-\kappa - \frac{1}{r} \right) \frac{e^{-\kappa r}}{r} \right) \text{grad}_2 \vec{f}(\vec{r}_2) dv_2 \\ &= \iiint \left(\frac{\sigma^{(1)} \vec{r}}{r^2} \right) \left(\frac{\kappa}{r^2} + \frac{1}{r^3} \right) e^{-\kappa r} \text{div}_2 \vec{f}(\vec{r}_2) dv_2 \\ &= - \iint \left(\frac{\sigma^{(1)} \vec{r}}{r^2} \right) \left(\frac{\kappa}{r^2} + \frac{1}{r^3} \right) e^{-\kappa r} \vec{f} \cdot d\vec{S} \end{aligned}$$

$$+ \iiint (\vec{f}_2 \text{grad}) (\sigma^{(1)} \vec{r}) \left(\frac{\kappa}{r^2} + \frac{1}{r^3} \right) e^{-\kappa r} dv$$

$$\vec{f} \rightarrow \vec{f}_2$$

$$= \iint \left(\frac{\sigma^{(1)}}{r} (\kappa r + 1) \right) f_r(\vec{r}) \sin \theta d\theta d\varphi + \iiint$$

$$= -4\pi \frac{\sigma^{(1)}}{r} f_r(\vec{r}) + \iiint$$

$$\frac{\sigma^{(1)} \frac{d}{dx} \frac{e^{-\kappa x}}{x}}{-\frac{4\pi}{3} (\sigma^{(1)} \vec{f}(\vec{r}))}$$

$$(\sigma^{(1)} \text{grad})$$

$$M_0 = \tilde{\Psi} \rho \frac{1}{c} \frac{\partial \Psi}{\partial t}$$

$$\vec{M} = \tilde{\Psi} \rho \text{grad } \Psi$$

$$\vec{M} = -\tilde{\Psi} \rho \left(\beta \frac{\partial \Psi}{\partial t} + \frac{\partial \Psi}{\partial x} \right)$$

$$\vec{S} = \tilde{\Psi} \rho (\vec{\alpha} \times \text{grad}) \Psi$$

curl



$$\left\{ \frac{\hbar^2}{M} \Delta + E - V \right\} \psi = 0$$

$$V = \frac{\tau_1^{(1)} \tau_1^{(2)} + \tau_2^{(1)} \tau_2^{(2)}}{2} \left\{ g_1^2 + g_2^2 (\sigma^{(1)} \sigma^{(2)}) - g_2^2 \frac{(\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad})}{r^2} \right\}$$

$$\times \frac{e^{-\alpha r}}{r}$$

a) { symmetric state } $\frac{\tau_1^{(1)} \tau_1^{(2)} + \tau_2^{(1)} \tau_2^{(2)}}{2} \left\{ \begin{matrix} = 1 & ({}^3S, {}^1P, {}^3D, \dots) \\ = -1 & ({}^1S, {}^3P, {}^1D, \dots) \end{matrix} \right\}$

b) { Triplet state } $\sigma^{(1)} \sigma^{(2)} \left\{ \begin{matrix} 1 \\ -3 \end{matrix} \right\}$

$$\begin{aligned} [(\sigma^{(1)} \sigma^{(2)}), (\sigma^{(1)} \text{grad})] &= [(\sigma_x^{(1)} \sigma_x^{(2)} + \sigma_y^{(1)} \sigma_y^{(2)} + \sigma_z^{(1)} \sigma_z^{(2)}), (\sigma_x^{(1)} \frac{\partial}{\partial x} + \sigma_y^{(1)} \frac{\partial}{\partial y} + \sigma_z^{(1)} \frac{\partial}{\partial z})] \\ &= 2i (\sigma_z^{(1)} \sigma_x^{(2)} \frac{\partial}{\partial y} - \sigma_z^{(1)} \sigma_y^{(2)} \frac{\partial}{\partial x} + \sigma_y^{(1)} \sigma_z^{(2)} \frac{\partial}{\partial x} - \sigma_y^{(1)} \sigma_x^{(2)} \frac{\partial}{\partial z} \dots) \\ &= 2i [\sigma_y \end{aligned}$$

