

Rigidity and Flow Near Jamming

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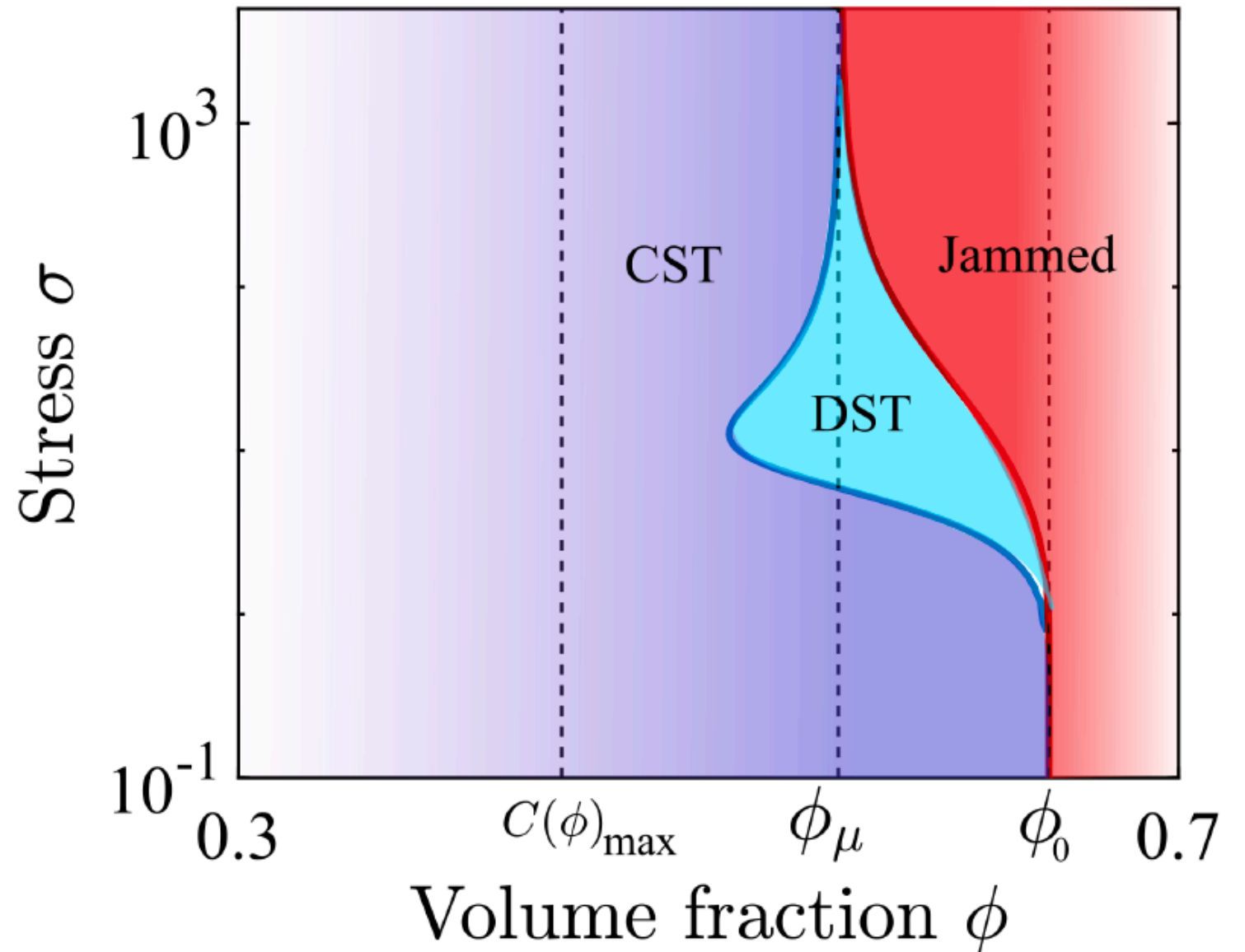
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With eternal gratitude to Bob Behringer



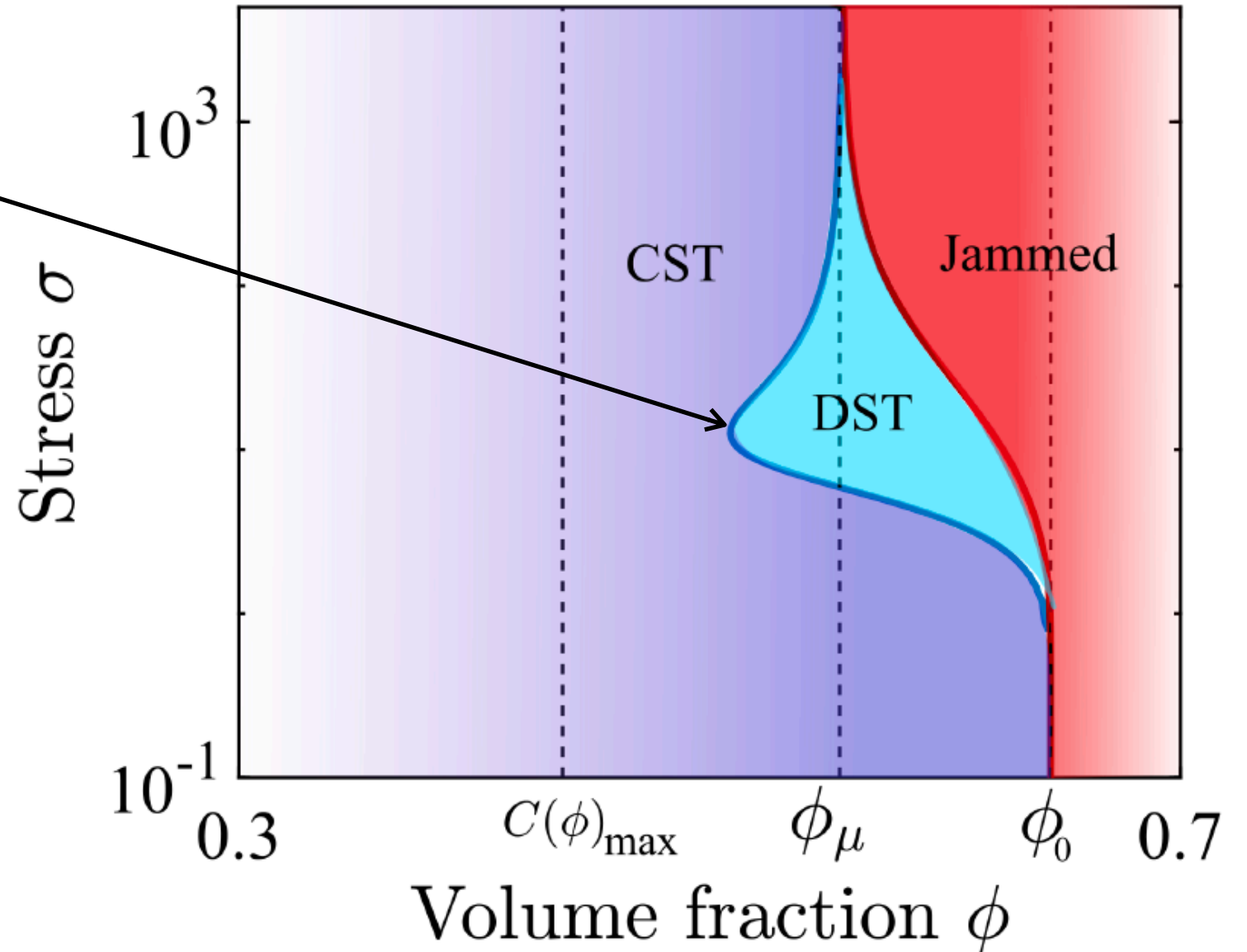
Shear-thickening Suspensions (Steady States)



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Locus of points :

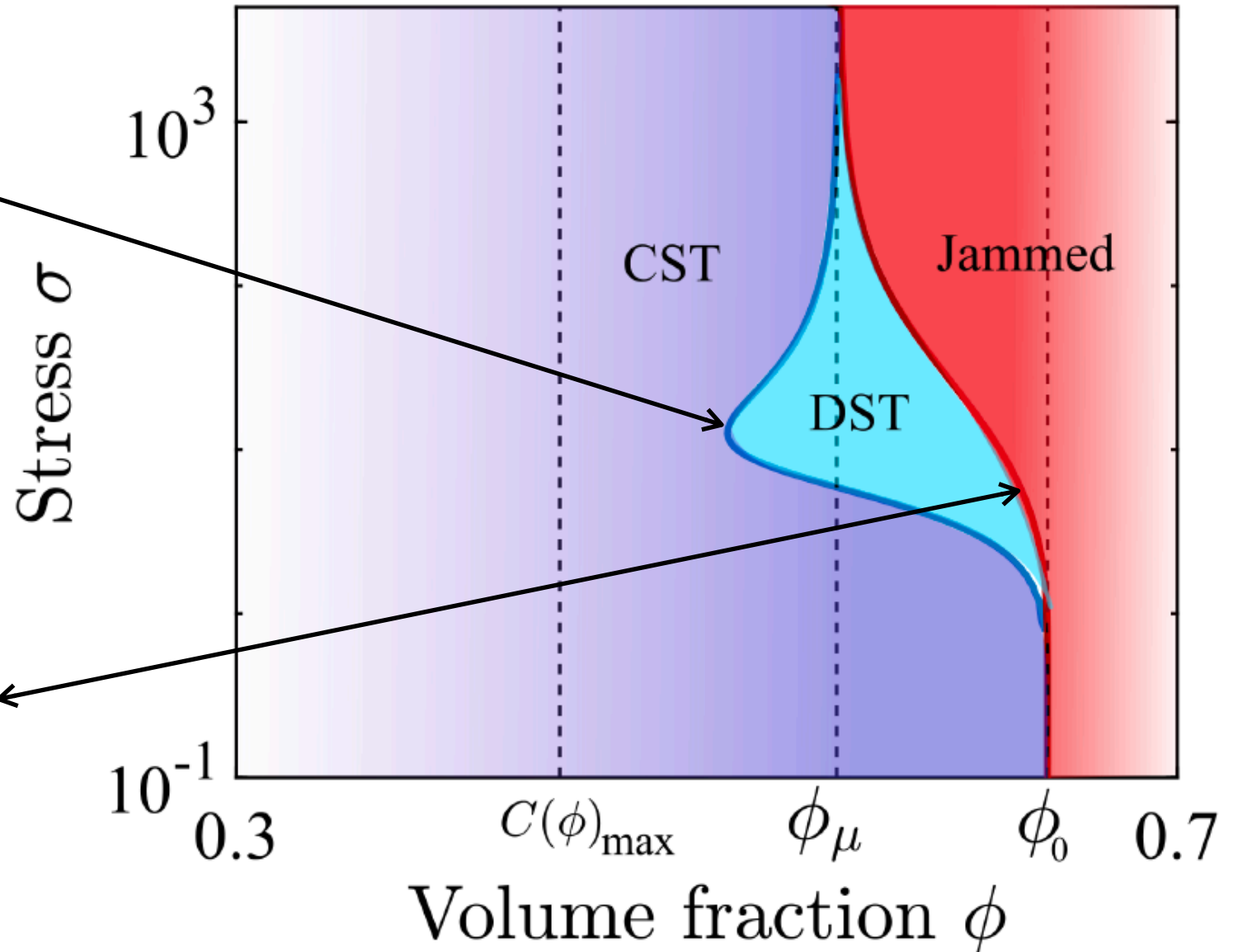
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Line of critical points: viscosity divergence is controlled by interactions at particle contacts: friction, adhesion, ...
Networks that emerge exhibit rigidity, a shear modulus

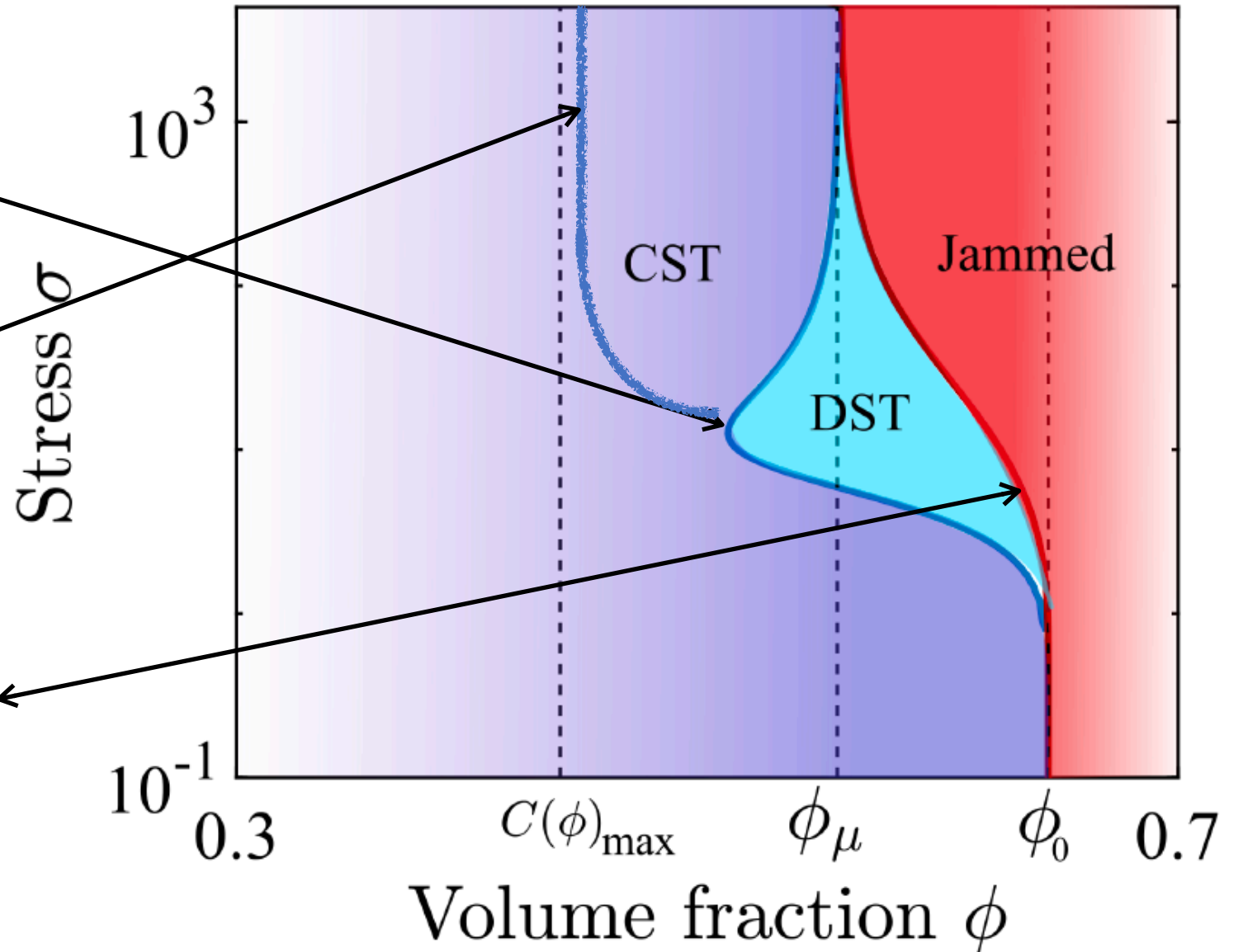
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A grayscale microscopic image showing a dense packing of irregular, light-colored particles. The particles are roughly spherical to sub-spherical with jagged, irregular surfaces, characteristic of a disordered packing of hard particles. They are closely packed together, filling most of the frame. The lighting creates highlights and shadows on the surfaces, giving a three-dimensional appearance.

Indeterminate/noisy interactions: friction, adhesion,...

Non-Brownian, no underlying Boltzmann distribution

Phase space explored ONLY via external driving



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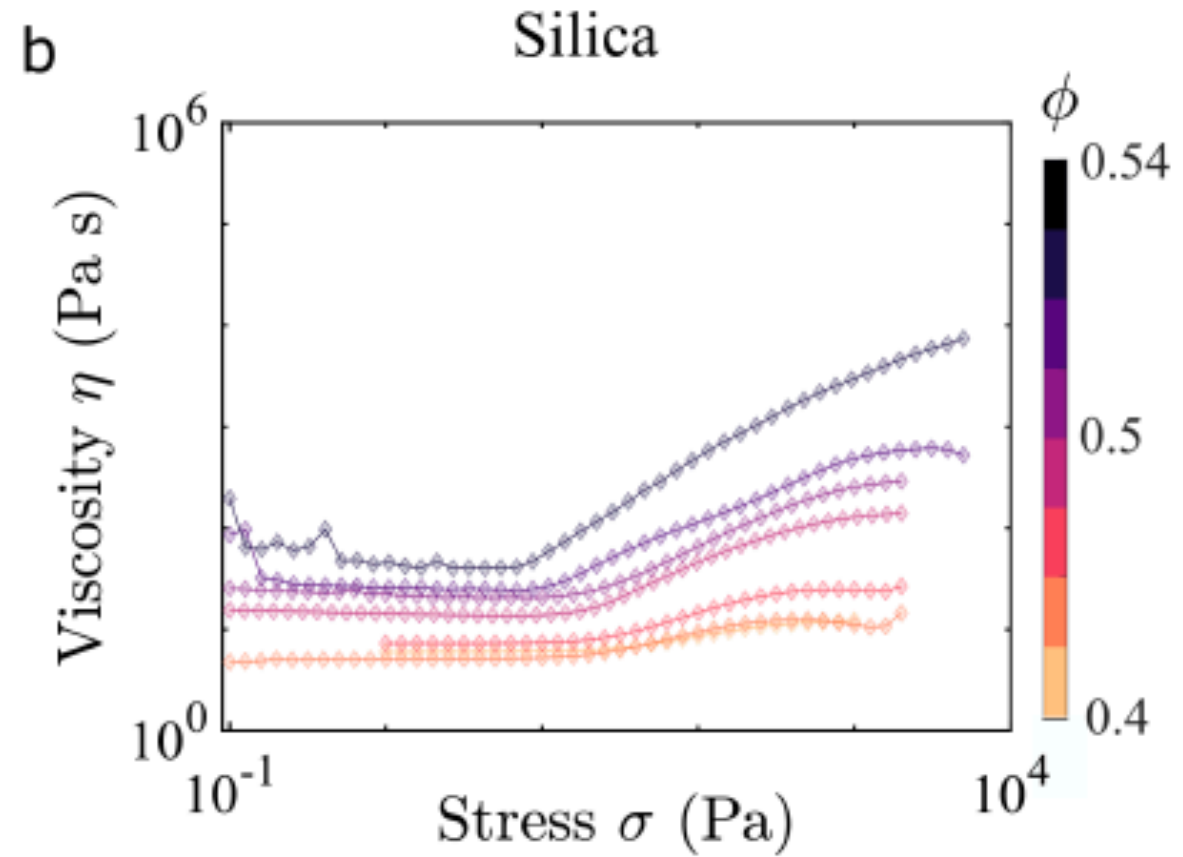
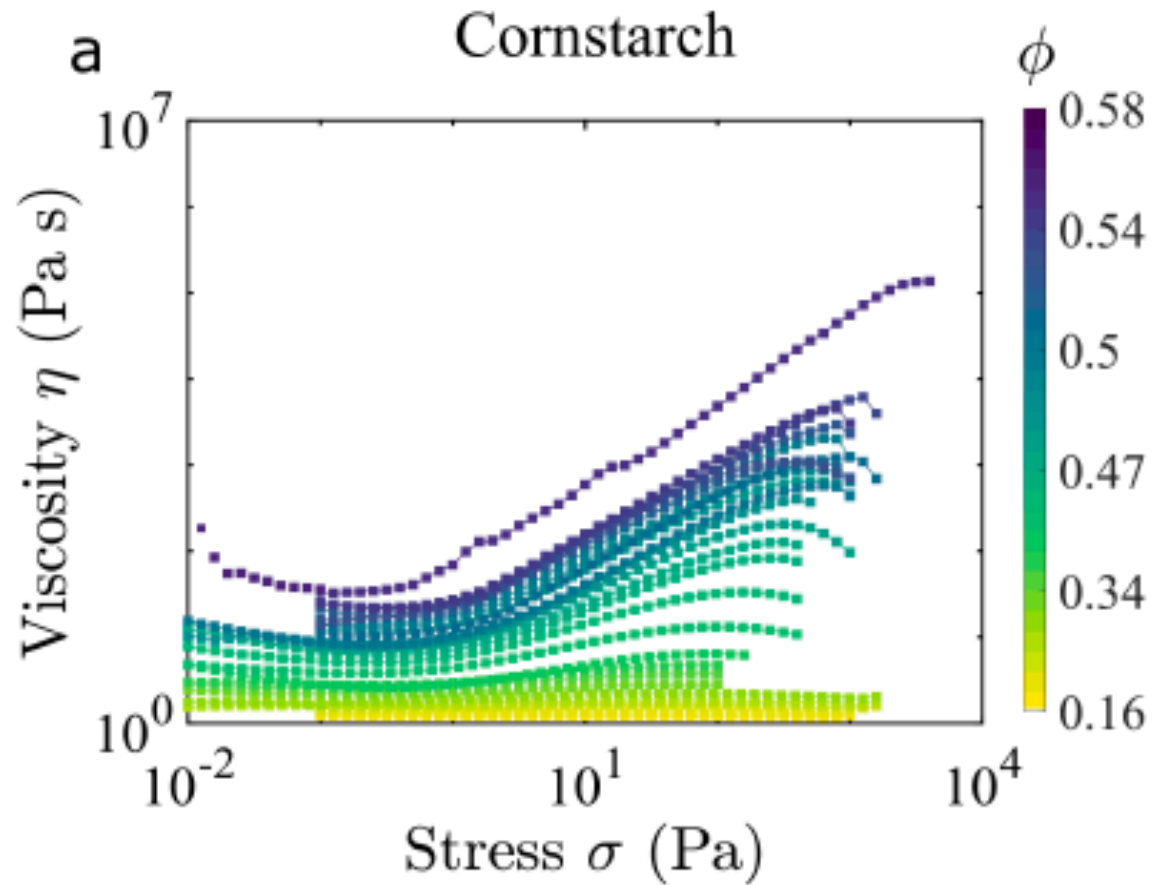
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Strongly Rate-dependent Viscosity

**Experimental results from Meera Ramaswamy
(Cornell Collaboration)**



Crossover Behavior Controlled by Multiple, Different Critical Points

Wyart & Cates *PRL* 2014

Key Idea: stress controls fraction of frictional contacts

Viscosity of stress independent states

$$\eta_r(\phi) = \alpha(\phi_J - \phi)^{-2}$$

Controlled by geometrical constraints: depends only on density

Key idea: interpolate jamming fraction

$$\phi_J(\sigma) = f(\sigma)\phi_\mu + (1 - f)\phi_0$$

Friction introduces a different type of constraint and shifts the critical point to a different packing fraction

Discontinuous shear thickening arises from a “crossover” between these two different critical points

Crossover Behavior Controlled by Multiple, Different Critical Points

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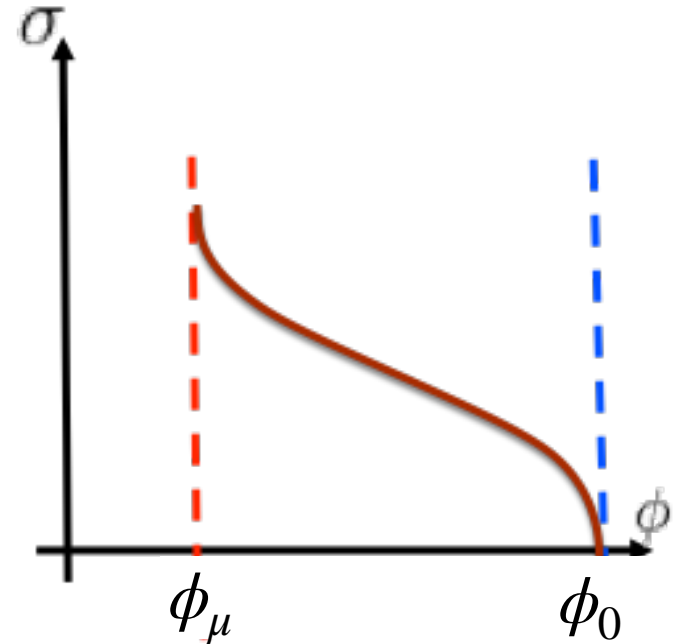
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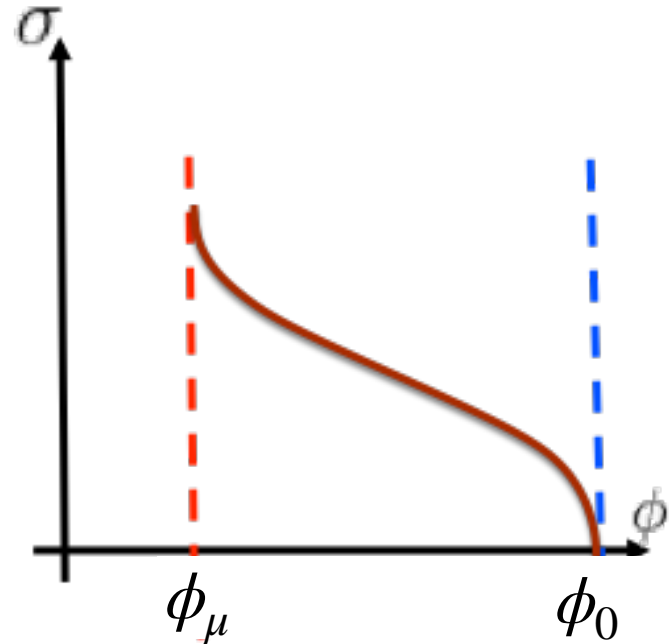
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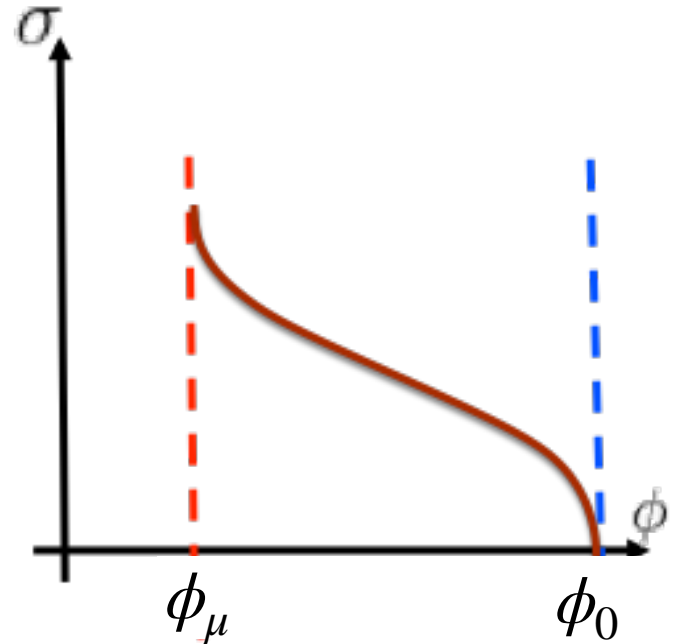
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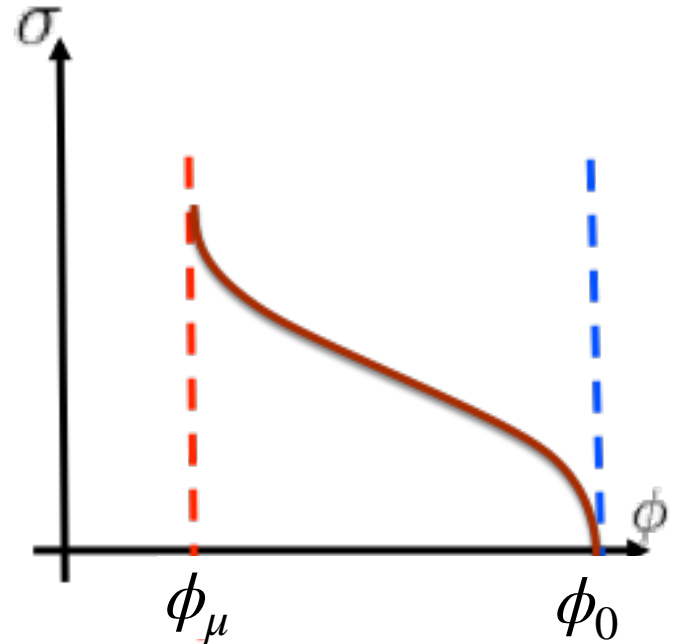
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Rate-dependent Viscosity is a signature of Crossover Scaling

Complex Phase Behavior from Crossover Scaling

Multiple, different critical points lead to complex phase behavior in equilibrium systems

Example: Magnetic Systems

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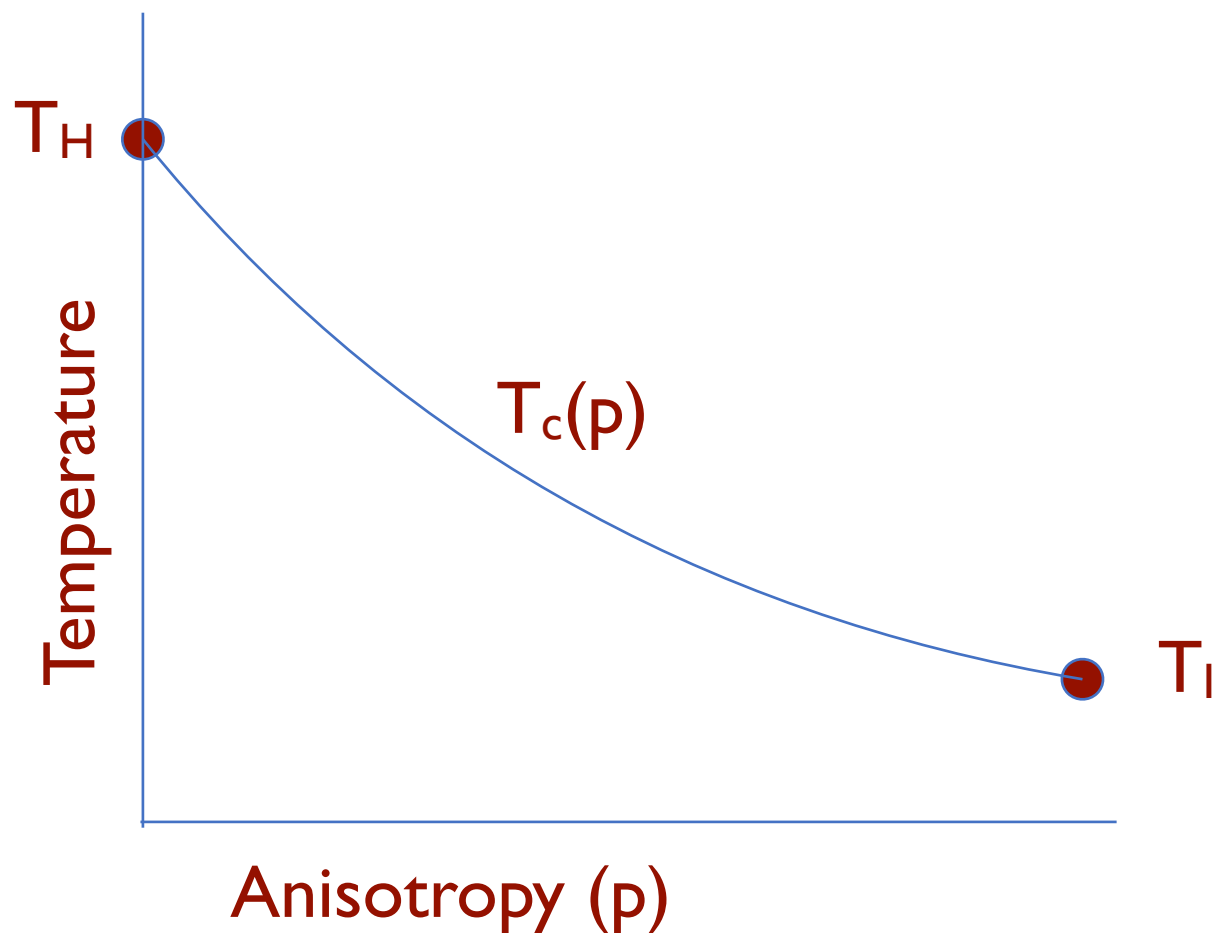
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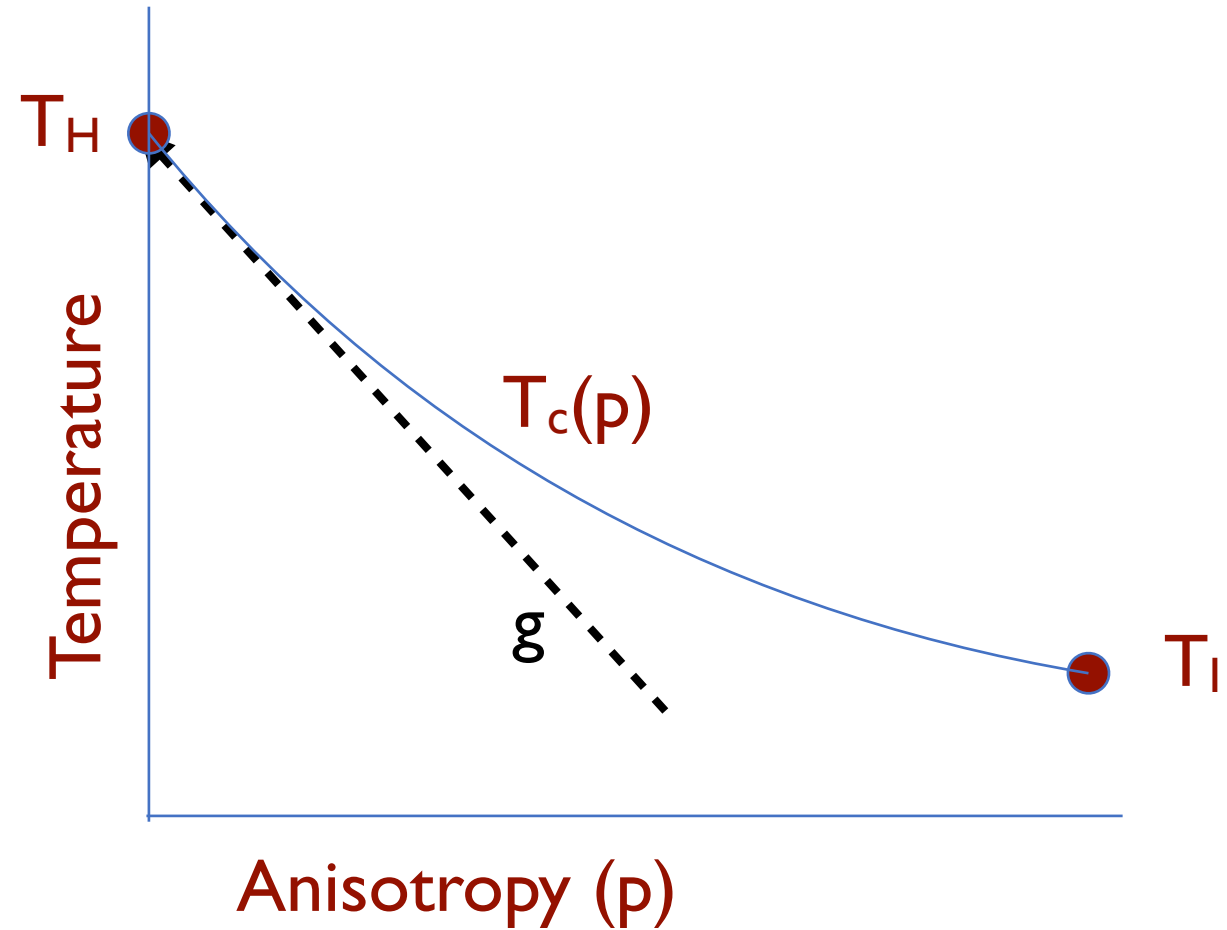
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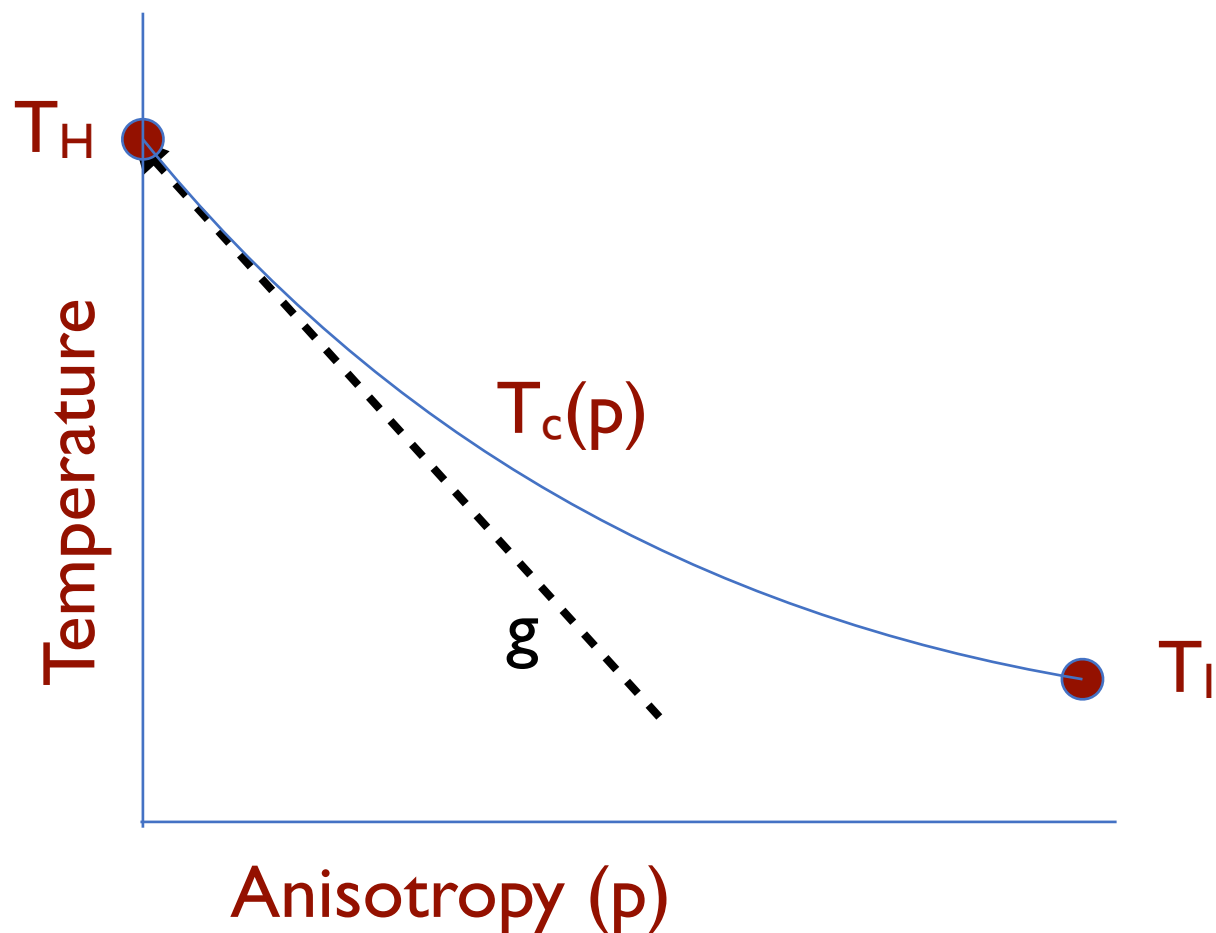
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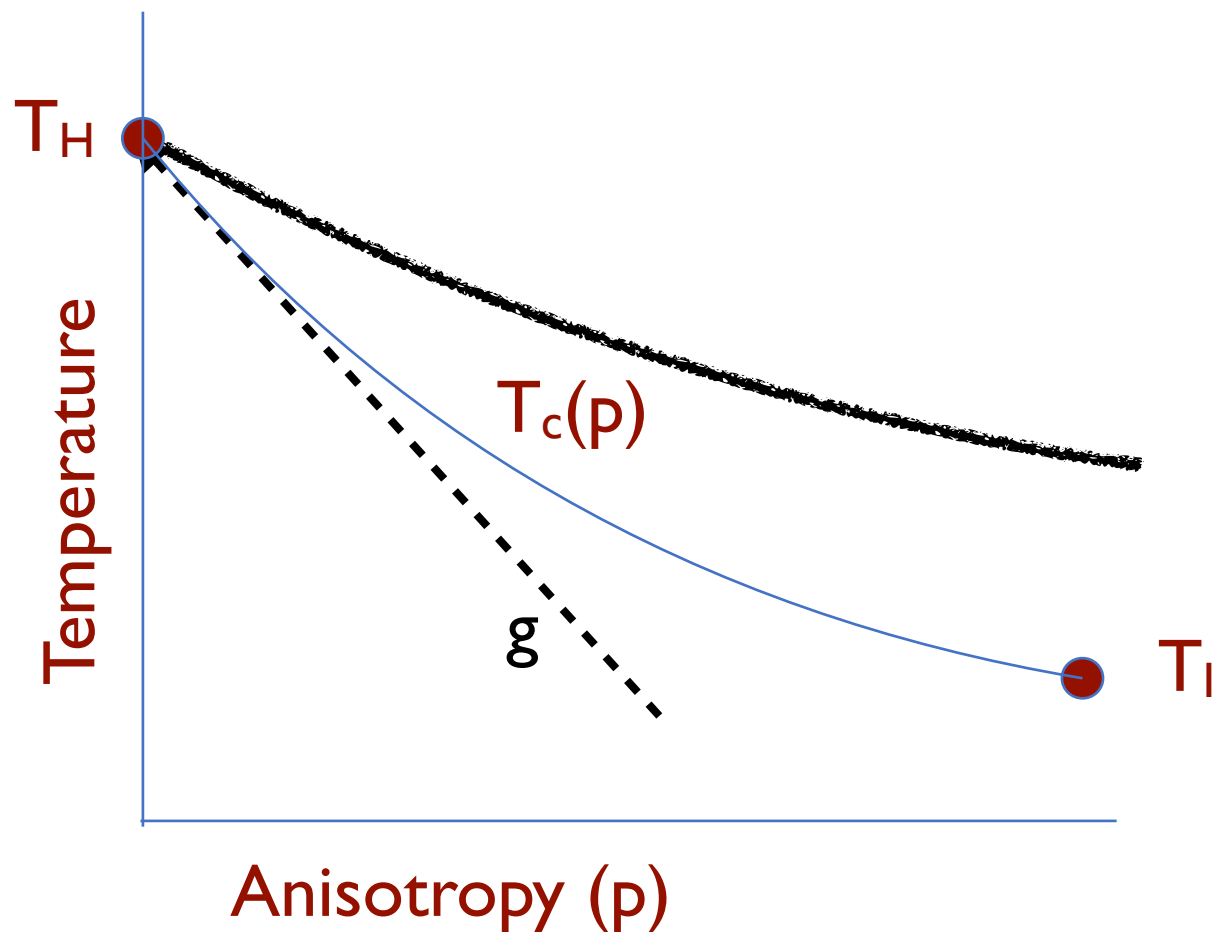
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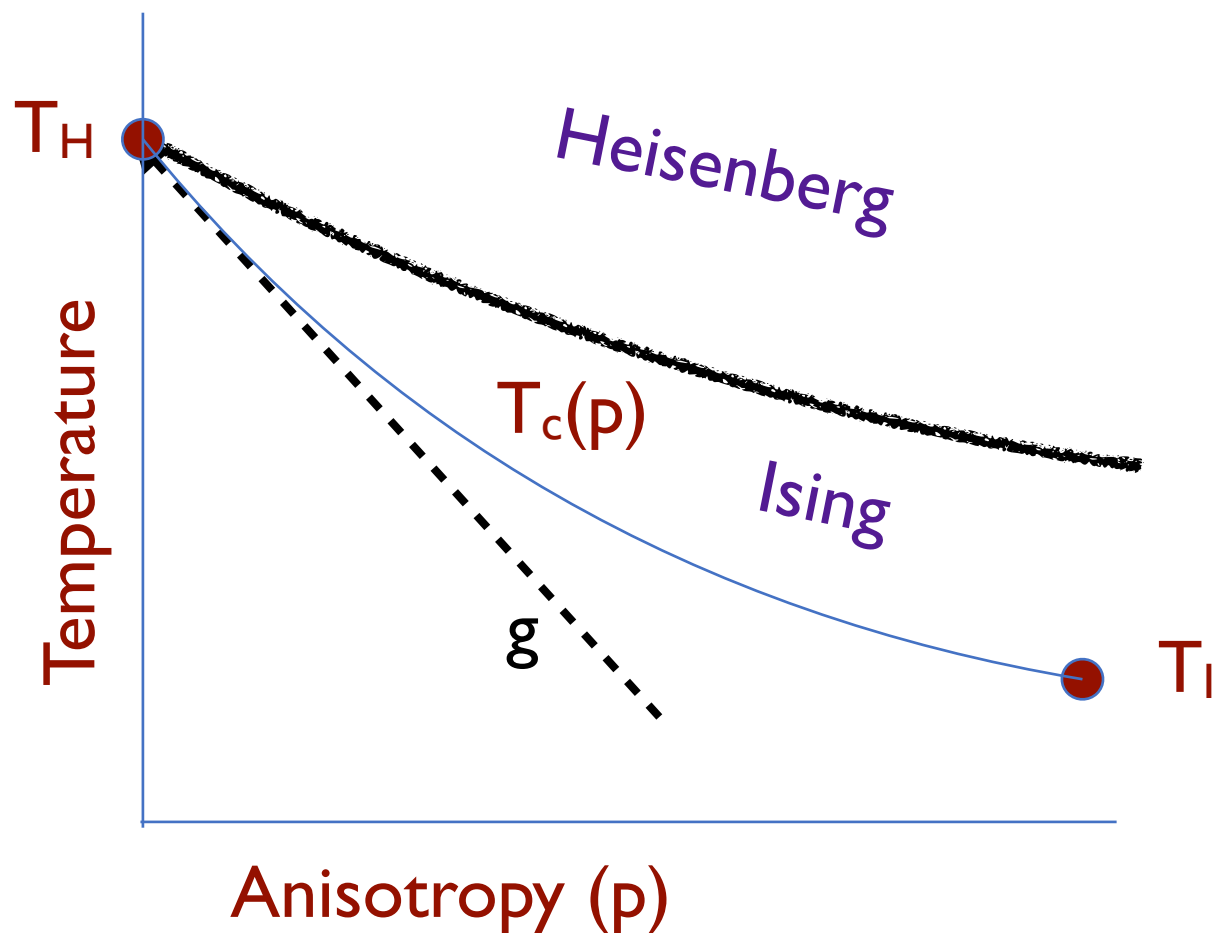
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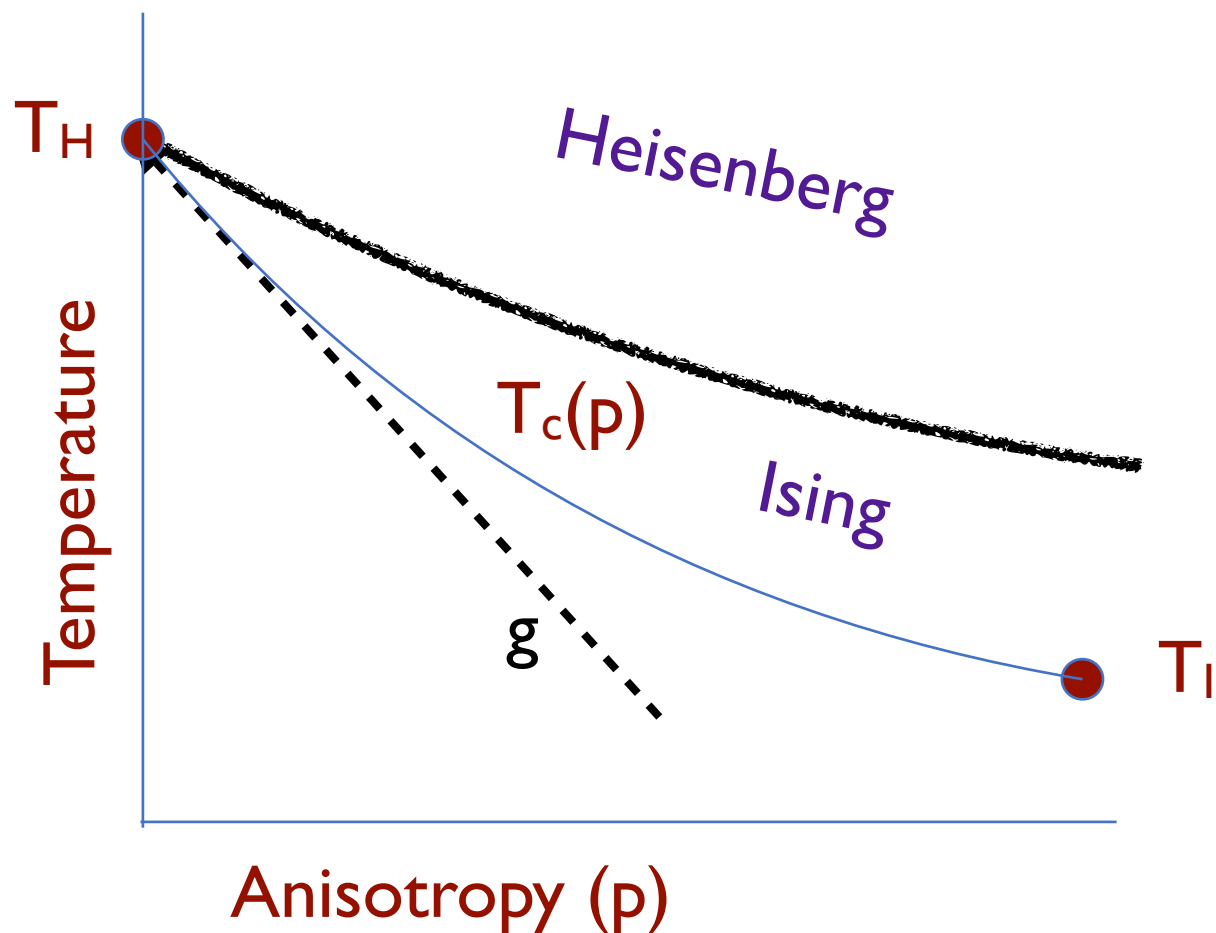
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Note: Controlling p is not the same as controlling g or the distance x .