$$\begin{aligned} [(\sigma^{(1)} \sigma^{(2)}), (\sigma^{(1)} \text{grad})(\sigma^{(2)} \text{grad})] &= [(\sigma^{(1)} \sigma^{(2)}), \sigma^{(1)} \text{grad}] (\sigma^{(2)} \text{grad}) \\ &\quad + (\sigma^{(2)} \text{grad}) [(\sigma^{(1)} \sigma^{(2)}), \sigma^{(2)} \text{grad}] \\ &= 2i (\sigma_z^{(1)} \sigma_x^{(2)} \frac{\partial}{\partial y} \dots) (\sigma_x^{(2)} \frac{\partial}{\partial x} + \sigma_y^{(2)} \frac{\partial}{\partial y} + \sigma_z^{(2)} \frac{\partial}{\partial z}) \\ &\quad + 2i (\sigma_x^{(1)} \frac{\partial}{\partial x} + \sigma_y^{(1)} \frac{\partial}{\partial y} + \sigma_z^{(1)} \frac{\partial}{\partial z}) (\sigma_x^{(1)} \sigma_y^{(2)} \frac{\partial}{\partial z} - \sigma_x^{(1)} \sigma_z^{(2)} \frac{\partial}{\partial y} \dots) \\ &= 4i (\sigma_z^{(1)} \sigma_y^{(2)} \frac{\partial}{\partial y} \frac{\partial}{\partial z} - \dots) \\ &\quad + 4 (-\sigma_z^{(1)} \sigma_y^{(2)} \frac{\partial}{\partial y} \frac{\partial}{\partial z} + \dots) = 0 \end{aligned}$$

twice, Triplet - Singlet or Intercomb. $\hbar^2 \tau^2$,

twice, Symm. - Anti. or Intercomb. $\hbar^2 \tau^2$,

Total Angular Momentum $(\vec{r} \times \vec{p}) + \frac{\hbar}{2} (\sigma^{(1)} + \sigma^{(2)})$ is $\nabla^2 \chi$ commutative,

twice 3S & combine to ${}^3P > {}^1D, {}^3D$.

3'S - 3D₁ - combination

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$$V = - \left\{ g_1^2 + \frac{2}{3} g_2^2 + g_2^2 \left(\frac{1}{3} + \frac{1}{\kappa r} + \frac{1}{\kappa^2 r^2} \right) \right\} \frac{e^{-\kappa r}}{r}$$

$$\left(1 - \frac{3(\sigma^{(1)} r)(\sigma^{(2)} r)}{r^2} \right)$$

$$\frac{\hbar^2}{M} \frac{d^2 u'}{dr^2} + E u' + (g_1^2 + \frac{2}{3} g_2^2) \frac{e^{-\kappa r}}{r} u' - 2\sqrt{2} g_2^2 \left(\frac{1}{3} + \frac{1}{\kappa r} + \frac{1}{\kappa^2 r^2} \right) \frac{e^{-\kappa r}}{r} u' = 0$$

$$\frac{\hbar^2}{M} \left(\frac{d^2 v}{dr^2} - \frac{6v}{r^2} \right) + E v + (g_1^2 + \frac{2}{3} g_2^2) \frac{e^{-\kappa r}}{r} v + 2 g_2^2 \left(\frac{1}{3} + \frac{1}{\kappa r} + \frac{1}{\kappa^2 r^2} \right) \frac{e^{-\kappa r}}{r} v - 2\sqrt{2} g_2^2 \left(\frac{1}{3} + \frac{1}{\kappa r} + \frac{1}{\kappa^2 r^2} \right) \frac{e^{-\kappa r}}{r} v = 0$$