Crossover Scaling in Shear Thickening

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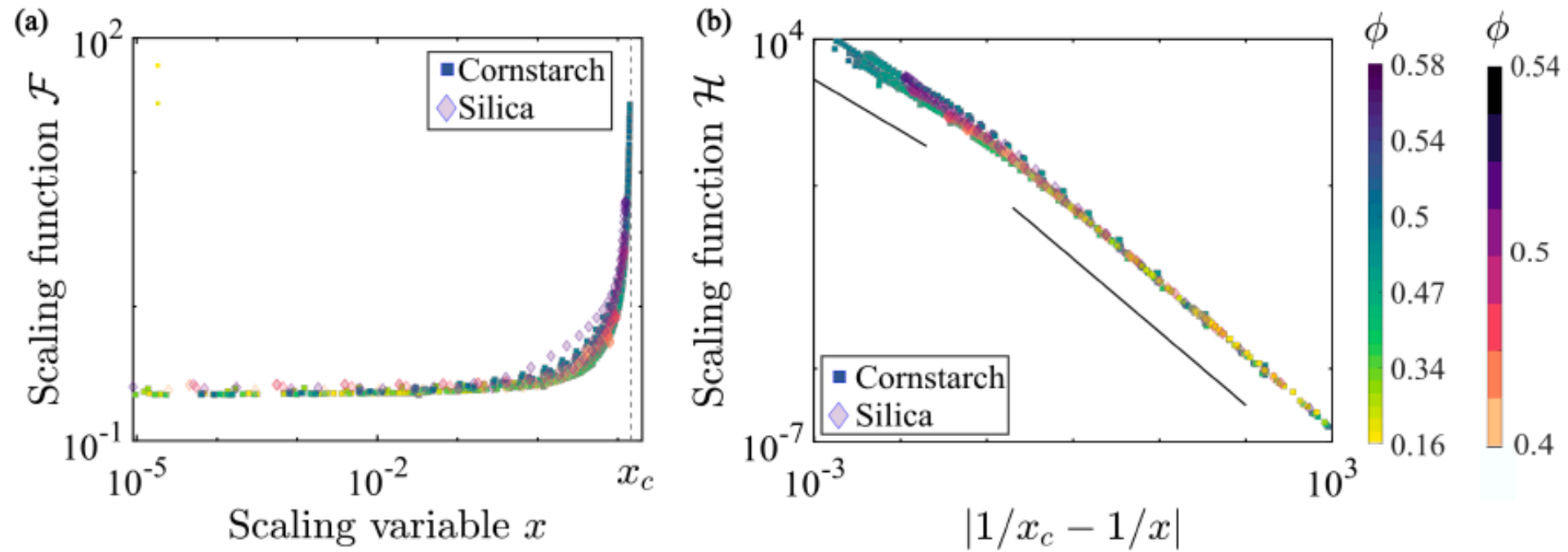
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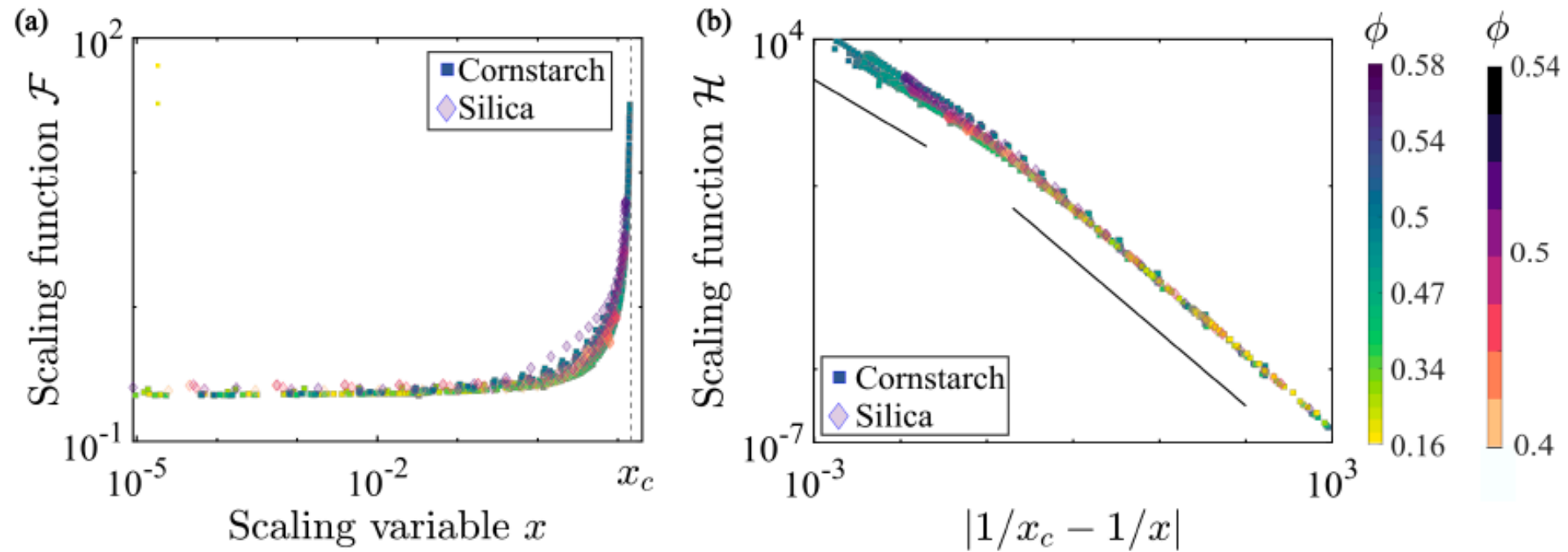
Does it work ?

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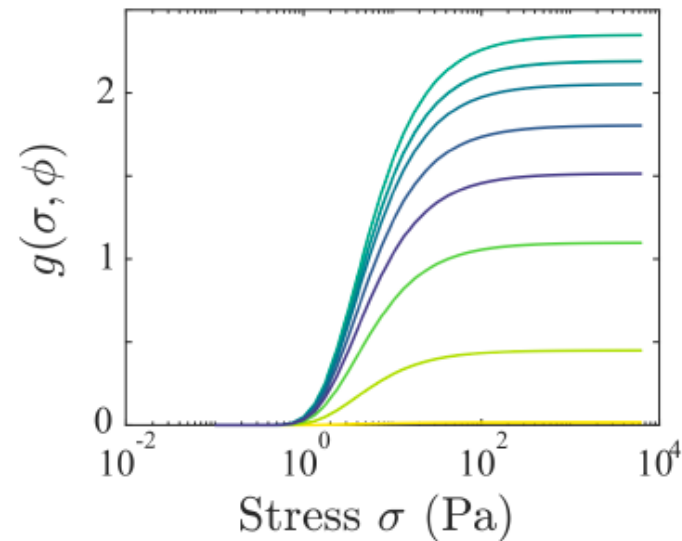


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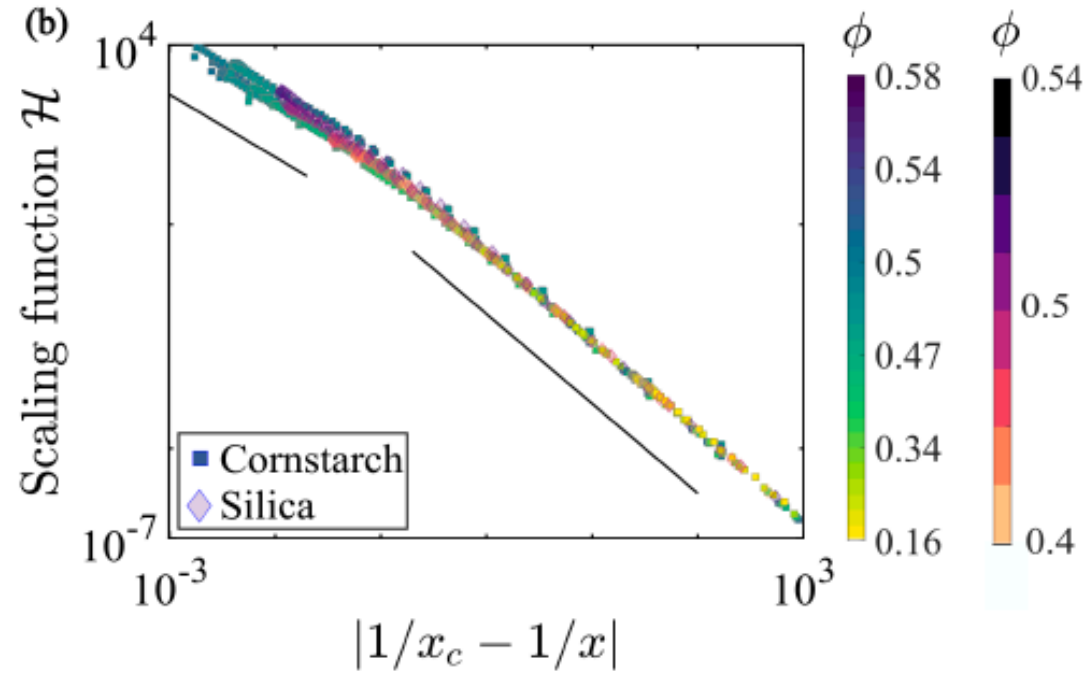
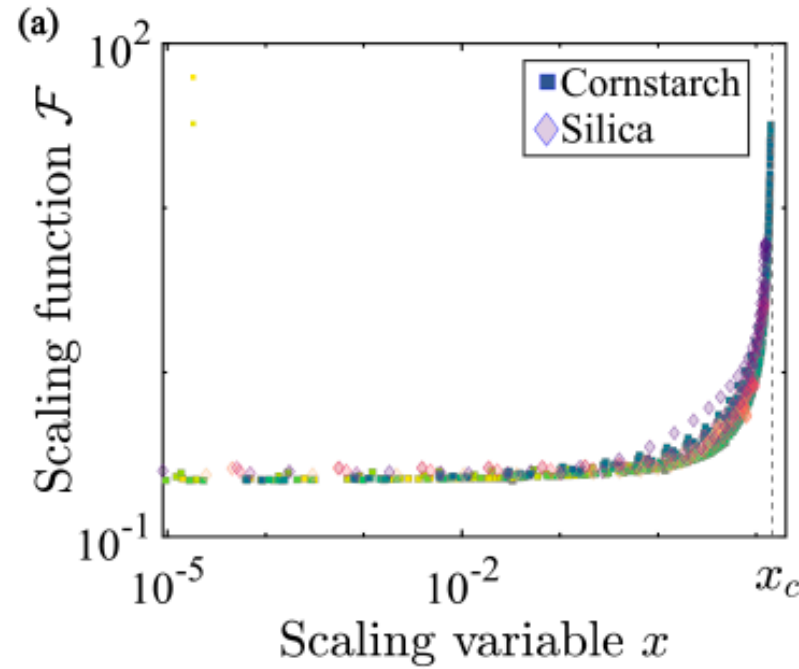
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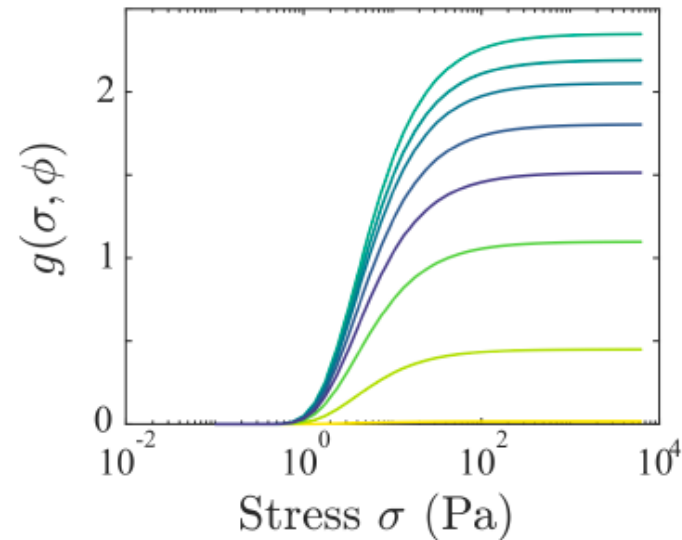
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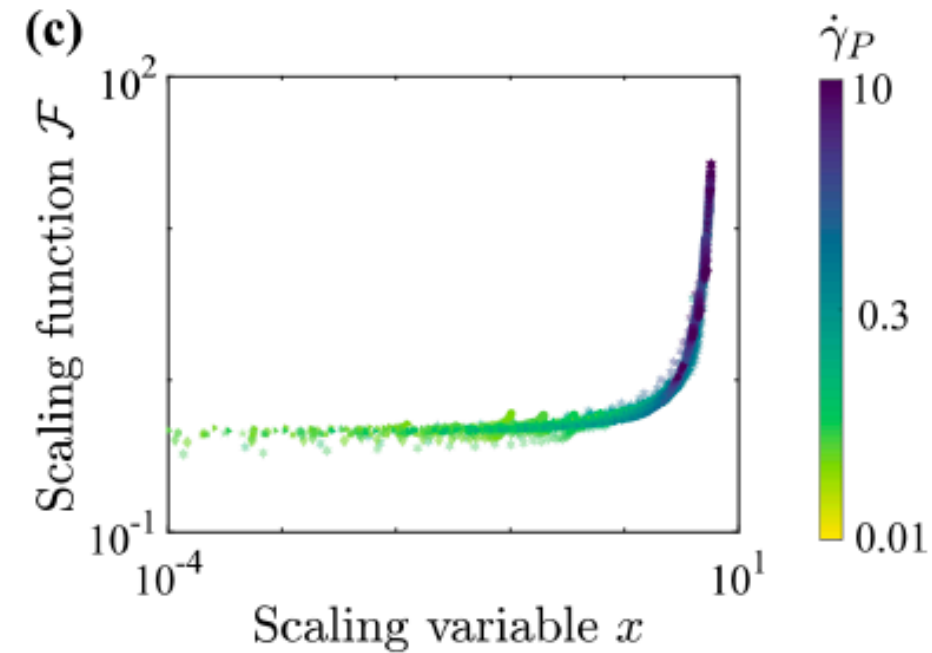
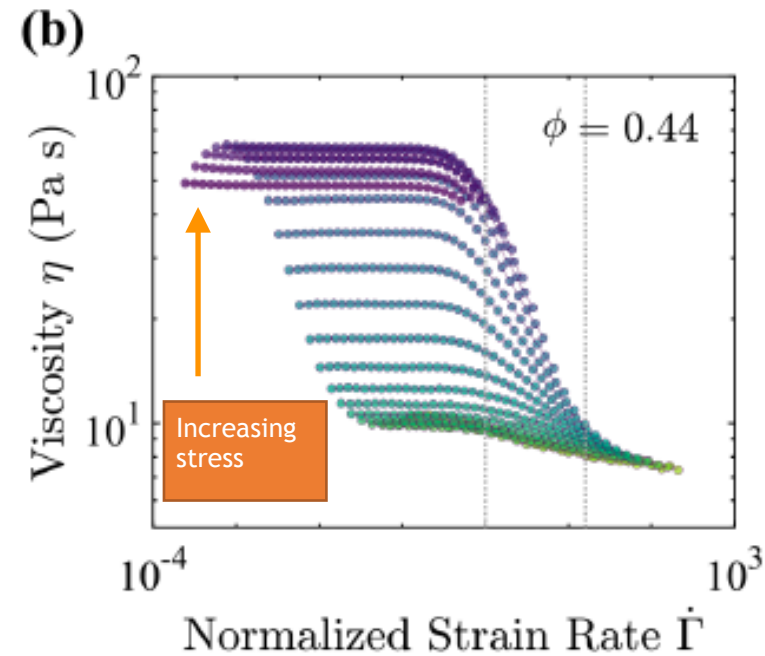
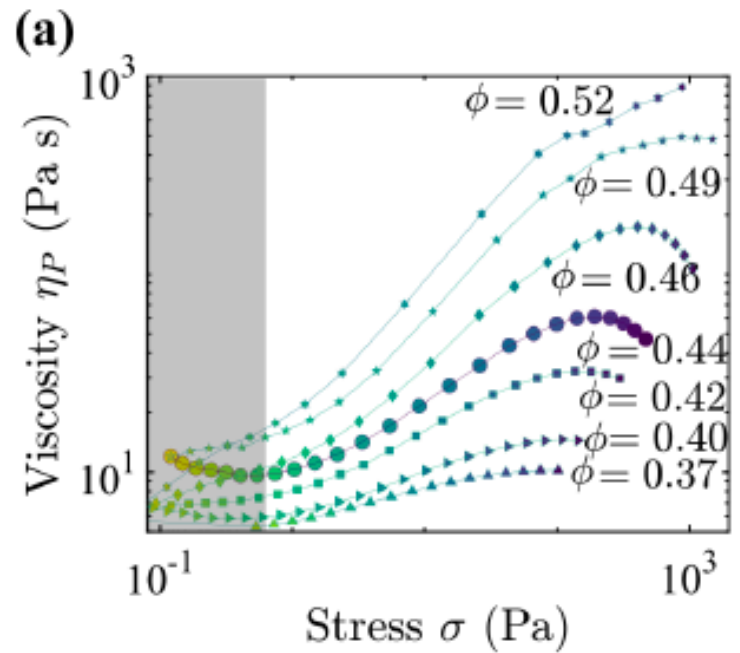
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Incorporate other tuning parameters in g ?

Universality? What determines it?

Orthogonal Shear

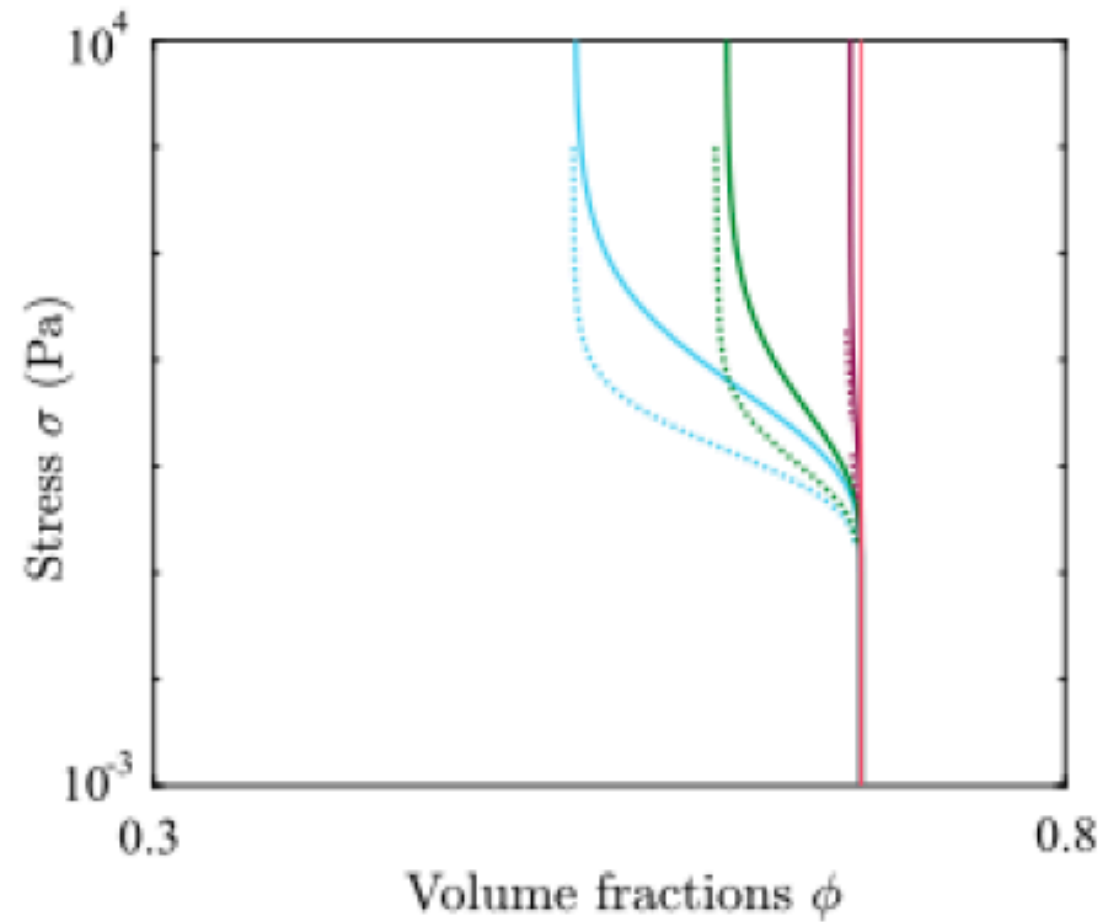
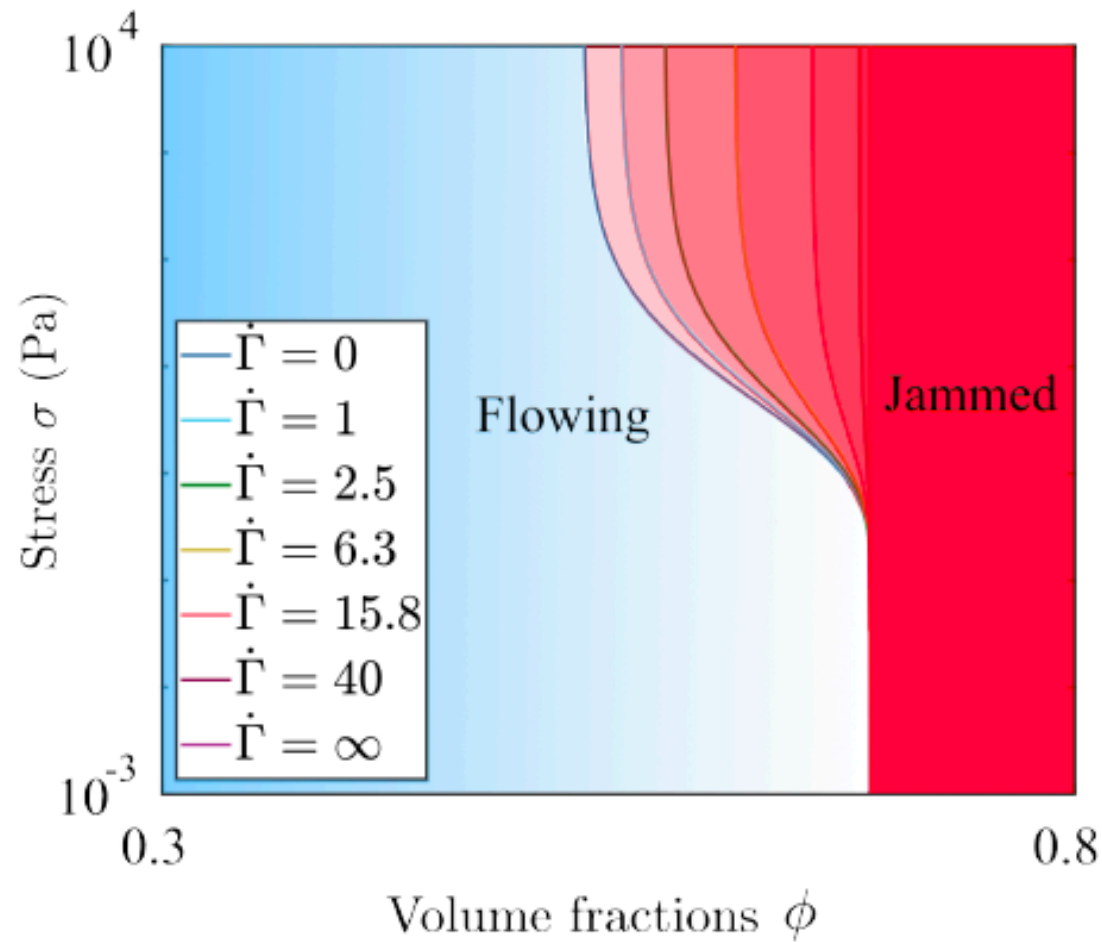


A Universal Scaling Framework for Tunable Shear Thickening

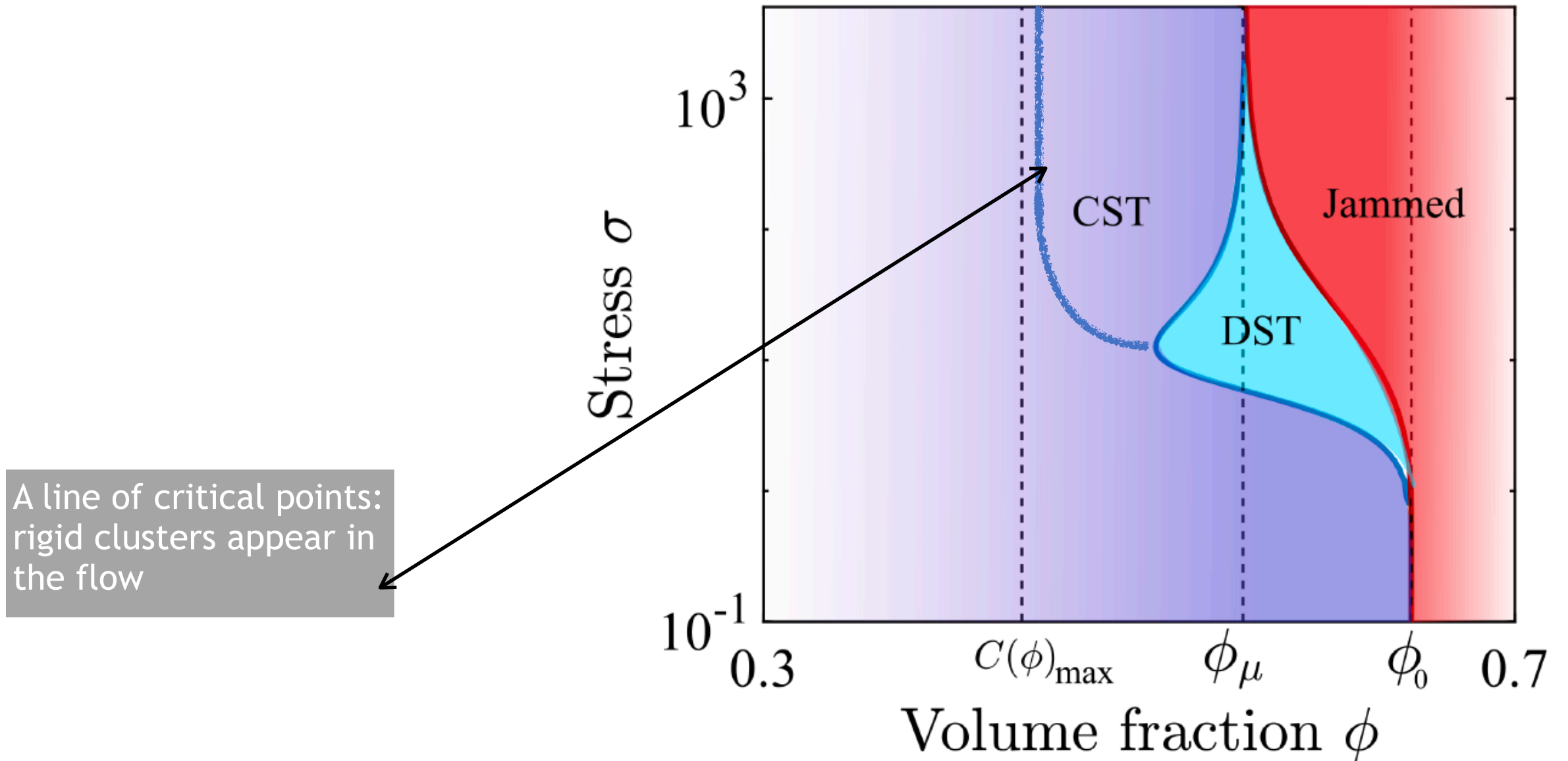
(arXiv: 2205.02184 and 2107.13338)

$$x(\phi, \sigma, \dot{\Gamma}) = \frac{f(\sigma)C(\phi)g(\dot{\Gamma})}{(\phi_0 - \phi)}$$