$r \gg \frac{1}{\kappa}$ $H_{\frac{5}{2}}^{(1)}(i\kappa r)$

$$\frac{\hbar^2}{M} \frac{d^2 u'}{dr^2} + E u' = 0 \quad \left. \begin{array}{l} \frac{d^2 u}{dr^2} - \alpha^2 u = 0 \\ \frac{d^2 v}{dr^2} - \frac{6v}{r^2} - \alpha^2 v = 0 \end{array} \right\}$$

$$u' = e^{-\alpha r} \quad \alpha = \frac{\sqrt{-ME}}{\hbar}$$

$$\frac{d^2 v}{d(\alpha r)^2} - \frac{6}{(\alpha r)^2} v = 0$$

$$v = \mathcal{N} e^{-\alpha r} \quad \frac{dv}{dr} = \frac{d\mathcal{N}}{dr} e^{-\alpha r} - \alpha \mathcal{N} e^{-\alpha r}$$

$$\frac{d^2 v}{dr^2} = \frac{d^2 \mathcal{N}}{dr^2} e^{-\alpha r} - 2\alpha \frac{d\mathcal{N}}{dr} e^{-\alpha r} + \alpha^2 \mathcal{N} e^{-\alpha r}$$

$$\frac{d^2 \mathcal{N}}{dr^2} - 2\alpha \frac{d\mathcal{N}}{dr} - \frac{6\mathcal{N}}{r^2} = 0$$

$$v = \sum_n c_n r^n \quad \sum_n \{ n(n-1) - 6 \} c_n r^{n-2} = 2\alpha \sum_n c_n r^{n-1}$$

$$\sum_n \{ n(n-1) - 6 \} c_n - 2\alpha(n-1) c_{n-1} r^{n-2} = 0$$

$n = 3, -2; \quad v' = \sum$

i) $n = -2$:
 -1 : $-4C_{-1} + \alpha C_{-2} = 0 \quad C_{-1} = \alpha C_{-2}$
 0 : $-6C_0 + 2\alpha C_{-1} = 0 \quad C_0 = \frac{\alpha}{3} C_{-1}$
 1 : $C_1 = 0$

$$v'_2 = C_{-2} \left\{ \frac{d}{r^2} + \frac{\alpha}{r} + \frac{\alpha^2}{3} \right\}$$

ii) $n = 3$: $C_2 = 0$

$n = 5$: $C_n = \frac{2\alpha(n-1)}{n(n-1)-6} C_{n-1}$

$n = m+3$: $C_m = \frac{2\alpha(m+2)}{m(m+5)} C_{m-1}$

$m = 0, 1, 2, \dots$

$$m^2 + 5m = \frac{(2\alpha(m+2))! 5!}{m!(m+5)! 2!} C_0$$

$$\frac{d^2 v'}{d(\alpha r)^2} + 2 \frac{dv'}{d(\alpha r)} - \frac{6v'}{(\alpha r)^2} = 0$$

$\sim e^{2\alpha r}$

Bessel.

$r < \frac{1}{\alpha}$: $\frac{\hbar^2}{M} \frac{d^2 u'}{dr^2} + (E + V_0) u' - \sqrt{2} V_1 v = 0$

$- \sqrt{2} V_1 v = 0$

$V_1 > V_0$: $\frac{\hbar^2}{M} \left(\frac{dv}{dr^2} - \frac{6v}{r^2} \right) + (E + V_0) v + 2V_1 v - \sqrt{2} V_1 u' = 0$

$$u' = \sum_n u_n r^n \quad \frac{\hbar^2}{M} \sum_n u_n n(n-1) r^{n-2} + \sum_n \frac{M(E+V_0)}{\hbar^2} u_n r^n$$

$$v = \sum_n v_n r^n \quad - \sqrt{2} V_1 \sum_n v_n r^n = 0$$

$kr \gg \frac{1}{\lambda}$

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$$\frac{\hbar^2}{M} \frac{d^2 u}{dr^2} - \alpha^2 u = 0$$

$$\frac{\hbar^2}{M} \left(\frac{d^2 v}{dr^2} - \frac{v}{r^2} \right) + EV = 0 \quad \frac{dv}{dr^2} - \frac{v}{r^2} - \alpha^2 v = 0$$

和名