Jamming Phase Diagram from Scaling



Shadows of an Equilibrium Transition

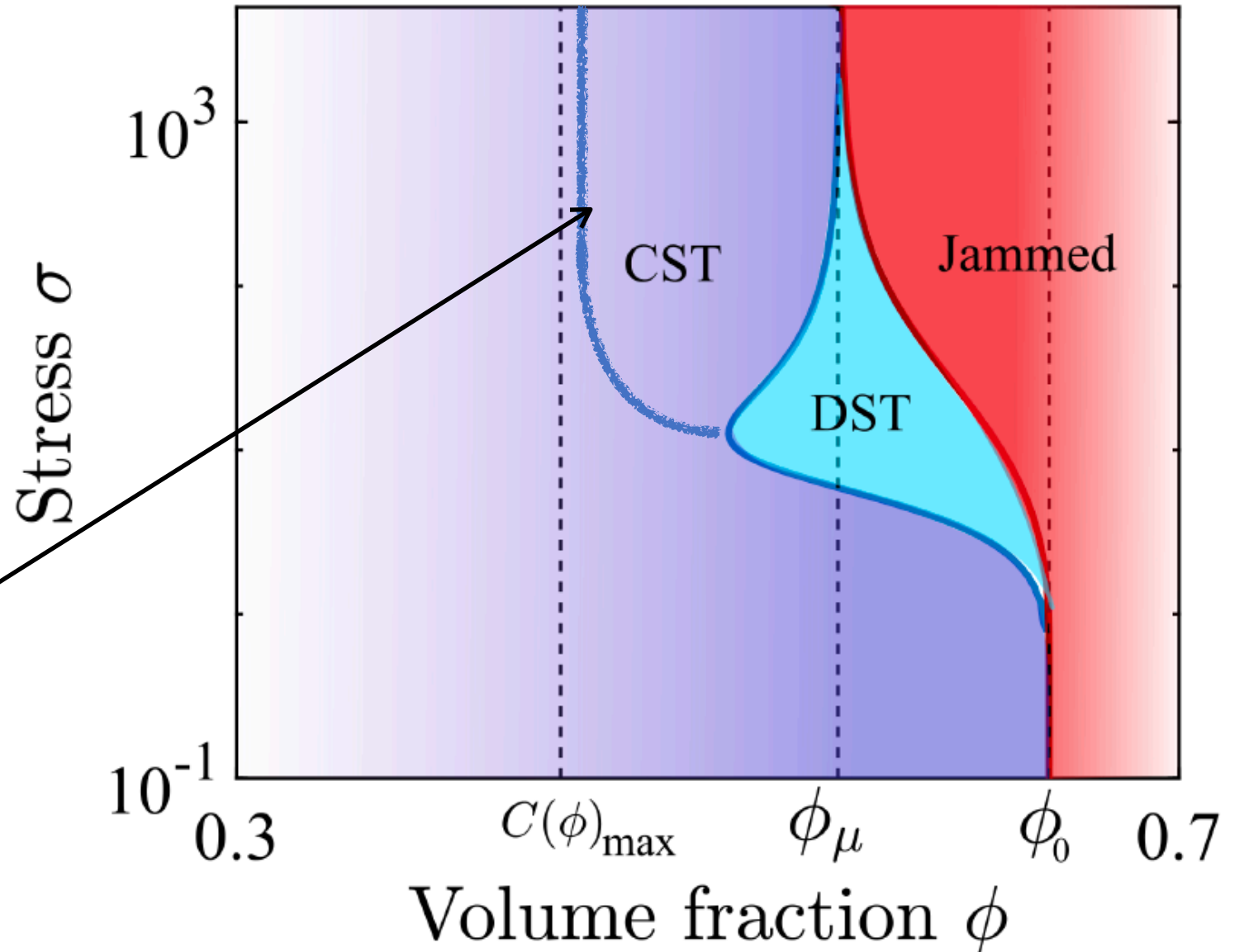


Shadows of an Equilibrium Transition

Aritra Santra, Michel Orsi, & Jeffrey Morris

Simulations in 2D

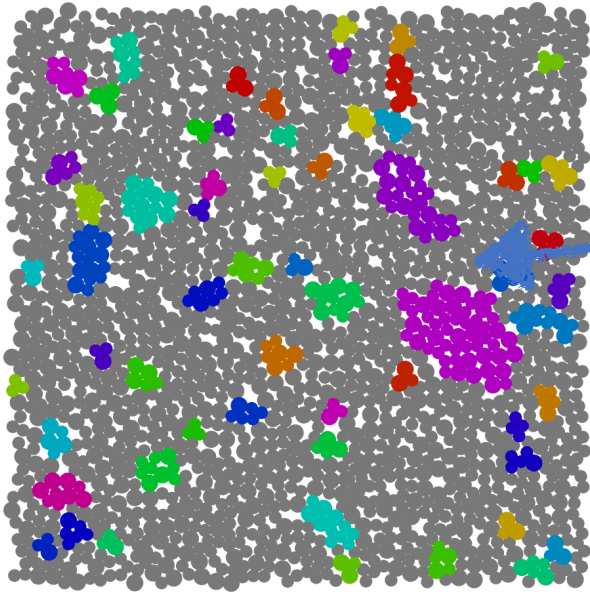
Mari, R., R. Seto, J. F. Morris, and M. M. Denn, "Shear thickening, frictionless and frictional rheologies in non-Brownian suspensions," *J. Rheol.* 58(6), 1693–1724 (2014).



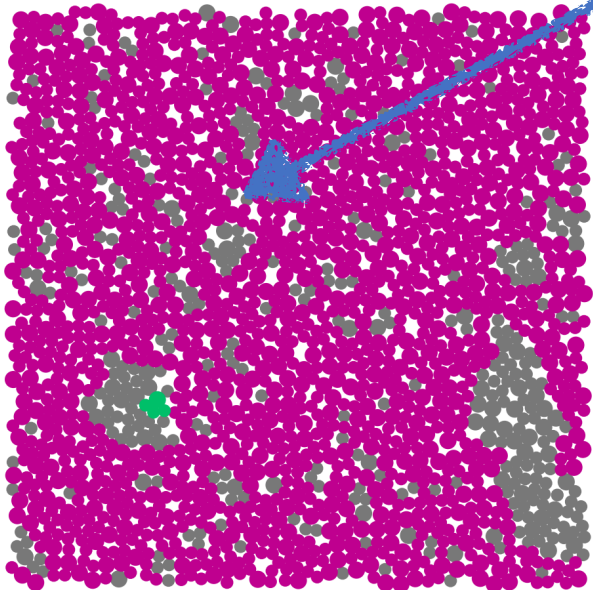
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Clusters of Rigid Particles

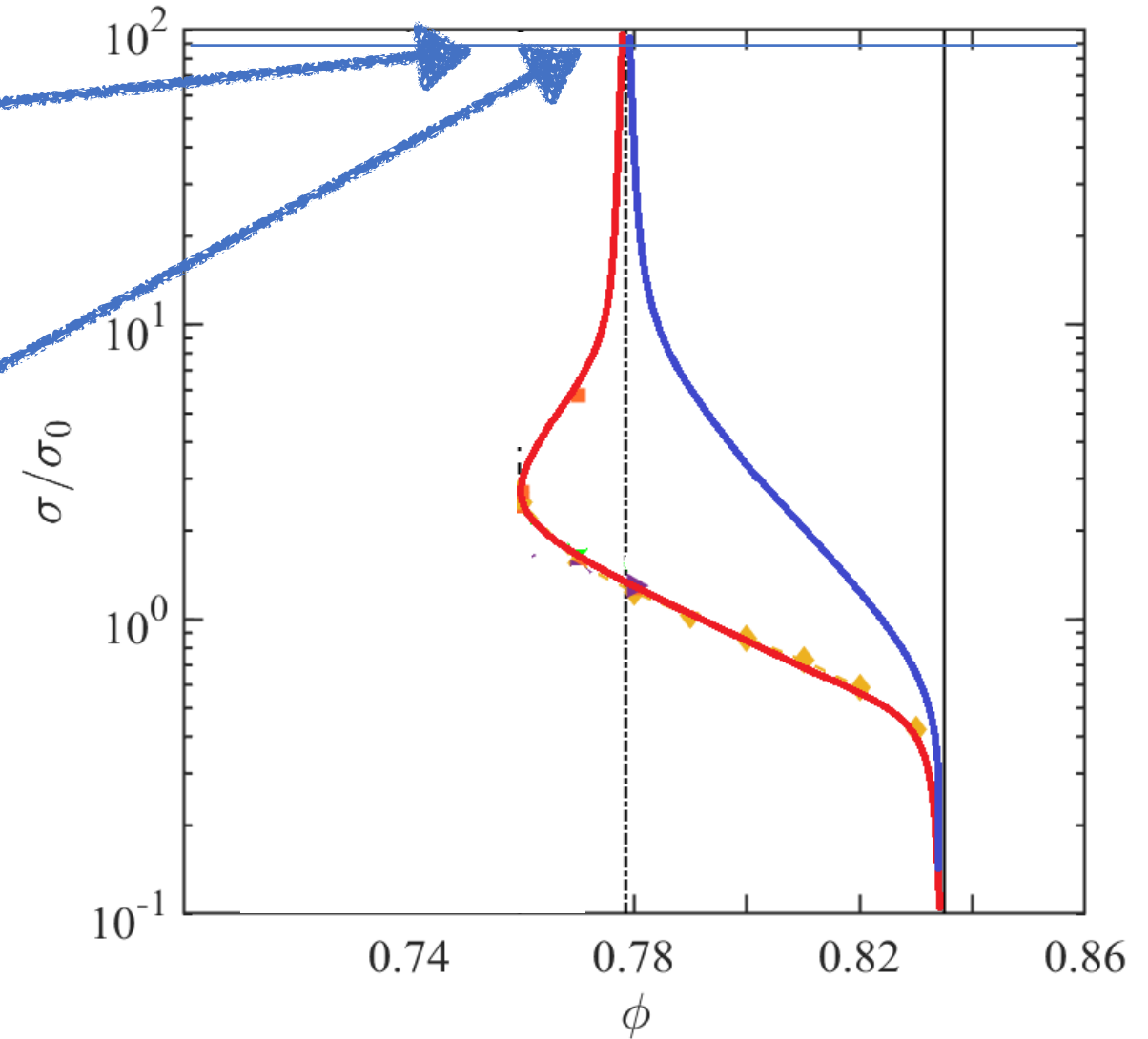
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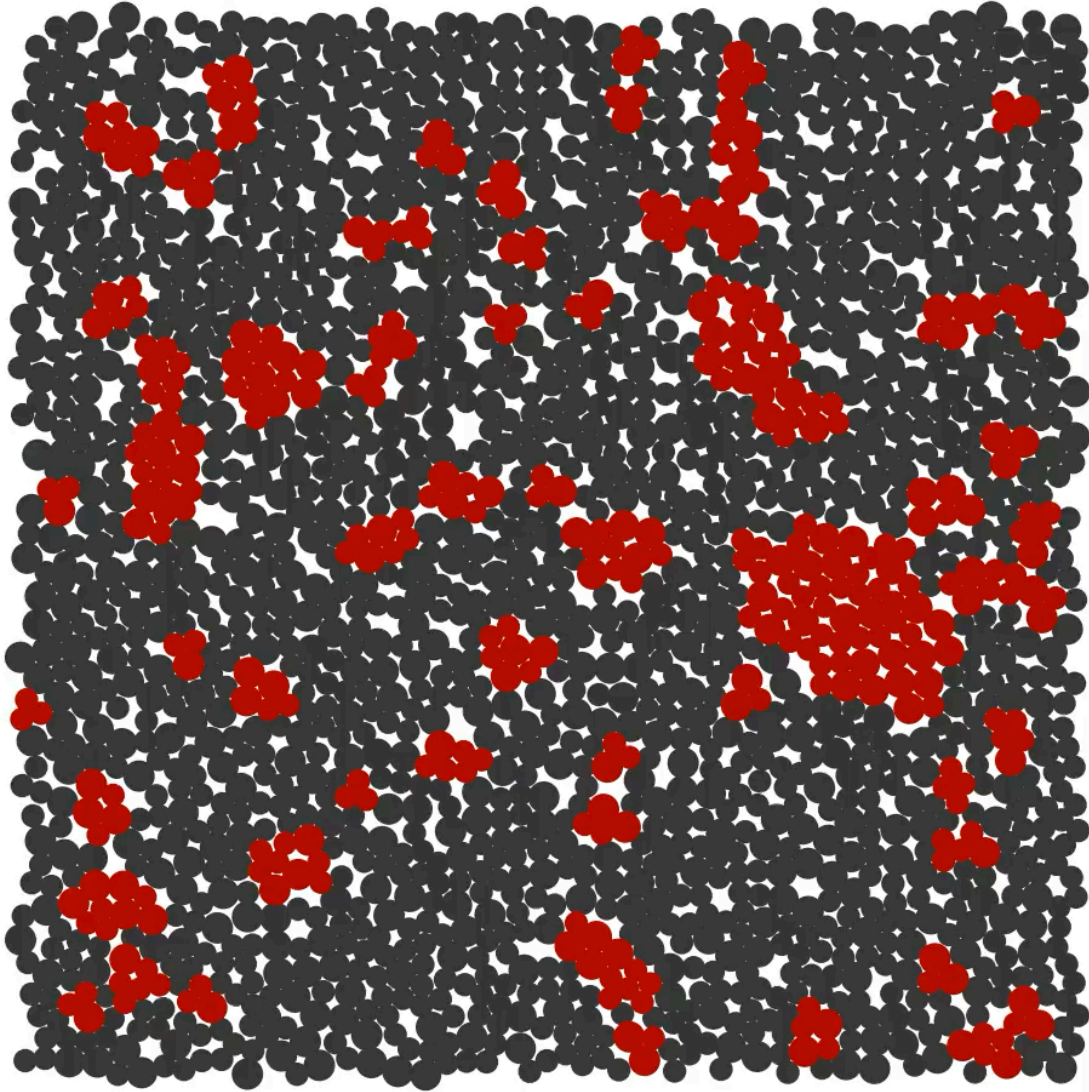


Pebble Game identifies rigid clusters (Silke Henkes)

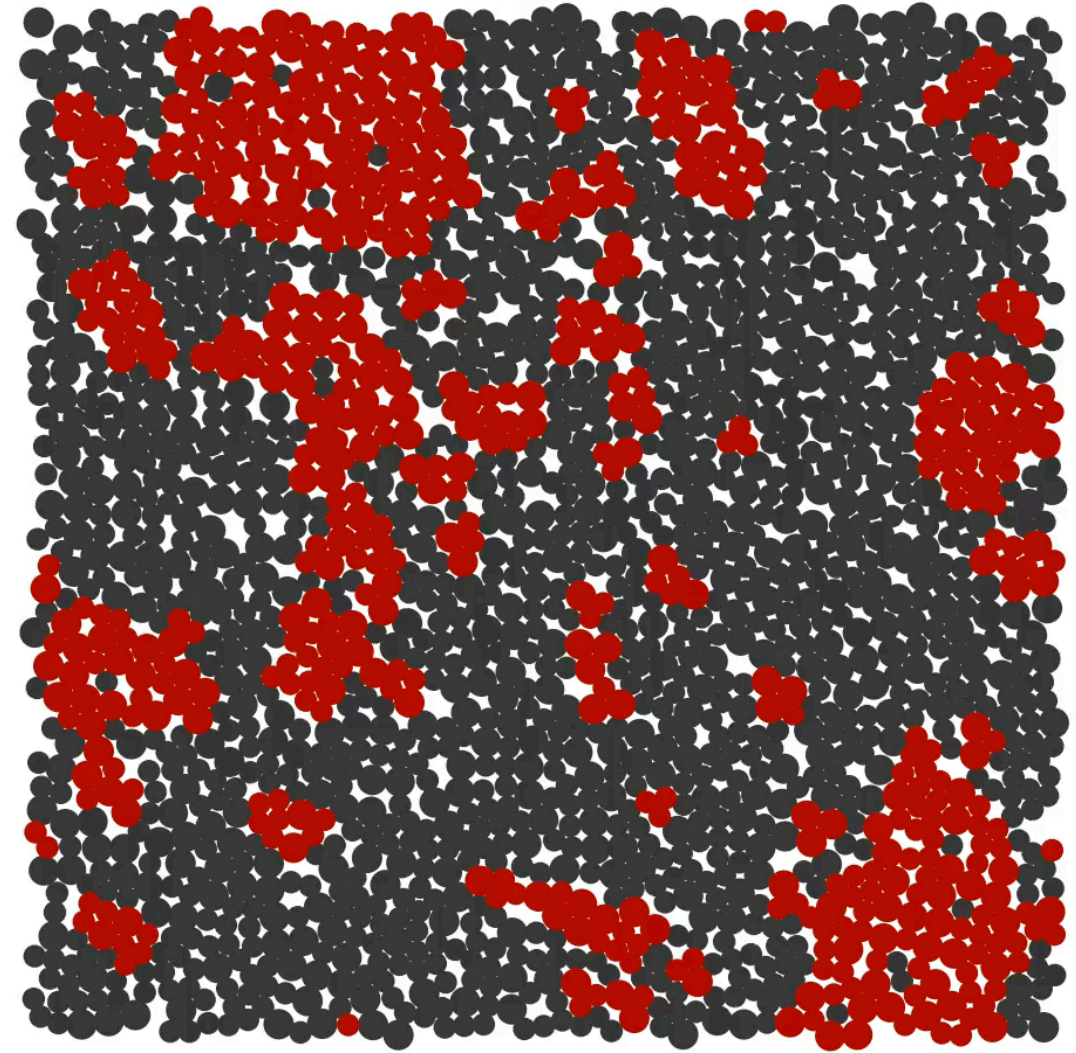


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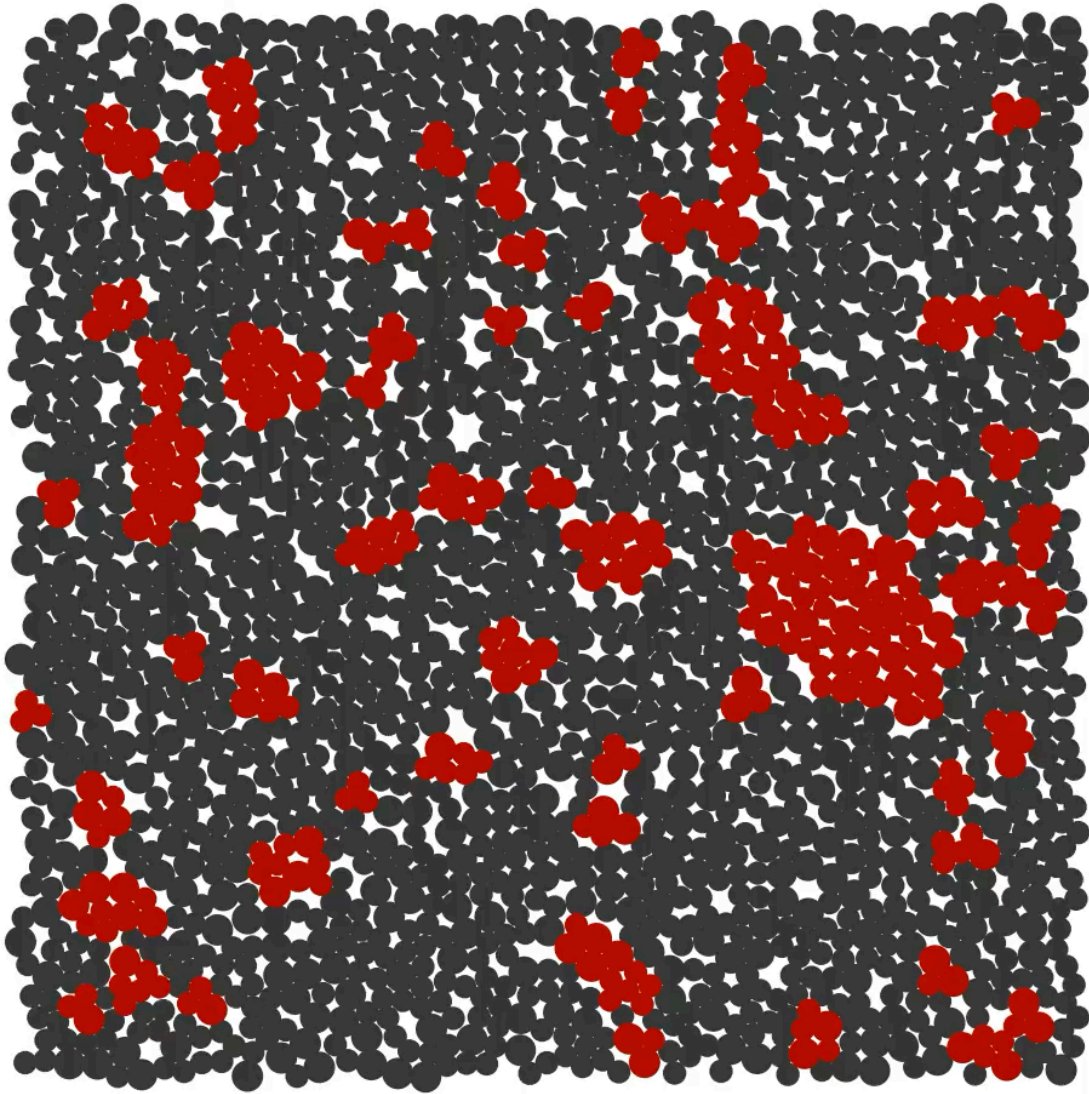


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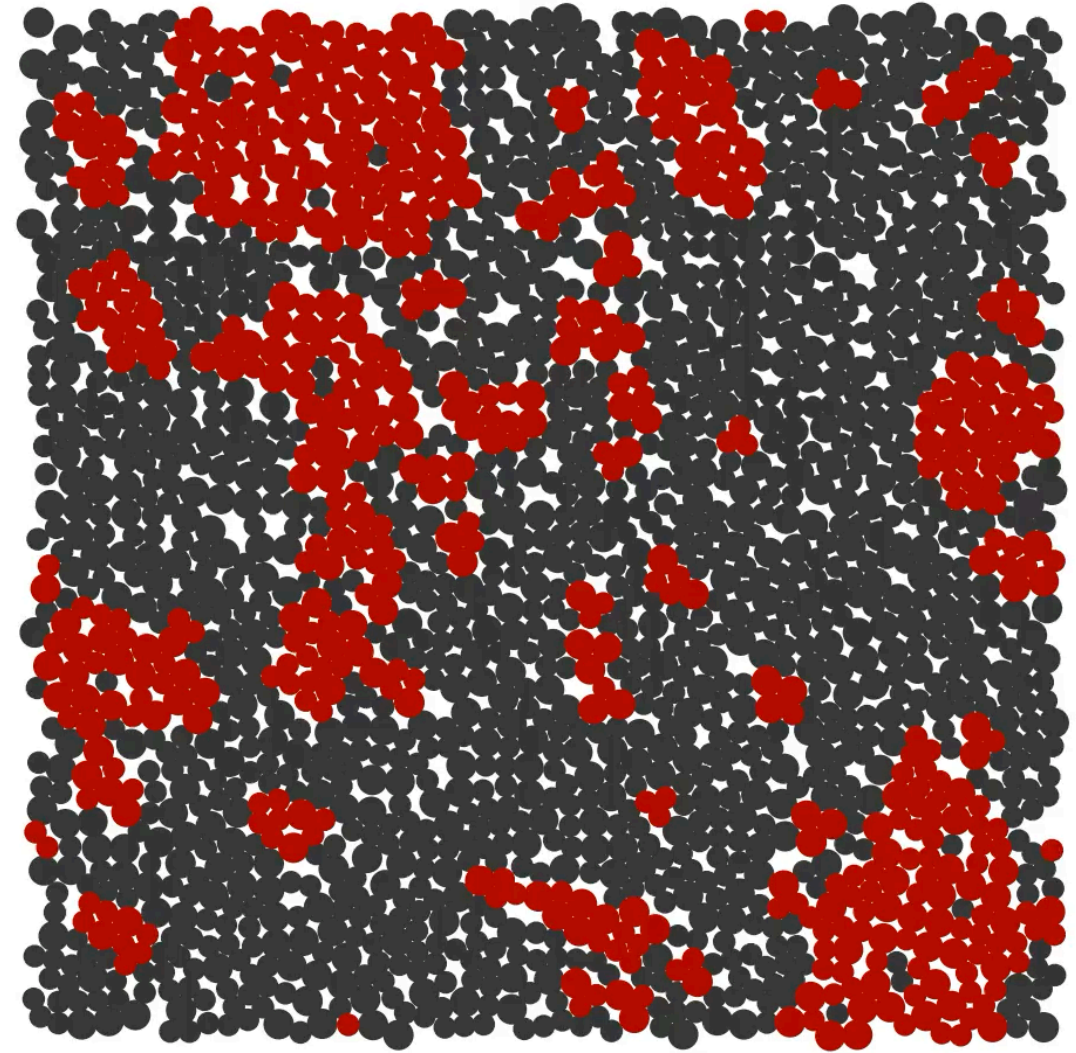


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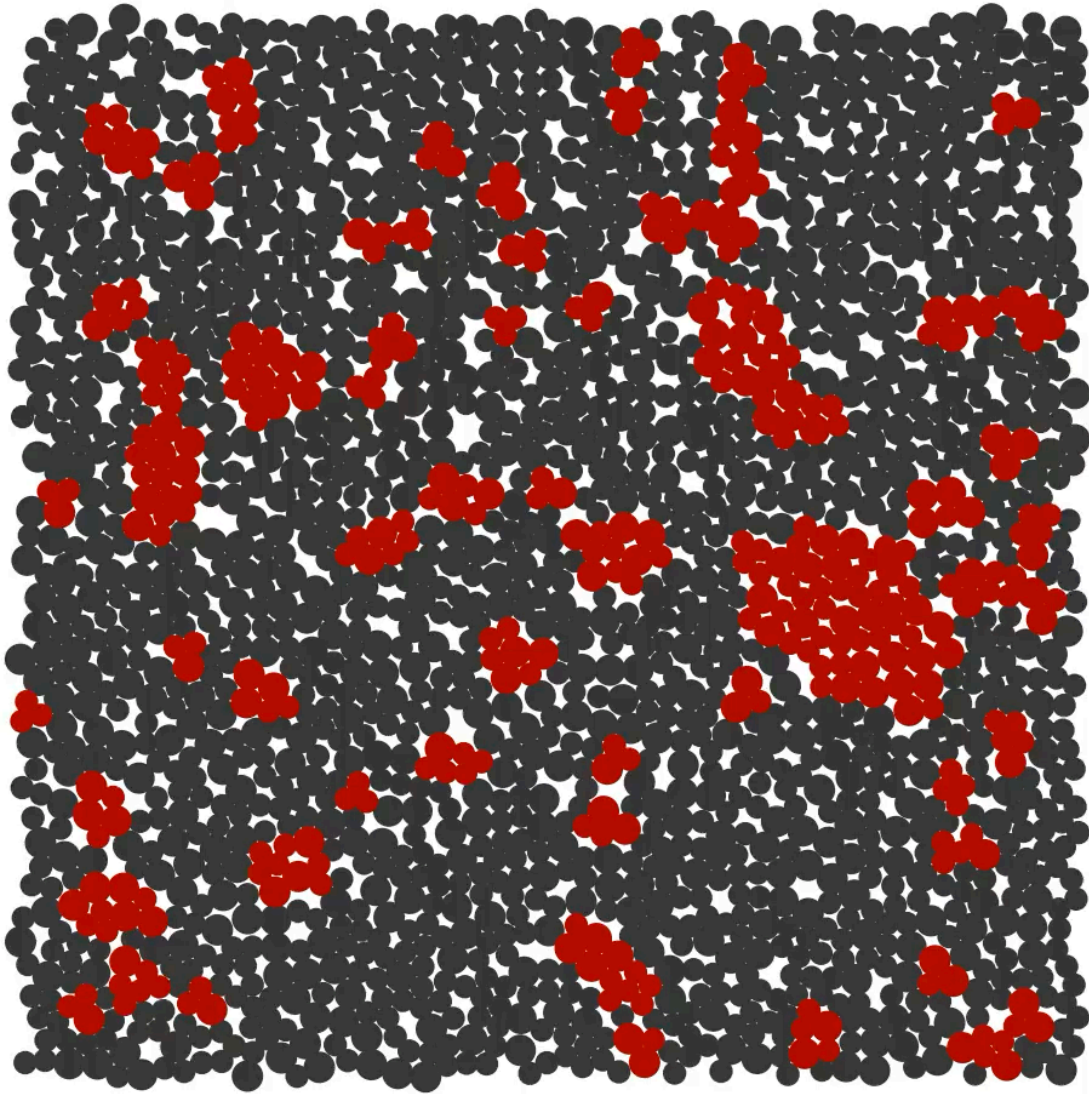


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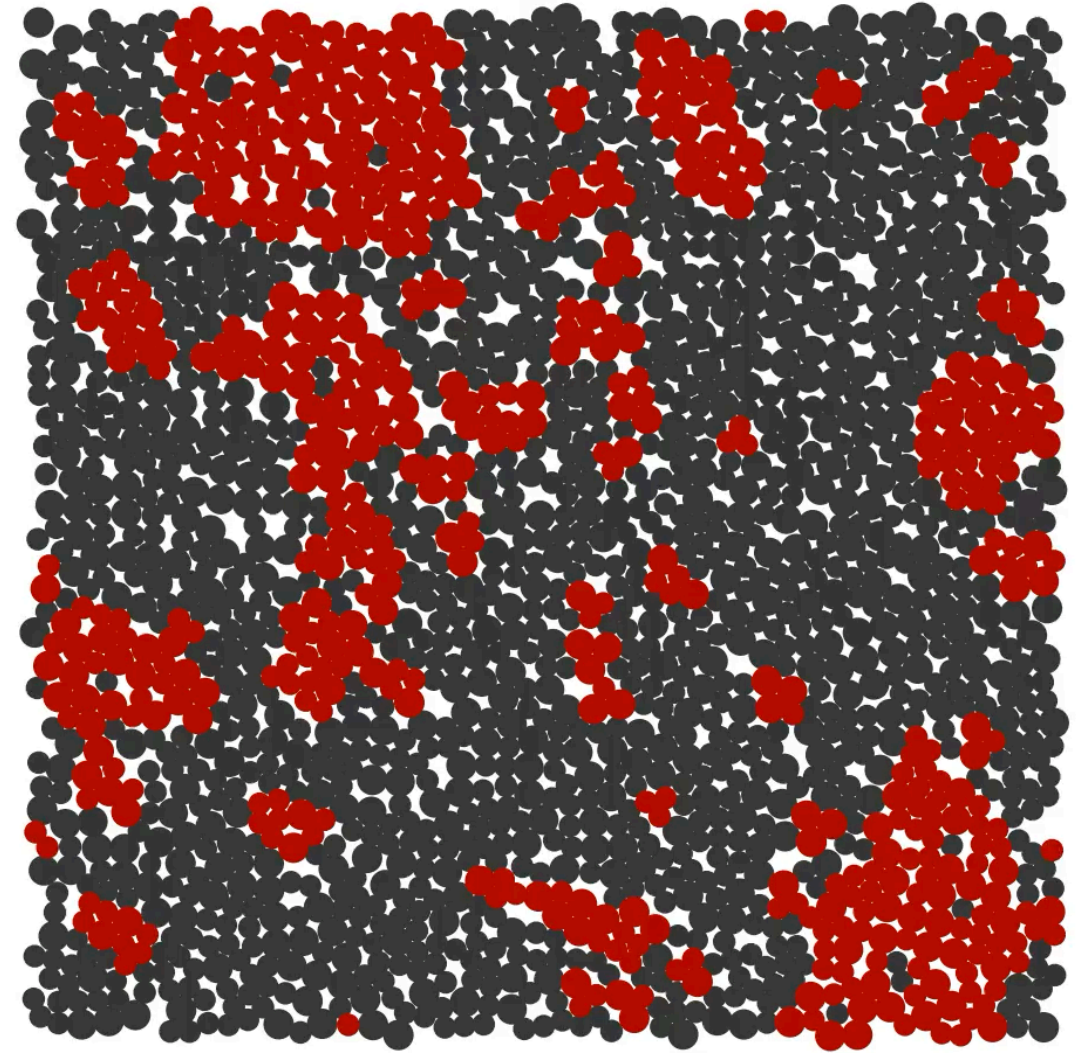


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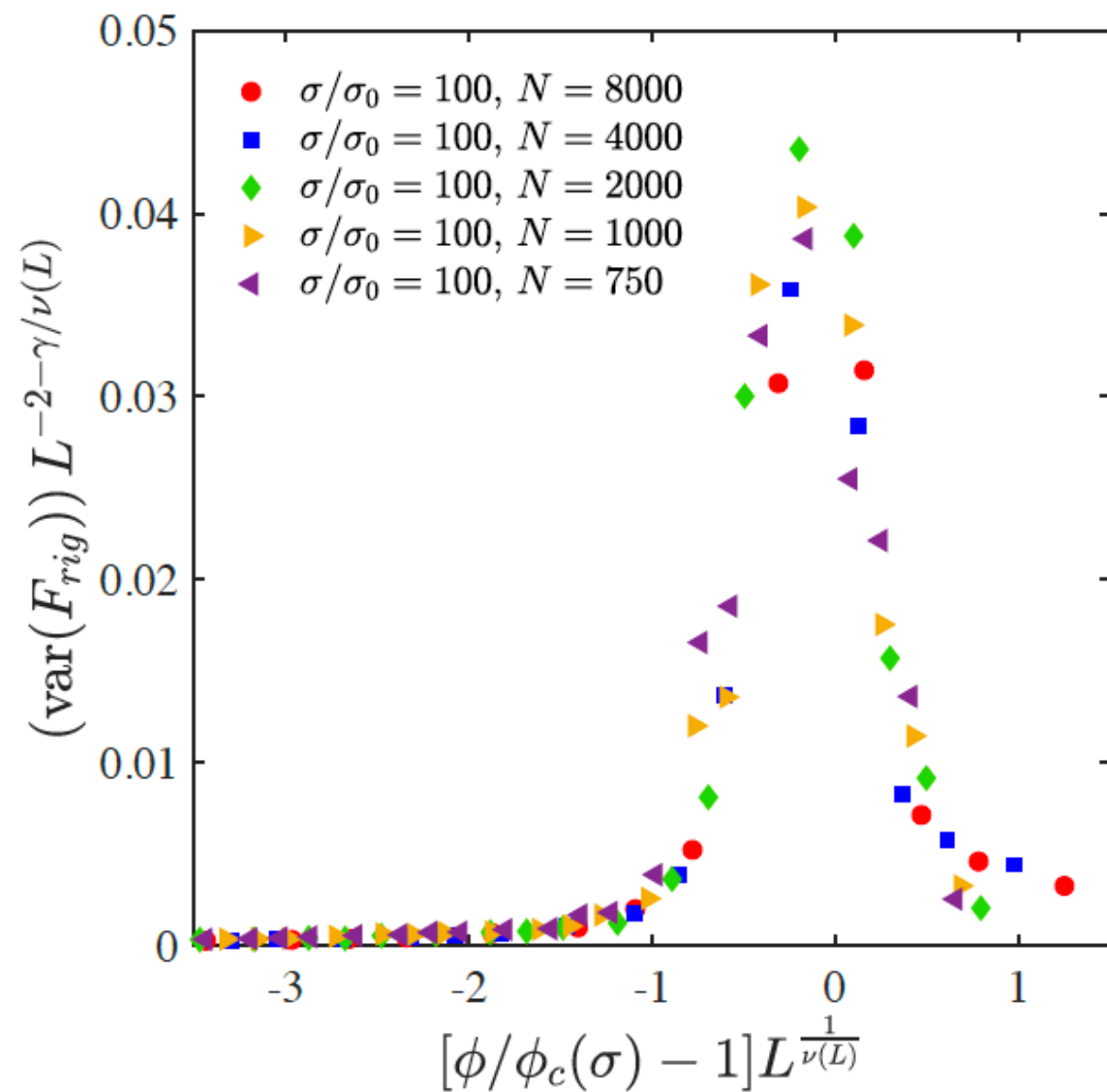
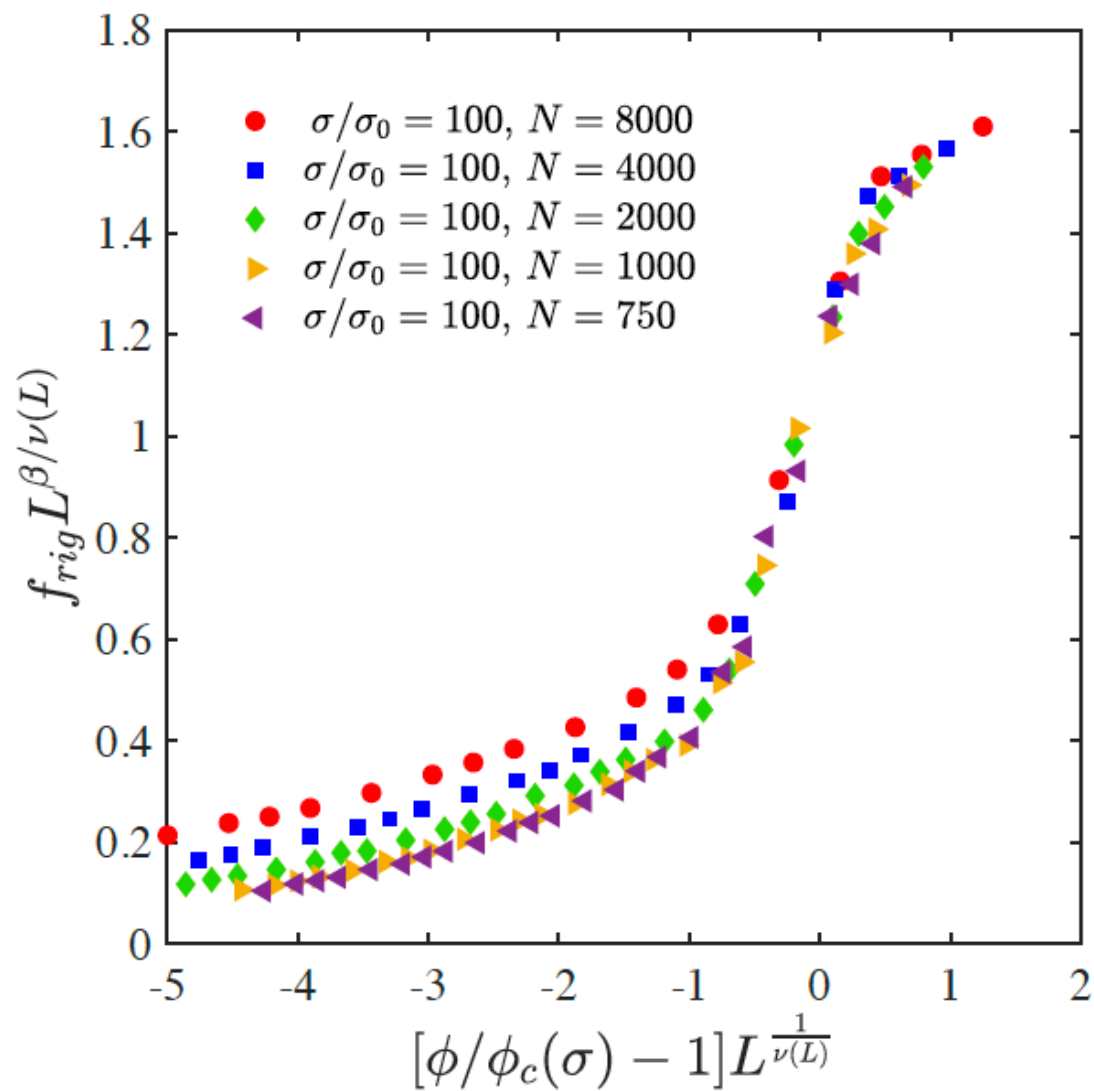
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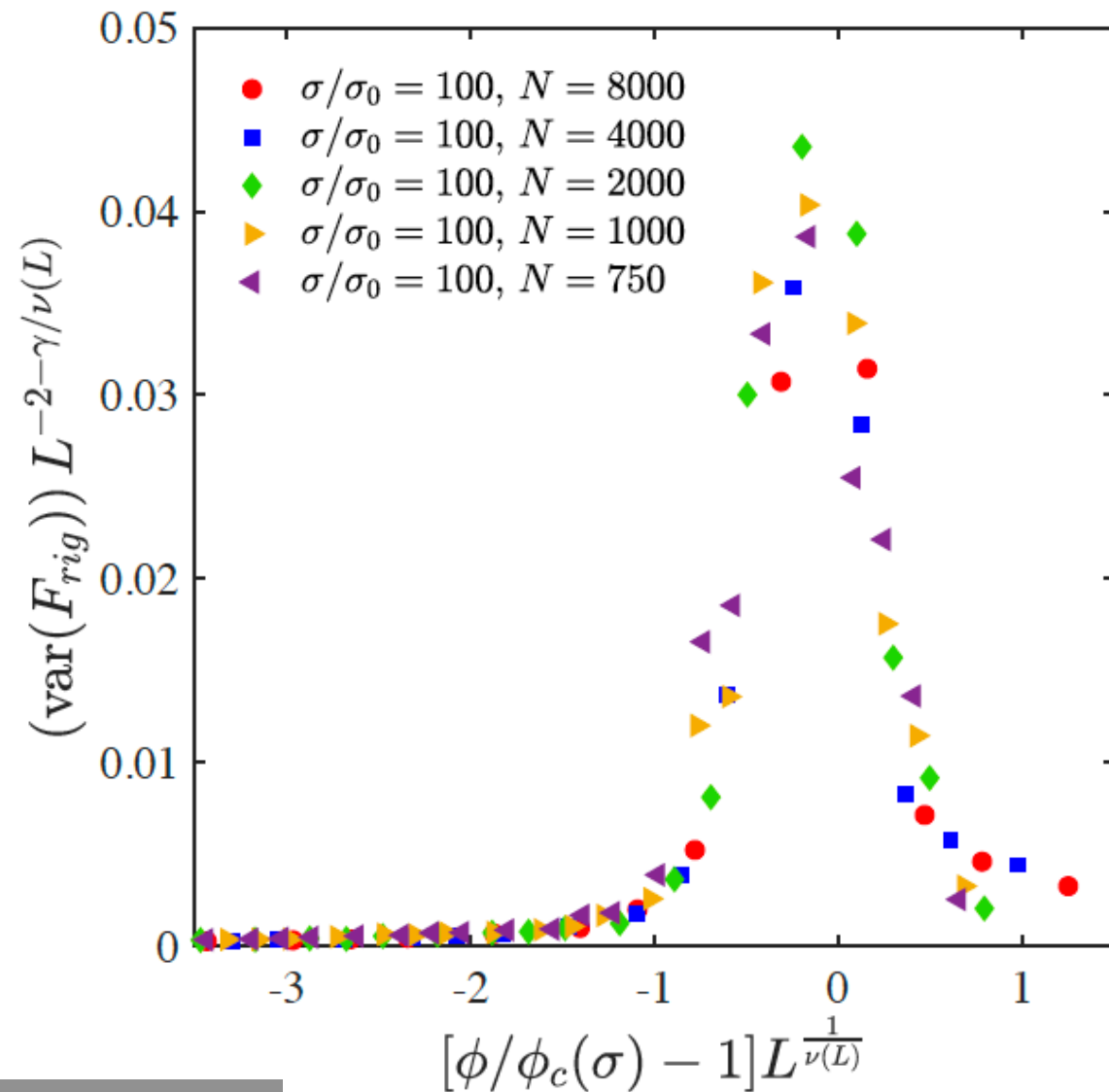
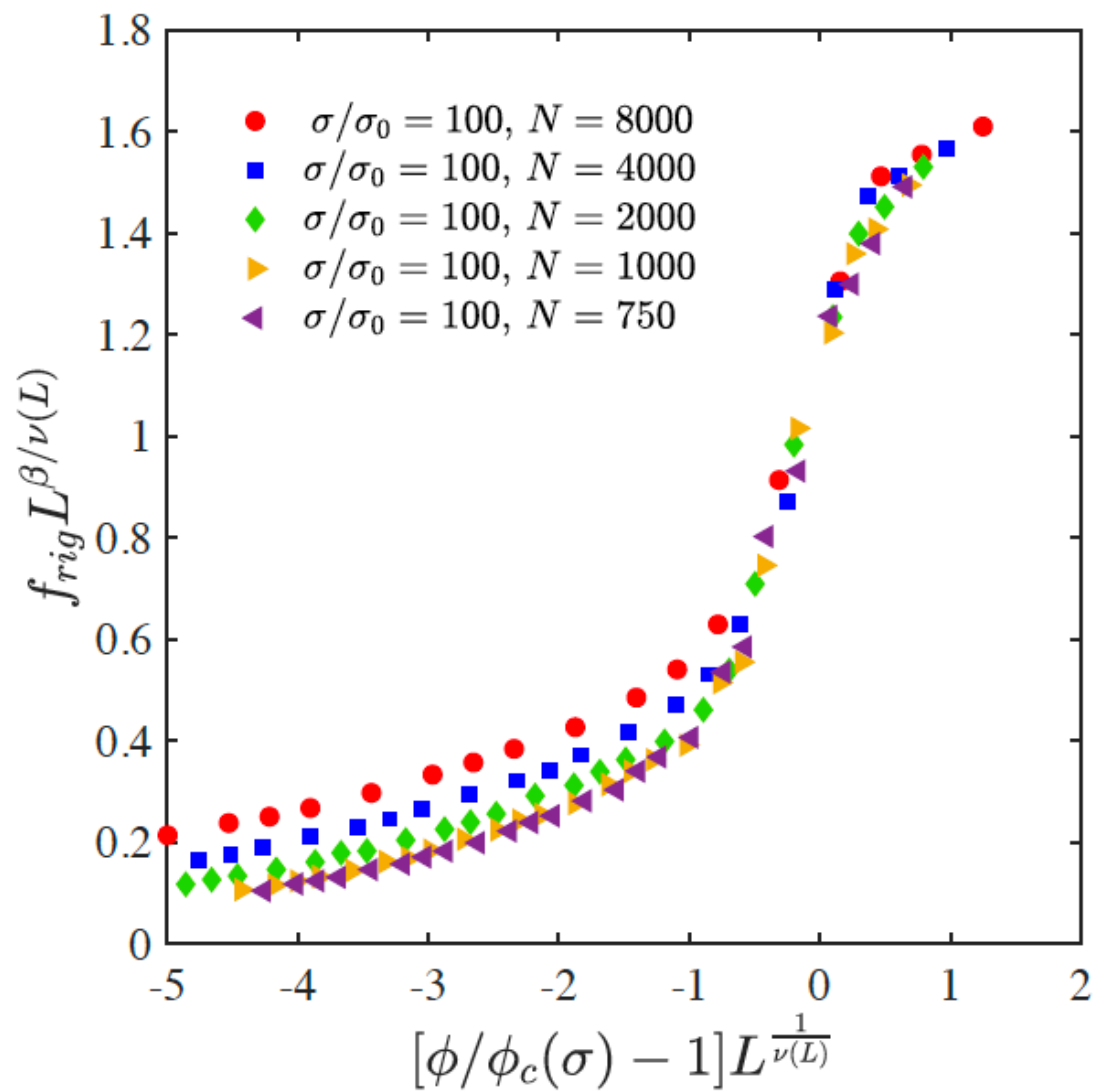
$NP = 2000$ $\phi = 0.757$ $t^* = 1.0$ $\gamma = 0.41$



Clusters of Rigid Particles

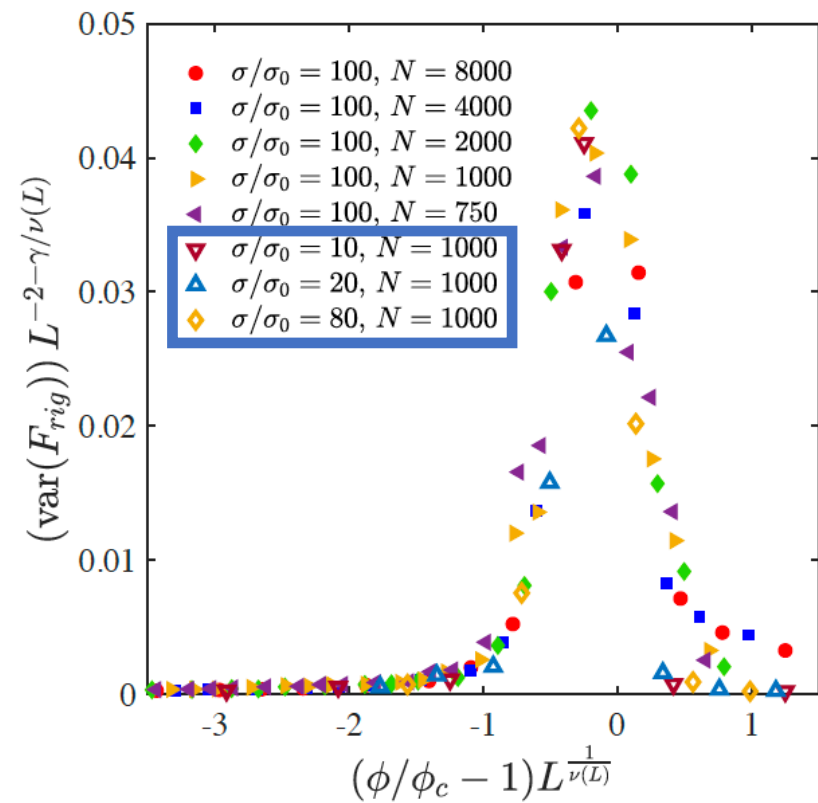
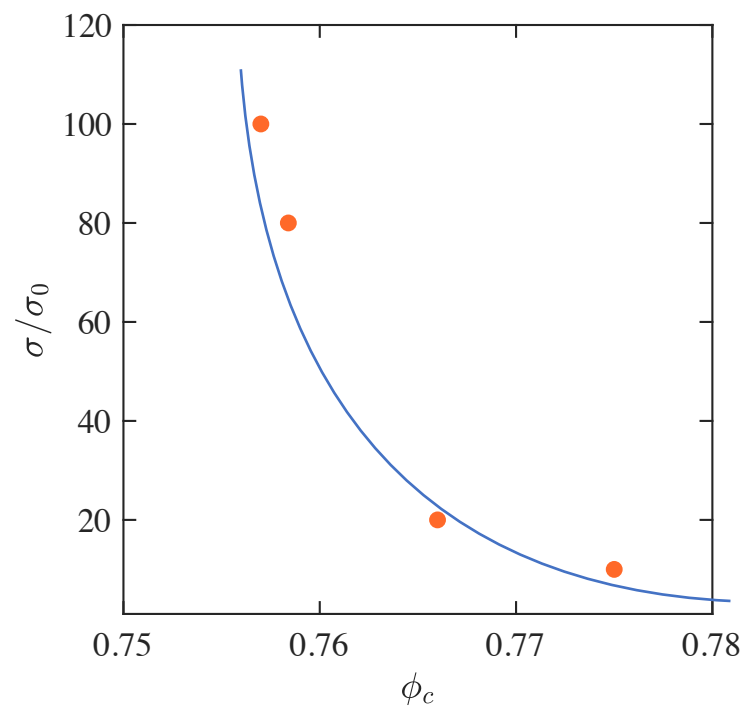
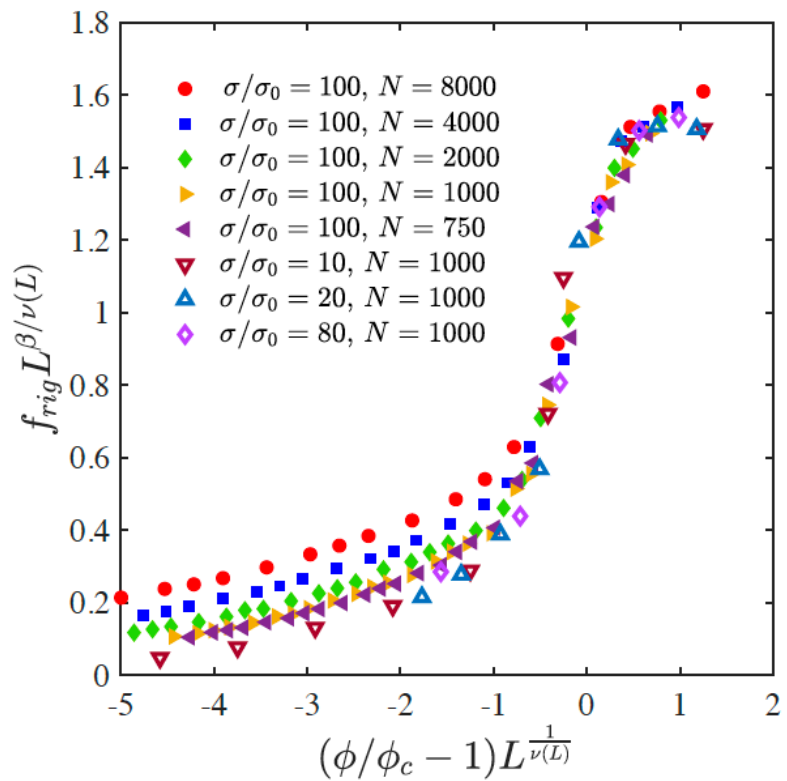


Clusters of Rigid Particles



2D Ising Exponents!

Clusters of Rigid Particles

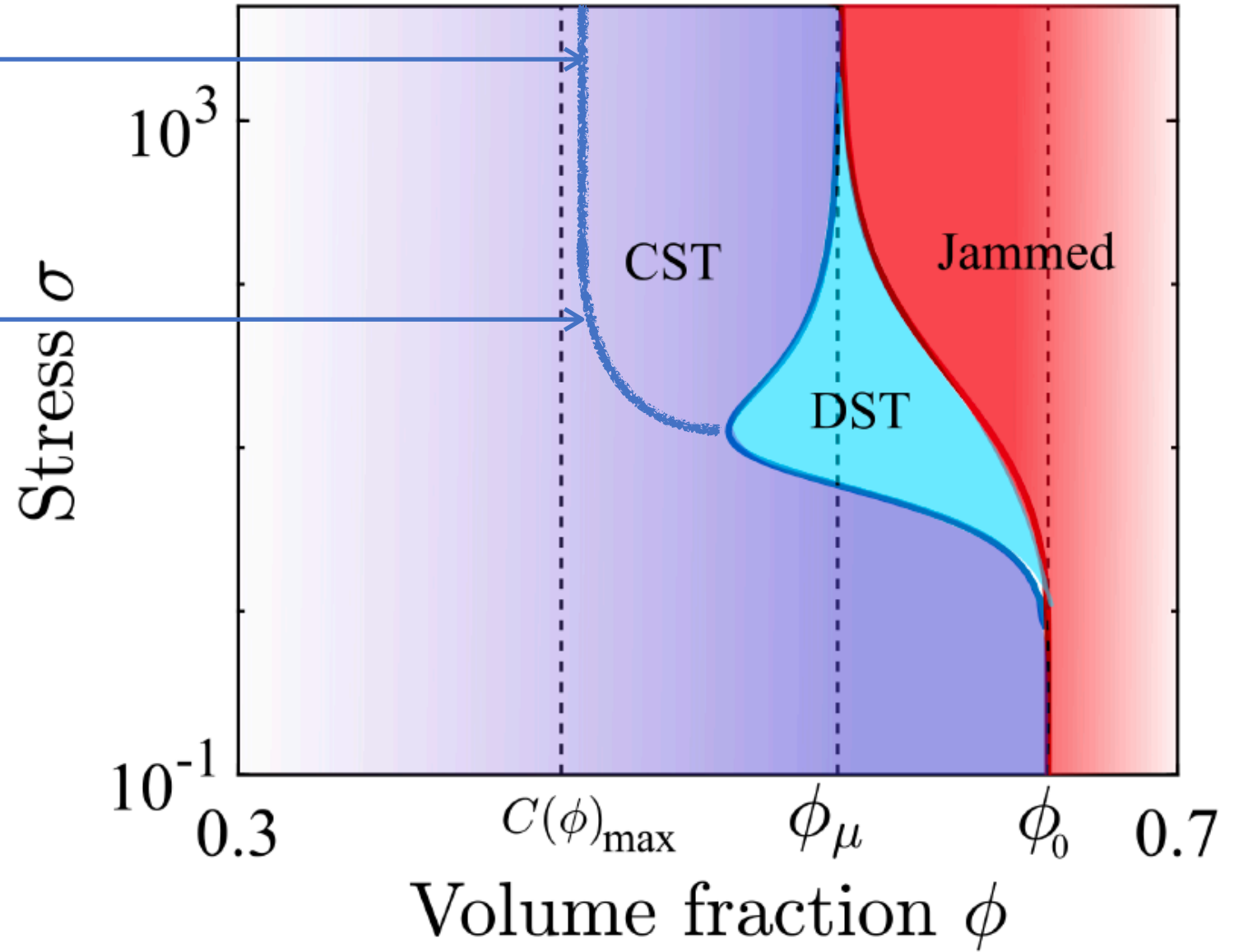


Clusters of Rigid Particles

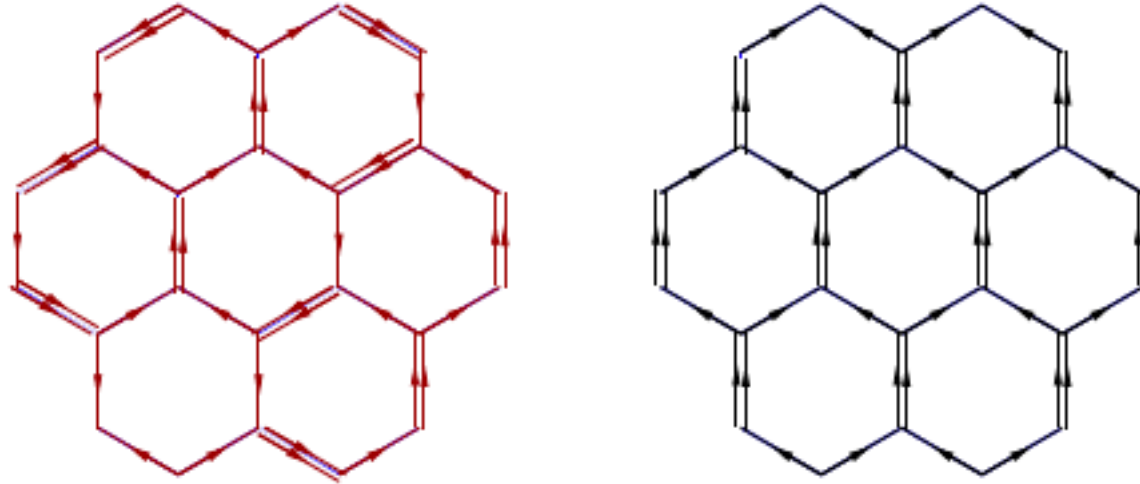
All contacts are frictional
Pure Ising Transition

Frictionless contacts
proliferate: vacancies/ spin 0

Tricritical Point ?
Two-Phase coexistence



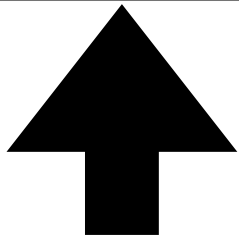
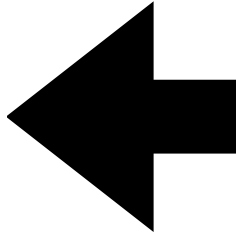
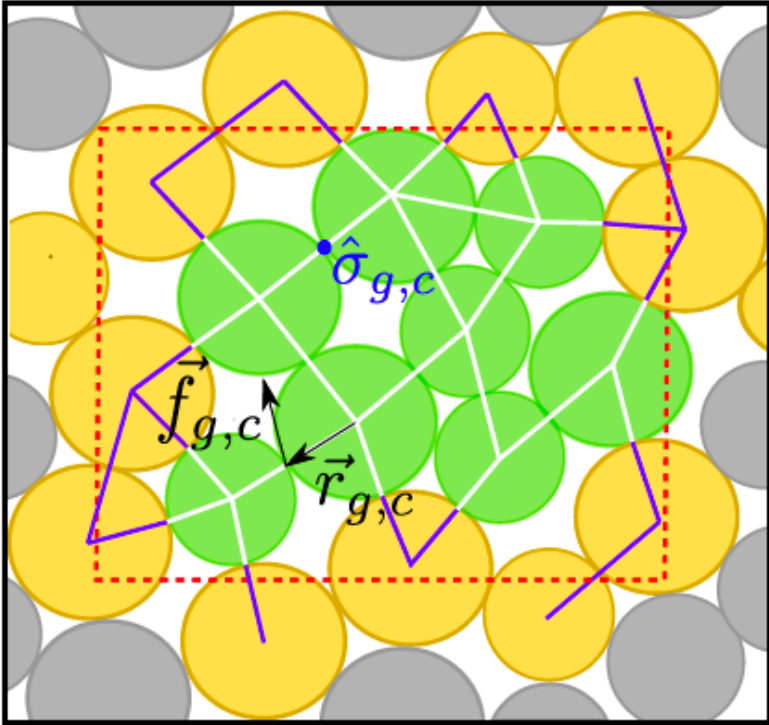
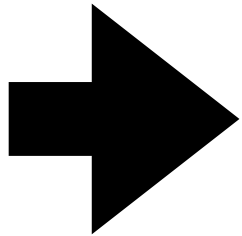
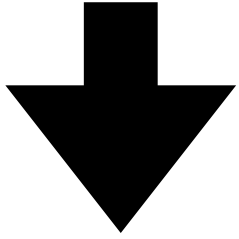
Constraints and Conservation Laws



- Lattice “fluxes” add up to zero at every vertex: divergence free condition satisfied by electric/magnetic fluxes
- Total “flux” in any direction is conserved
- Many microscopic configurations give the same total flux
- Appropriate coarse-graining variable: E field

$\nabla \cdot E = 0$ \longrightarrow Total flux is “conserved” \longrightarrow Constant Flux Ensemble

Force & Torque Balance: Boundary forces



$$\begin{aligned} \sum_{c \in g} \vec{f}_{g,c} &= 0 \\ &= \vec{f}_{body} \\ \sum_{c \in g} \vec{r}_{g,c} \times \vec{f}_{g,c} &= 0 \end{aligned}$$

Force-Moment Tensor

$$\hat{\sigma}_{g,c} = \vec{r}_{g,c} \otimes \vec{f}_{g,c}$$

Coarse-grained Stress Tensor

$$\hat{\sigma}(\vec{r}) = \frac{1}{\Omega_r} \sum_{g,c \in \Omega_r} \vec{r}_{g,c} \otimes \vec{f}_{g,c}$$

Mapping to Vector-charge U(1) Gauge Theory

M. Pretko (2018)

Gauss's Law: $\partial_i E_{ij} = \rho_j$

E_{ij} and A_{ij} are conjugate variables

$$A_{ij} = A_{ij} + \partial_i \phi_j + \partial_j \phi_i$$

Charge and Charge angular momentum are conserved

Maxwell's Equations in Vacuum

$$\partial_i E_{ij} = \rho_j$$

$$\partial_i B_{ij} = \tilde{\rho}_j$$

$$\epsilon_{iab} \epsilon_{jcd} \partial_a \partial_c E_{bd} = -\partial_t B_{ij} - \tilde{J}_{ij}$$

$$\epsilon_{iab} \epsilon_{jcd} \partial_a \partial_c B_{bd} = \partial_t E_{ij} + J_{ij}$$

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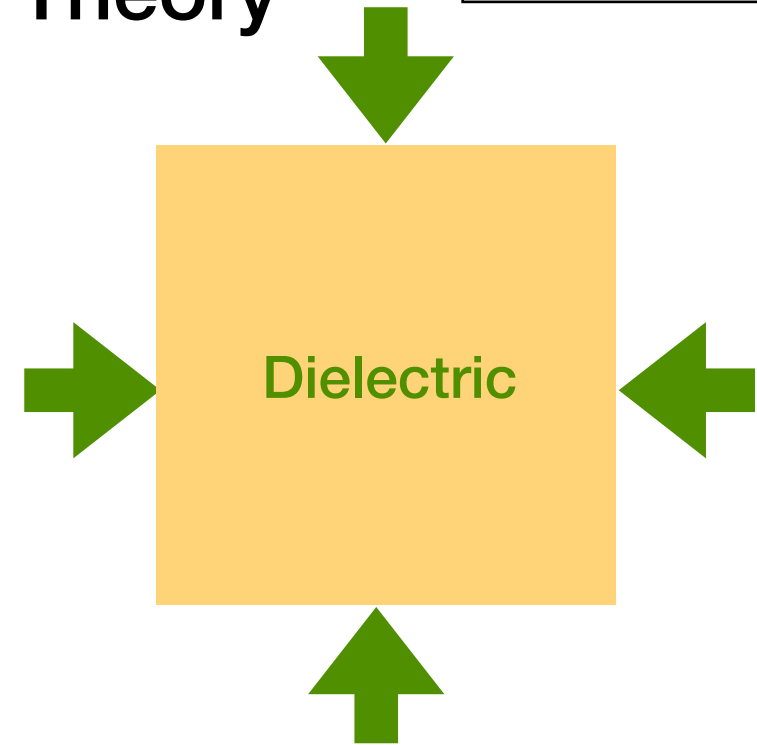
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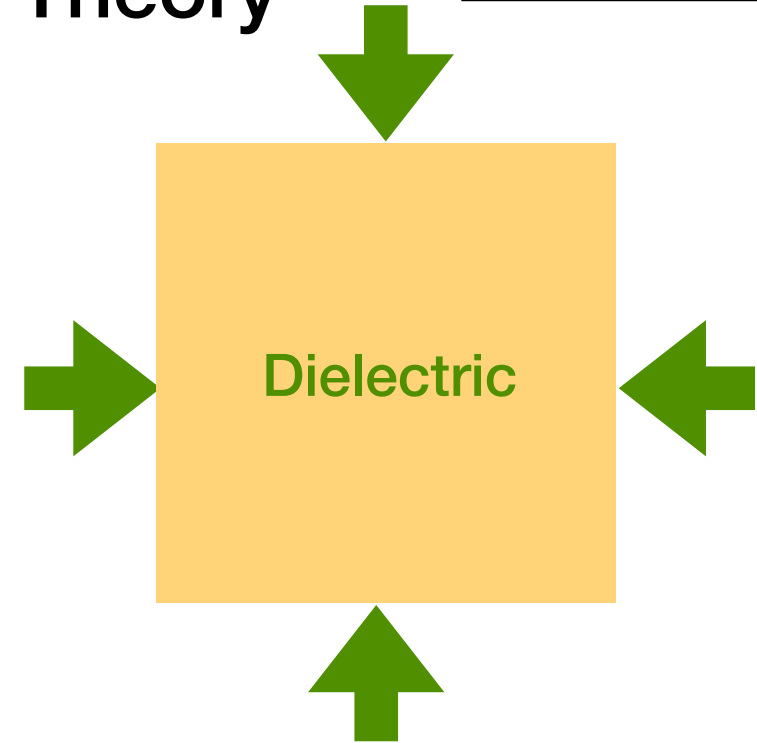
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Electrostatics in a Dielectric

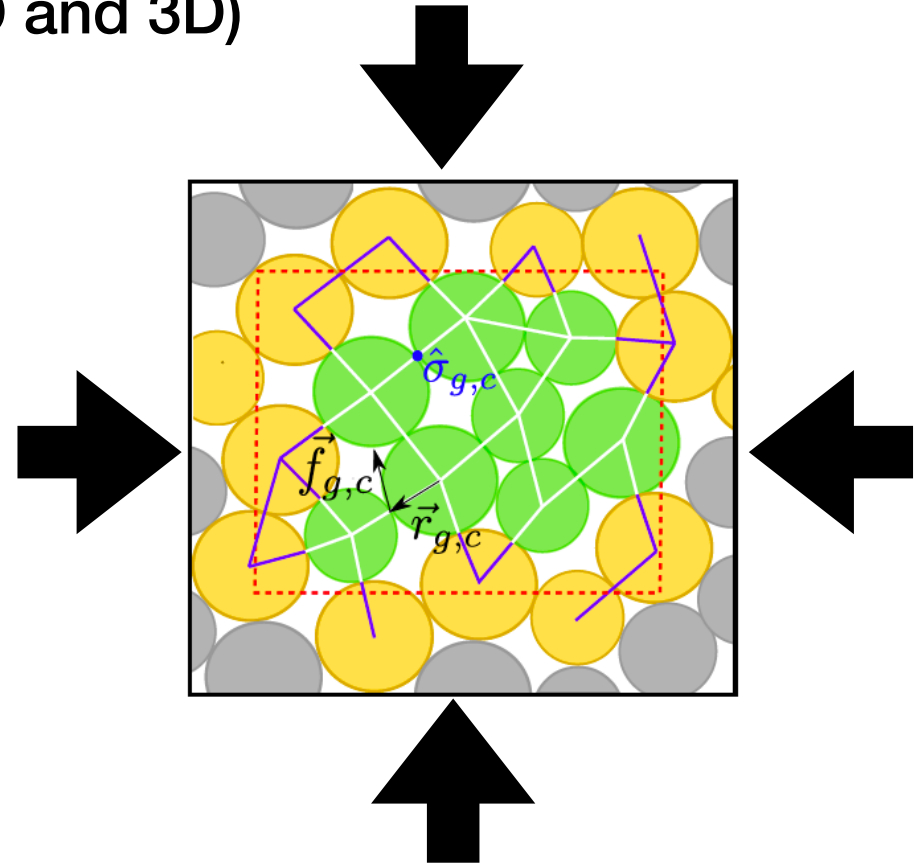
$$\partial_i E_{ij} = \rho_j^{free} + \rho_j^{bound}$$

$$\epsilon_{iab} \epsilon_{jcd} \partial_a \partial_c E_{bd} = 0$$

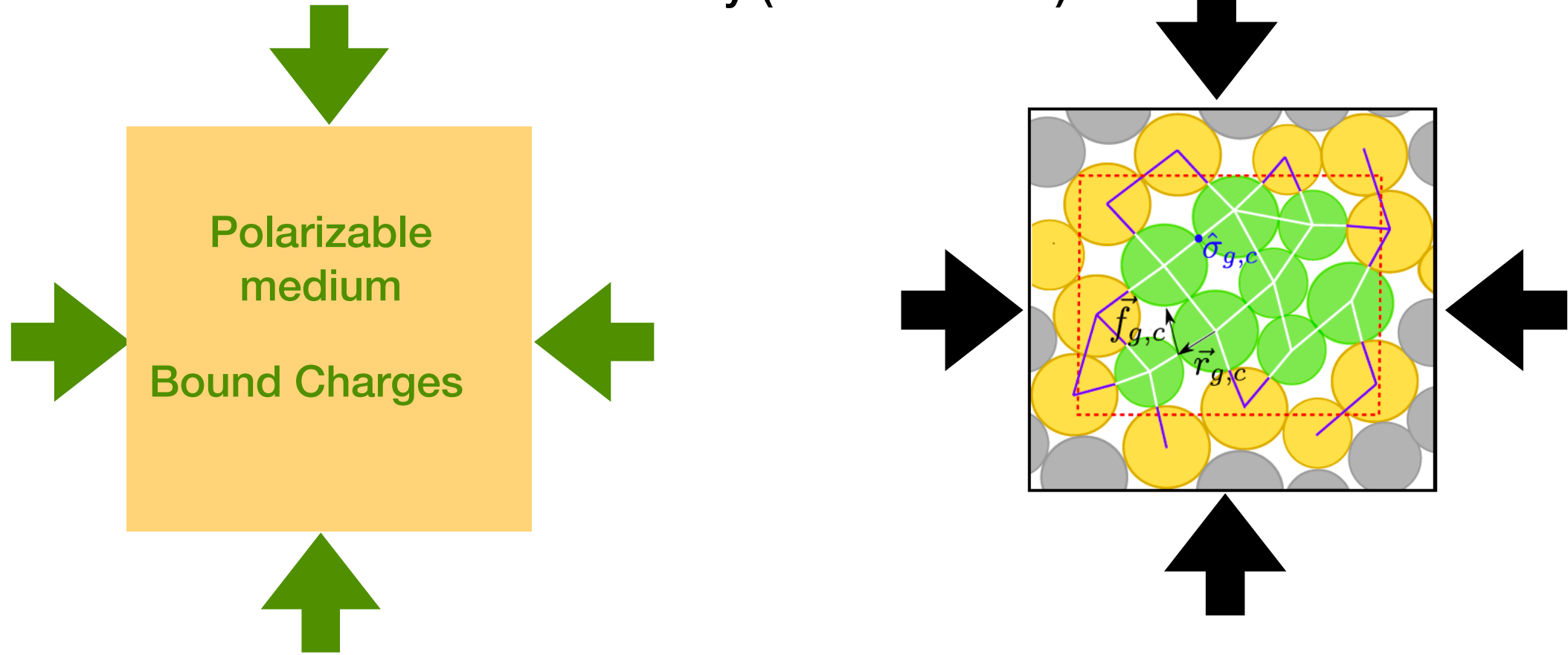
$$\partial_i D_{ij} = \rho_j^{free}$$

$$D_{ij} = \chi_{ijkl} E_{kl}$$

Mapping of amorphous elasticity to Vector-charge U(1) Gauge Theory (in 2D and 3D)



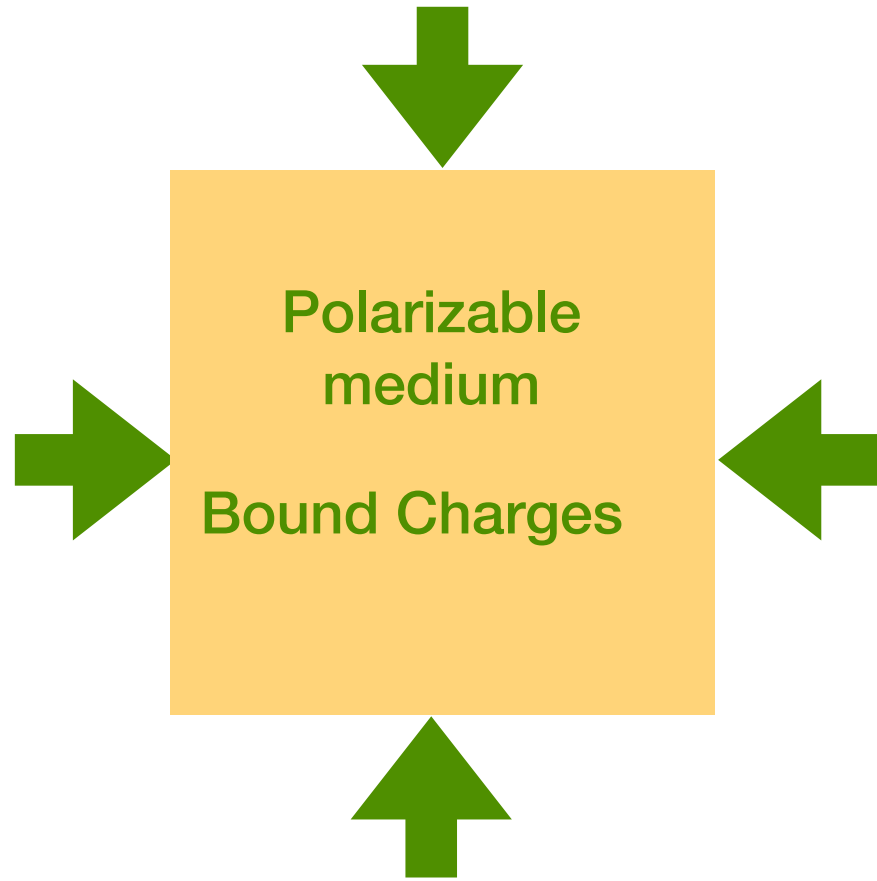
Mapping of amorphous elasticity to Vector-charge U(1) Gauge Theory (in 2D and 3D)



Vectorial "free" Charges/
Tensorial, Symmetric E field

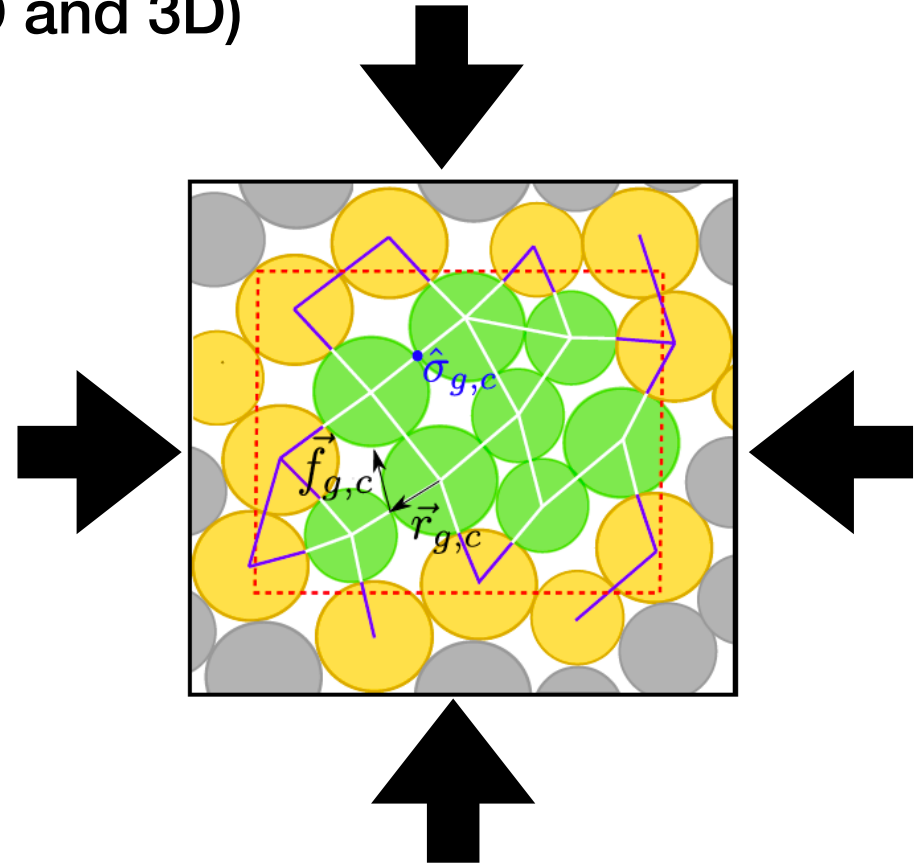
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Mapping of amorphous elasticity to Vector-charge U(1) Gauge Theory (in 2D and 3D)





Vectorial "free" Charges/
Tensorial, Symmetric E field

Gauss's Law: $\partial_i E_{ij} = \rho_j$



Charges map to Forces

Bound  Contact Forces
Free  Body/External forces

Stress-only Formulation of the Elasticity of Jammed States

$$\partial_i \sigma_{ij} = f_j^{\text{external}}$$

$$E_{ij} = \frac{1}{2} (\partial_i \phi_j + \partial_j \phi_i) \implies \epsilon_{iab} \epsilon_{jcd} \partial_a \partial_c E_{bd} = 0$$

$$\sigma_{ij} = K_{ijkl} E_{kl}$$

J. Nampoothiri et al
PRL (2021), PRE (2023)

Crucial Differences from Classical Elasticity:

- Rigidity is a consequence of constraints not broken symmetry
- Instead of physical displacement fields defining a strain tensor, there are gauge potentials defining a field that looks like the strain tensor
- The elastic moduli are not material properties but emerge from properties of the network created by external stresses (does not have the usual symmetries)
- The elastic moduli do not have to satisfy the symmetry requirements coming from a free-energy.

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PRL (2021), PRE (2023)

Total flux of stress
components is conserved
Bi et al: Annual Reviews of
Condensed Matter (2015)

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Constraints Conserved Quantities

$$\frac{dP_\alpha(t)}{dt} = \sum_{\beta} W(\alpha|\beta)P_\beta(t) - W(\beta|\alpha)P_\alpha(t)$$

If dynamics conserves some quantity (U),
then $P_\alpha = f_\alpha / Z_\mu(U)$

$$Z_\mu(U) = \sum_{\alpha} f_\alpha \delta(U_\alpha - U)$$

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- Analogs of Microcanonical and Canonical Ensembles
- Edwards “Thermodynamics”
- Field Theories are Emergent Gauge Theories (due to constraints)
- Effective Hamiltonians ==> Universality and Scaling ?